

A Consumer's Guide

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When to Use Autonomy?



















Where To Use Autonomy?



Autonomy / Advisory Loop

- Quick Analysis
 - Quick Calibration
 - Quick QC
 - Quick Analysis
 - Quick Knowledge
- Annotate
- Advise / React
- Repeat

Quick-Look products enable earlier reaction

Advisory systems direct focus

Three Operational Frameworks



Archival / Ground



Real Time / Ops / Pipelines



Onboard Autonomy

Compute: High

Data Volume: High

Data Velocity: Low

Compute: High

Data Volume: Med

Data Velocity: High

Compute: Low **

Data Volume: High

Data Velocity: High

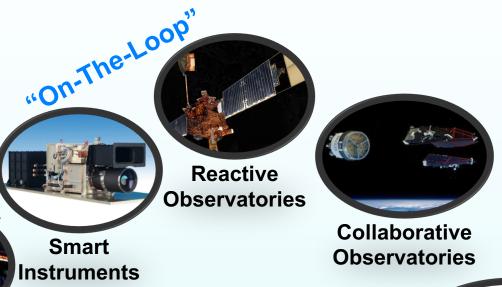
Anomaly Detection	
Focus of Attention	
Content-based Search	
Quality Estimation	
Exploration / Mining	
Interactivity / Insight	
V & V	
Change Detection	
Triage / Prioritization	
Reactive Systems	
Knowledge Compression	
Auto-calibration	

- Support publications
- Understand data better
- Root Cause Analysis
- System trending

- Min bandwidth
- Max science return 4

Related and Interdependent

- Autonomy is just the march of data analysis upstream to the edge
- Con: Easier towards the ground (human in the loop)
- Pro: Unique opportunities exist with earlier insight



Planning & Operations

Discovery & Exploration

"In-The-Loop"

Never "Fire & Forget"
Humans are invaluable...
...when you can get them



Cross-Generational Collaboration

JPL Autonomy Examples

Is the Signal Even In The Telemetry?

DSWG Tech – ON-WATCH

Onboard Numeric Watchdog for Analysis of Telemetry Channel Heuristics
Jack Lightholder

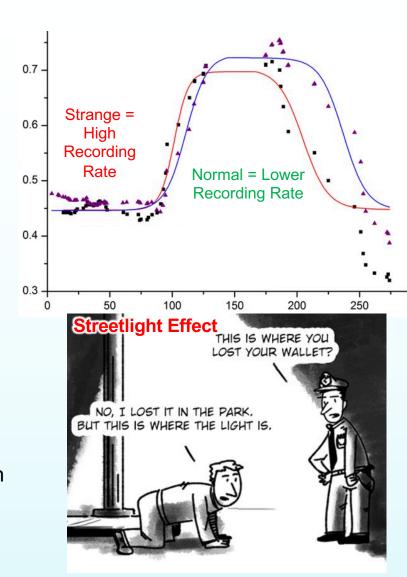
Different channels are manually ordered to take data at high (~1s), medium (~6s), or low (>10 s) rates.

What if anomaly happens faster than you're sampling? You miss it!

ON-WATCH automatically adjusts telemetry recording rates based on how unusual the spacecraft state.

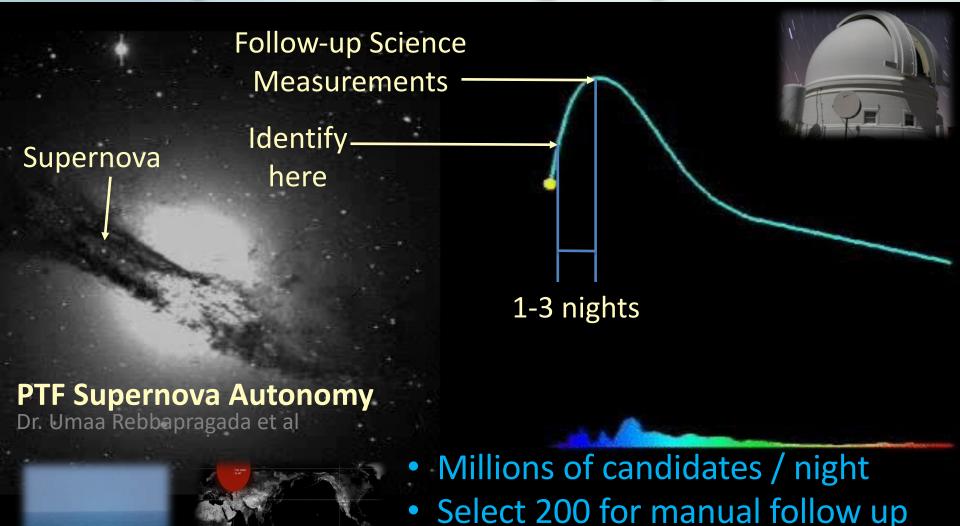
Would already have initial guesses of when to look for anomalies based on high-resolution data!

GRACE-FO team has already said, "If our telemetry even captured the anomaly itself..."





Early Warning Systems



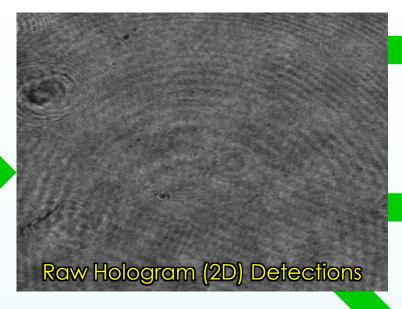
- Current PTF Supernova Detector! Launch
- Launch / Detonation Detection

Better be right: sound world alert

Holographic Life Detection

Drs. Lukas Mandrake, Gary Doran, Brian Bue







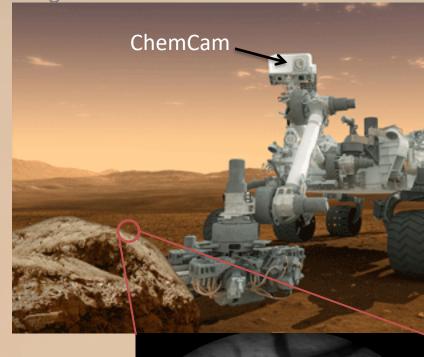


- Digital Holographic Microscopes
 - Big data (4D, ~GB/s), rare findings
- Motility ~ Life (composition agnostic!)
- HELM ML system detects, tracks, and classifies in messy, raw 2D holograms



AEGIS/ChemCam on MSL Autonomous Exploration for Gathering Increased Science

- Target & Zap Rock
- Manually Scheduled Targets
- Round Trip Delays
- Trouble hitting 1st time
- Targeted science not possible right after drive
- Autonomy selects interesting targets
- Refines targeting automatically
- ~30-100% additional ChemCam science targets on drive sols



Drs. Tara Estlin, Dan Gaines, Gary Doran, Raymond Francis, et al...

AVIRIS-NG Hyperspectral

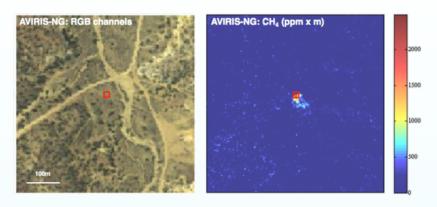
Dr. David Thompson, Dr. Brian Bue, et al



Airborne Imaging Spectrometer

Multiple gas pipelines shut down / repaired Machine Learning "That Matters"

CH4 detection in four corners



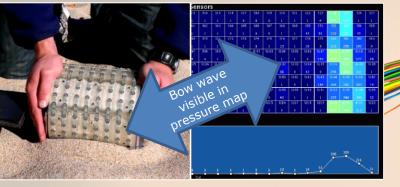
Enabled ground team to find underground pipe leaks





The Barefoot Rover

Jack Lightholder, Dr. Lukas Mandrake



Real-Time
On-Board
Analytics





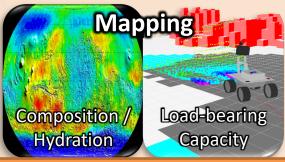




What if rover wheels could:

- Feel the ground like we use bare feet?
- Taste for specific compounds like a fly? (like water or)
- Hear the electrical properties of buried metal, or power lines?







Active Development: Earth & Mars Applications 2020 timeframe





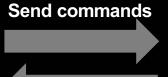
Content-based On-board Summarization to Monitor Infrequent Change

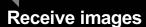
PI: Dr. Lukas Mandrake Co-l's: Dr. Kiri Wagstaff, Dr. Gary Doran, <u>Steven Lu</u>, Jimmie Young, and Dr. Umaa Rebbapragada

Machine Learning and Instrument Autonomy Group

Current Operation Mode

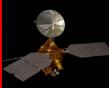








Very, very limited bandwidth

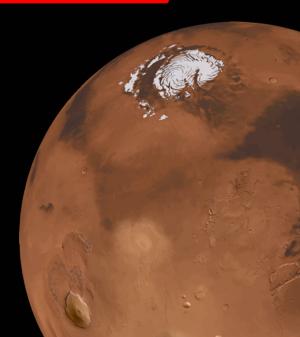




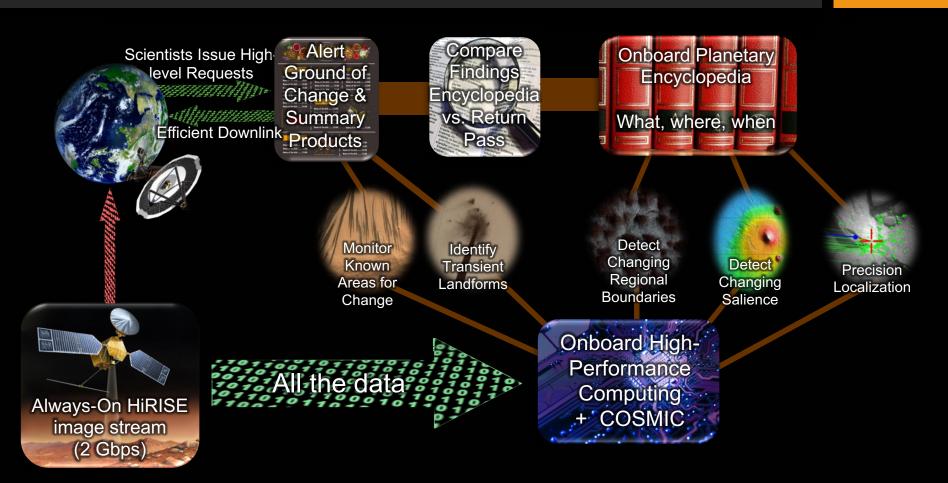
- Scientists select where and what to look for
- Spacecraft responds to commands
- Return data to ground
- Ground data analysis
- THIS WORKS! (if the target stays put)

Limitation: must know where to look to make request

Unaddressed need: Change Detection

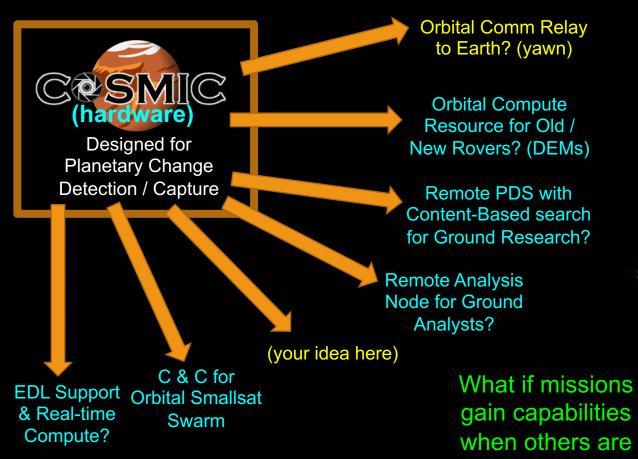


COSMIC-in-the-loop Operation Mode



Planetary Change Detection with minimal downlink!

Break Out of the Box – Implicit Collaboration



What if we permit craft to exchange analysis requests rather than just data?

What if we schedule planetary compute like we schedule comm passes?

nearby?