

Topic: Methods

Parametric fitting
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Designing future CMB Experiments
Workshop



Foregrounds versus systematics

- For Planck, the most difficult problem was not to remove synchrotron or thermal dust, but to disentangle instrumental systematics from foregrounds
 - The calibration process is “disturbed” by the presence of foregrounds
 - To calibrate the instrument, one needs to know what the sky is, but in order to know what the sky is, one needs well calibrated data
- Should assume that the same will be true for any future experiment as well
 - If one is lucky, and the systematics are low, then that is good, but one shouldn't count on it
- If that is the case, one will need a detailed and realistic astrophysical model, not only Taylor-expansion approximations
 - For a true polarimeter-based experiment, this requires only estimation of synchrotron and thermal dust (and possibly polarized AME++) => moderate frequency range
 - For total-power experiments, one needs to decompose the temperature sky also into free-free, AME, CIB, zodi etc... => widest possible frequency range allowed by budget/power/focal plane

Parametric fitting

- Parametric fitting is often implemented through Bayesian methods
- Assume that the data may be written as the sum of signal and noise,

$$\mathbf{d}_v = \mathbf{s}_v + \mathbf{n}_v$$

where the signal may be written on the following form

$$\mathbf{s}_v(\theta) = s_v(\mathbf{a}_i, \beta_i, g_v, \mathbf{m}_v, \Delta_v)$$

Calibration

Spectral index

Bandpass

Signal amplitude

Monopole/dipole

- The posterior distribution reads

$$P(\theta|\mathbf{d}) = \frac{P(\mathbf{d}|\theta)P(\theta)}{P(\mathbf{d})} \propto \mathcal{L}(\theta)P(\theta)$$

Likelihood

Prior

- If the noise is very nearly Gaussian distributed, then the likelihood is given by

$$\mathcal{L}(\mathbf{a}_i, \beta_i, g_v, \mathbf{m}_v, \Delta_v) \propto e^{-\frac{1}{2} \sum_v [\mathbf{d}_v - \mathbf{s}_v(\theta)]' \mathbf{N}^{-1} [\mathbf{d}_v - \mathbf{s}_v(\theta)]}$$

Gibbs sampling

- The posterior contains millions of correlated and non-Gaussian parameters. How is it possible to map out this distribution?
- Answer: Gibbs sampling
 - Rather than sampling from or maximizing the full joint distribution, iterate over conditionals
- We apply this to our problem in terms of the following Gibbs chain:

$$\mathbf{a}_i \leftarrow P(\mathbf{a}_i | \beta_i, g_v, \mathbf{m}_v, \Delta_v, C_\ell)$$

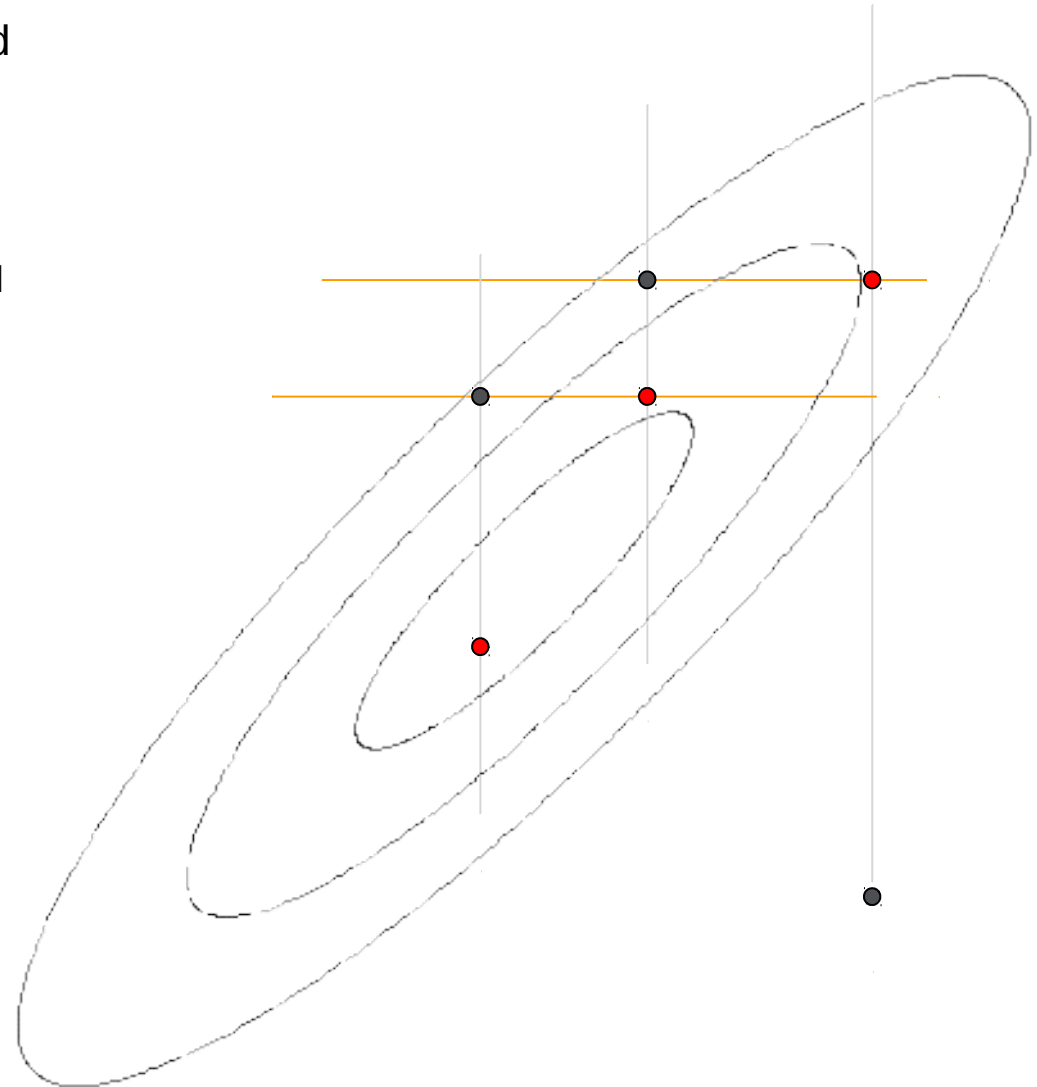
$$\beta_i \leftarrow P(\beta_i | \mathbf{a}_i, g_v, \mathbf{m}_v, \Delta_v, C_\ell)$$

$$g_v \leftarrow P(g_v | \mathbf{a}_i, \beta_i, \mathbf{m}_v, \Delta_v, C_\ell)$$

$$\mathbf{m}_v \leftarrow P(\mathbf{m}_v | \mathbf{a}_i, \beta_i, g_v, \Delta_v, C_\ell)$$

$$\Delta_v \leftarrow P(\Delta_v | \mathbf{a}_i, \beta_i, g_v, \mathbf{m}_v, C_\ell)$$

$$C_\ell \leftarrow P(C_\ell | \mathbf{a}_i, \beta_i, g_v, \mathbf{m}_v, \Delta_v)$$

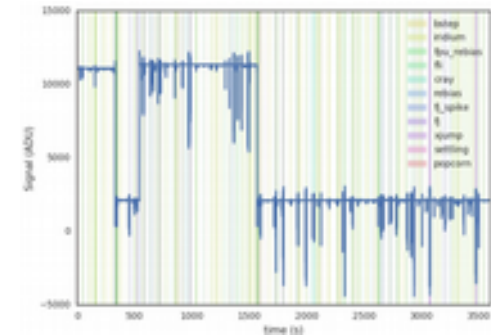


Gibbs sampling for future experiments

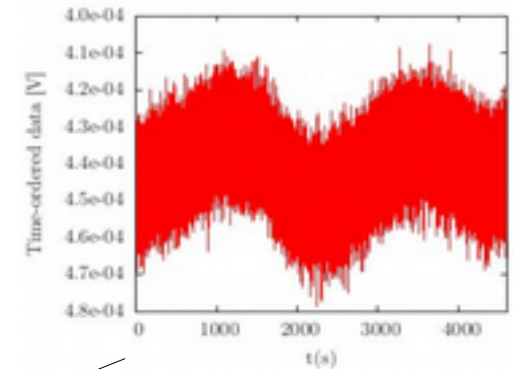
- It is easy to fit for astrophysical foreground parameters with ideal sky maps without systematics
- The difficult part is to account simultaneously for foregrounds and instrumental effects
 - Bandpass mismatch, calibration, ADC correction etc.
- In practice, one has to iterate between low-level TOD processing and map making and high-level component separation
 - Done by LFI, HFI and NPIPE in latest Planck processing
- Ideal solution: Build one big Gibbs sampler including both low- and high-level data processing (“time-domain Gibbs sampling”)
 - No need for human interaction between different processing steps

Classic linear analysis pipeline

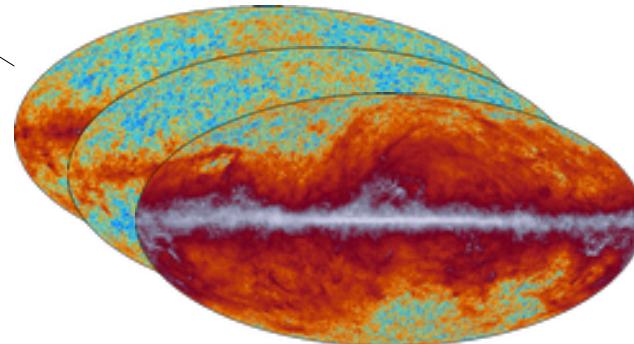
Observations



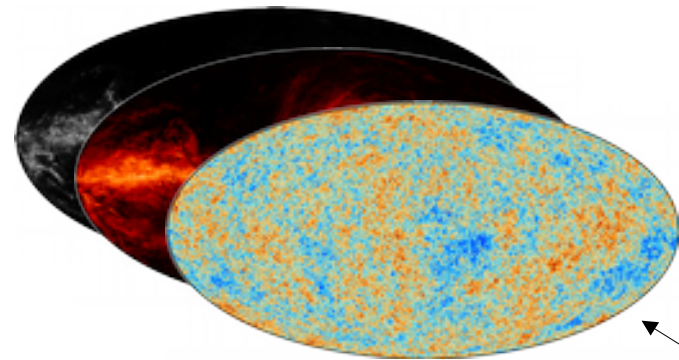
Calibration



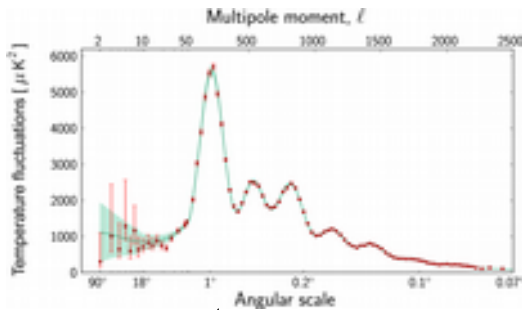
Map making



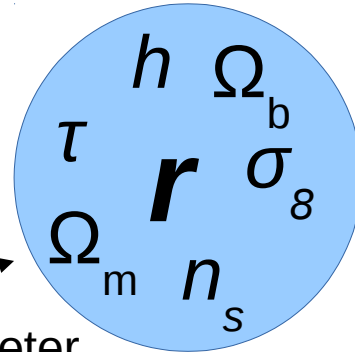
Component separation



Power spectrum estimation

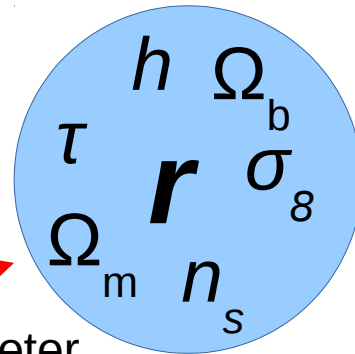
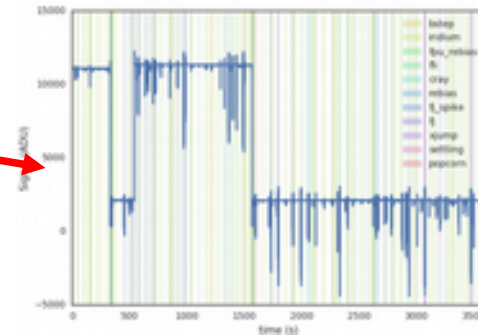


Parameter estimation

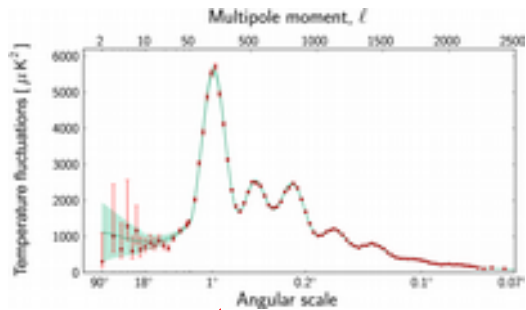


Iterative analysis pipeline

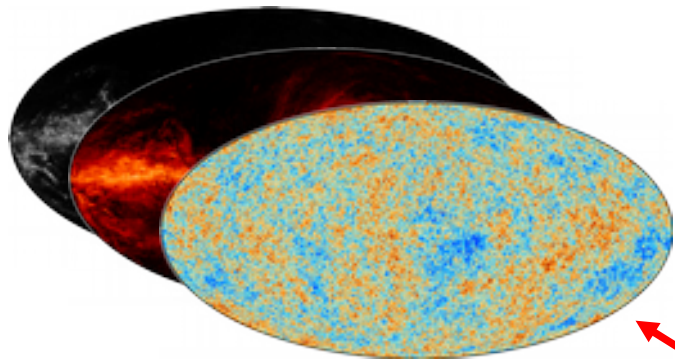
Observations



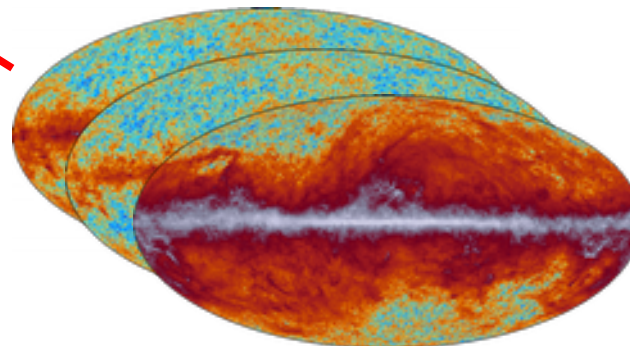
Parameter estimation



Power spectrum estimation

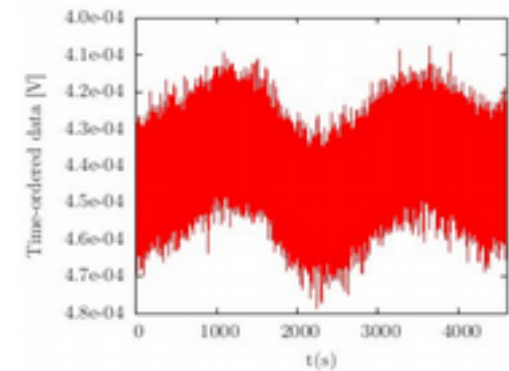


Component separation

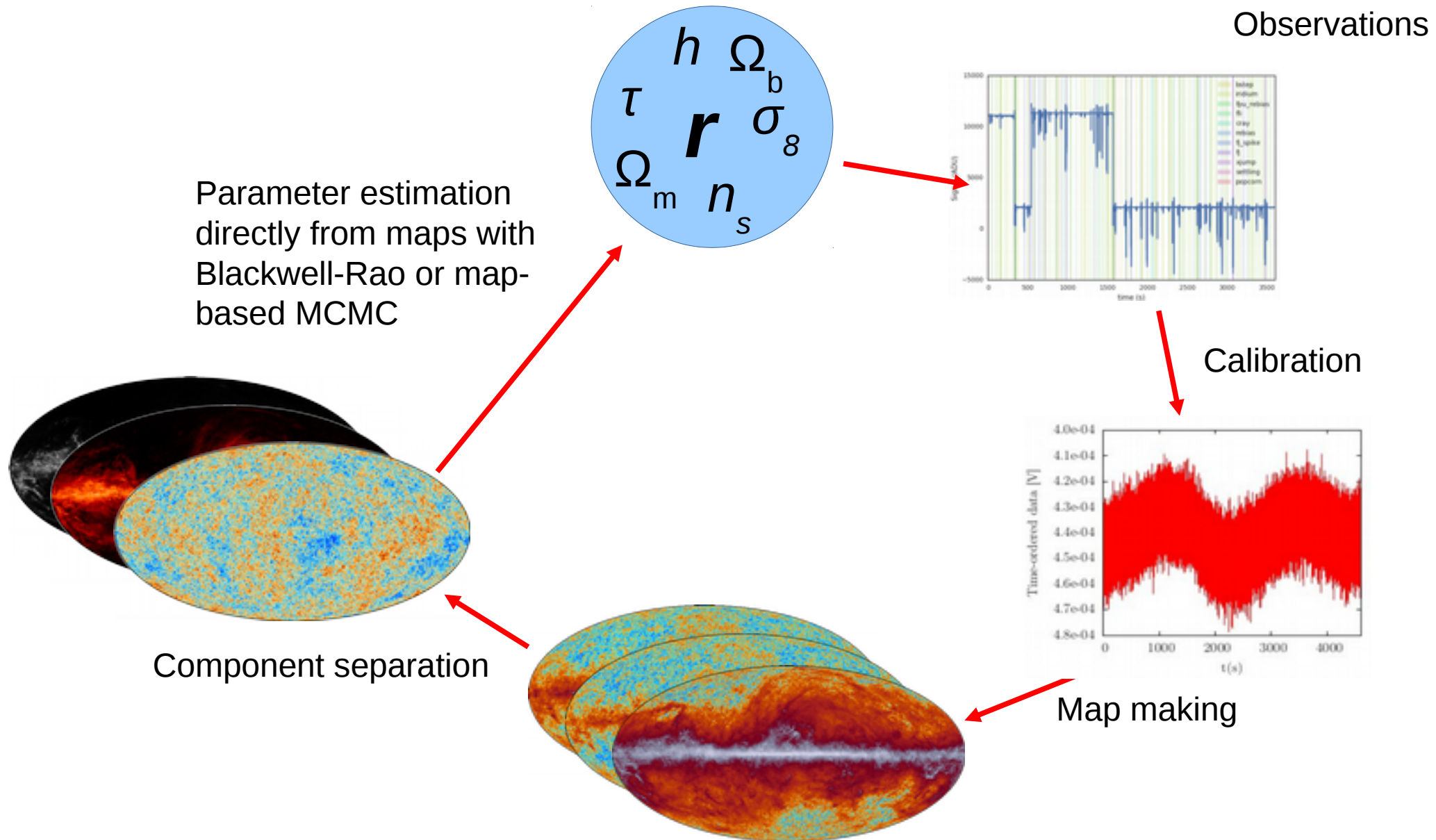


Map making

Calibration



Iterative analysis pipeline



'Out-of-the-box' discussion topics

- Analysis of spectra vs maps vs timestreams
- Uncertainties through Gibbs sampling vs from simulations
- Separate low- l and high- l analysis vs joint
- Parameters directly from maps/TODs vs likelihood