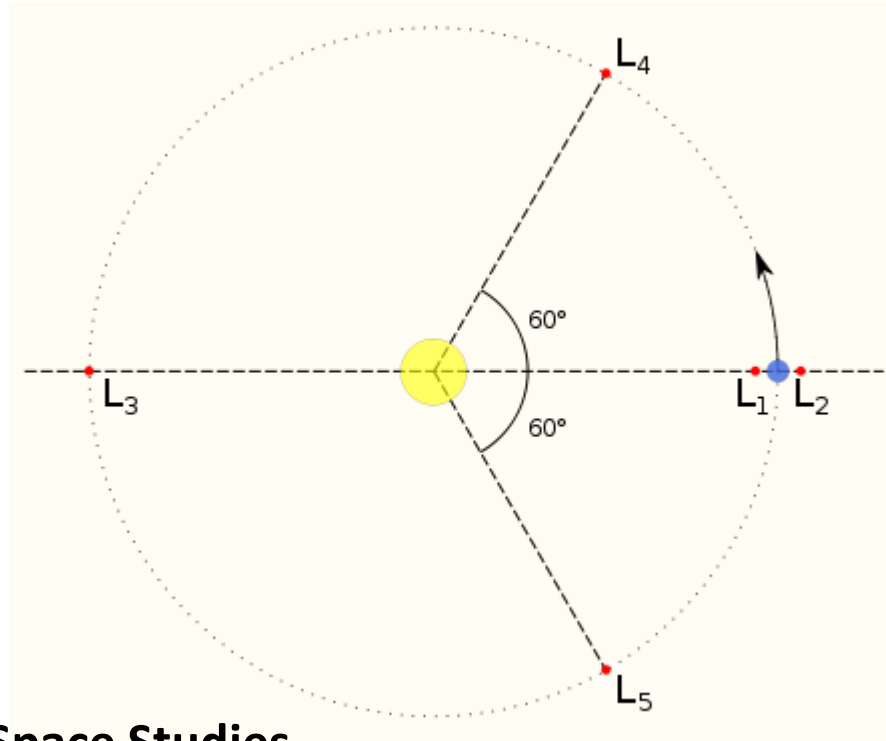


Low-deltaV Trajectories

to move a small asteroid to a Lagrange point



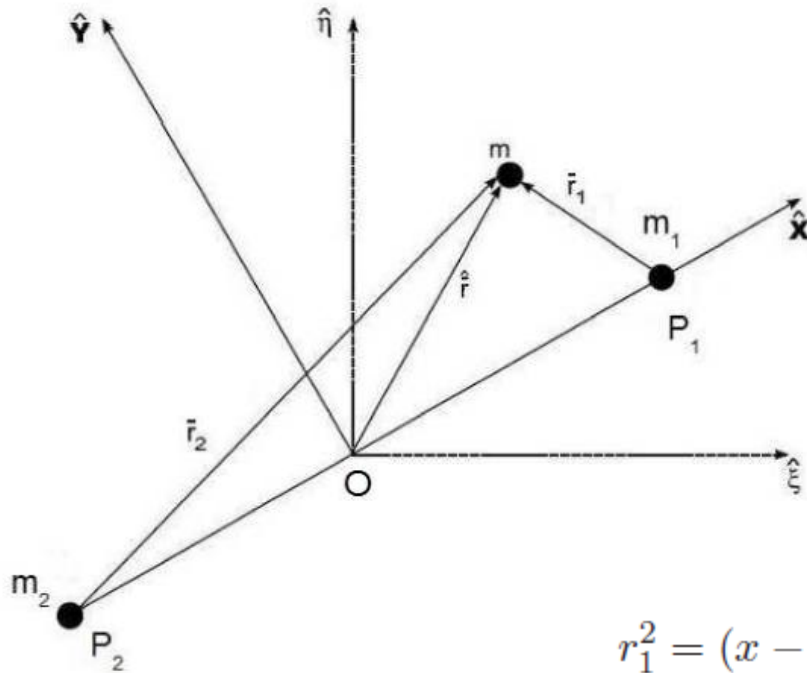
Keck Institute for Space Studies
Asteroid Retrieval Mission Study
Short Course
09/27/2011

Marco Tantardini
marco.tantardini@gmail.com

Summary

- Lagrange points: definition
- Orbits about Lagrange points and invariant manifolds (Low DeltaV Trajectories)
- Why a NEA near EM L1/L2 or SE L2? Potential destination for human missions
- Missions to Lagrange points: overview
- Asteroid Retrieval Mission Study: matching low-thrust with invariant manifolds?

CR3BP



$$r_1^2 = (x - \mu)^2 + y^2 + z^2$$

Equations of motion

$$\begin{aligned}\ddot{x} - 2\dot{y} &= \frac{\partial U}{\partial x} \\ \ddot{y} + 2\dot{x} &= \frac{\partial U}{\partial y} \\ \ddot{z} &= \frac{\partial U}{\partial z}\end{aligned}$$

$$U = \frac{1}{2}(x^2 + y^2) + \frac{1 - \mu}{r_1} + \frac{\mu}{r_2}$$

$$r_2^2 = (x - \mu + 1)^2 + y^2 + z^2$$

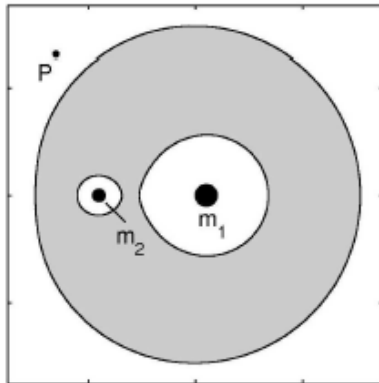
The Circular Restricted 3-Body Problem describes the motion of a massless particle under the gravitational influence of two point masses m_1 and m_2 , called primaries, in circular motion around their common centre of mass.

Jacobi constant

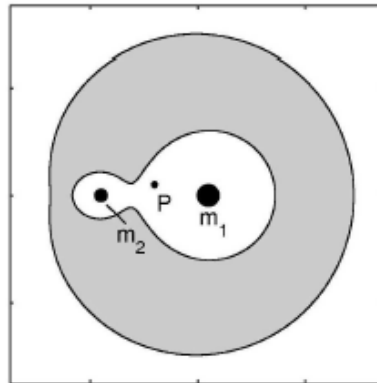
$$C = x^2 + y^2 + \frac{2(1 - \mu)}{r_1} + \frac{2\mu}{r_2} - V^2$$

Surfaces of Hill

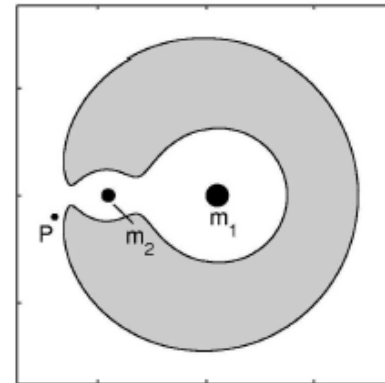
boundary for the admissible motion



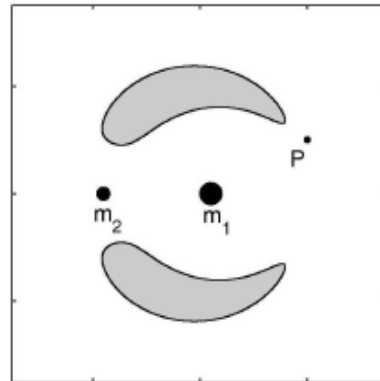
Case 1 : $C > C_1$



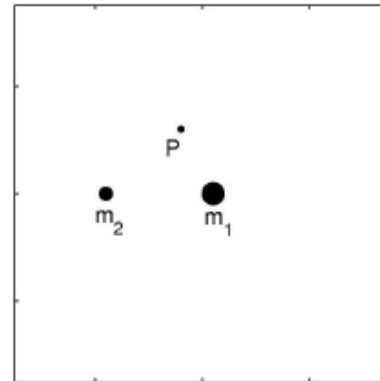
Case 2 : $C_1 > C > C_2$



Case 3 : $C_2 > C > C_3$

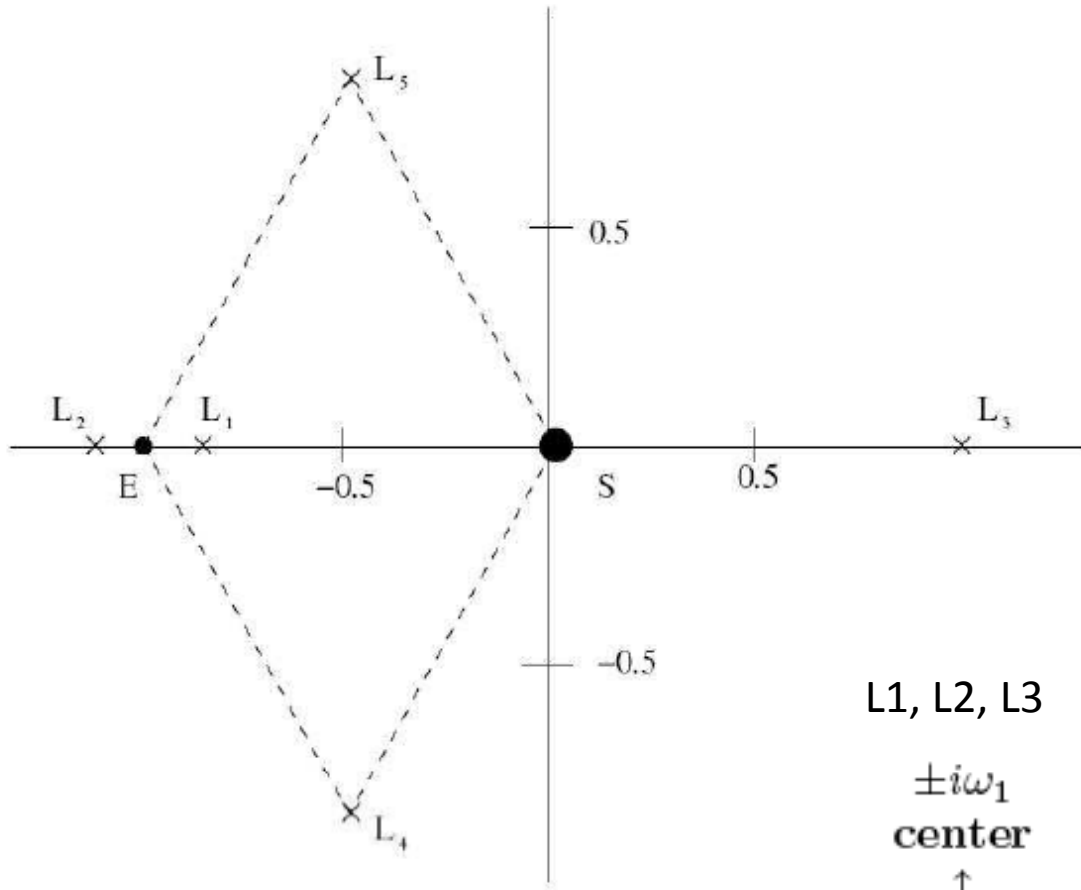


Case 4 : $C_3 > C > C_4$



Case 5 : $C_4 > C$

Lagrange points



SE L1/L2: about 1.5 million km from the Earth

EM L1/L2: about 60,000 km from the Moon

1 AU: about 150 million km

1 LD: 384,403 km

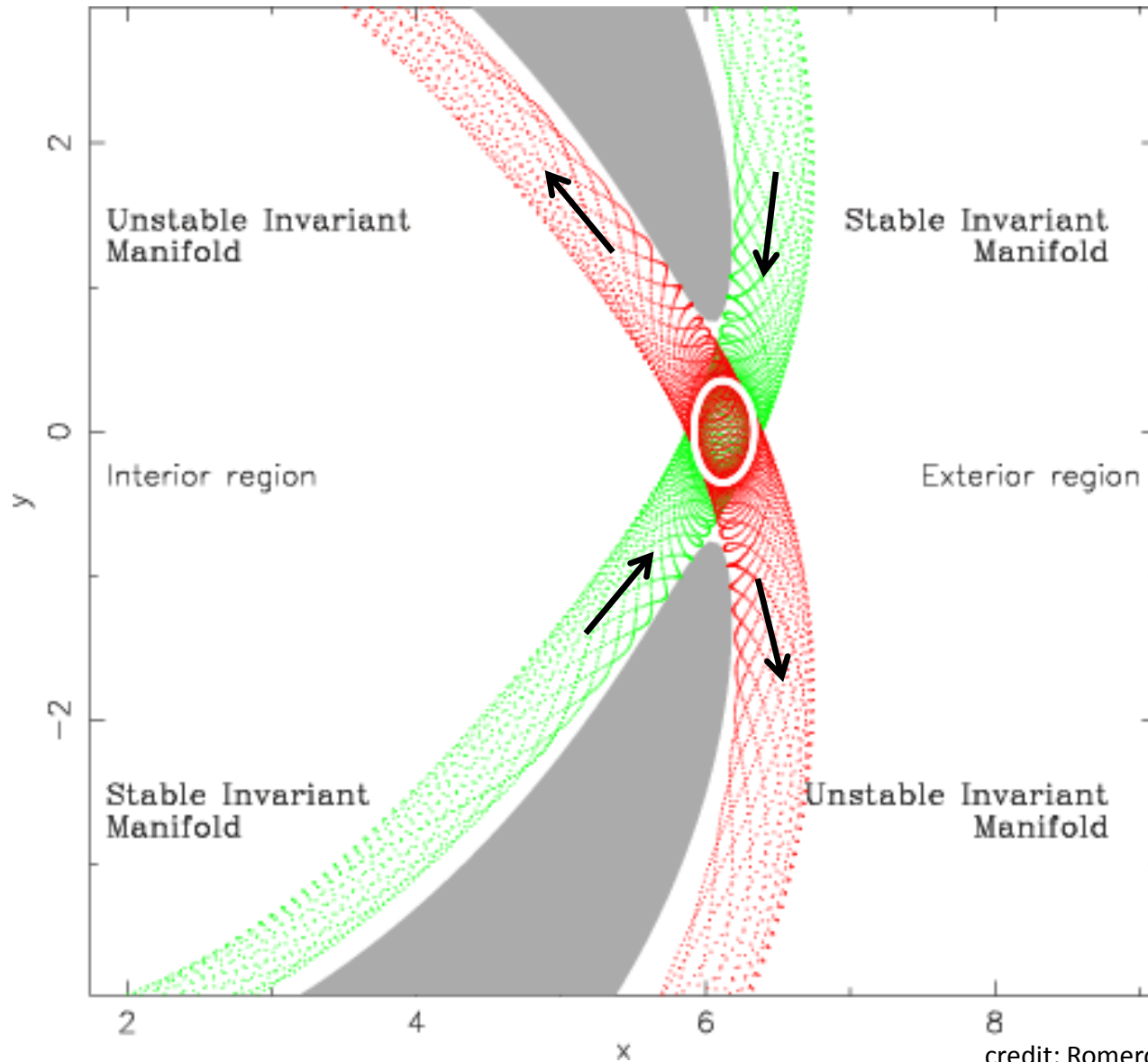
L1, L2, L3

$\pm i\omega_1$	\times	$\pm i\omega_2$	\times	$\pm\lambda$
center		center		saddle
\uparrow		\uparrow		\uparrow
planar p.o.		vertical p.o.		inv. manif.



Cantor set of 2D tori

Invariant Manifolds



EM L1/L2 vs SE L2 as targets for human missions

EM L1

$\Delta V_1 = 3.0661$ km/s
 $\Delta V_2 = 0.8859$ km/s
 $\Delta V_{tot} = 3.9520$ km/s
Transfer = 3.8 days

EM L2

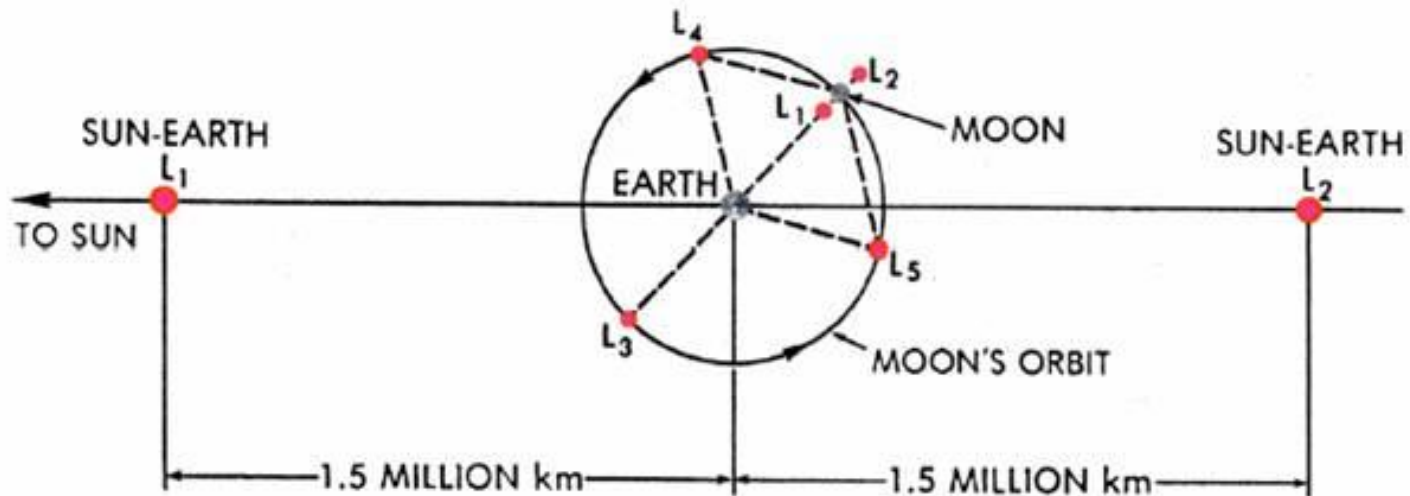
$\Delta V_1 = 3.0966$ km/s
 $\Delta V_2 = 0.7819$ km/s
 $\Delta V_{tot} = 3.8786$ km/s
Transfer = 6.2 days

SE L2

$\Delta V_1 = 3.1537$ km/s
 $\Delta V_2 = \mathbf{0.4666}$ km/s
 $\Delta V_{tot} = 3.6203$ km/s
Transfer = 37.6 days

Hohmann transfer from LEO ($h = 400$ km)

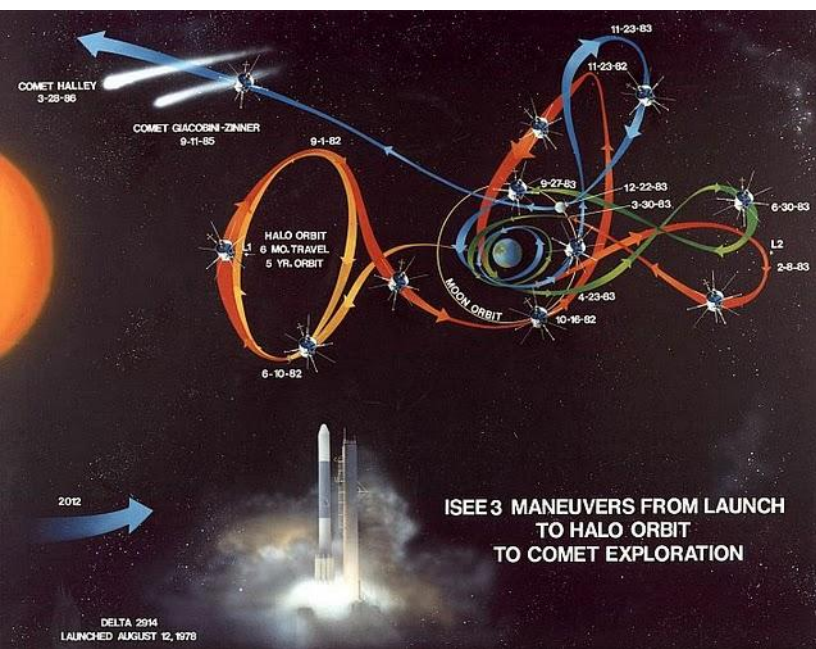
Current NASA plans for manned missions to a NEA, total mission duration: 180 days.
Targets: 2009 OS5 (2020 and 2036), 1999 AO10 (2025), 2003 SM84 (2046)



credit: Ross and Lo

ISEE-3

International Sun-Earth Explorer-3

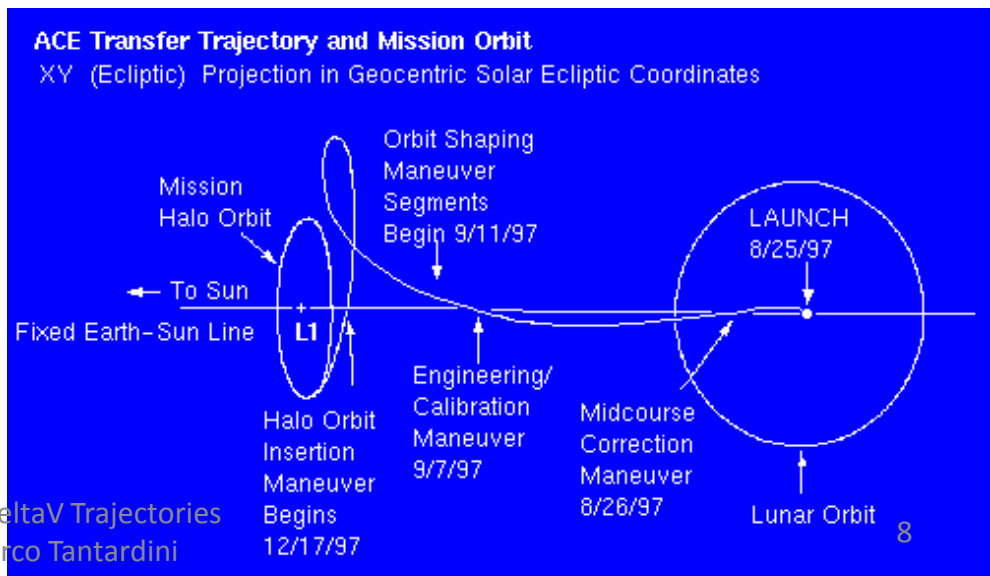
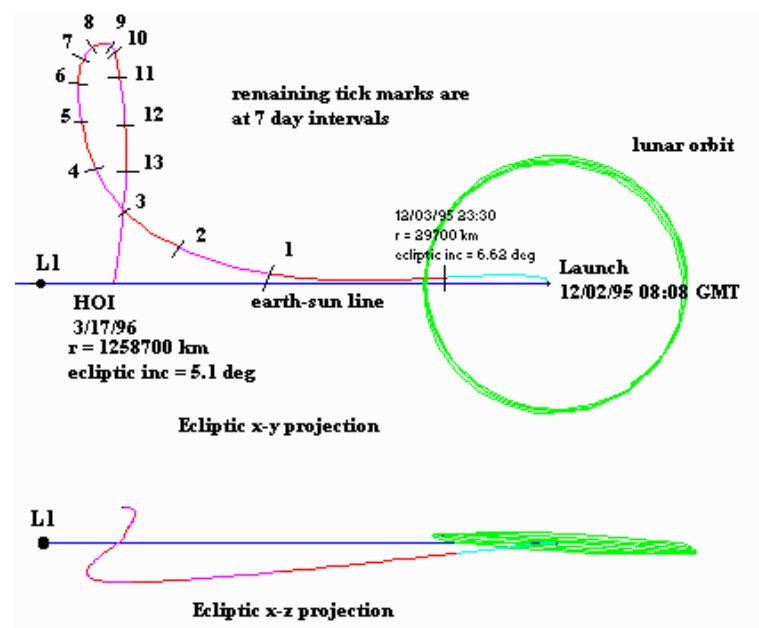


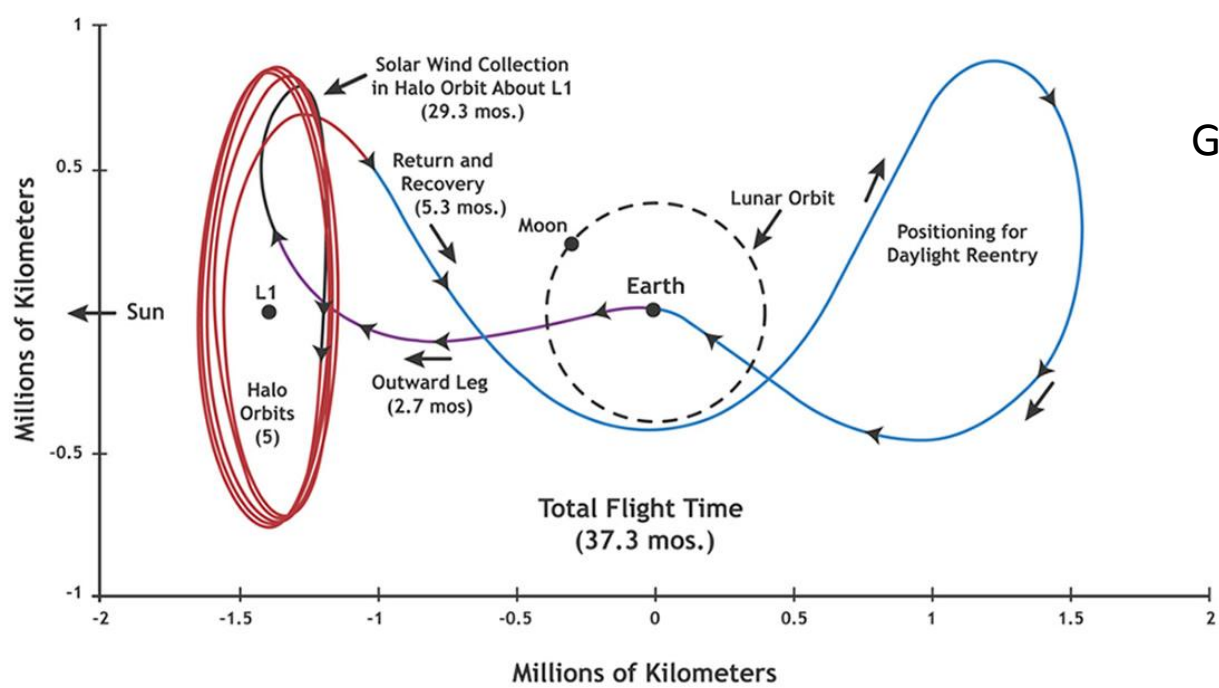
ACE

Advanced Composition Explorer

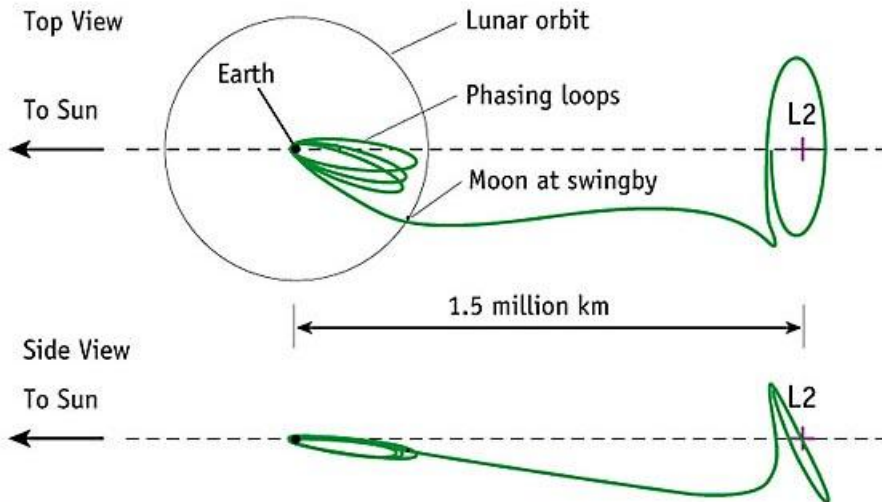
SOHO

Solar and Heliospheric Observatory





GENESIS



WMAP Wilkinson Microwave Anisotropy Probe



Other missions to Lagrange points

Wind (SE L1)

Grail (SE L1)

Herschel and Planck (SE L2)

Chang'e 2 (SE L2)

Artemis (EM L1 and L2)

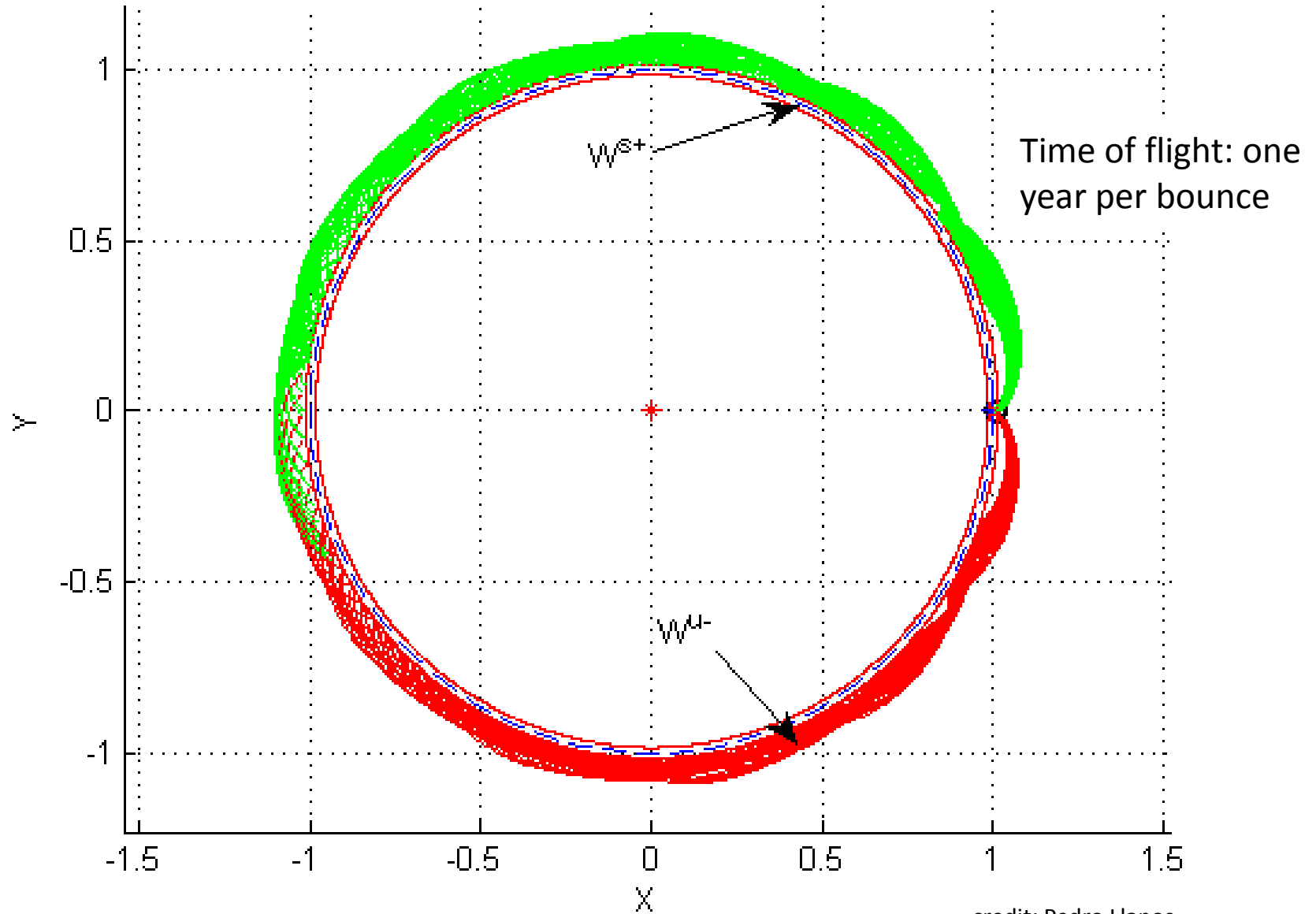
James Webb Space Telescope (SE L2) ?

Trajectory design for Asteroid Retrieval Mission

1) Earth - NEA leg: pure low-thrust

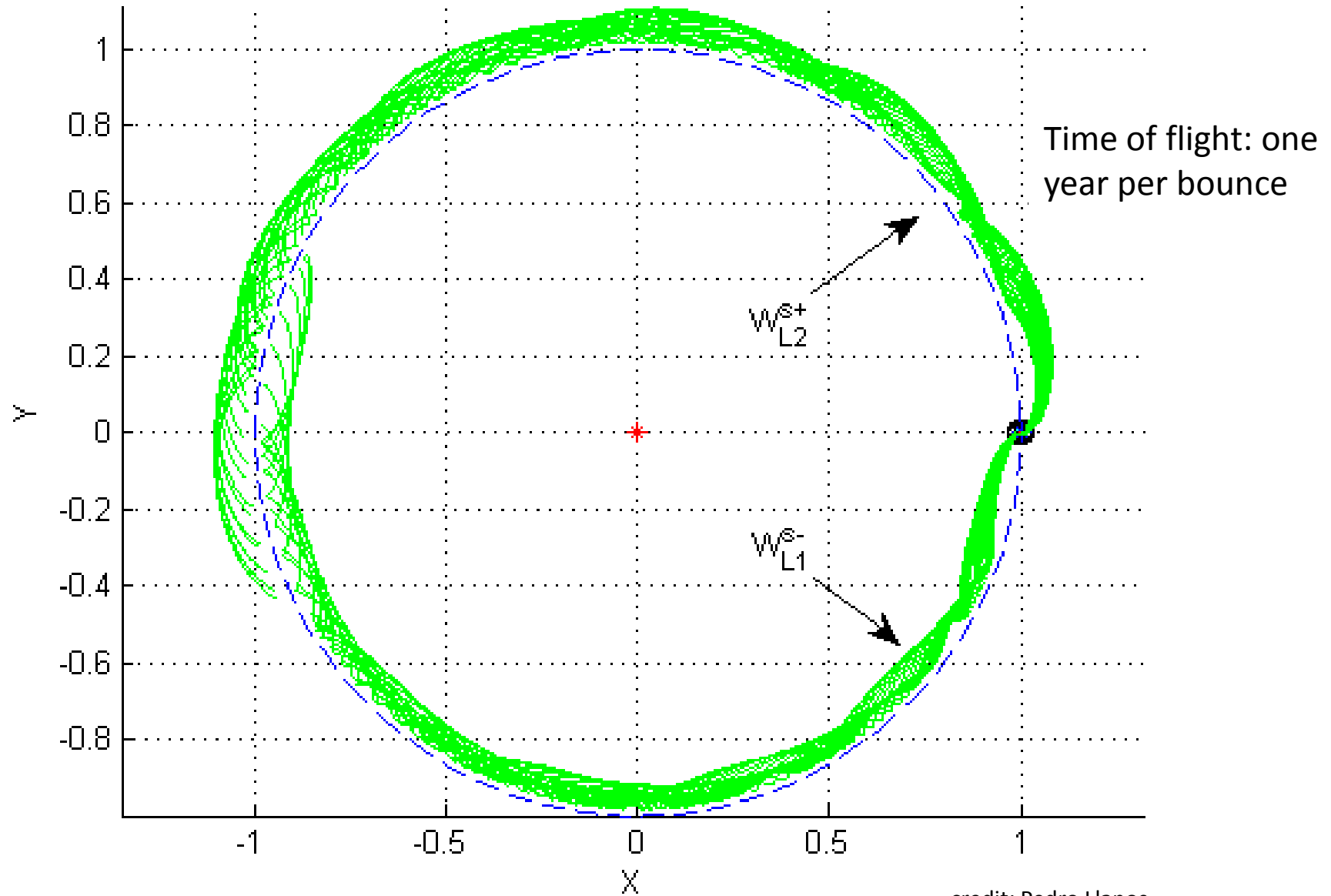
2) NEA - Lagrange point: how?

Invariant Manifolds SE L2



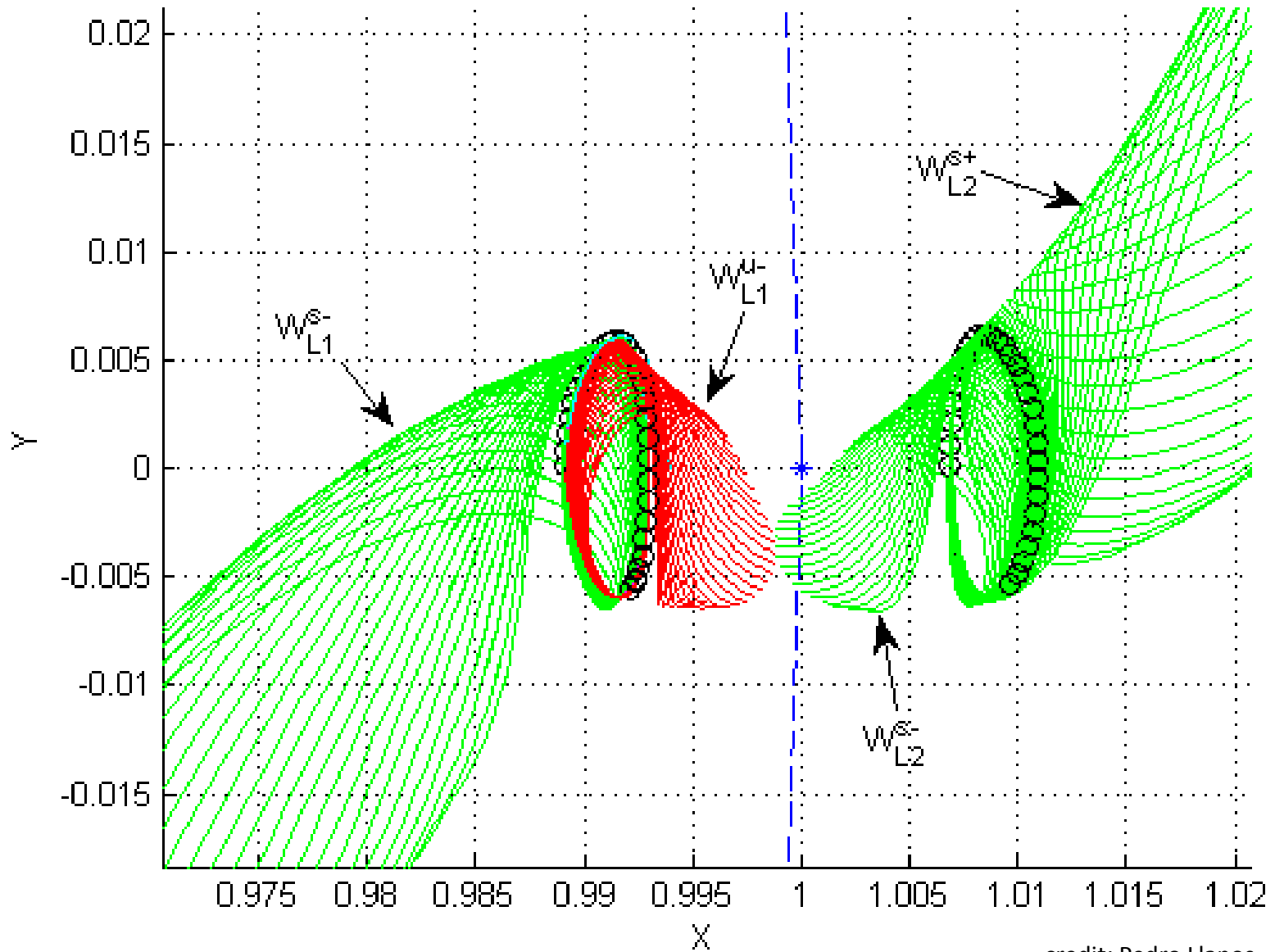
credit: Pedro Llanos

Stable Manifolds SE L1/L2



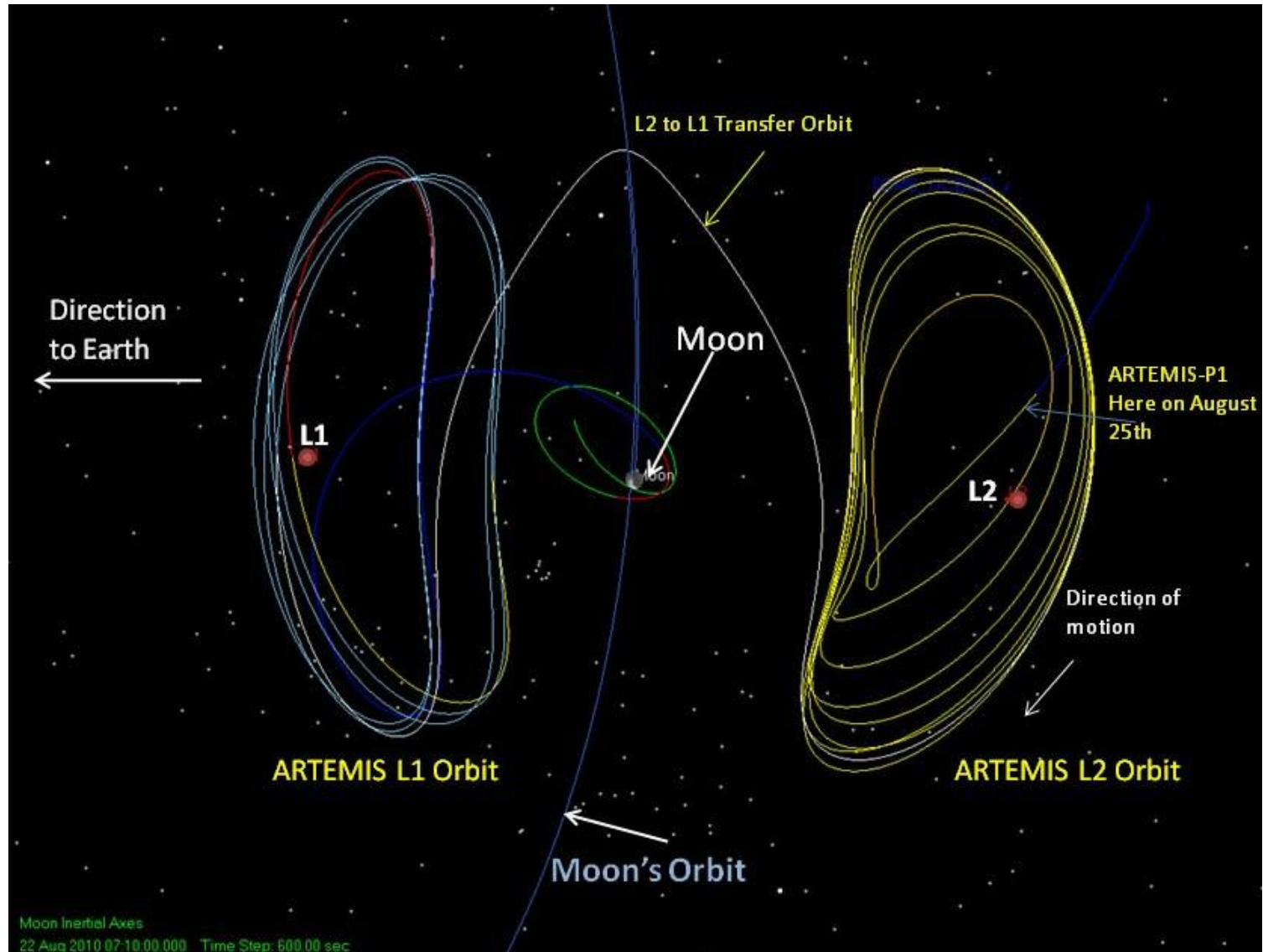
credit: Pedro Llanos

SE L1 L2 Heteroclinic Connection

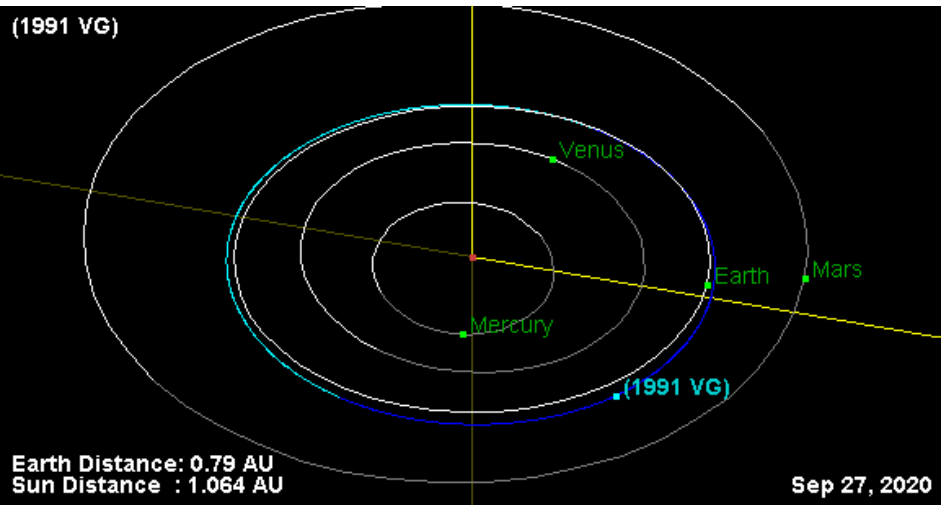


credit: Pedro Llanos

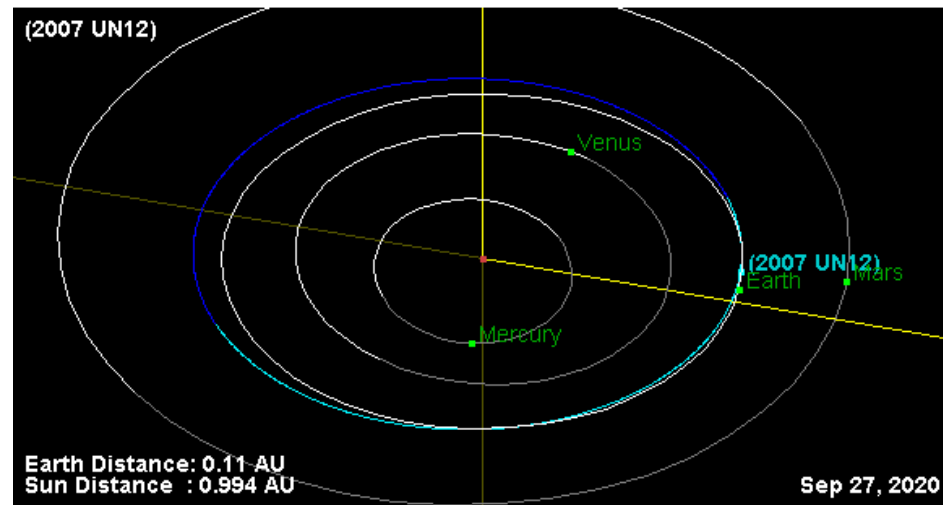
Connection between L1 and L2



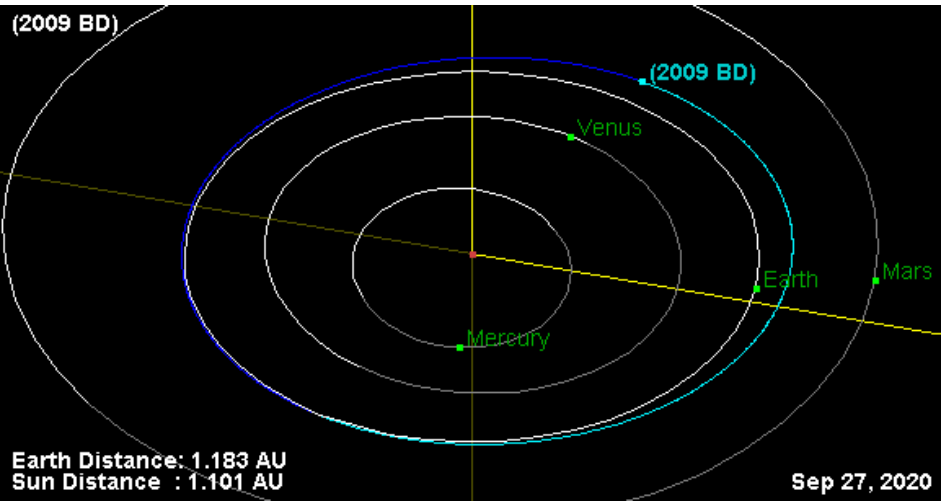
1991 VG



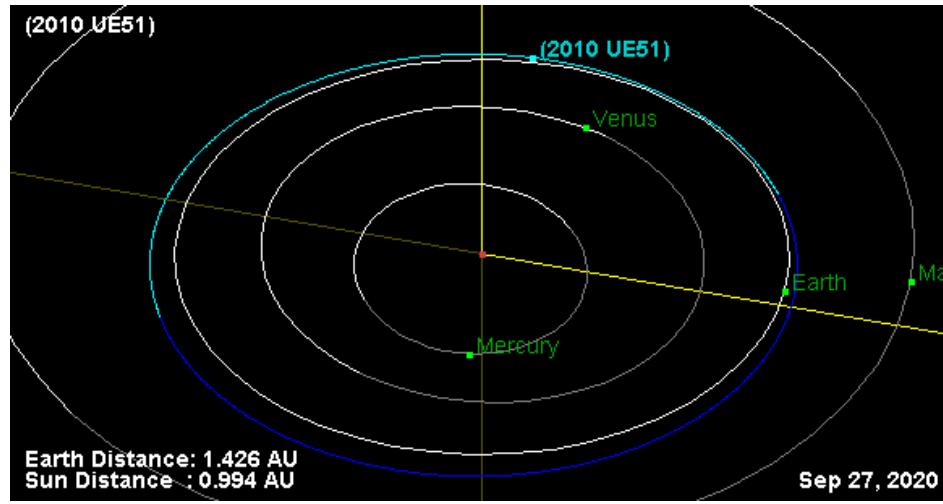
2007 UN12



2009 BD



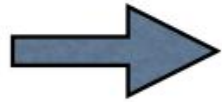
2010 UE51



ssd.jpl.nasa.gov

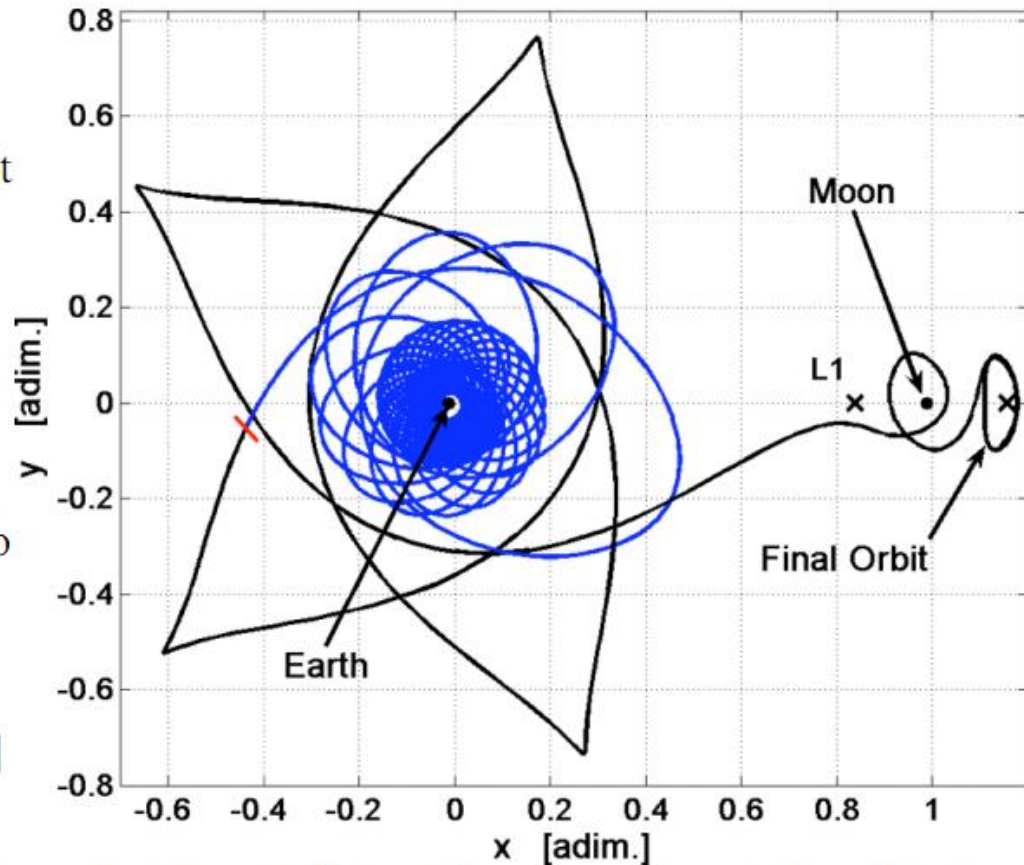
Combining low-thrust + invariant manifolds has been studied

G. Mingotti, F. Topputo, F. Bernelli-Zazzera (2006)



GTO -> thrust arc -> stable manifold -> halo orbit

- GTO:
chosen as the starting orbit
- thrust arc:
solution of an optimal control problem
- stable manifold:
associated to the final halo
- halo orbit:
computed through the Richardson method [1980]



G. Mingotti, F. Topputo, and F. Bernelli-Zazzera - Low Thrust, Stable Manifold Trajectories to the Earth-Moon Halo Orbits

IDEA for Asteroid Retrieval

NEA -> thrust arc -> stable manifold -> target Lagrange point (SE L1/L2)

Why study SE L1/L2 first? Because if the NEA is in SE L1/L2 then it can be moved to EM L1/L2 through invariant manifolds (EM CR3BP)

If the final destination is a Lagrange point, low-thrust + invariant manifolds might be more energy efficient than pure low-thrust. Thus, for a selected NEA, we might need smaller SEP.