

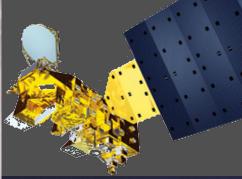
# Are microwave sounders

obsolete?

Bjorn Lambrigtsen
(with contributions from many others)

**JPL** 







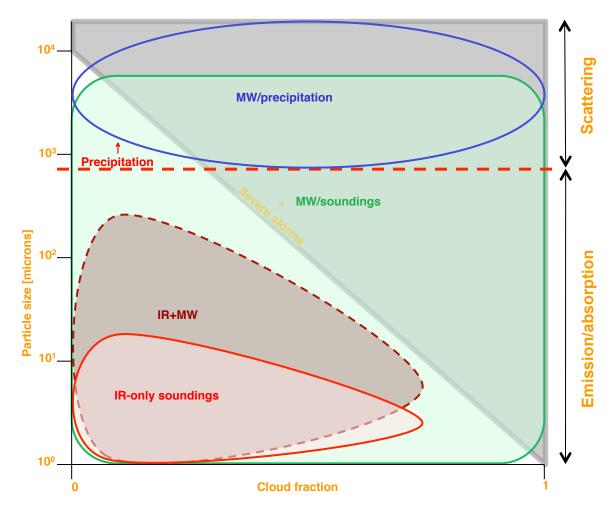


KISS Workshop on Innovative Satellite Observations to Characterize the Cloudy Boundary Layer

Caltech; September 22, 2010

# Why we need microwave sounders

MW sounders measure all three phases of water: vapor, liquid (incl. rain), solid (incl. snow) Ideally suited for the hydrologic cycle



Note: This is a 2-D view of a multidimensional world Additional dimensions include spatial and temporal scales

## Why not just IR sounders?

IR vs. MW: Pros & Cons

# IR sounders vs. MW sounders

#### **Spatial resolution**

--IR vs. MW: 10-15 km vs. 15-50 km hor.res.; 1-1.5 km vs. ~2 km vert.res.

#### **Basic sounding accuracy**

--IR vs. MW: 1 K vs. 1.5 K for T(z); 15% vs. 20% for q(z); none vs. 40% for L(z)

#### Scene coverage

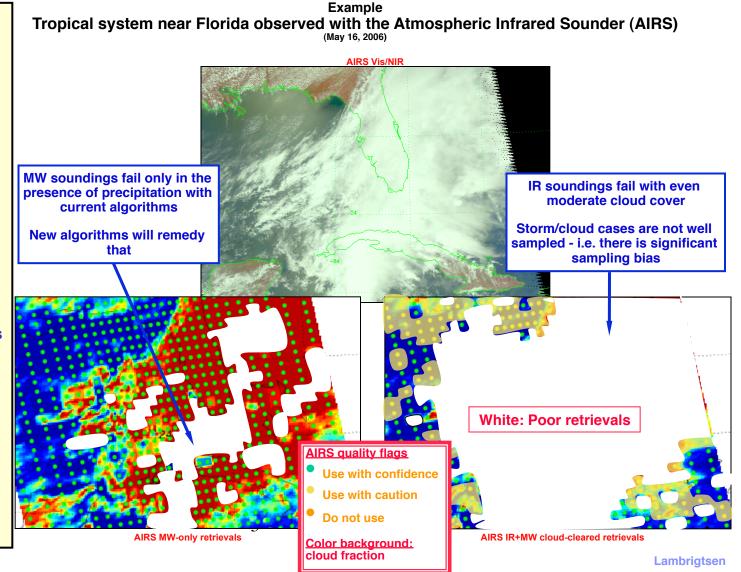
- --Cloud free: IR outperforms MW (but IR = MW in coverage)
- --Partly cloudy: IR < MW (IR depends on "cloud clearing", a noise-amplifying process)
- --Fully cloudy, storms: MW far outperforms IR ("cloud clearing" cannot be done)

#### **Hurricanes & severe storms**

- --IR can only see cloud tops, often obscured by cirrus canopy
- --MW can see to surface (except in heavy precipitation: switch to convection algorithms)

#### Summary

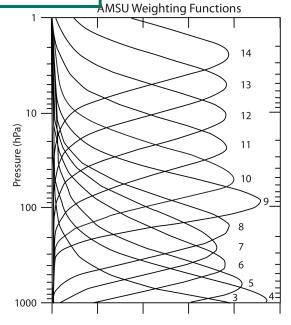
- --IR is best suited for global observations and storm precursor conditions in clear sky
- --MW is best suited for observing in/through storms and precursor conditions in clouds



## Satellite MWS state of the art: AMSU

AMSU-A (temperature sounder); spatial res ~ 50 km

C)	G 6	L D . 1.1.1		<b>D</b> 1
Ch	Cen.freq.	B-width	Meas.	Pol
#	[MHz]	[MHz]	NEDT [K]	
1	23800	1x270	0.17	V
2	31400	1x180	0.25	V
3	50300	1x160	0.25	V
4	52800	1x380	0.14	V
5	53596±115	2x170	0.19	Н
6	54400	1x380	0.17	Н
7	54940	1x380	0.14	V
8	55500	1x310	0.16	Н
9	57290.344 [fo]	1x310	0.16	Н
10	fo±217	2x 77	0.22	Н
11	fo±322.4±48	4x 35	0.24	Н
12	fo±322.4±22	4x 16	0.36	Н
13	fo±322.4±10	4x 8	0.50	Н
14	fo±322.4±4.5	4x 3	0.81	Н
15	89000	1x2000	0.12	V



# AMSUs are flying on multiple satellites:

- NASA/Aqua
- NOAA-15
- NOAA-16
- NOAA-17
- NOAA-18
- NOAA-19
- Metop-A

Producing > 2 million soundings per day!

### **ATMS** coming soon

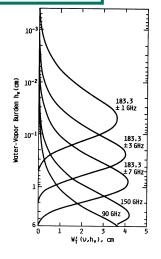
- NASA/NPP
- JPSS

### ATMS ≈ AMSU, except

- 2x humidity channels
- 30 km res T-sounding

### AMSU-B (humidity sounder); spatial res ~ 15 km

Ch	Cen.freq.	B-width	Meas. NEDT	Pol
#	[MHz]	[MHz]	[K]	
	89000	1x4000	N/A	V
	150000	1x4000	0.68	V
	183310±1000	2x 500	0.57	_
	183310±3000	2x1000	0.39	_
	183310±7000	2x2000	0.30	V

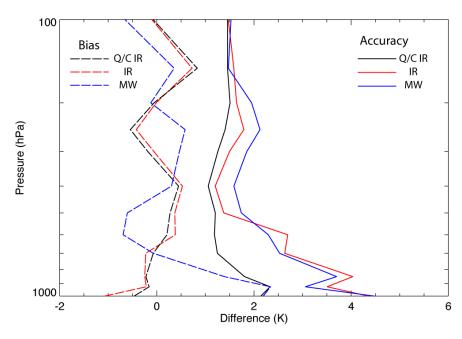


## Other products:

- Cloud liquid water (~ 1 piece of info ≈ LWC or nominal profile
- Precipitation (height resolved)

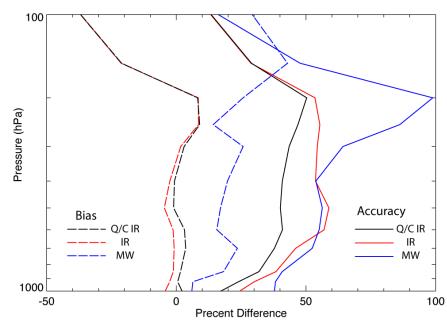
# Sounding accuracy: IR vs. MW

## Global statistics, one day



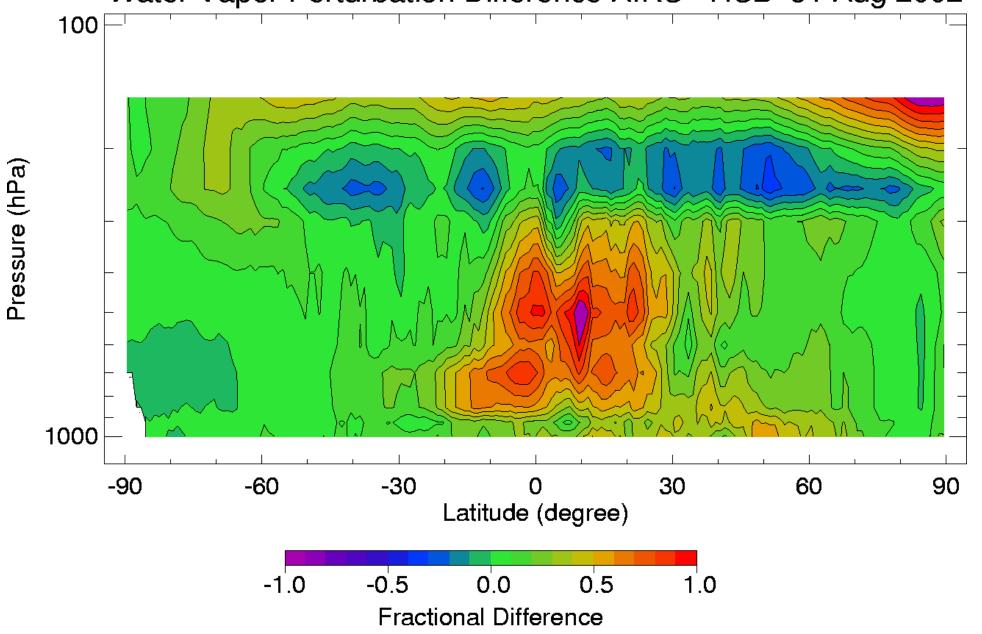
Water vapor retrievals →

## **←** Temperature retrievals



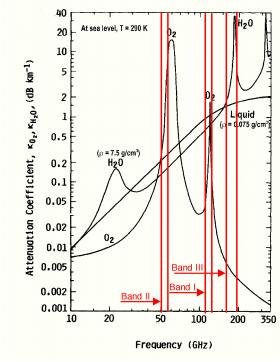
# Regime sampling: IR vs. MW

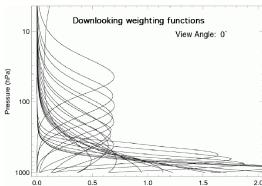
Water Vapor Perturbation Difference AIRS - HSB 31 Aug 2002

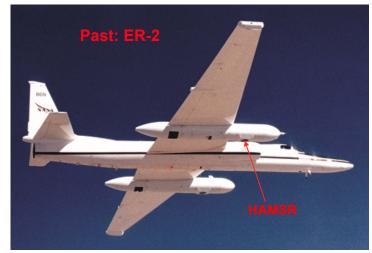


## Aircraft MWS state of the art: HAMSR

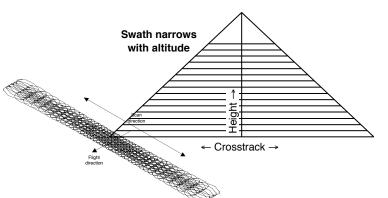
# The High Altitude MMIC Sounding Radiometer HAMSR









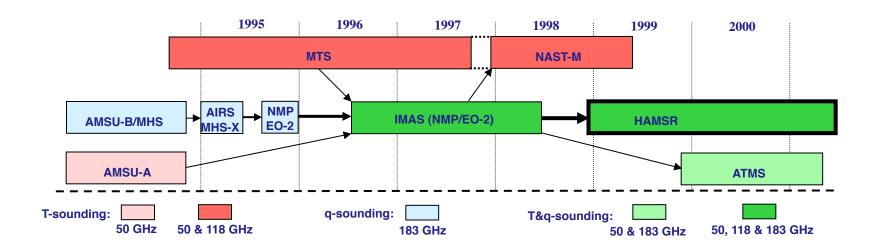


Chan	Center	Offset	Bandwidth	Wt-func. Peak
#	freq.	[GHz]	[MHz]	[mb or mm]
	[GHz]			
I-1	118.75	-5.500	1500	Sfc/[30 mm]
I-2	"	-3.500	1000	Surface
I-3	"	-2.550	500	Surface
I-4	"	-2.050	500	1000 mb
I-5	"	-1.600	400	750 mb
I-6	"	-1.200	400	400 mb
I-7	"	±0.800	2x400	250 mb
I-8	"	±0.450	2x300	150 mb
I-9	"	±0.235	2x130	80 mb
I-10	"	±0.120	2x100	40 mb
(I-1)	50.30	0	180	Sfc/[100 mm]
II-2	51.76	0	400	Surface
(II-3)	52.80	0	400	1000 mb
(II-4)	53.596	±0.115	2x170	750 mb
<b>(11-5)</b>	54.40	0	400	400 mb
(II-6)	54.94	0	400	250 mb
(II-7)	55.50	0	330	150 mb
(II-8)	56.02	0	270	90 mb
	56.67		330	
(II-)	183.31	-17.0	4000	[11 mm]
III-2	"	±10.0	2x3000	[6.8 mm]
(II-3)	"	±7.0	2x2000	[4.2 mm]
III-4	"	±4.5	2x2000	[2.4 mm]
(II-5)	"	±3.0	2x1000	[1.2 mm]
III-6	"	±1.8	2x1000	[0.6 mm]
(II-7)	"	±1.0	2x500	[0.3 mm]



Lambrigtsen

# **Context and Pedigree of HAMSR**



- HAMSR carries the IMAS development effort to maturity
  - Dual-band T-sounding + q-sounding in single package
  - New MMIC receiver technology; Small instrument
- ATMS is also based on IMAS
  - Single-band T-sounding + q-sounding
- NAST-M implements IMAS T-sounding
  - Dual-band T-sounding No q-sounding

## **HAMSR Microwave Sounder on Global Hawk**

## New receiver technology

- 183 GHz receiver upgraded with LNA developed under ESTO/ACT
- Noise reduced by an order of magnitude
- Defines new state-of-the art

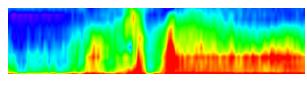
## **Multiple platforms**

- ER-2 (CAMEX-4, TCSP)
- DC-8 (NAMMA)
- Global Hawk (GRIP, 2010)

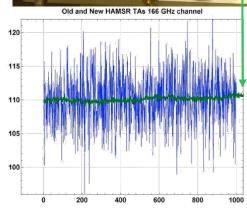


### **Convective structure**

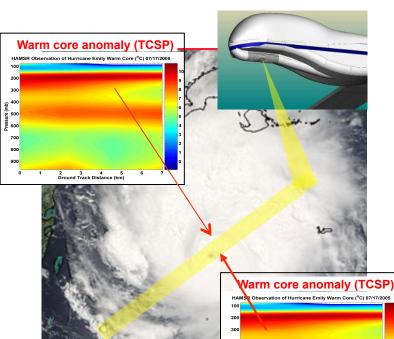
- Radar-like reflectivity
- -1 km vert.res/40 km swath
- Conv.intens., precip(z), ice(z)



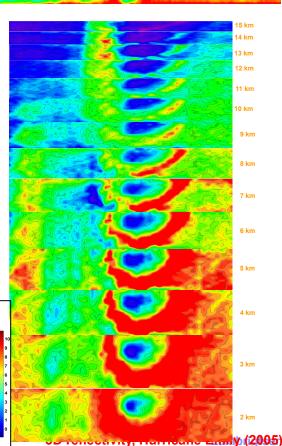




Noise reduced from 2 K to 0.2 K

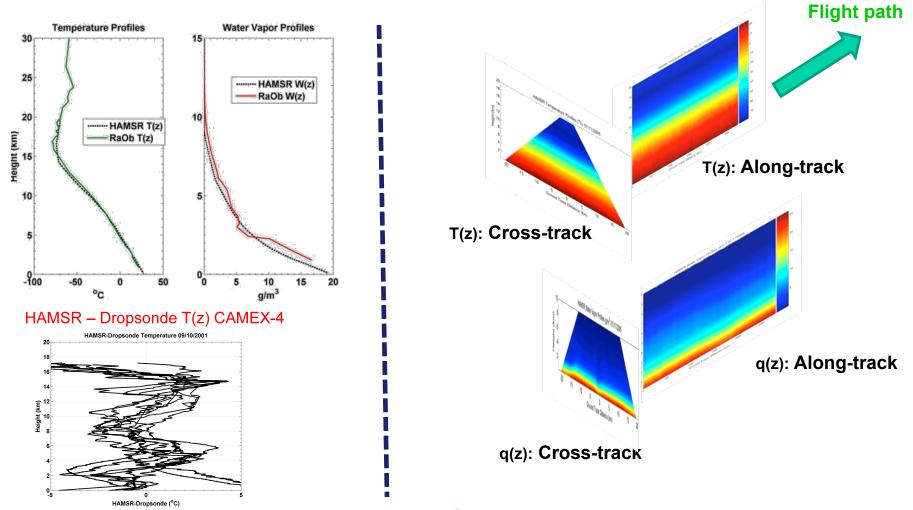


2 3 4 5 Ground Track Distance (km)



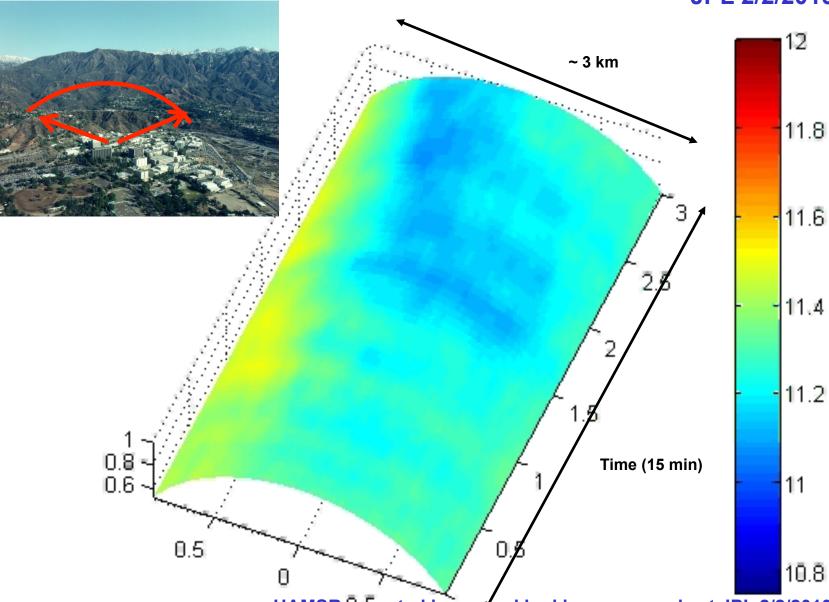
# **HAMSR** sounding accuracy

- Retrieval of 3-D atmospheric temperature, water vapor and cloud liquid water profiles using optimal estimation inversion approach
- Good agreement with dropsonde observations



Note: Third band (118 GHz) also makes it possible to retrieve L(z)

# **Boundary layer sounding with HAMSR**

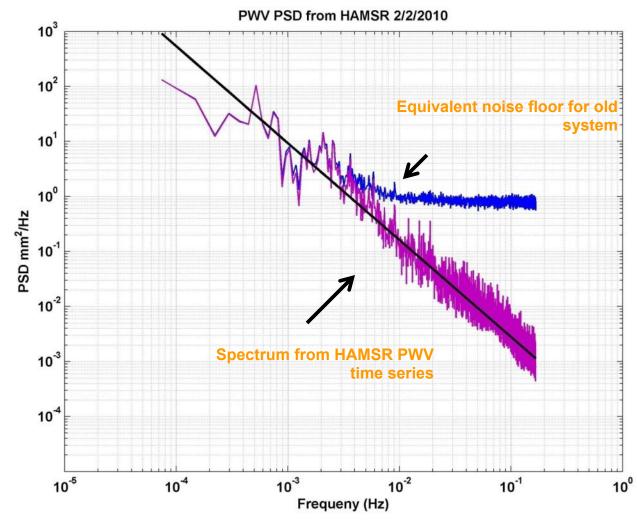


- HAMSR-operated in upward looking scan mode at JPL 2/2/2010
- Retrieved PWV time series along scan arc reveals small scale structure

• 0.3 mm resolution brigtsen

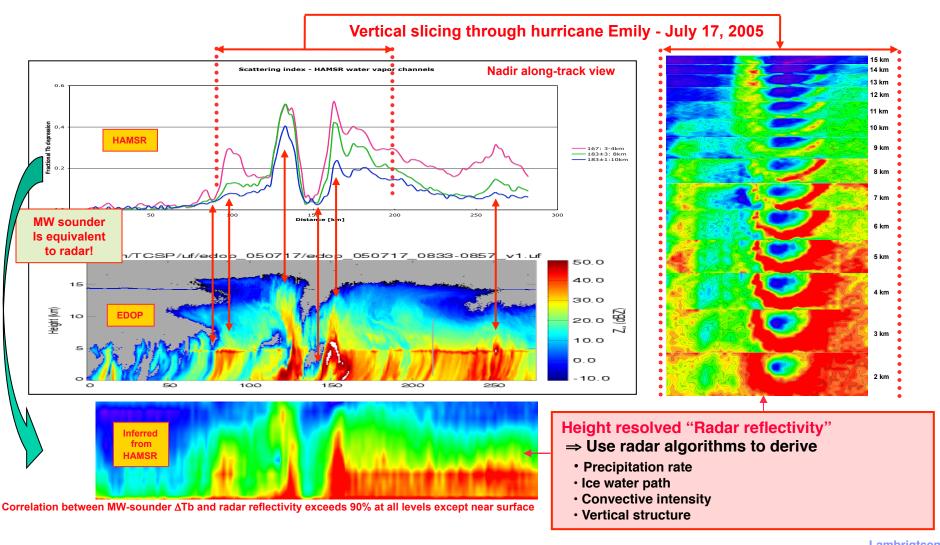
## HAMSR TPW spectrum reveals fine structure

 In upward looking mode, low noise floor enables measurement of variability on seconds to minutes time scales



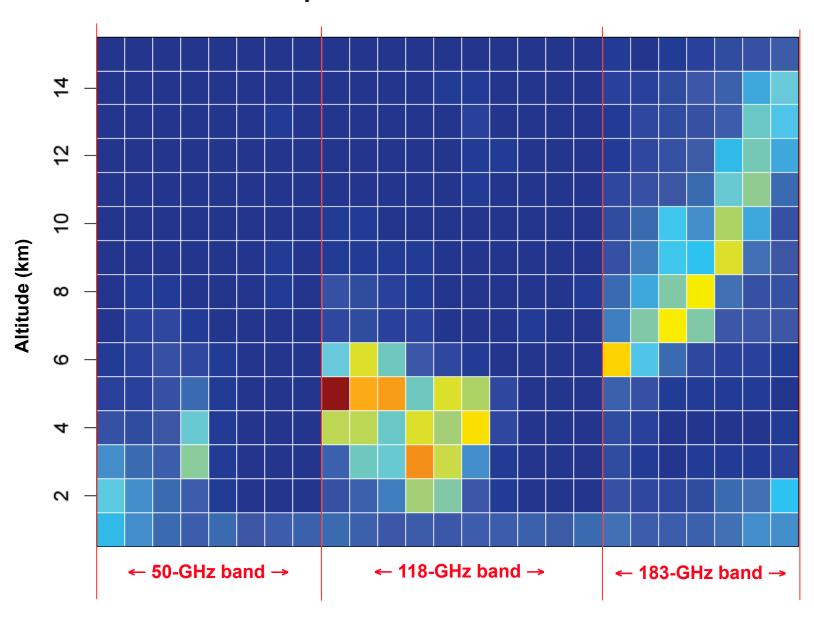
# A new application: Scattering profiling

Hurricane observations with MW sounder (HAMSR) compared with doppler radar (EDOP)
Observations from NASA TCSP campaign, Costa Rica, 2005



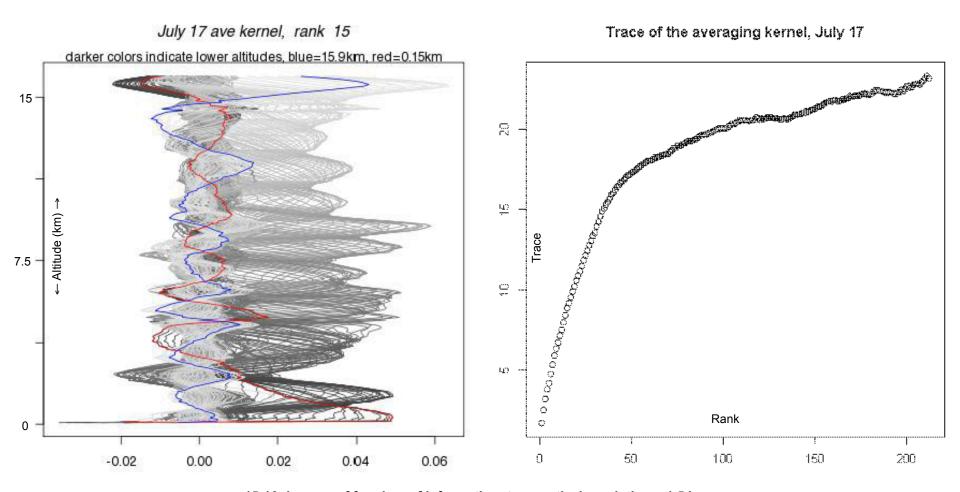
## All cannels contribute information

HAMSR Variable Importance based on the Contribution to the Fit



# **Averaging kernels**

## Single flight - July 17 (Emily)



 $\sim$  15-16 degrees of freedom of information; true vertical resolution  $\sim$  1.5 km

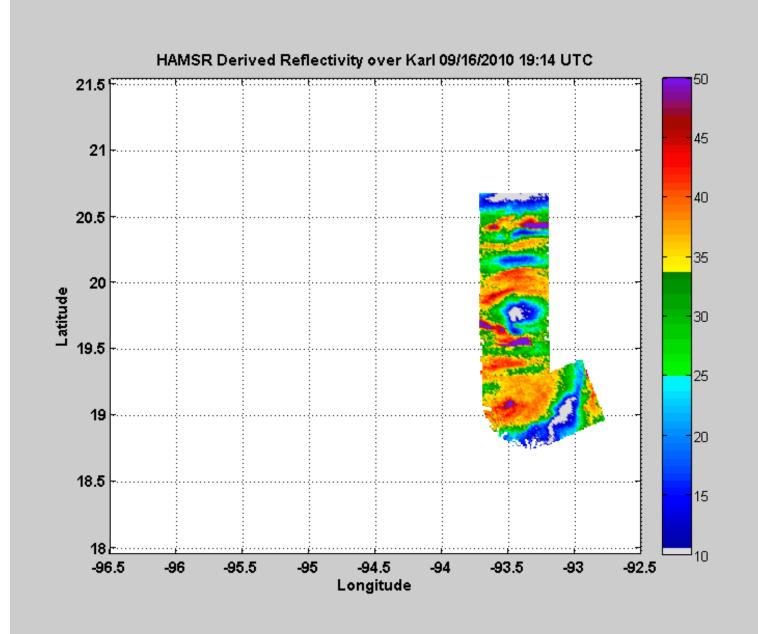
# Retrieval accuracy

## **Several empirical models investigated:**

Linear regression, Random forest, Projection pursuit regression, Perceptron neural network, RBF neural network

### The winner: Random forest 6 Full Results differ little if Training data: Emily/July 17 + Dennis/July 6 by 3 training data are Test case: Dennis/July 9 averaged to simulate coarser α spatial resolution This means the empirical model derived from aircraft data can be applied Reflectivity error (dBZ) to satellite data 9 4 Scattering = "signal" (S) T/q variability = "noise" (N) က S/N-ratio is low @ low alt/freq S/N-ratio is high @ high alt/freq ← Altitude (km) → 2 12 14 10

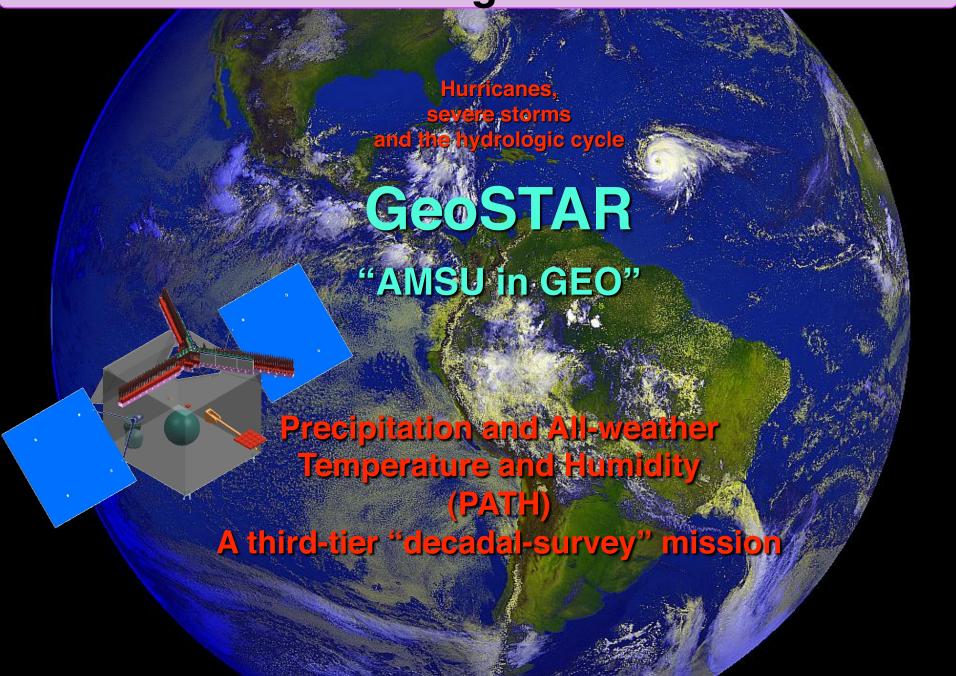
# Hurricane Karl, September 16, 2010



Reflectivity derived from HAMSR flying on Global Hawk UAV

20 consecutive passes over eye

# **GEO MWS coming soon: GeoSTAR**



## **GeoSTAR** overview

## Problem: How to develop a microwave sounder for geostationary orbit?

- Need: Time-continuous all-weather observations of the atmosphere
- Challenge: Achieve adequate spatial resolution from 37,000 km

### Solution: Aperture-synthesis concept

- Can make a very large aperture w/out large parabolic dish antenna
- Sparse array employed to synthesize large aperture
- Spatial interferometry -> Fourier transform of Tb field
- Inverse Fourier transform on ground -> Tb field
- Bonus: No moving parts, simultaneous 2-D "synoptic" imaging

### Design: Sparse array - GeoSTAR

- Optimal: Y-configuration; 3 "sticks"; 100-200 elements each
- Each element = I/Q receiver, ~4λ wide (6 mm @ 183 GHz!)
- Example: 100/arm ⇒ Pixel = 50 km at nadir ≈ LEO sounders
- One "Y"-array per sounding band, interleaved

### Proof of concept

- Ground-based prototype under NASA/ESTO/IIP, 2003-2006
- Performance is excellent & as predicted => Proof of concept

### Risk reduction for space mission

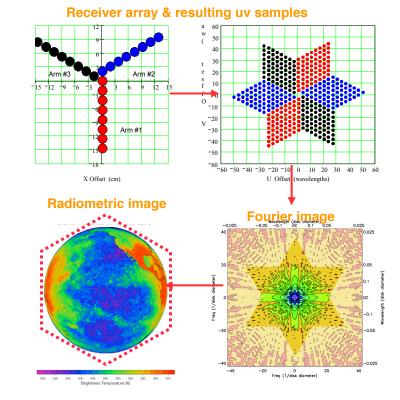
- Further technology development under IIP, 2008-2010
- Mission design studies

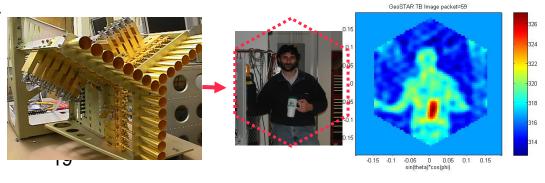
### "PATH" decadal-survey mission

- Precipitation and All-weather Temperature and Humidity
- Ready to start implementation ~2012

### "GeoSTAR-pathfinder"

- GeoSTAR-lite
- Mission of opportunity
- Launch ~2016-18





# **GeoSTAR/PATH** applications

### <u>Hurricanes - Severe storms - Moisture flow - Hydrologic cycle - Climate</u>

#### Weather forecasting -Improve regional forecasts; severe storms

- All-weather soundings, including cloudy and stormy scenes
- Full hemispheric soundings @<50/25 km every ~ 15-30 minutes (continuous)</li>
- "Synoptic" rapid-update soundings => Forecast error detection; 4DVAR applications

#### Severe-storm diagnostics -Quintessential hurricane sensor

- · Scattering signal from convection easily measurable
- Measure location, intensity & vertical structure (incl. shear) of deep convection
- Detect intensification/weakening in real time, frequently sampled (< 15 minutes)</li>
- Measure all three phases of water: vapor, liquid, ice including rain/snow
- Use for operational analysis & in research to improve microphysics of models

#### **Rain** -Complements current capabilities

- Full hemisphere @ ≤ 25 km every 15 minutes (continuous) both can be improved
- Directly measure storm and diurnal total rainfall: predict flooding events
- · Measure snowfall, light rain, intense convective precipitation

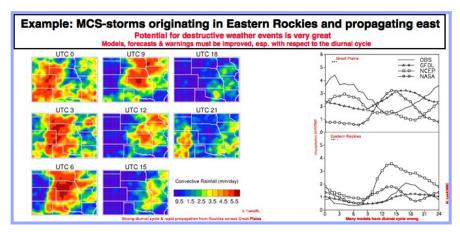
#### Tropospheric wind profiling -NWP, transport applications

- Surface to 300 mb; very high temp.res.; in & below clouds
- Major forecast impact expected (OSSE planned) particularly for hurricanes
- Air quality applications (pollution transport)

#### Climate research -Hydrology cycle, climate variability

- · Stable & continuous MW observations => Long term trends in T & q and storm stats
- Fully resolved diurnal cycle: water vapor, clouds, convection
- ENSO observer: Continuous observations from "warm pool" to Pacific coast under all conditions
- "Science continuity": PATH 

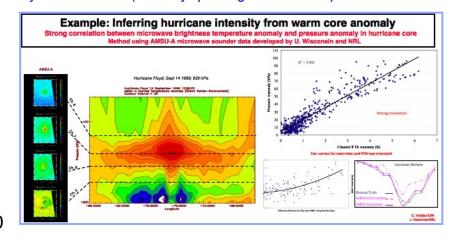
  AMSU (currently operating LEO sounders)



W120 W

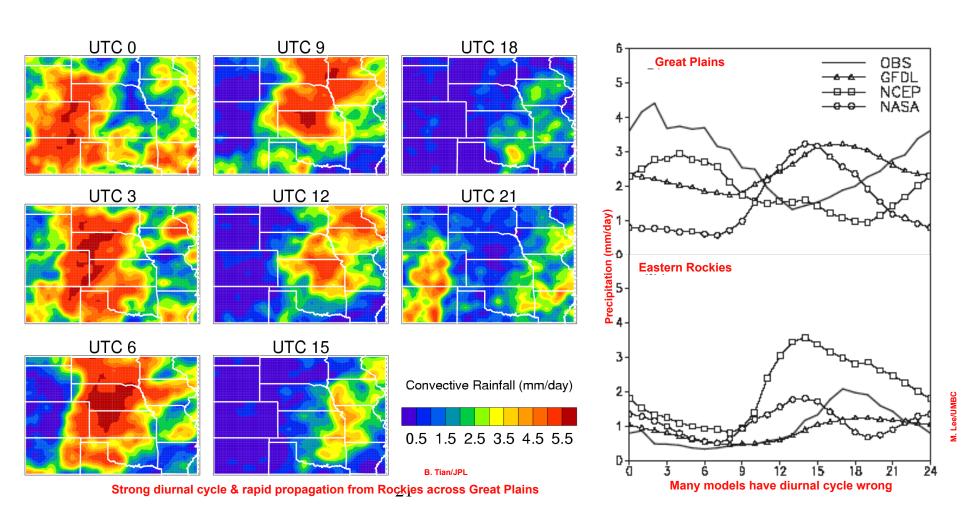
aliased image

rom opposing limb



# Diurnal cycle: Problem with models

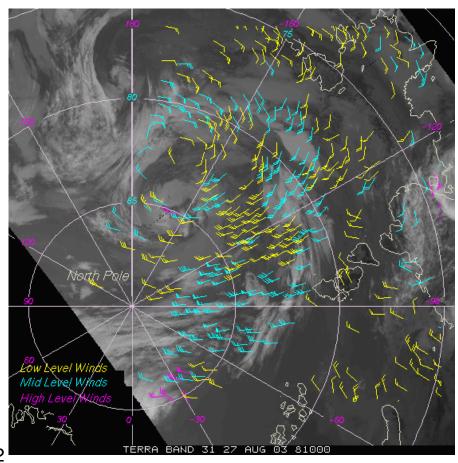
In Sounding Science Workshop held in May 2009 accurate modeling of the diurnal cycle was identified as an issue



# Key application: 3-D tropospheric wind

### **Tropospheric wind vector profiles**

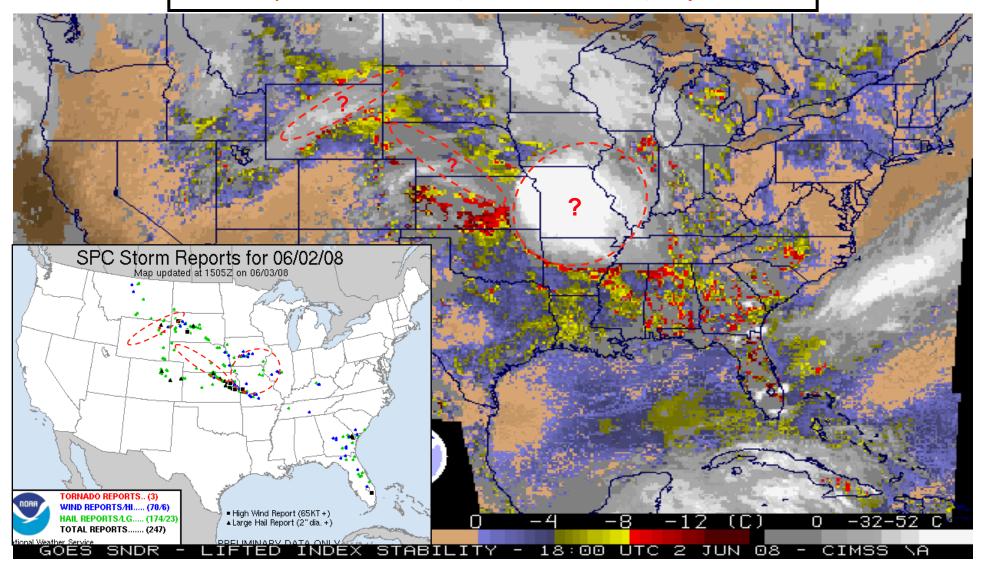
- Derived from moisture feature tracking
- Key parameter for improved numerical weather prediction
- Tropospheric wind (esp. at 500 mb) will have more impact on forecast accuracy than surface wind (Bob Atlas)
- Current capabilities
  - LEO satellites: MODIS
    - Polar regions only
    - Limited-accuracy water vapor profiles
  - GEO satellites: IR sounder
    - Poor sampling: clear only
    - Uncertain height assignment
  - GEO satellites: IR/Vis imager
    - Cloud tracking: cloud tops only
- GeoSTAR capabilities
  - Clear and cloudy
    - Including below clouds
  - Continuous: no time gaps
  - Applicable algorithms available
    - · UW (Velden et al.)



**Example wind vectors from MODIS** 

# Storms: What's going on below the clouds?

Current capabilities: Poorly observed; infrequently sampled; poorly modeled PATH capabilities: *All* conditions, observations *in* storms; every 15 minutes



Let's not forget about storms – They are important to boundary layer dynamics

# Some thoughts

- Need to assess continuous vs. regime-sampling observational needs
- Need to consider spatial and temporal scales
- HAMSR demonstrates some valuable lessons:
  - Adding 118-GHz band adds enough info to enable full L(z) sounding
  - Just as in IR, there is more info.content in MW soundings than currently exploited
  - Upward-sounding example demonstrates that there is very high spatial variability in WV
    - · Can probably only be observed from ground or air
  - Ability to resolve sub-mm water vapor features enabled by high radiometric sensitivity
    - Enabled by new receiver technology

# **Lines of pursuit**

- Hyperspectral MW sounders => 100's of channels
  - Increased information content
    - => increased vertical resolution
    - => higher accuracy
    - => solve for more independent parameters
  - Can be done with moderate development
  - Will be demo'd with GeoSTAR (LO tunable to any frequency)
  - Could be demo'd with HAMSR
    - FPGA/ASIC auto-correlator spectrometer for HAMSR: ~ \$1M
- Large-aperture satellite sounders => 1-5 km spatial resolution
  - Aperture synthesis (suitable for GEO/MEO, could be adapted for LEO)
  - Focal plane arrays (suitable for LEO)
- Combined active-passive methods
  - Is a "sounding radar" feasible?
- Solve surface problem
  - On-line/off-line spectral sampling near weak lines
  - Combine imagers & sounders to solve for surface emissivity
    - SSM/IS is an example, but conical scanners are problematic
- Algorithm development
  - Data fusion: low-res MW + high-res "other
  - Optimal estimation: error & information characterization