

Universal laws and architectures

John Doyle

John G Braun Professor

Control and Dynamical Systems, EE, BE

Caltech

Turing on layering

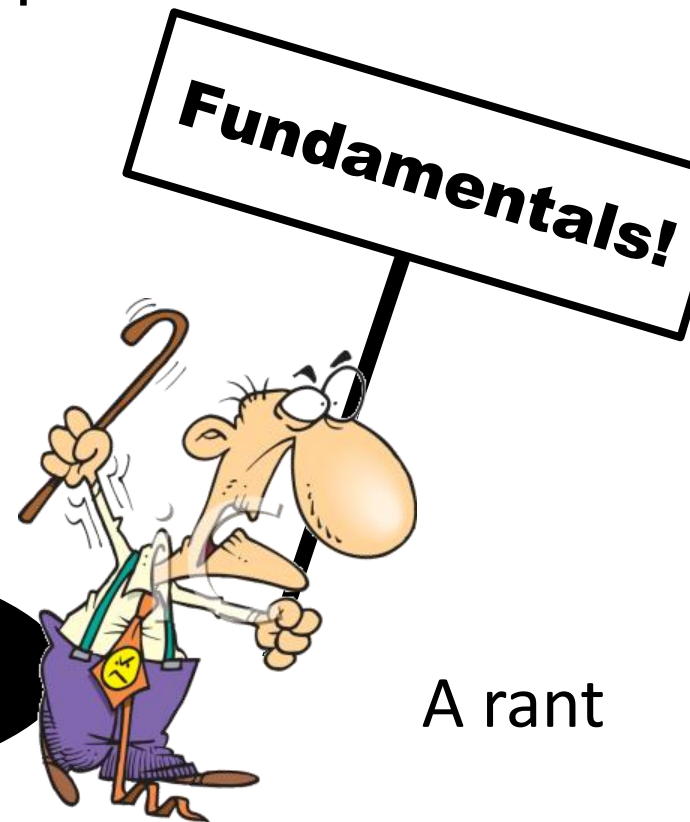
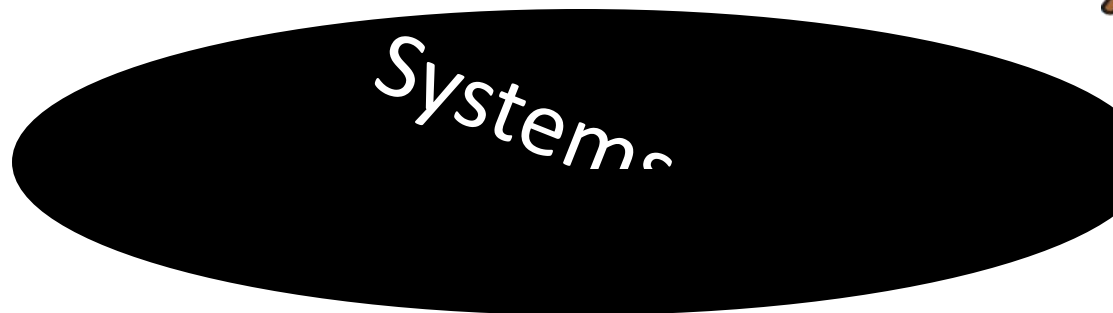
The 'skin of an onion' analogy is also helpful. In considering the functions of the mind or the brain we find certain operations which we can explain in purely mechanical terms. This we say does not correspond to the real mind: it is a sort of skin which we must strip off if we are to find the real mind. But then in what remains we find a further skin to be stripped off, and so on. Proceeding in this way do we ever come to the 'real' mind, or do we eventually come to the skin which has nothing in it? In the latter case the whole mind is mechanical.

1950, Computing Machinery and Intelligence, *Mind*

“Universal laws and architectures?”

- **Universal “conservation laws” (constraints)**
- Universal architectures (constraints that deconstrain)
- Mention recent papers*
- Focus on broader context not in papers
- Lots of case studies for motivation

*try to get you
to read them?



A rant

This paper aims to bridge progress in **neuroscience** involving sophisticated quantitative analysis of behavior, including the use of **robust control**, with other relevant conceptual and theoretical frameworks from **systems engineering, systems biology, and mathematics**.

Very accessible
No math

Architecture, constraints, and behavior

John C. Doyle^{a,1} and Marie Csete^{b,1}

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Edited by Donald W. Pfaff, The Rockefeller University, New York, NY, and approved June 10, 2011 (received for review March 3, 2011)

This paper aims to bridge progress in neuroscience involving sophisticated quantitative analysis of behavior, including the use of robust control, with other relevant conceptual and theoretical frameworks from systems engineering, systems biology, and mathematics. Familiar and accessible case studies are used to illustrate concepts of robustness, organization, and architecture (modularity and protocols) that are central to understanding complex networks. These essential organizational features are hidden during normal function of a system but are fundamental for understanding the nature, design, and function of complex biologic and technologic systems.

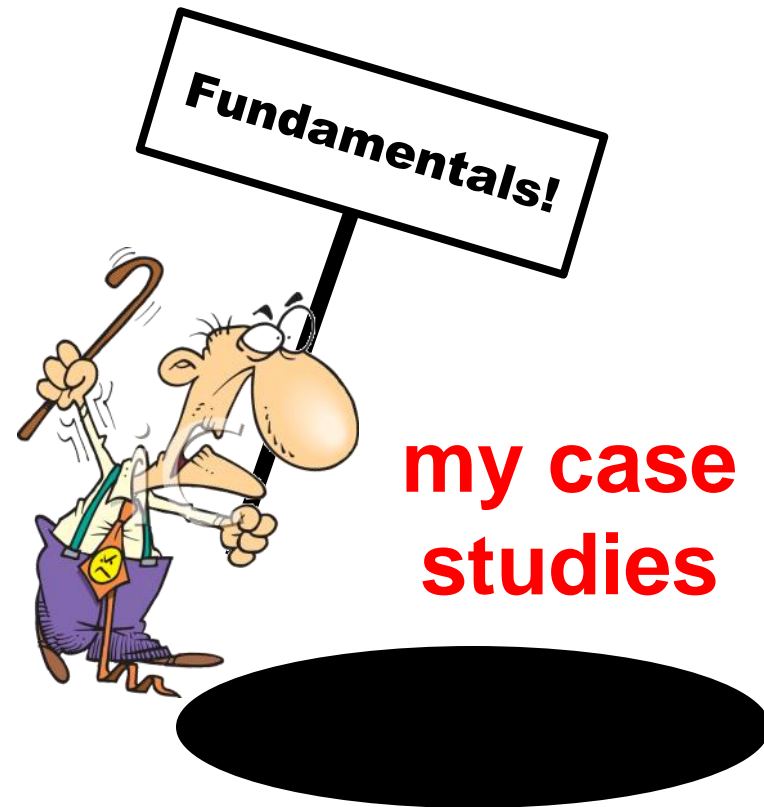
evolved for sensorimotor control and retain much of that evolved architecture, then the apparent distinctions between perceptual, cognitive, and motor processes may be another form of illusion (9), reinforcing the claim that robust control and adaptive feedback (7, 11) rather than more conventional serial signal processing might be more useful in interpreting neurophysiology data (9). This view also seems broadly consistent with the arguments from grounded cognition that modal simulations, bodily states, and situated action underlie not only motor control but cognition in general (12), including language (13). Furthermore, the myriad constraints involved in the evolution of circuit

Doyle, Csete, *Proc Nat Acad Sci USA*, JULY 25 2011

my case studies

- Lots from cell biology
 - glycolytic oscillations for hard limits
 - bacterial layering for architecture
- Networking and “clean slate” architectures
 - wireless end systems
 - info or content centric application layer
 - integrate routing, control, scheduling, coding, caching
 - control of cyber-physical
 - PC, OS, VLSI, antennas, etc (IT components)
- Neuroscience
 - brains
 - neuroendocrine control
- Medical and exercise physiology

- **Cell biology**
- **Networking & “clean slate” architectures**
- **Neuroscience**
- **Medical physiology**
- Smartgrid, cyber-phys
- Wildfire ecology
- Earthquakes
- Lots of aerospace
- Physics:
 - turbulence,
 - stat mech (QM?)
- “Toy”:
 - Lego,
 - clothing,
 - buildings, ...
- **Synesthesia**

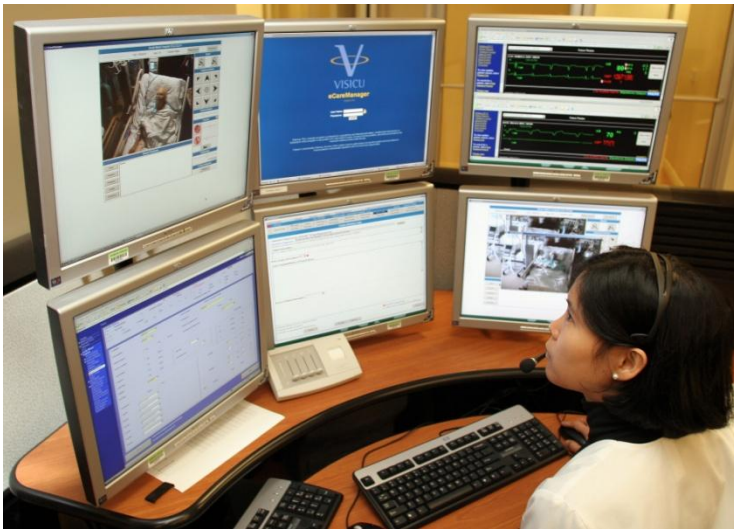


Existing design frameworks

- Sophisticated components
- Poor integration
- Limited theoretical framework



Fix?



Happy families are all alike; every unhappy family is unhappy in its own way.

Leo Tolstoy,
Anna Karenina,
Chapter 1, first line

- What could this mean? Given incredible ***diversity*** of people and environments?
- It has to be a statement about organization, and specifically ***architecture***.
- Happy = empathy + cooperation + simple rules?
- ***Constraints*** on components and architecture

Requirements on systems and architectures

accessible
accountable
accurate
adaptable
administrable
affordable
auditable
autonomy
available
credible
process
capable
compatible
composable
configurable
correctness
customizable
debugable
degradable
determinable
demonstrable

dependable
deployable
discoverable
distributable
durable
effective
efficient
evolvable
extensible
failure
transparent
fault-tolerant
fidelity
flexible
inspectable
installable
Integrity
interchangeable
interoperable
learnable
maintainable

manageable
mobile
modifiable
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precision
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provable
recoverable
relevant
reliable
repeatable
reproducible
resilient
responsive
reusable
robust

safety
scalable
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self-sustainable
serviceable
supportable
securable
simplicity
stable
standards
compliant
survivable
sustainable
tailorable
testable
timely
traceable
ubiquitous
understandable
upgradable
usable

Simplified, minimal requirements

accessible
accountable
accurate
adaptable
administrable
affordable
auditable
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Requirements on systems and architectures

efficient

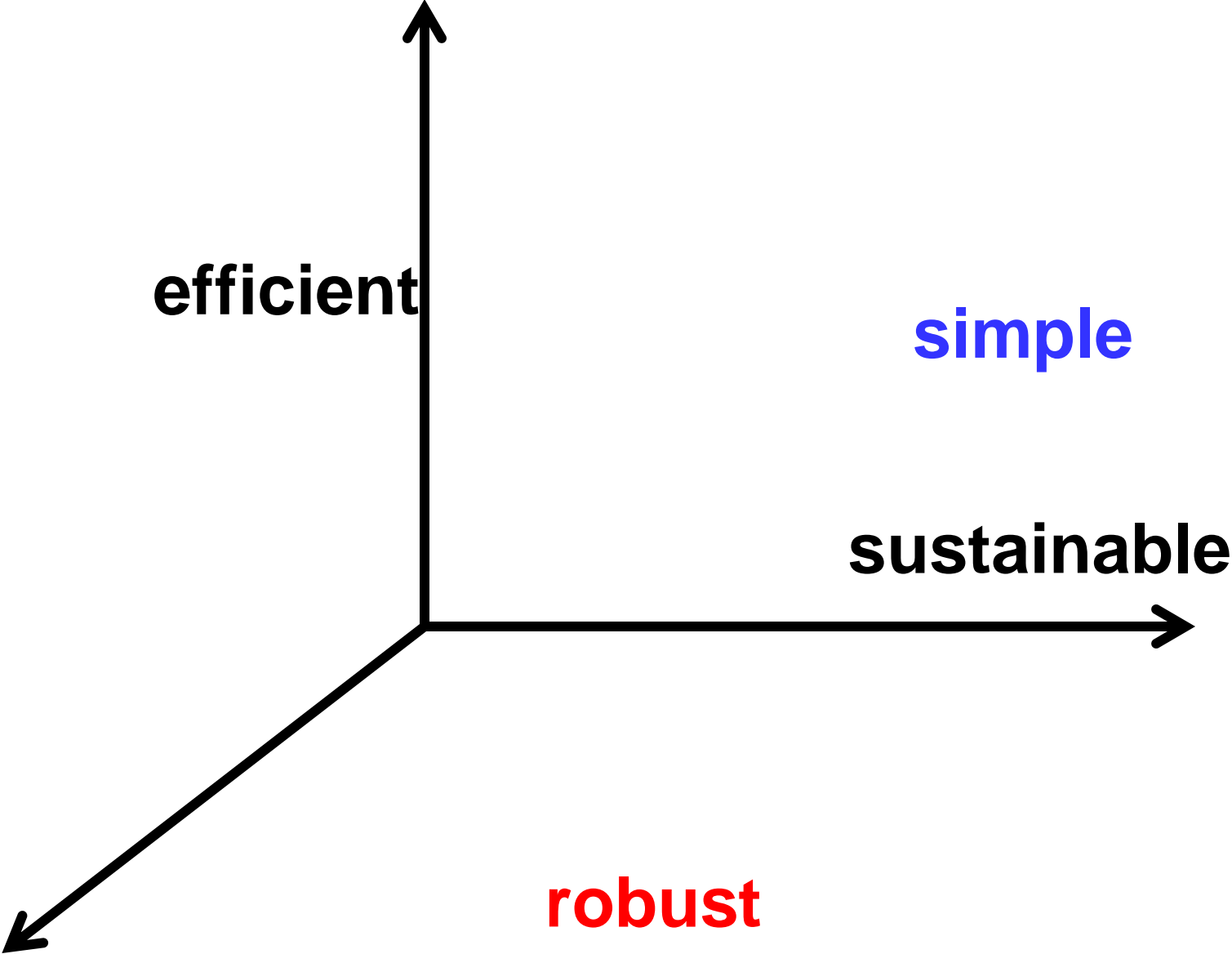
simple

sustainable

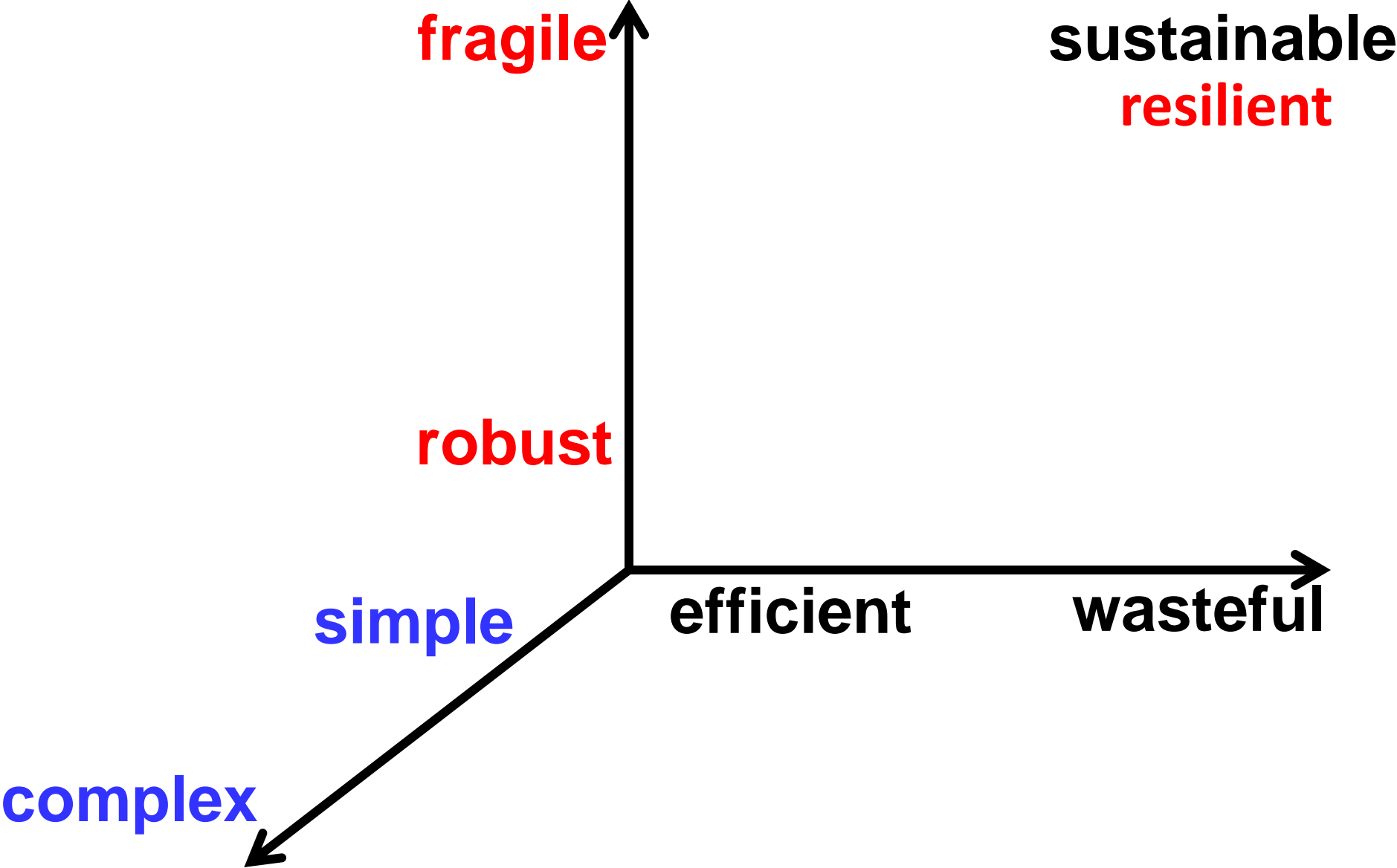
resilient

robust

Requirements on systems and architectures

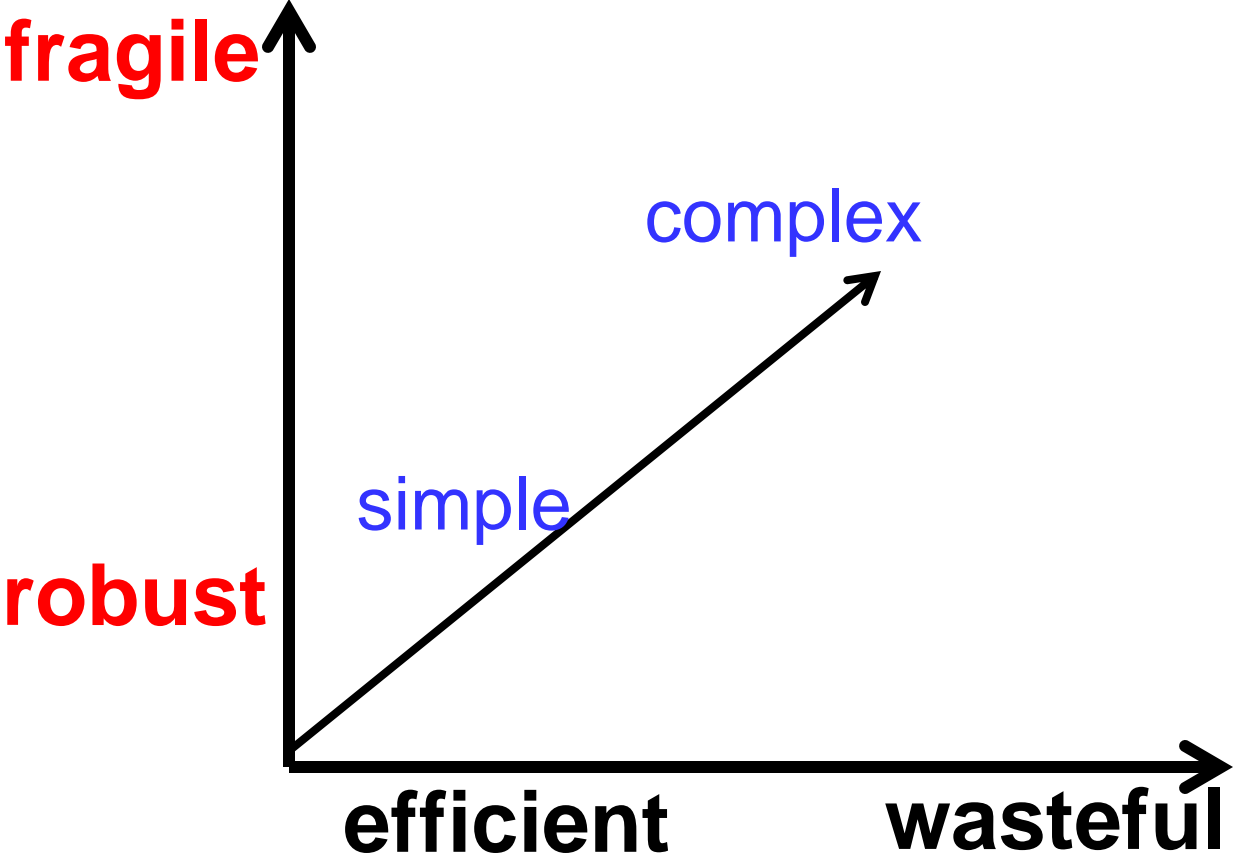


Requirements on systems and architectures

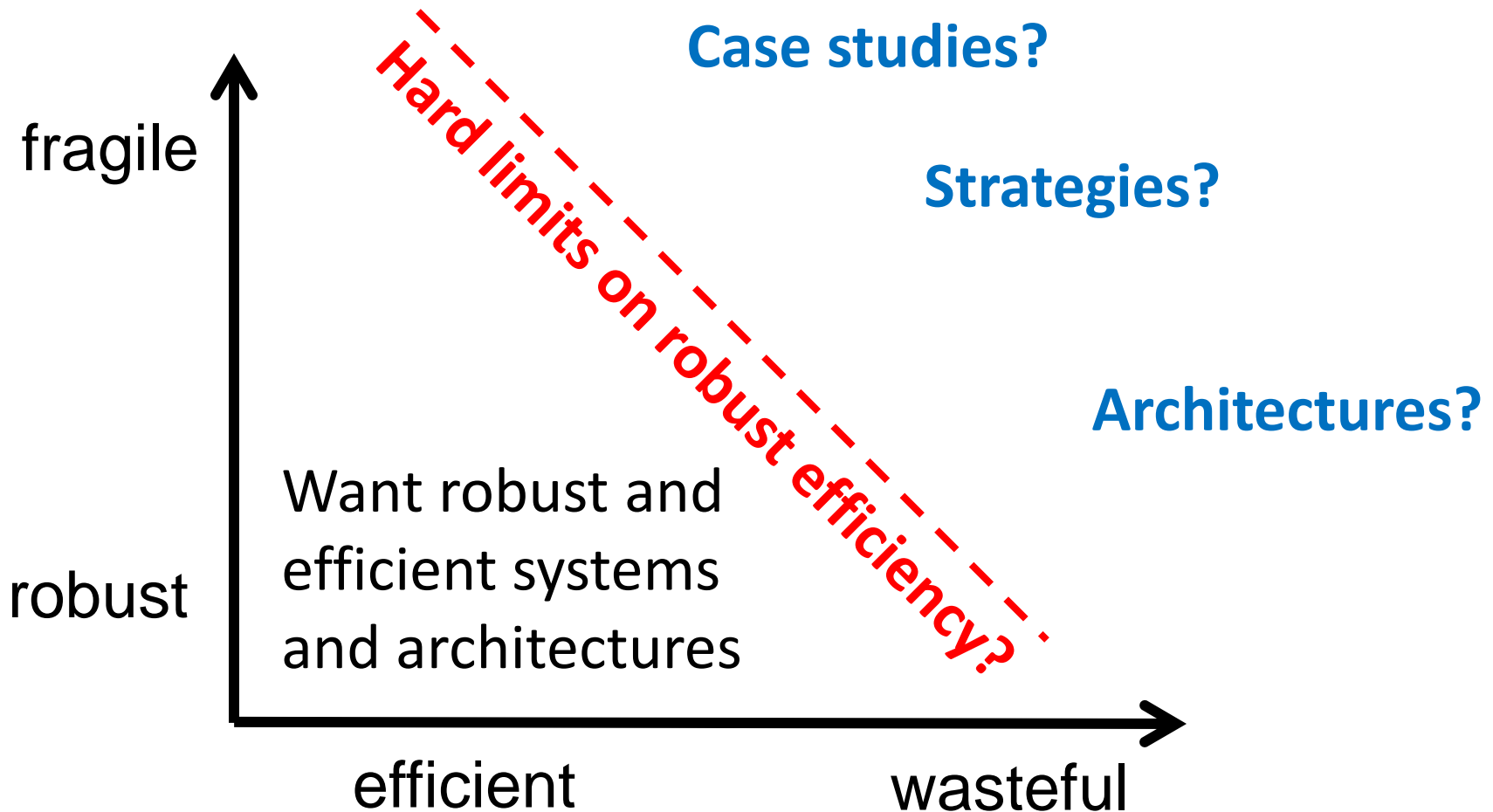


Requirements on systems and architectures

sustainable



Want to understand the space of systems/architectures



Resilient architectures are all alike; every brittle system is brittle in its own way.

Apologies to Tolstoy

- Resilience includes robustness, efficiency, sustainability, scalability, etc etc
- Effective architectures provide flexible tradeoffs across all these dimensions
- Subject to “laws” which are hard constraints on what is achievable
- Defer resolving terminology, focus on...
- **Theorems and concrete case studies**

Resilient architectures are all alike; every brittle system is brittle in its own way.

Good architecture =
“constrains that deconstrain”
(Gerhart and Kirschner)



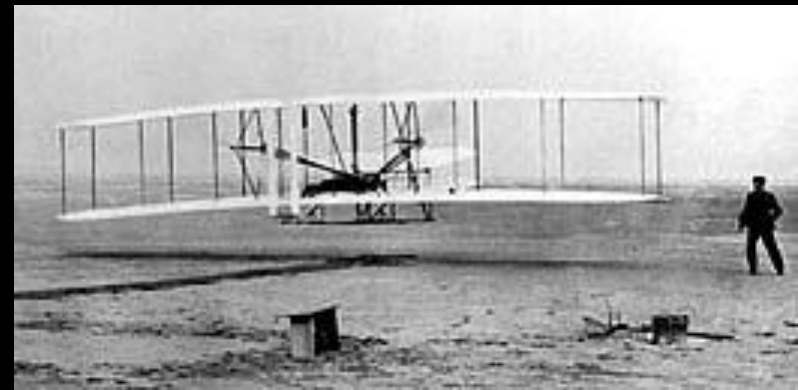
The dangers of naïve biomimetics



Feathers
and
flapping?



Or lift, drag, propulsion,
and *control*?



Getting it (W)right, 1901

- “We know how to construct airplanes...” (lift and drag)
- “... also know how to build engines.” (propulsion)
- “When... balance and steer[ing]... has been worked out, the age of flying will have arrived, for all other difficulties are of minor importance.” (control)

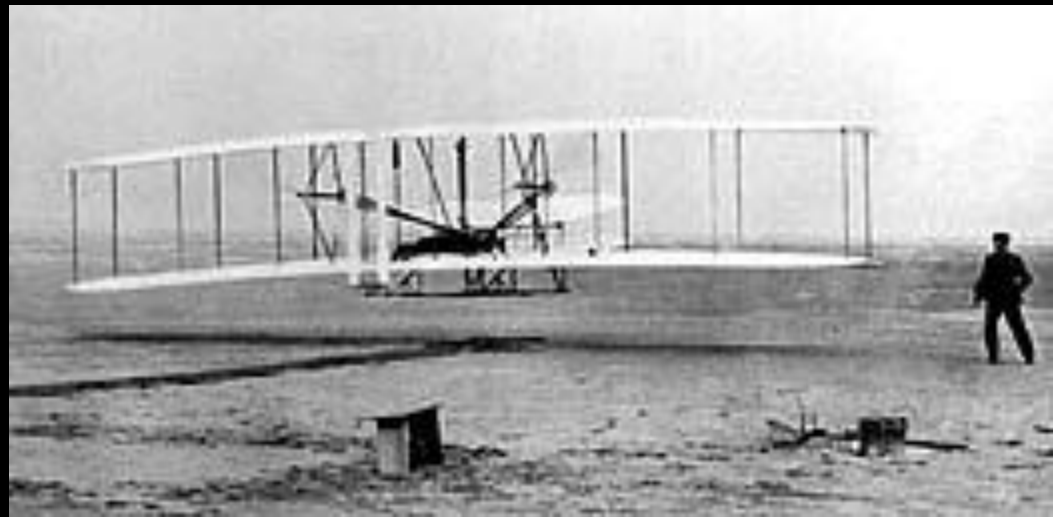


Wilbur Wright on Control, 1901
(First powered flight, 1903)

Universals?

~~Feathers
and
flapping?~~

Lift, drag, propulsion,
and *control*?



Universals?

- Complexity ← control, robust/fragile tradeoffs
- Fragility ← Hijacking, side effects, unintended...
- Of mechanisms evolved for robustness
- Math: robust/fragile constraints (“conservation laws”)

Both

Accident or necessity?



Fire in the Earth System

I'm interested
in fire...

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Jean M. Carlson,⁷ Mark A. Cochrane,⁸ Carla M. D'Antonio,⁹ Ruth S. DeFries,¹⁰ John C. Doyle,¹¹
Sandy P. Harrison,¹² Fay H. Johnston,¹³ Jon E. Keeley,^{14,15} Meg A. Krawchuk,¹⁶
Christian A. Kull,¹⁷ J. Brad Marston,¹⁸ Max A. Moritz,¹⁶ I. Colin Prentice,¹⁹ Christopher I. Roos,²⁰
Andrew C. Scott,²¹ Thomas W. Swetnam,²² Guido R. van der Werf,²³ Stephen J. Pyne²⁴

Fire is a worldwide phenomenon that appears in the geological record soon after the appearance of terrestrial plants. Fire influences global ecosystem patterns and processes, including vegetation distribution and structure, the carbon cycle, and climate. Although humans and fire have always coexisted, our capacity to manage fire remains imperfect and may become more difficult in the future as climate change alters fire regimes. This risk is difficult to assess, however, because fires are still poorly represented in global models. Here, we discuss some of the most important issues involved in developing a better understanding of the role of fire in the Earth system.

Very accessible
No math



Wildfires, complexity, and highly optimized tolerance

Max A. Moritz*, Marco E. Morais†, Lora A. Summerell‡, J. M. Carlson§¶, and John Doyle||

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Communicated by James S. Langer, University of California, Santa Barbara, CA, October 19, 2005 (received for review July 26, 2004)

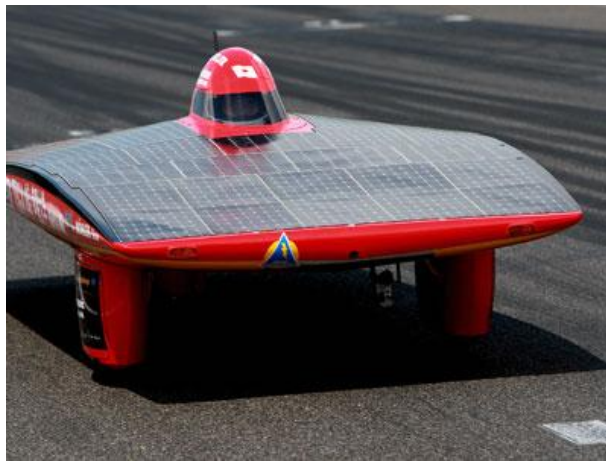
Recent, large fires in the western United States have rekindled debates about fire management and the role of natural fire regimes in the resilience of terrestrial ecosystems. This real-world experience parallels debates involving abstract models of forest fires, a central metaphor in complex systems theory. Both real and modeled fire-prone landscapes exhibit roughly power law statistics in fire size versus frequency. Here, we examine historical fire catalogs and a detailed fire simulation model; both are in agreement with a highly optimized tolerance model. Highly optimized tolerance suggests robustness tradeoffs underlie resilience in different fire-prone ecosystems. Understanding these mechanisms may provide new insights into the structure of ecological systems and be key in evaluating fire management strategies and sensitivities to climate change.

Highly optimized tolerance (HOT) is a conceptual framework for examining organization and structure in complex systems (18). Theoretically, HOT builds on models and mathematics from physics and engineering, and identifies robustness tradeoffs as a principle underlying mechanism for complexity and power law statistics. HOT has been discussed in the context of a variety of technological and natural systems, including wildfires (18, 22). A quantitative prediction for the distribution of fire sizes has come from an extremely simple analytical HOT model, referred to as the PLR (probability–loss–resource) model (22). As a precursor to results presented later in this article, Fig. 2 demonstrates the PLR prediction and truncated power law statistics (23) for several fire history catalogs. This plot represents the rank data as rank or cumulative frequency of fires $P(I)$ greater than

Accessible ecology
UG math

Wildfire ecosystem as ideal example

- Cycles on years to decades timescale
- Regime shifts: grass vs shrub vs tree
- Fire= keystone “specie”
 - Metabolism: consumes vegetation
 - Doesn’t (co-)evolve
 - Simplifies co-evolution spirals and metabolisms
- 4 ecosystems globally with convergent evo
 - So Cal, Australia, S Africa, E Mediterranean
 - Similar vegetation mix
 - Invasive species



Current Technology?

fragile

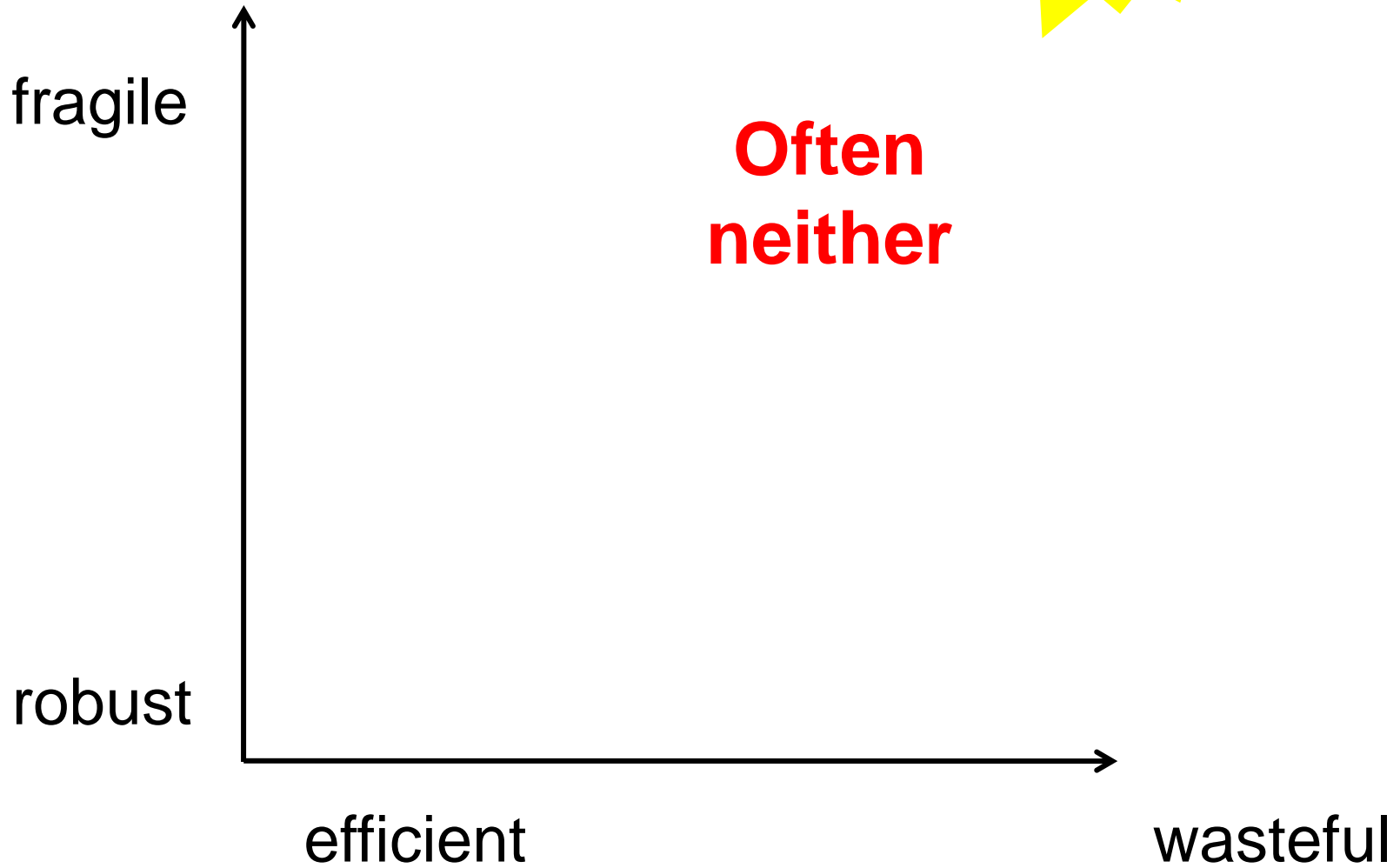
At best we get one

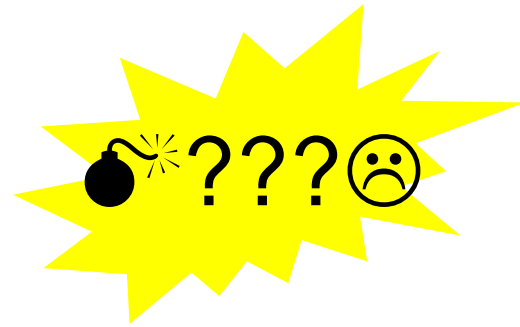
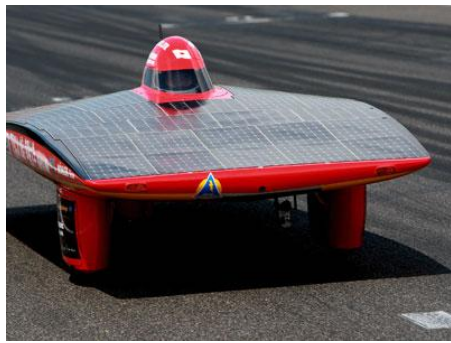


robust

efficient

wasteful



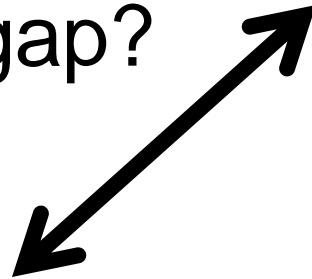


Bad architectures?

fragile

?

gap?



Bad theory?

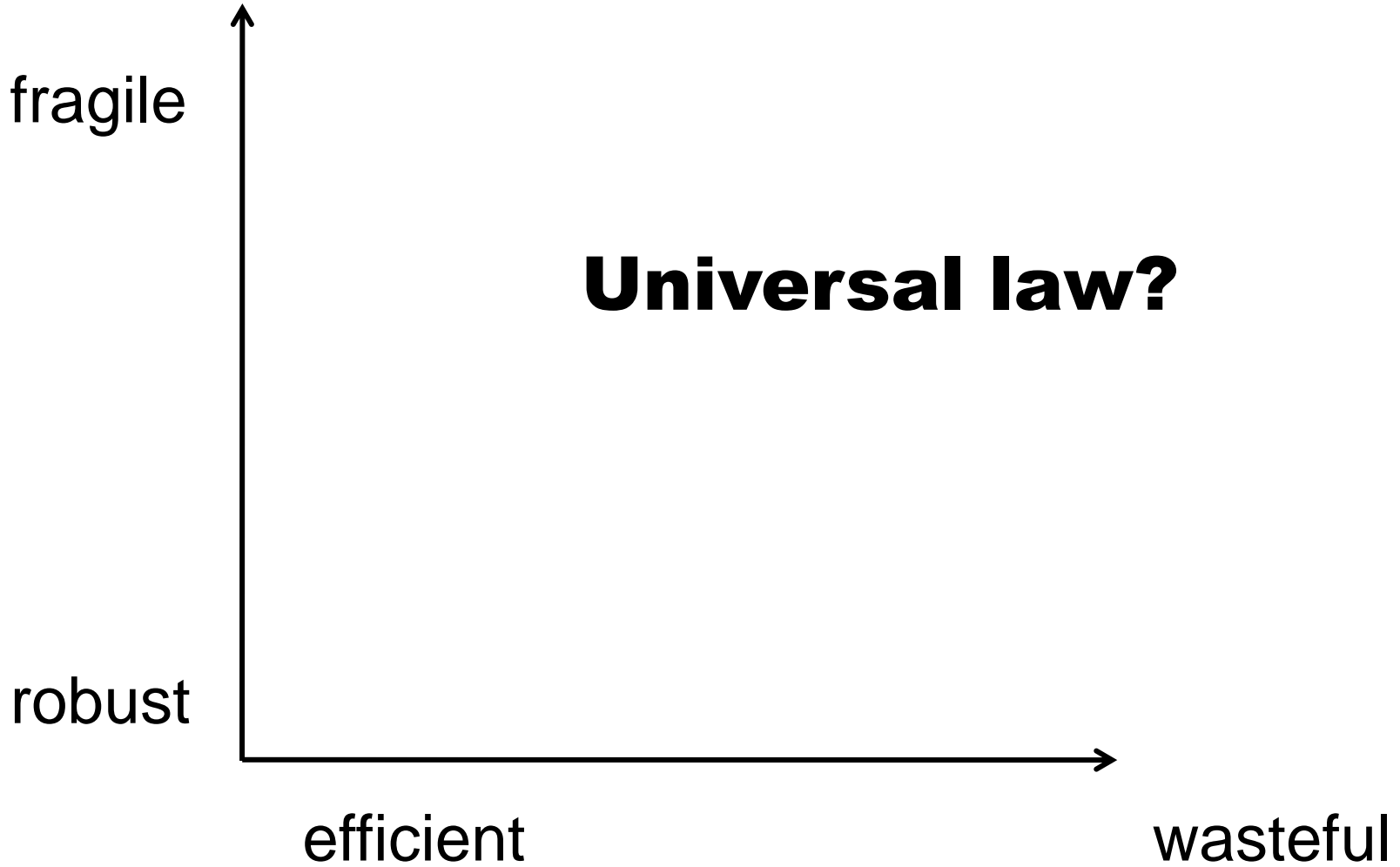
?



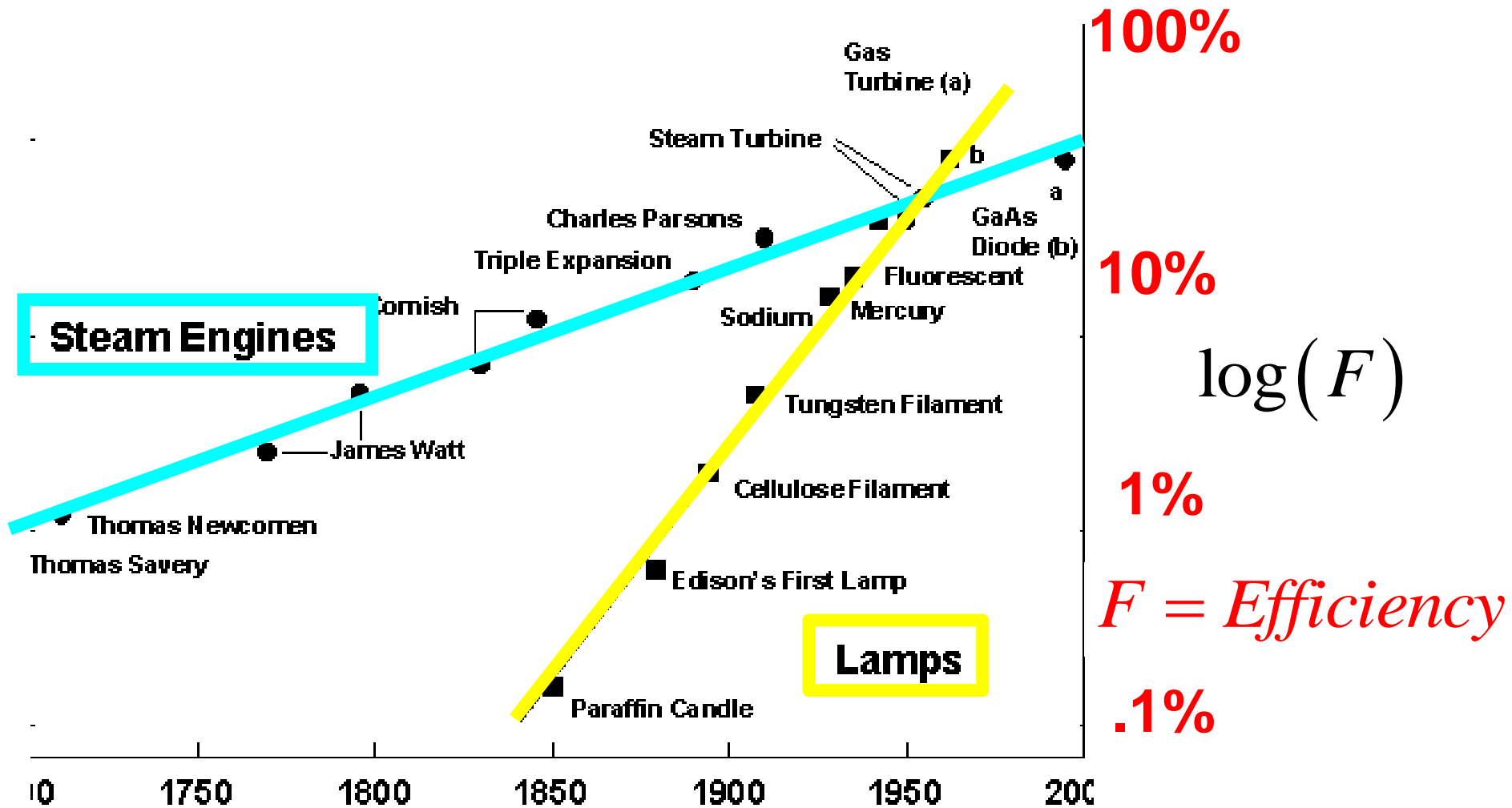
robust

efficient

wasteful

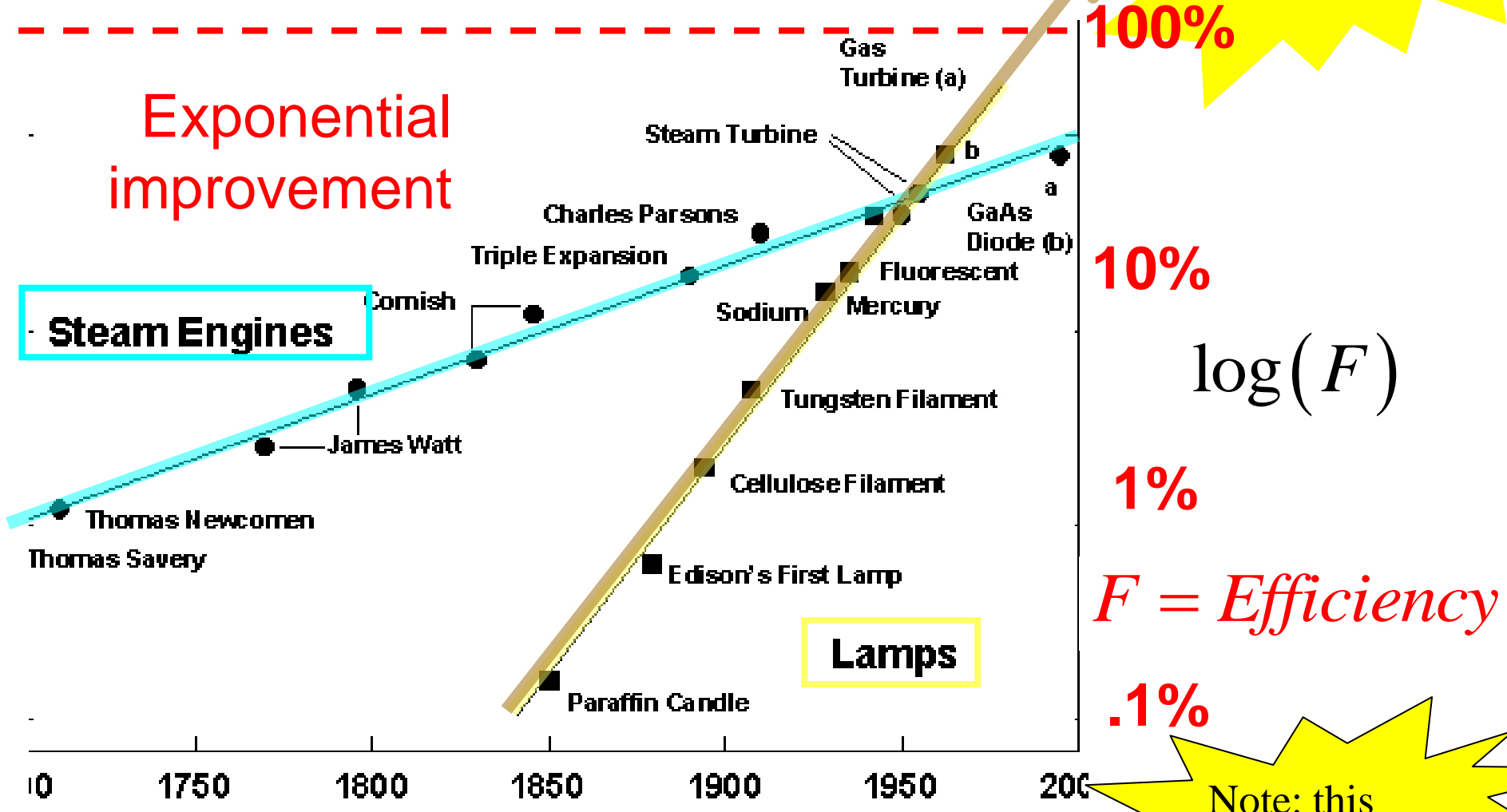


Exponential improvement in efficiency F



When will lamps be 200% efficient?

Solving all energy problems?



100%

10%

1%

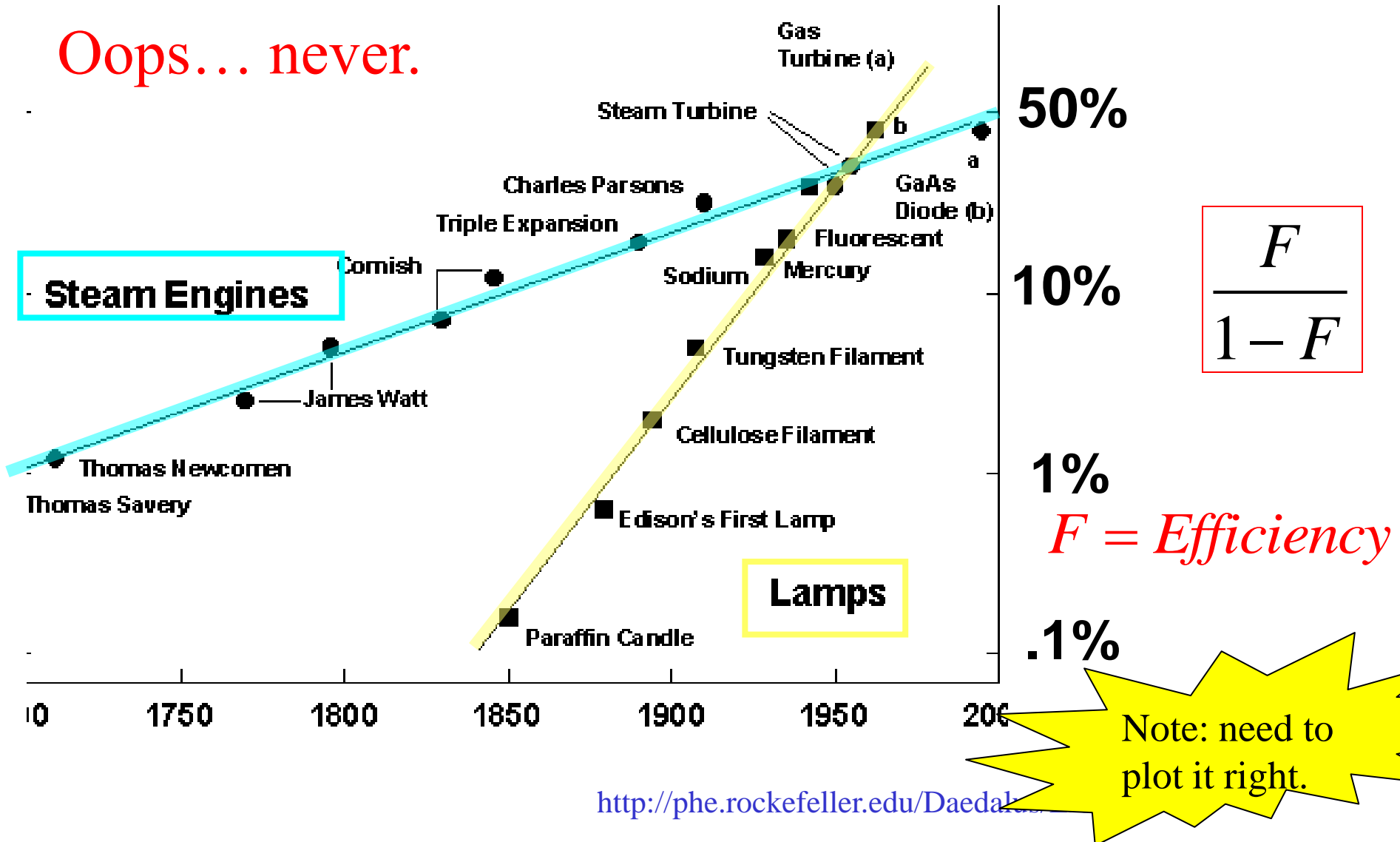
$F = \text{Efficiency}$

.1%

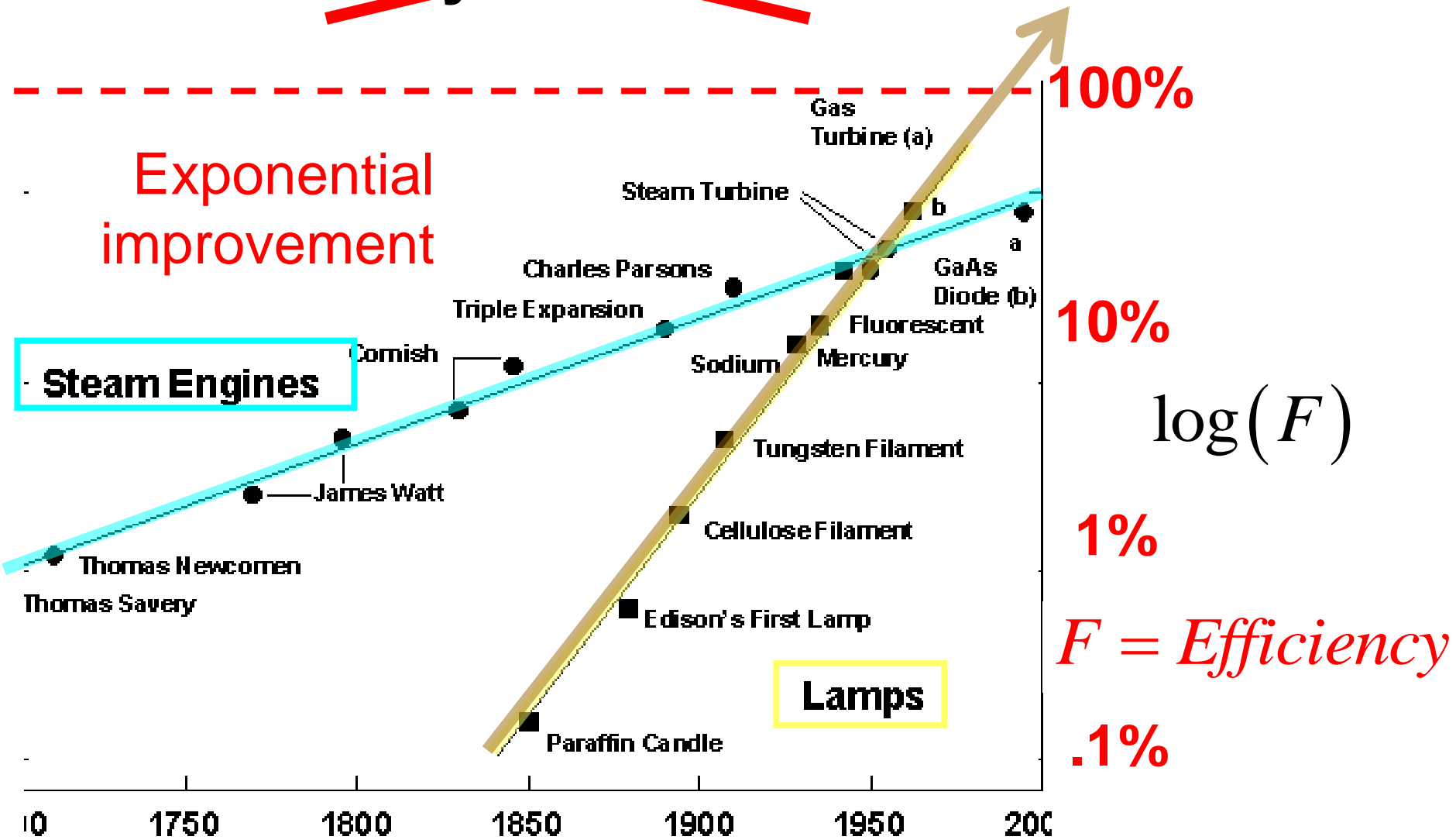
Note: this is real data!

When will lamps be 200% efficient?

Oops... never.



~~Doyle's law?~~



Universal law

■ ■ ■ ■ ■ ■ ■ 100%

10%

1%

F = Efficiency

.1%

Universal law?

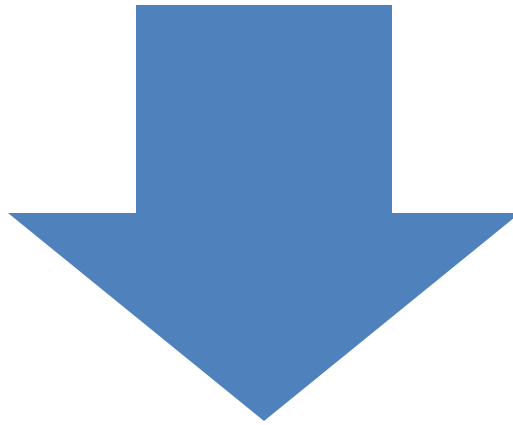


efficient

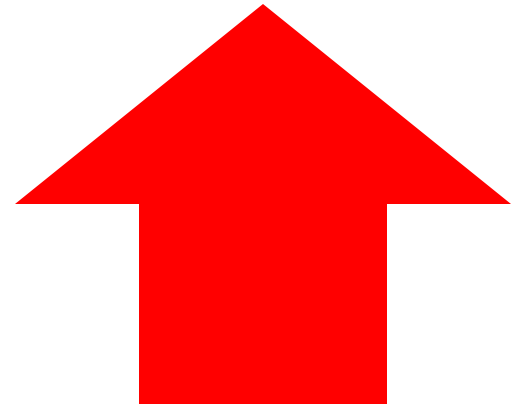
wasteful

100%

fragile



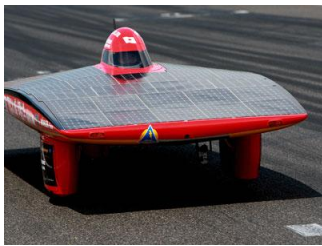
**Some features
robust to some
perturbations**



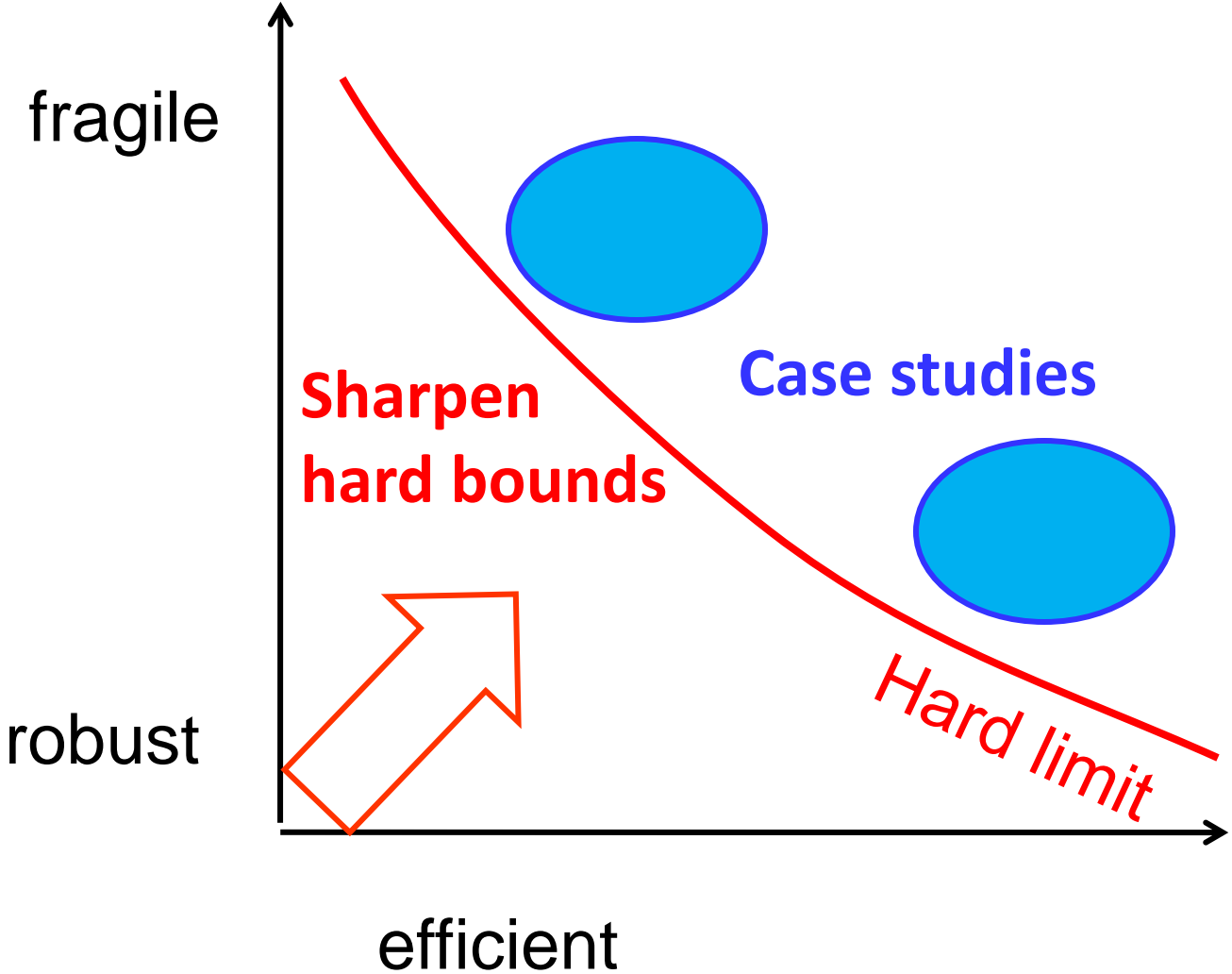
**Other features or
other
perturbations**

robust





laws and architectures?



Control, OR

Kalman

Comms

Bode

Pontryagin

Shannon

Nash

Theory?

Deep, but fragmented,
incoherent, incomplete

Von
Neumann

Carnot

Turing

Boltzmann

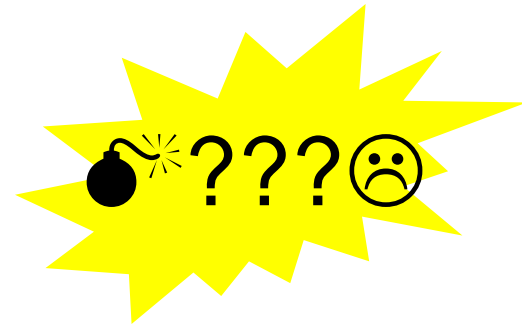
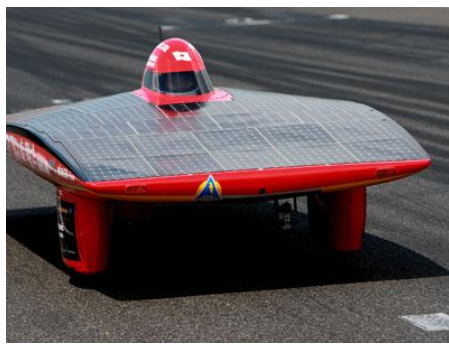
Godel

Heisenberg

Compute

Einstein

Physics

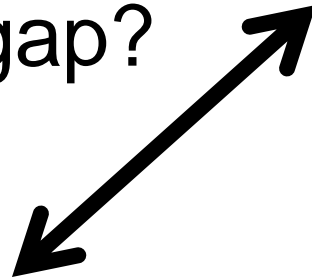


Bad architectures?

fragile

?

gap?



Bad theory?

?



robust

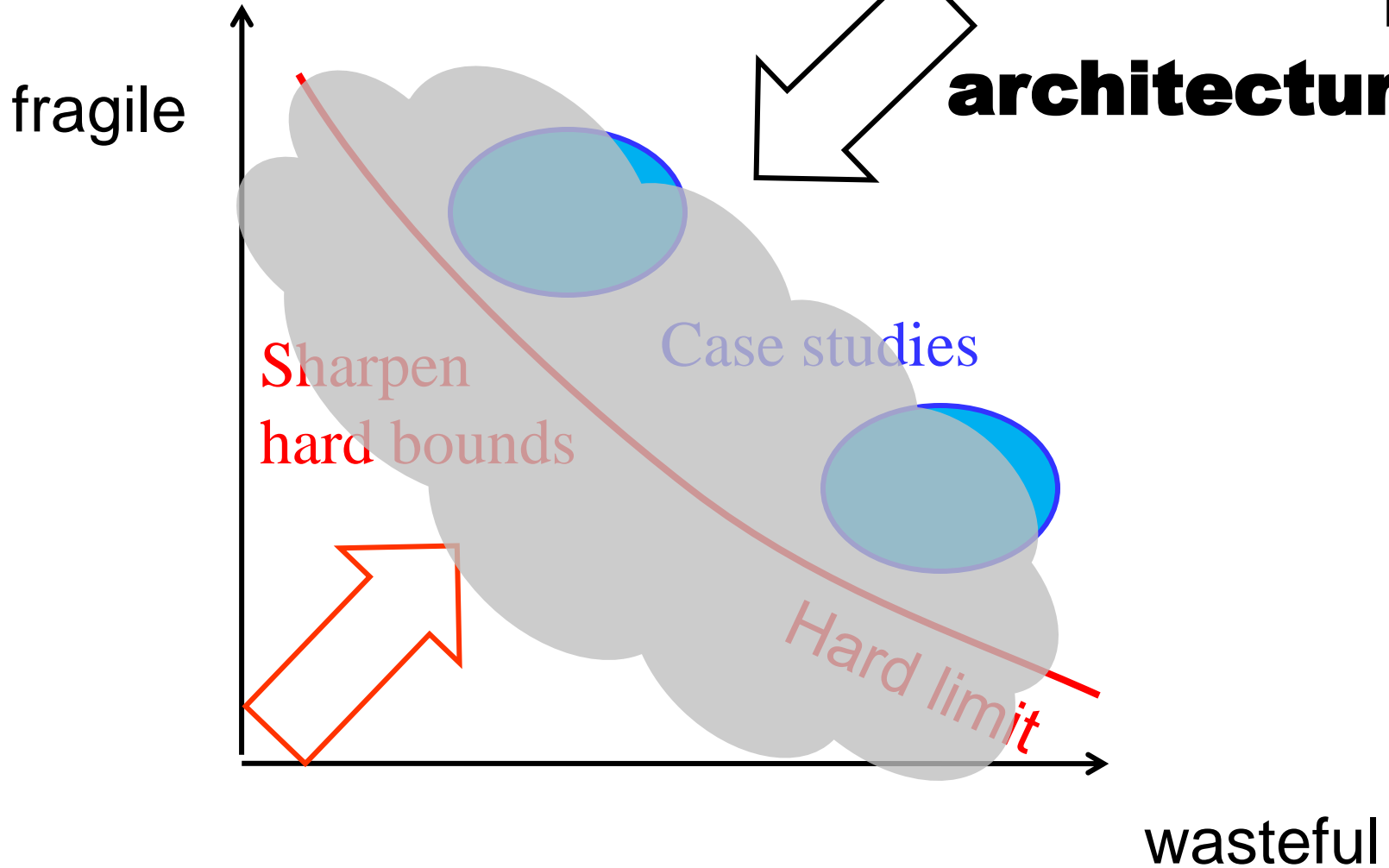
efficient

wasteful

**Find and
fix bugs**



**Bad
architectures?**



Compute

Turing (1912-1954)

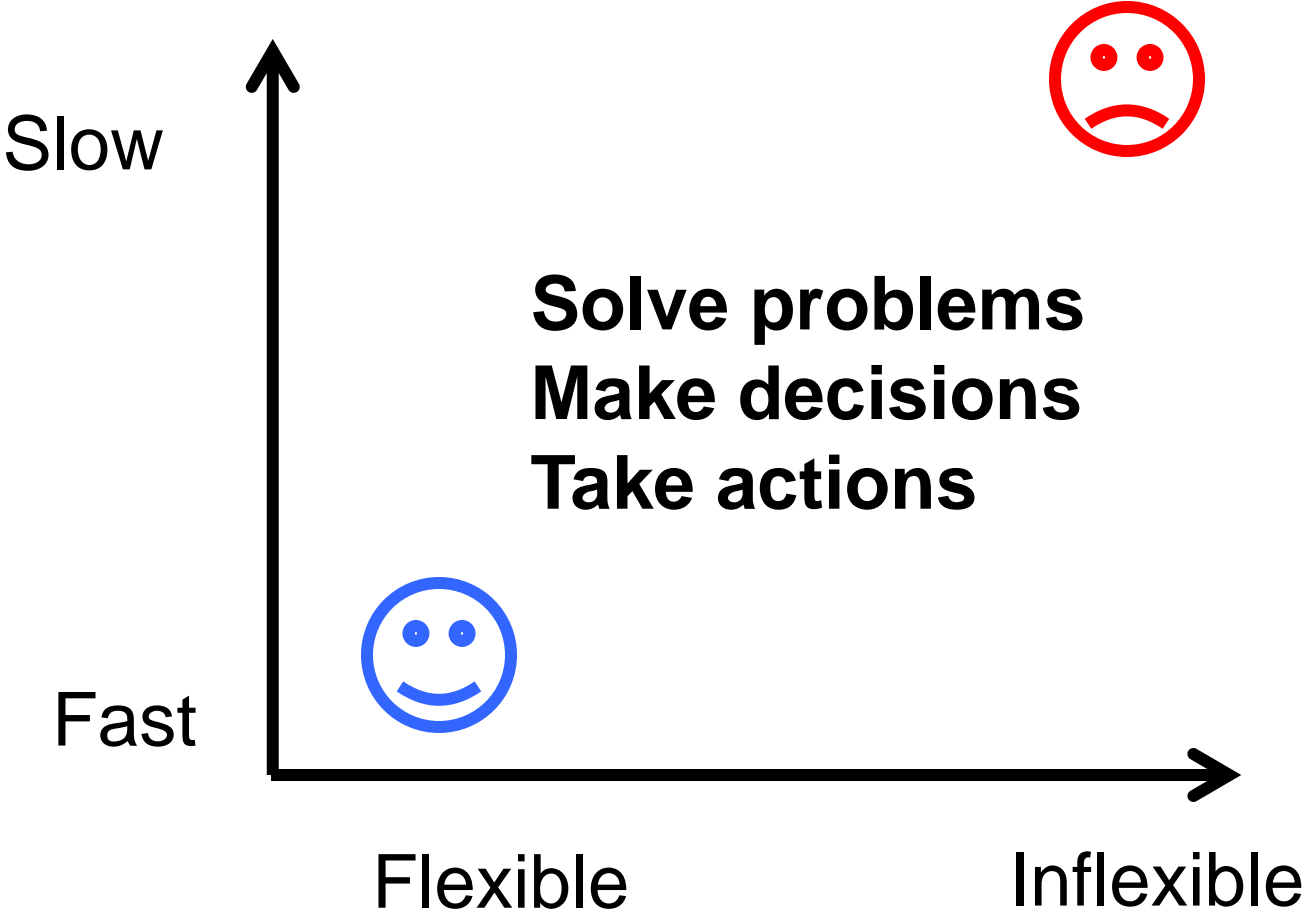
- Turing 100th birthday in 2012
- Turing
 - machine (math, CS)
 - test (AI, neuroscience)
 - pattern (biology)
- Arguably greatest*
 - all time math/engineering combination
 - WW2 hero
 - “invented” software

*Also world-class runner.

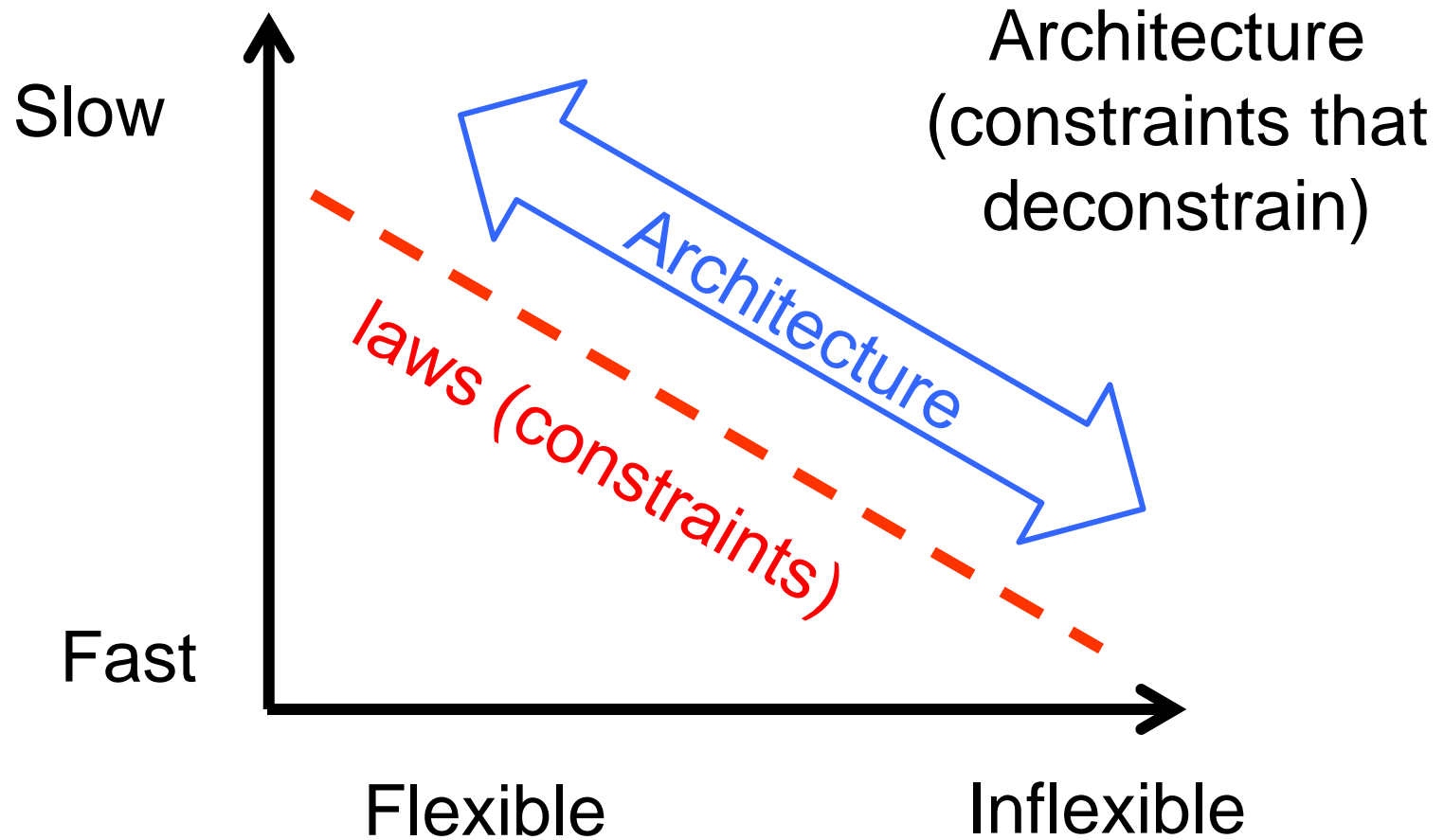
Key papers/results

- Theory (1936): Turing machine (TM), computability, (un)decidability, universal machine (UTM)
- Practical design (early 1940s): code-breaking, including the design of code-breaking machines
- Practical design (late 1940s): general purpose digital computers and software, layered architecture
- Theory (1950): Turing test for machine intelligence
- Theory (1952): Reaction diffusion model of morphogenesis, plus practical use of digital computers to simulate biochemical reactions

Fast and flexible



Laws and architectures



Compute

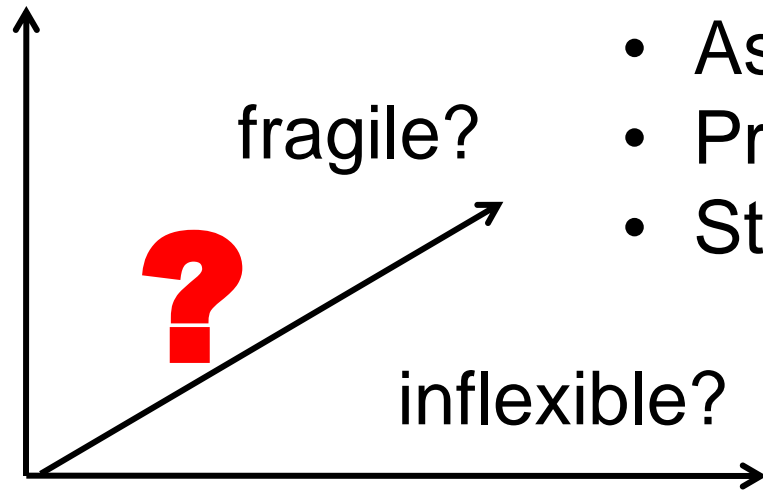
Comms

Godel

Shannon

Turing

slow?



- Each theory \approx one dimension
- Tradeoffs **across** dimensions
- Assume architectures a priori
- Progress is encouraging, but...
- Stovepipes are an obstacle...

Carnot

Boltzmann

Bode

Heisenberg

Control

Einstein

Physics

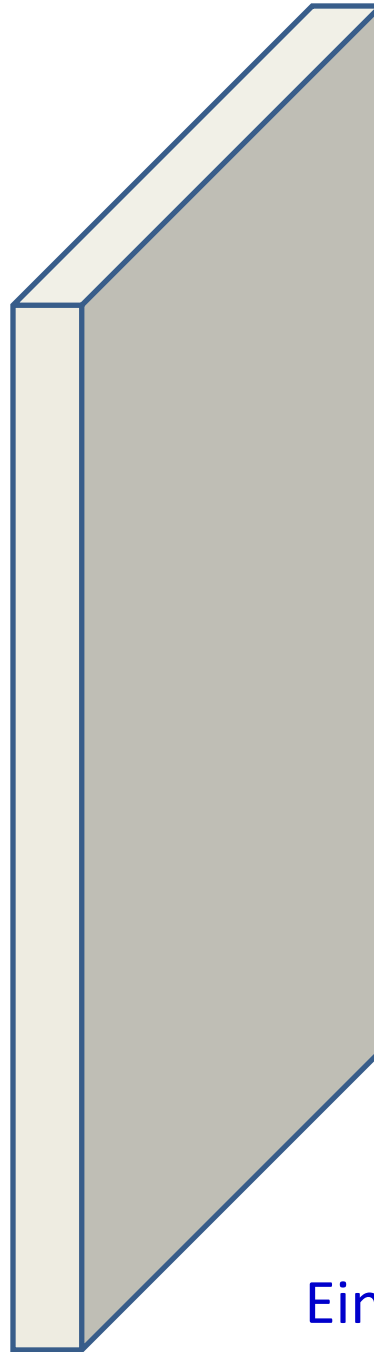
Compute

Turing

Delay is
most
important

Bode

Control, OR



Communicate

Shannon

Delay is
least
important

Carnot

Boltzmann

Heisenberg

Physics

Einstein

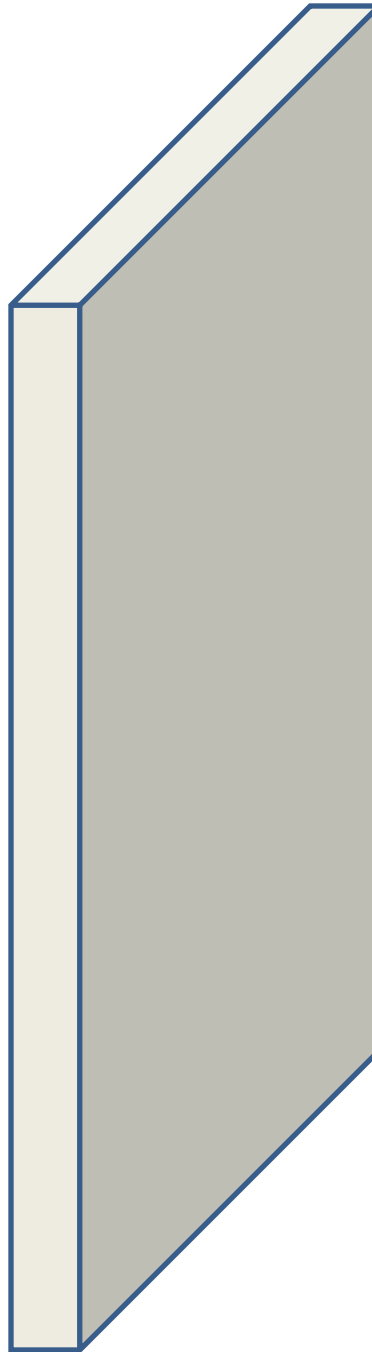
Compute

Turing

**Delay is
most
important**

Bode

Control, OR



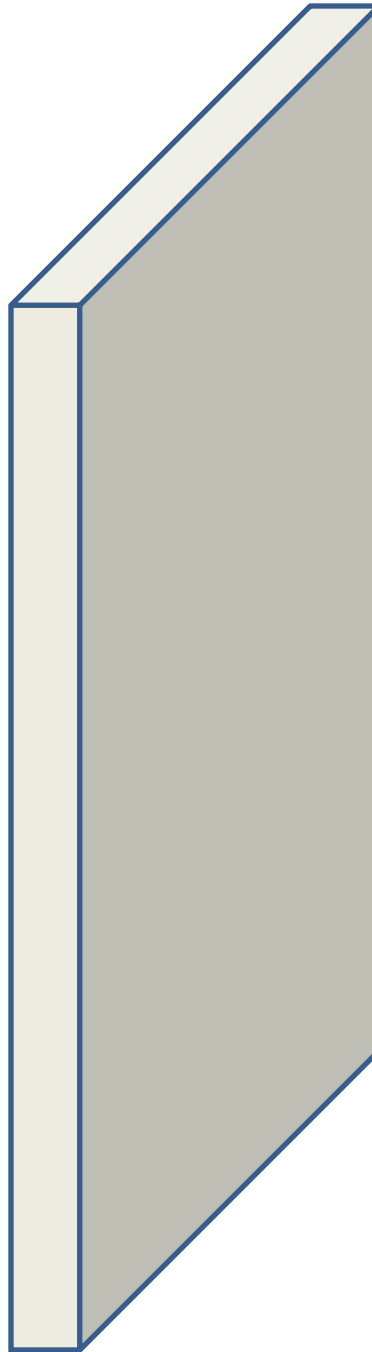
Compute

Turing

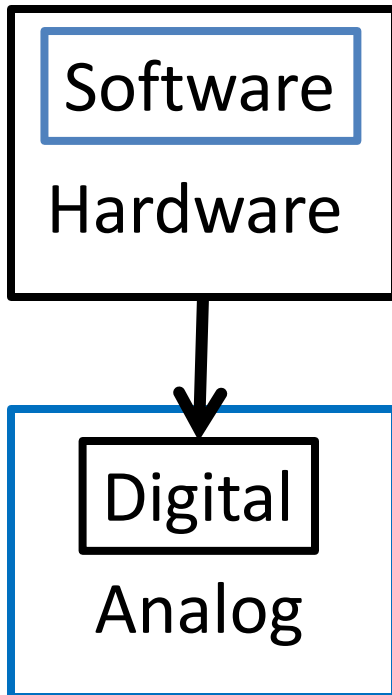
**Delay is
most
important**

Bode

Control, OR



Turing as
“new”
starting
point?



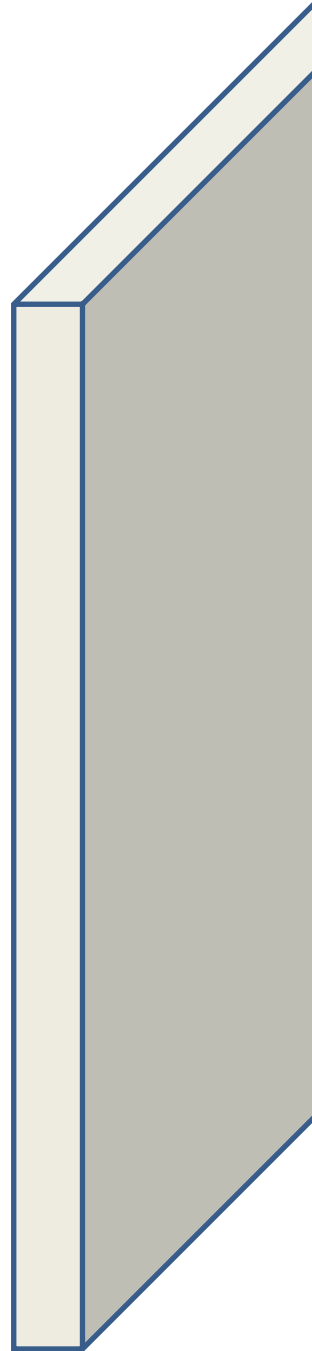
Compute

Turing

**Delay is
most
important**

Bode

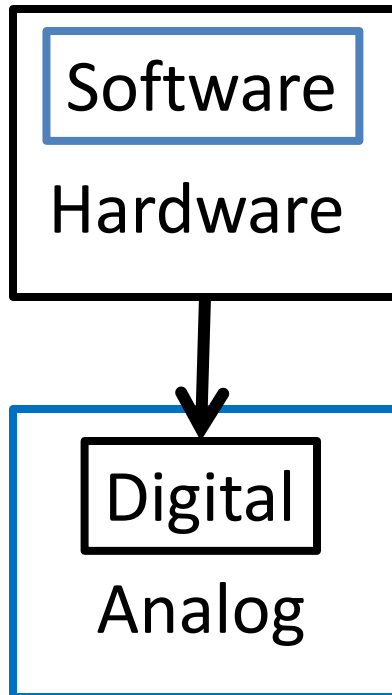
Control, OR



Turing as
“new”
starting
point?

Essentials:

0. Model
1. Universal laws
2. Universal architecture
3. Practical implementation

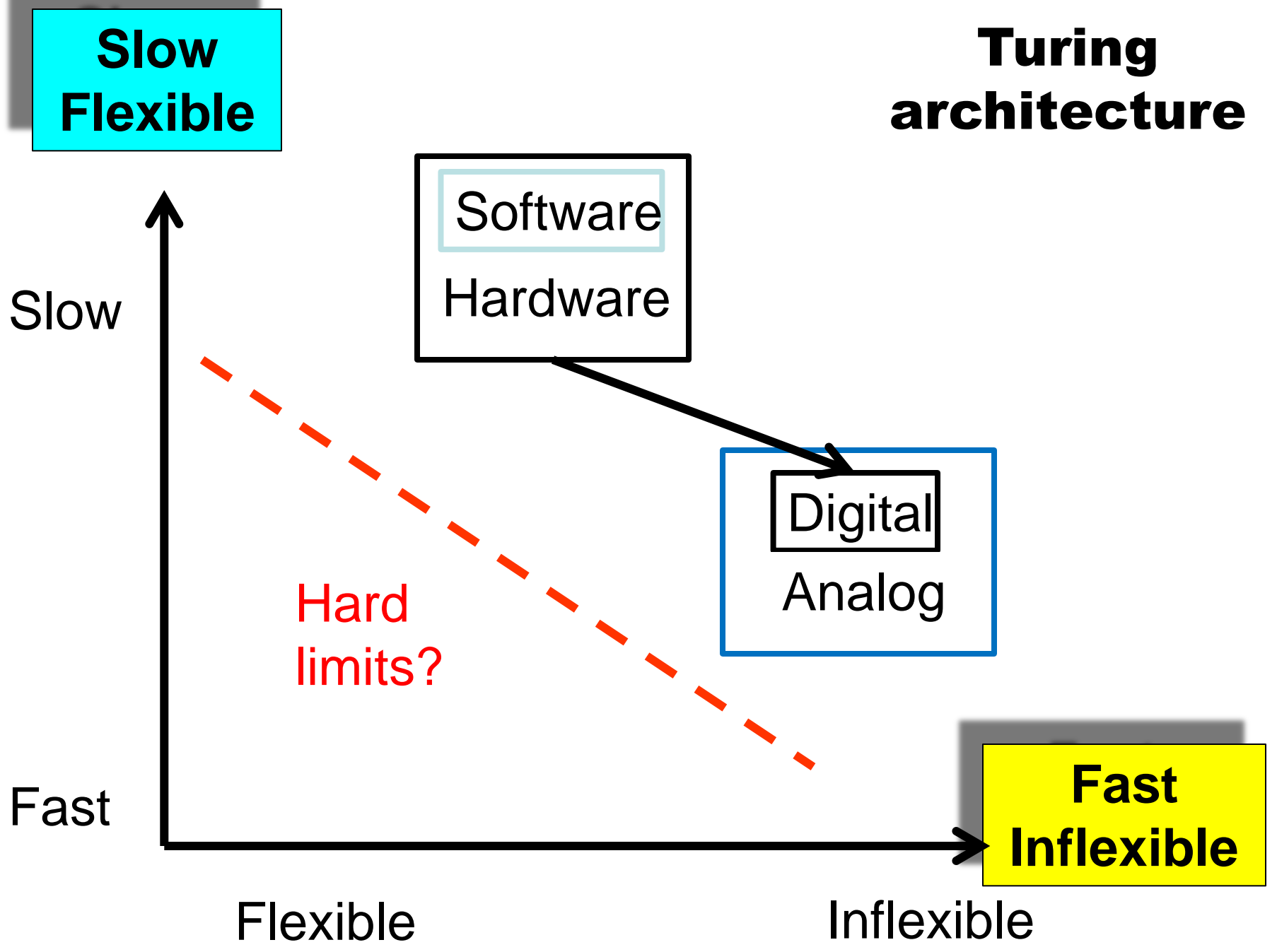


Turing's 3 step research:

0. Virtual (TM) machines
1. hard limits, (un)decidability using standard model (TM)
2. Universal architecture achieving hard limits (UTM)
3. Practical implementation in digital electronics (biology?)

Who/what

Turing architecture



Slow Flexible

Slow

Fast

Flexible

Inflexible

Software
Hardware

Digital
Analog

Hard
limits?

Fast Inflexible

Flexible

General purpose
Large uncertainties
Diverse problems

Solve problems
Make decisions
Take actions

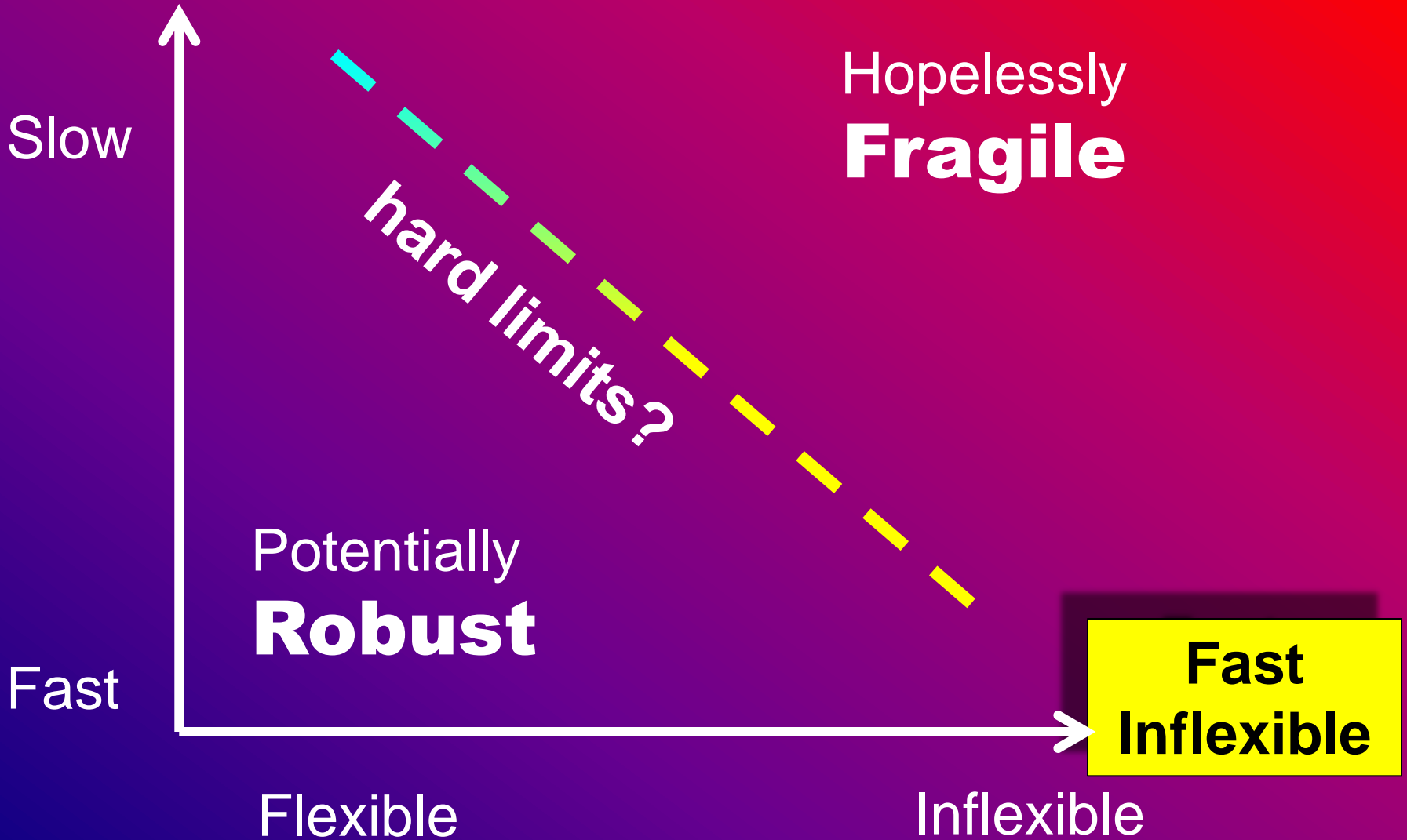
Low latency/delay

Fast

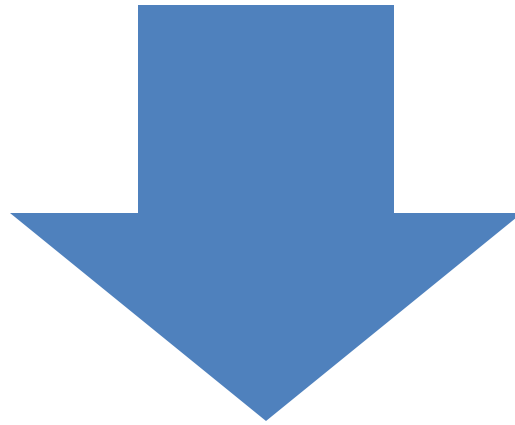
Fast

Flexible

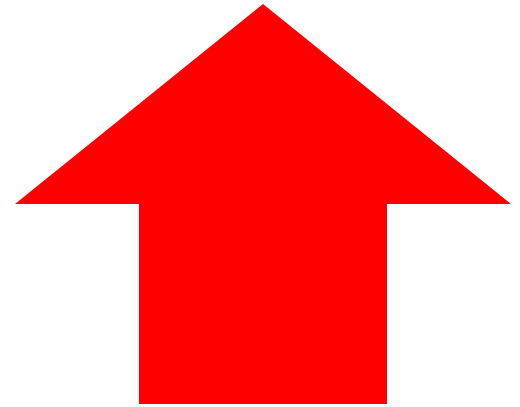
**Slow
Flexible**



fragile



**Some features
robust to some
perturbations**



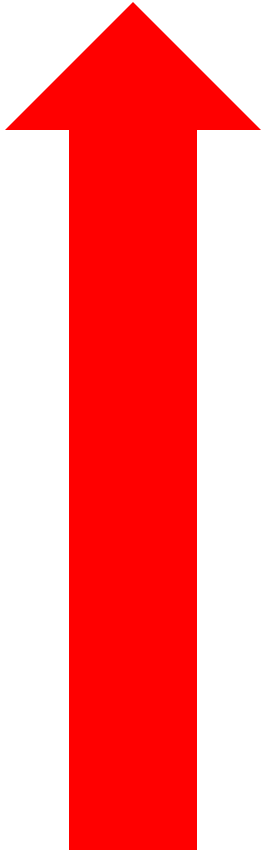
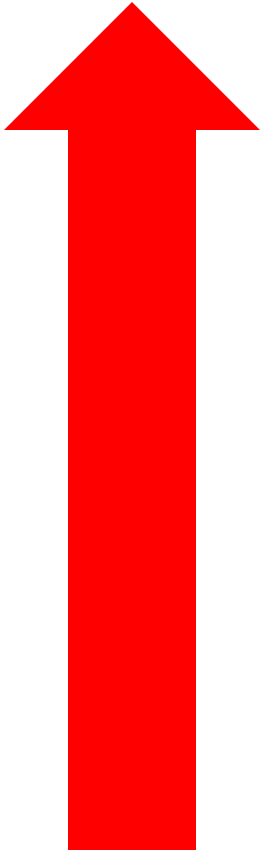
**Other features or
other
perturbations**

robust



Increased complexity?

fragile



robust

**Some features
robust to some
perturbations**

**Other features or
other
perturbations**

Robust

Modular

Simple

Plastic

Evolvability

and

~~**xor**~~

Fragile

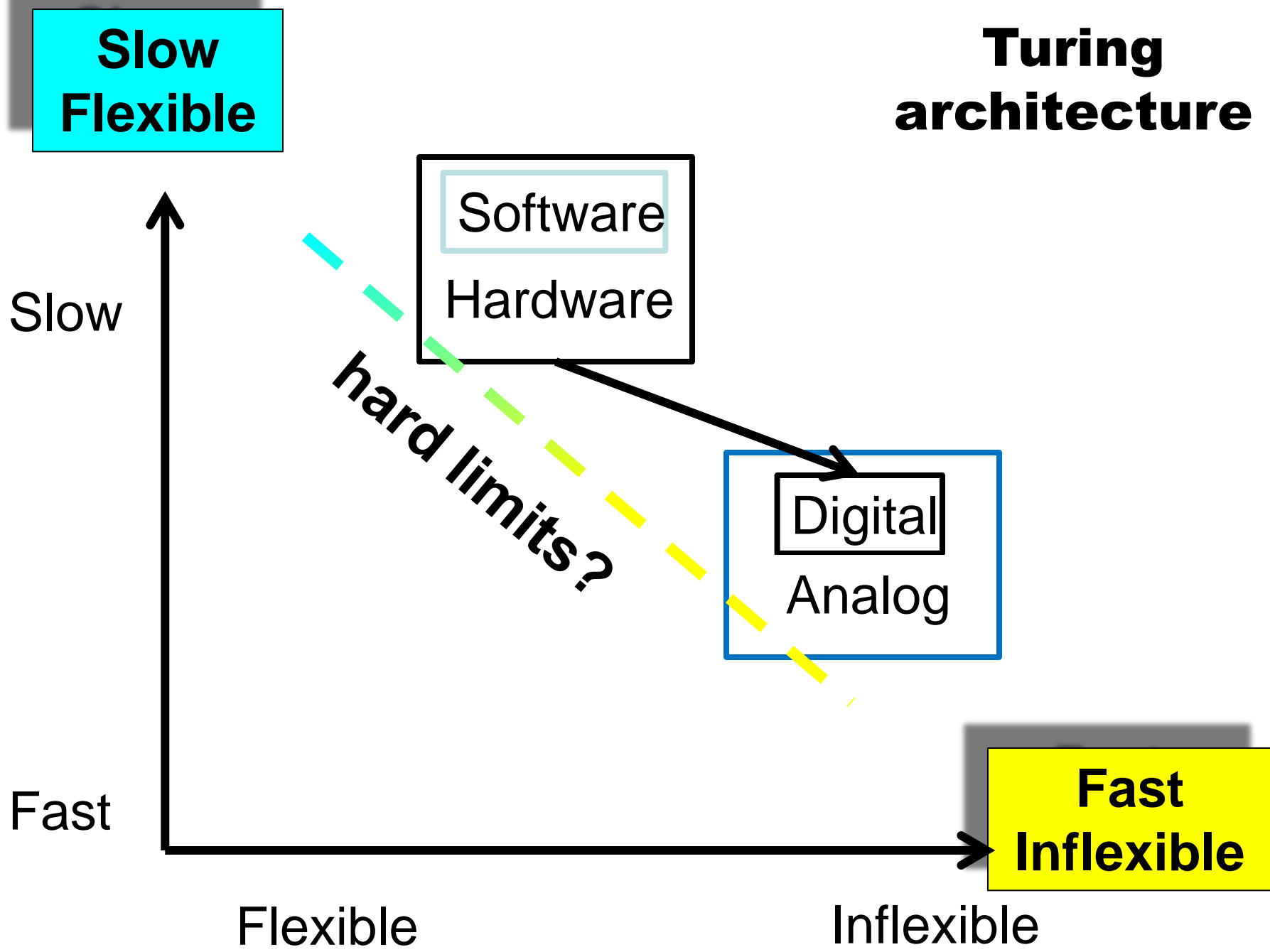
Distributed

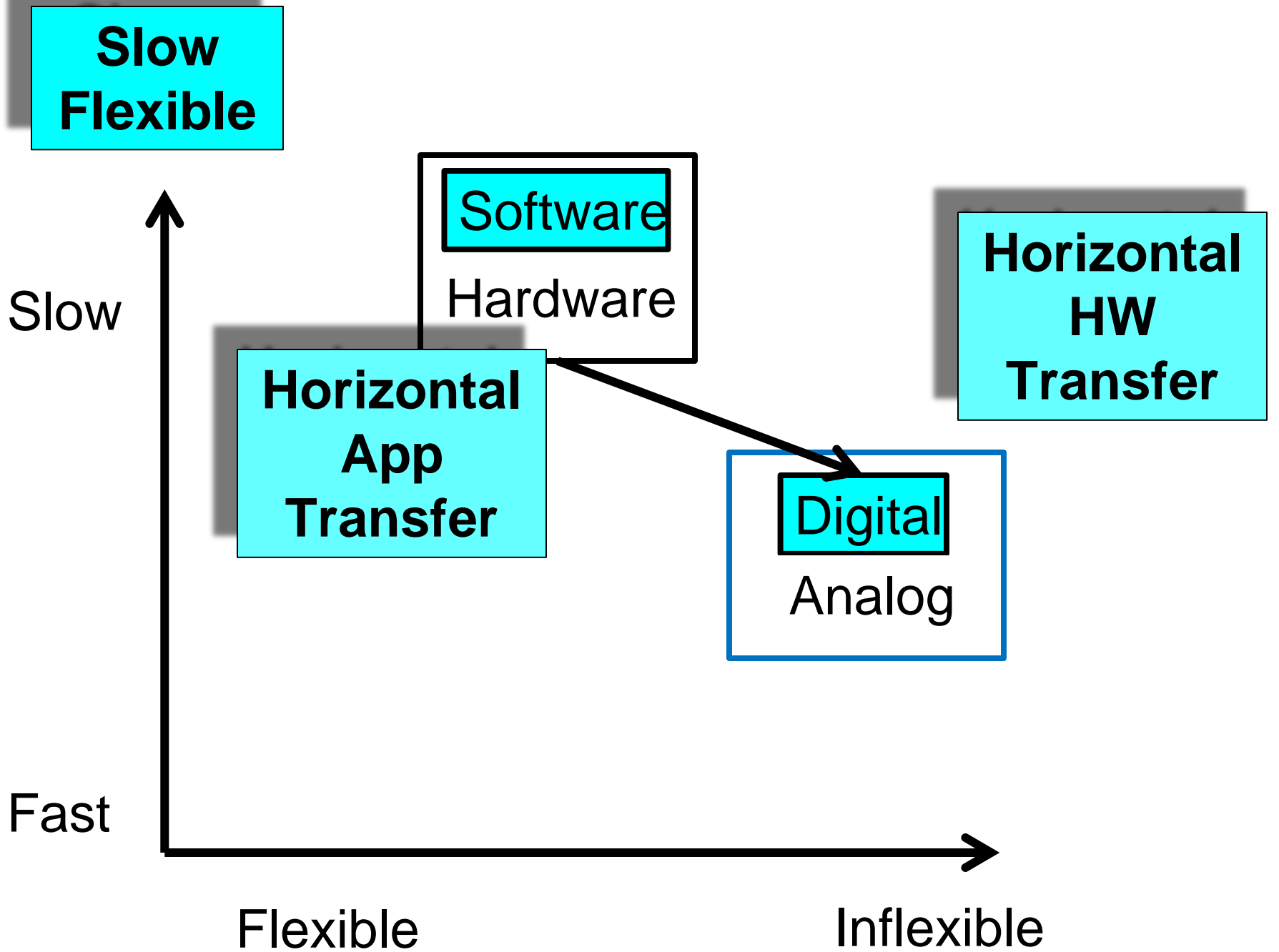
Complex

Frozen

Frozen

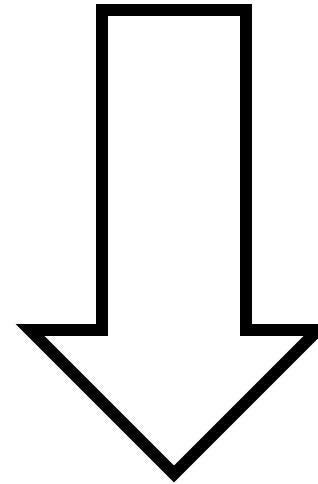
tradeoffs





Slow execution
Flexible reprogramming

Faster execution
Less flexible



Modern technology gives lots of intermediate alternatives.

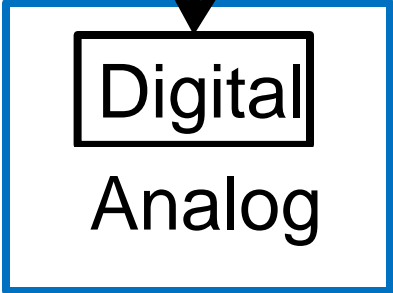
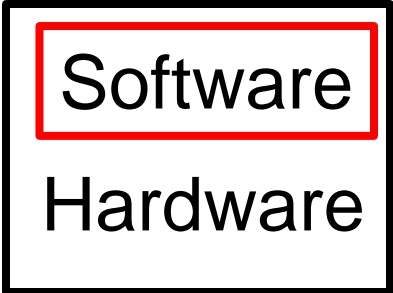
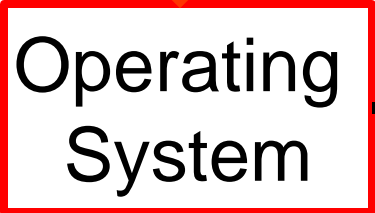
Software

Software

Hardware

Digital

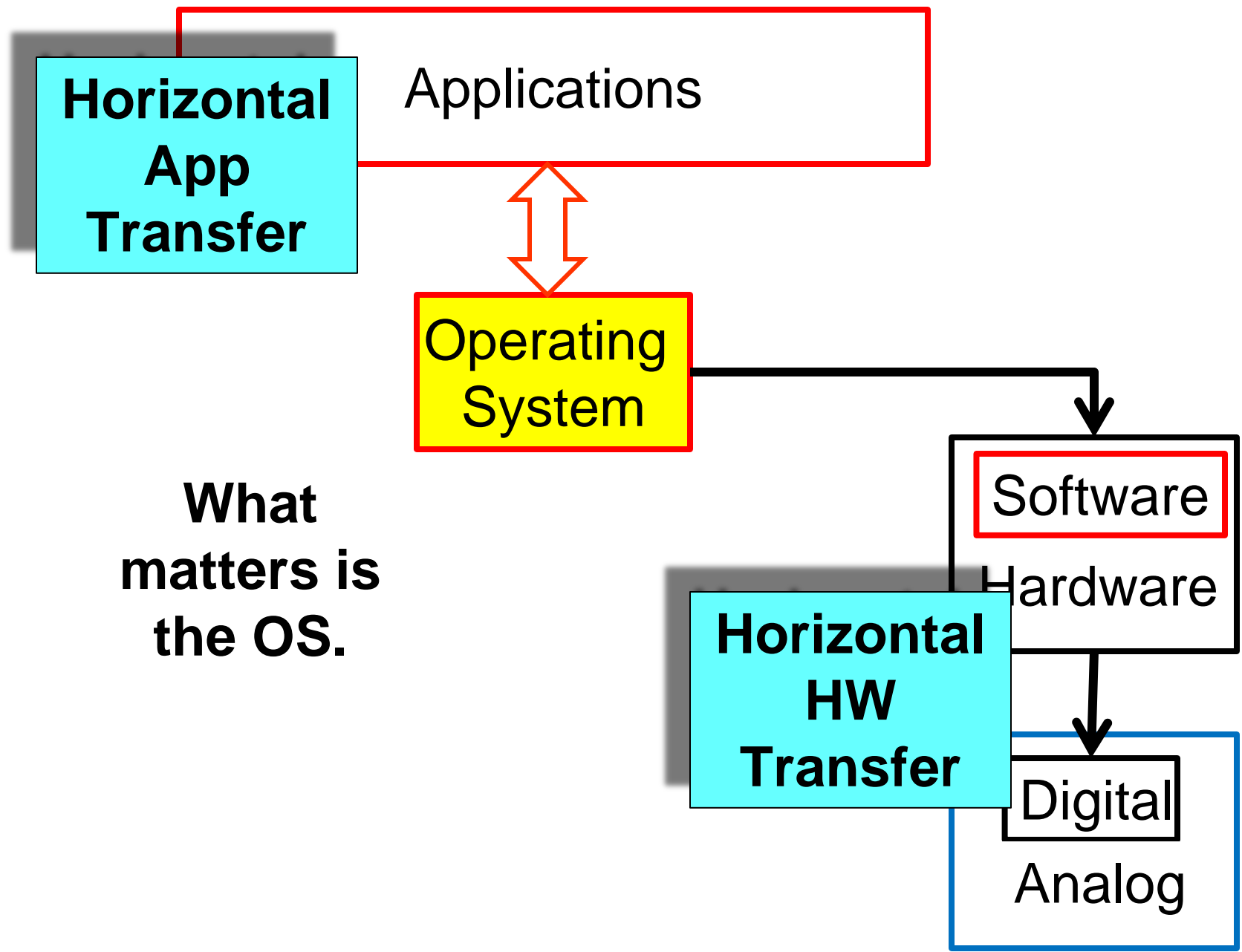
Analog



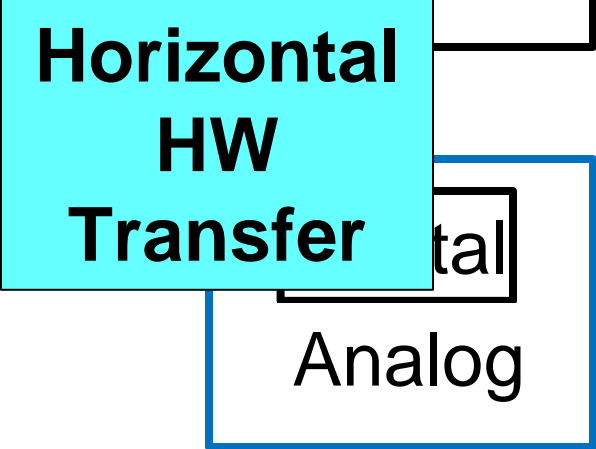
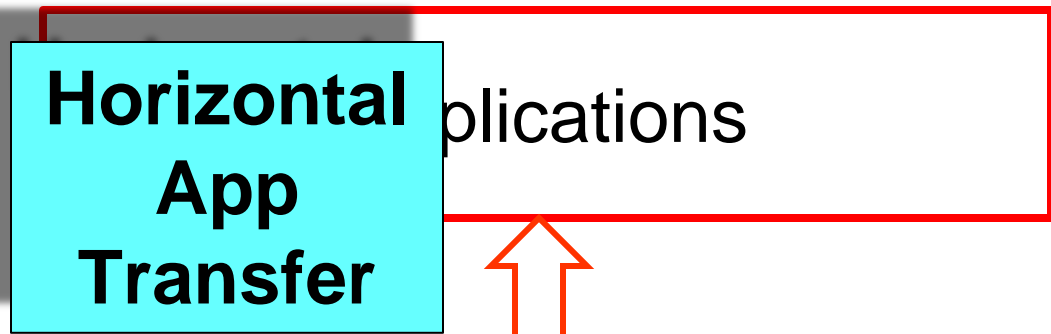
Control, share, virtualize, and manage resources

Processing
Memory
I/O

Want to emphasize the differences between these two types of layering.



What matters is the OS.



- Some people write apps and build hardware
- But most software and hardware is acquired by “horizontal” transfer from others
- Similarly, most new ideas (humans) and new genes (bacteria) are acquired horizontally

Compute

Turing

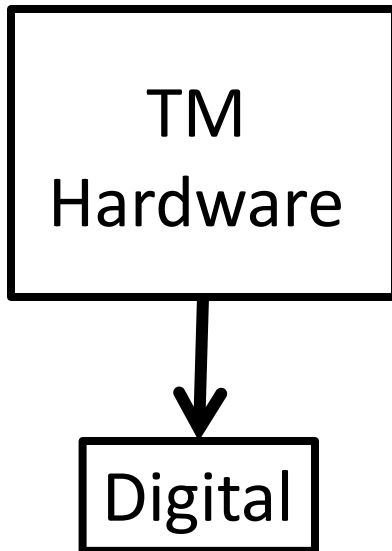
Why

Necessity

Essentials:

0. **Model**

1. Universal laws
2. Universal architecture
3. Practical implementation

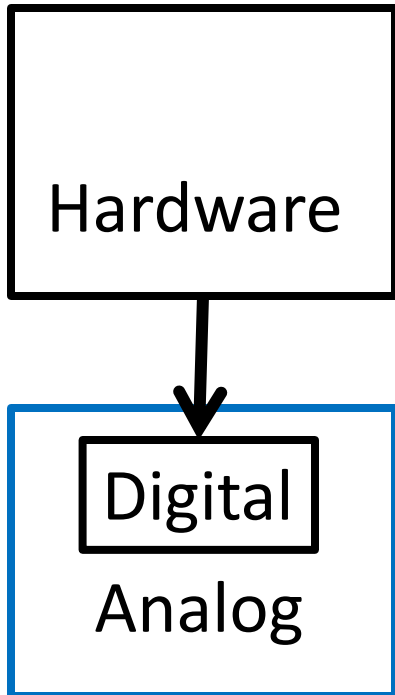


Turing's 3 step research:

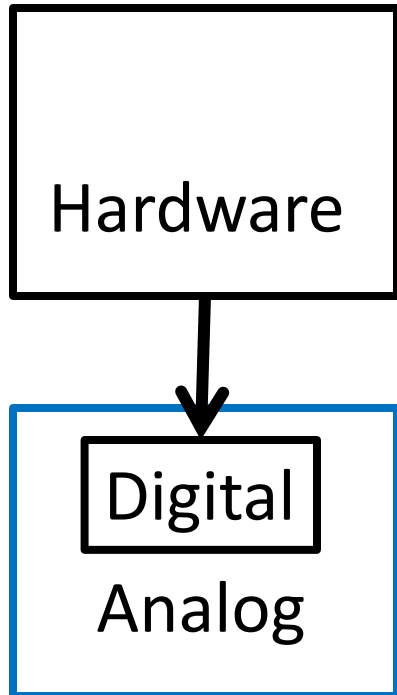
0. **Virtual (TM) machines**

1. hard limits, (un)decidability using standard model (TM)
2. Universal architecture achieving hard limits (UTM)
3. Practical implementation in digital electronics (biology?)

- ...being digital should be of greater interest than that of being electronic. That it is electronic is certainly important because these machines owe their high speed to this... But this is virtually all that there is to be said on that subject.
- That the machine is digital however has more subtle significance. ... One can therefore work to any desired degree of accuracy.



1947 Lecture to LMS

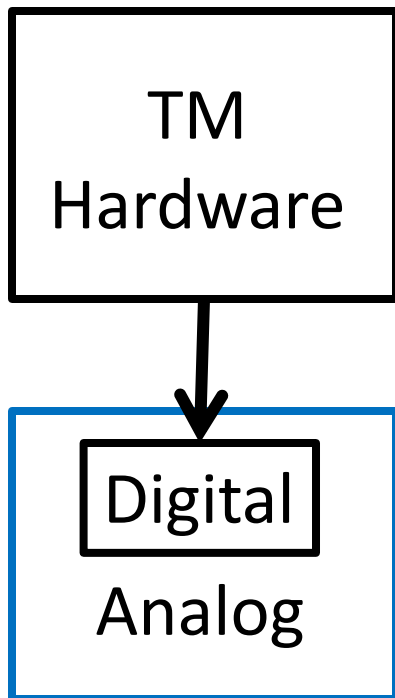


- ... digital ... of greater interest than that of being electronic ...
- ...any desired degree of accuracy...
- This accuracy is not obtained by more careful machining of parts, control of temperature variations, and such means, but by a slight increase in the amount of equipment in the machine.

1947 Lecture to LMS

Summarizing Turing:

- Digital more important than electronic...
- Robustness: accuracy and repeatability.
- Achieved more by internal hidden complexity than precise components or environments.



Turing Machine (TM)

- Digital
- Symbolic
- Logical
- Repeatable

avalanche

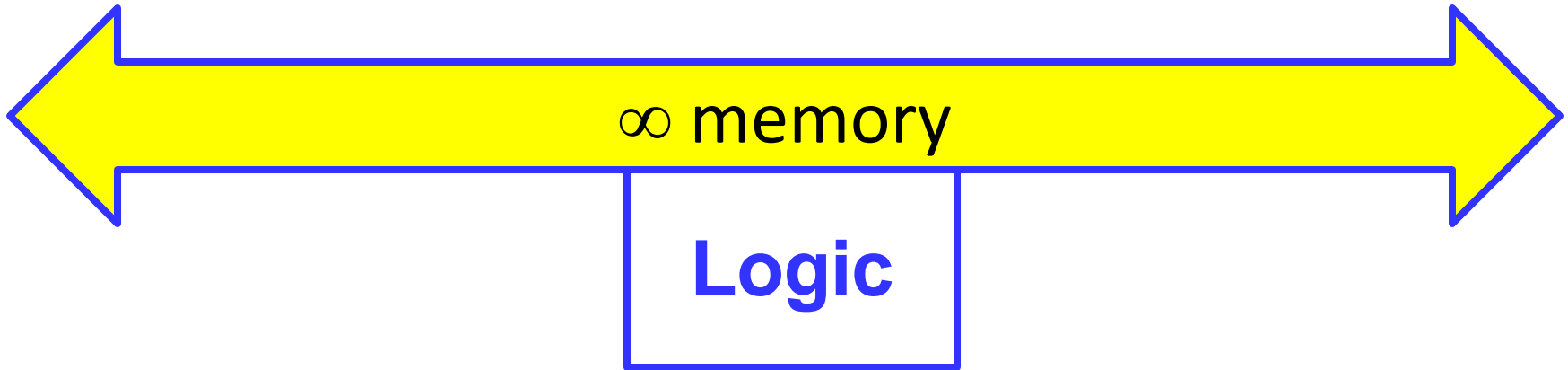
The ~~butterfly~~ effect

- ... quite small errors in the initial conditions can have an overwhelming effect at a later time. The displacement of a single electron by a billionth of a centimetre at one moment might make the difference between a man being killed by an avalanche a year later, or escaping.

1950, *Computing Machinery and Intelligence*,
Mind

- ... quite small errors in the initial conditions can have an overwhelming effect at a later time....
- It is an essential property of the mechanical systems which we have called 'discrete state machines' that this phenomenon does not occur.
- Even when we consider the actual physical machines instead of the idealised machines, reasonably accurate knowledge of the state at one moment yields reasonably accurate knowledge any number of steps later.

1950, Computing Machinery and Intelligence, *Mind*



TM
Hardware

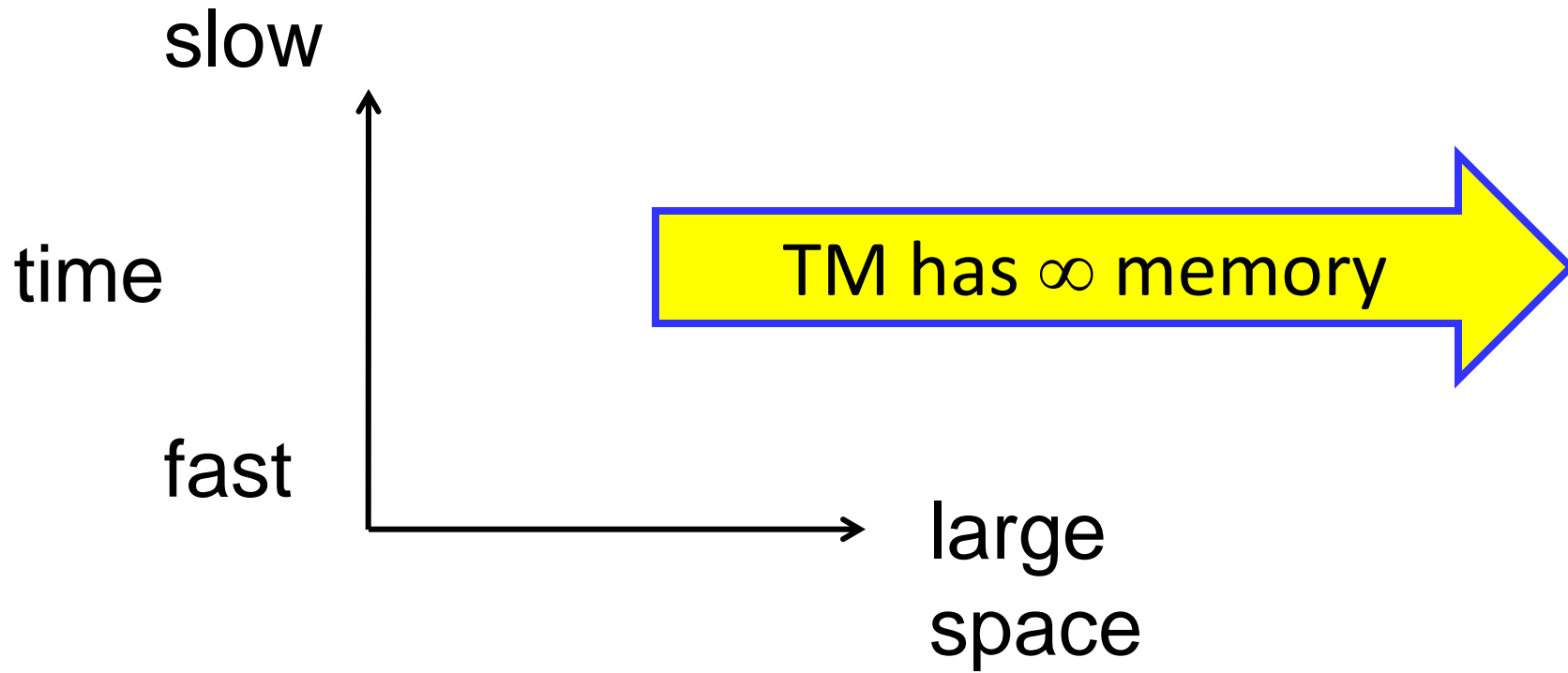
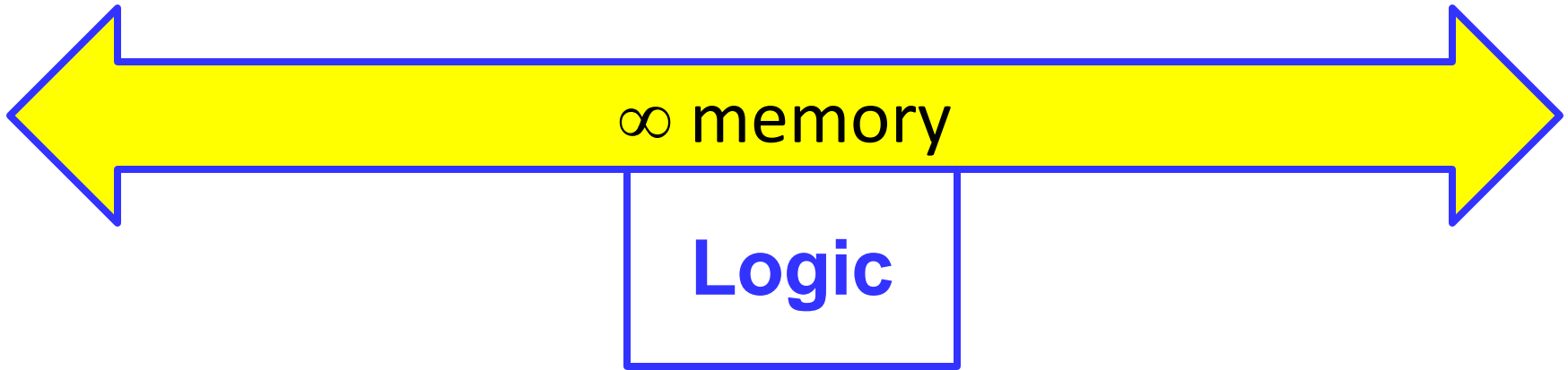
Turing's 3 step research:

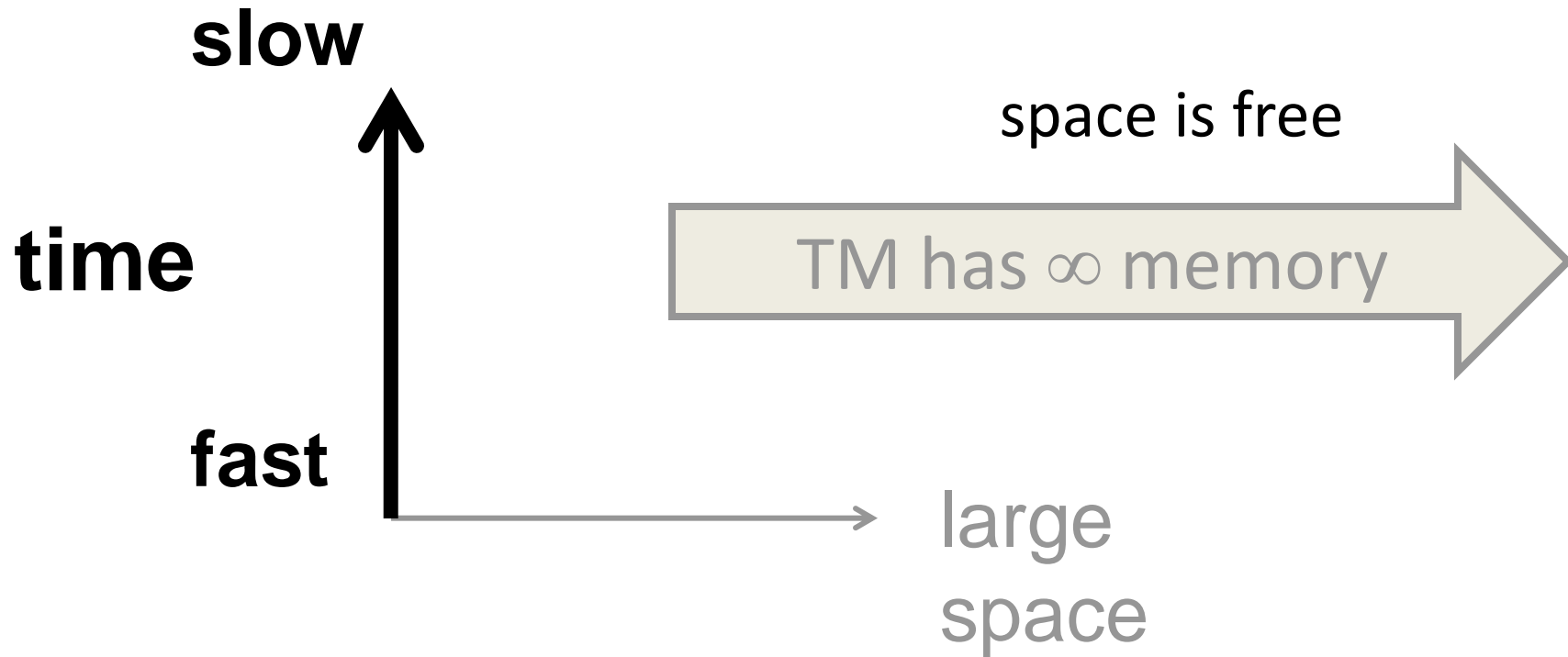
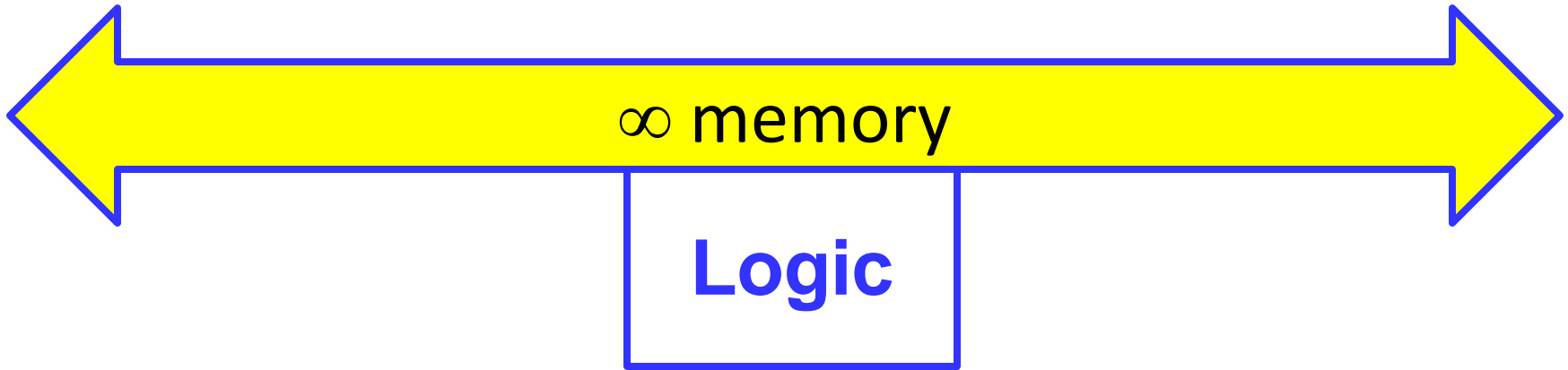
0. Virtual (TM) machines

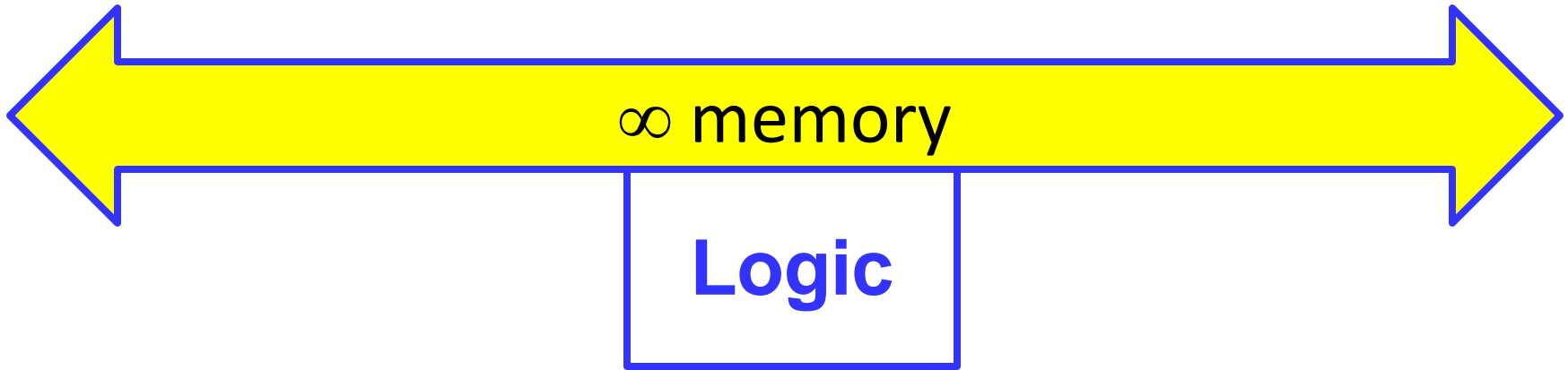
**1. hard limits, (un)decidability
using standard model (TM)**

2. Universal architecture
achieving hard limits (UTM)

3. Practical implementation in
digital electronics (biology?)



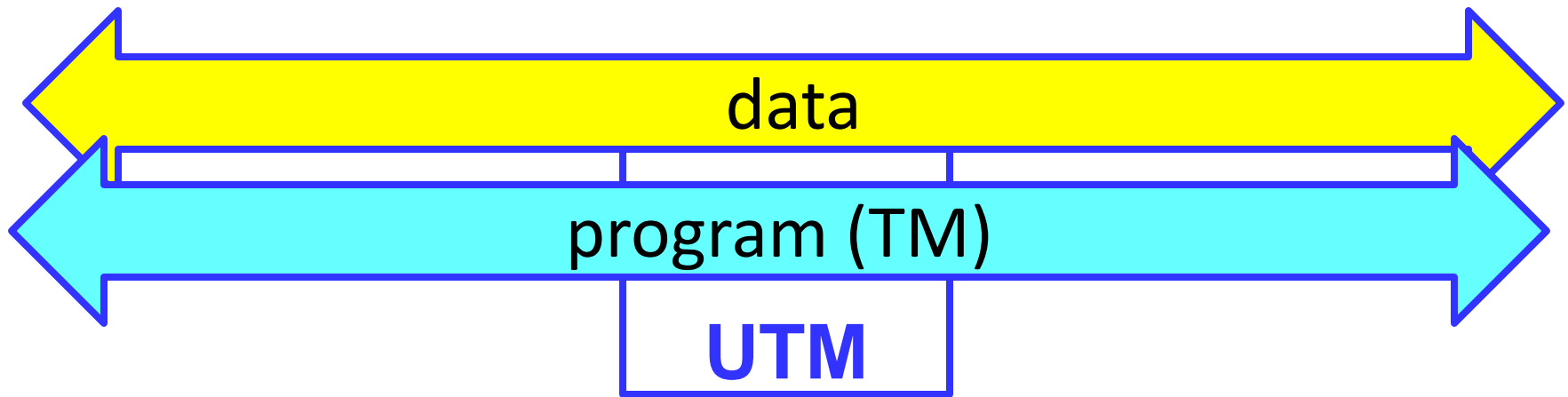




time?

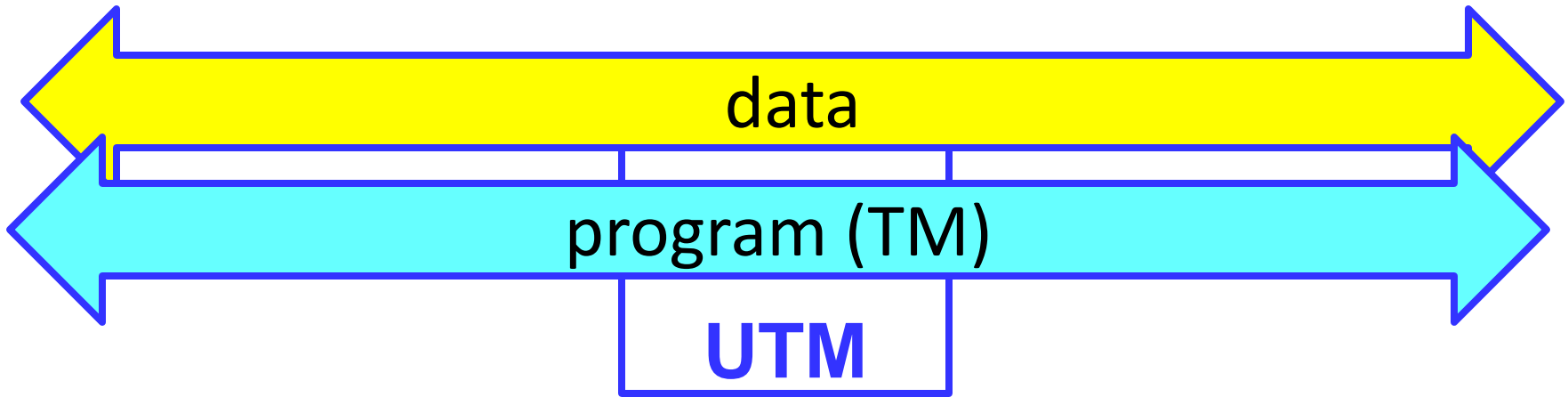
Decidable problem = \exists algorithm that solves it

Most naively posed problems are undecidable.



Turing's 3 step research:

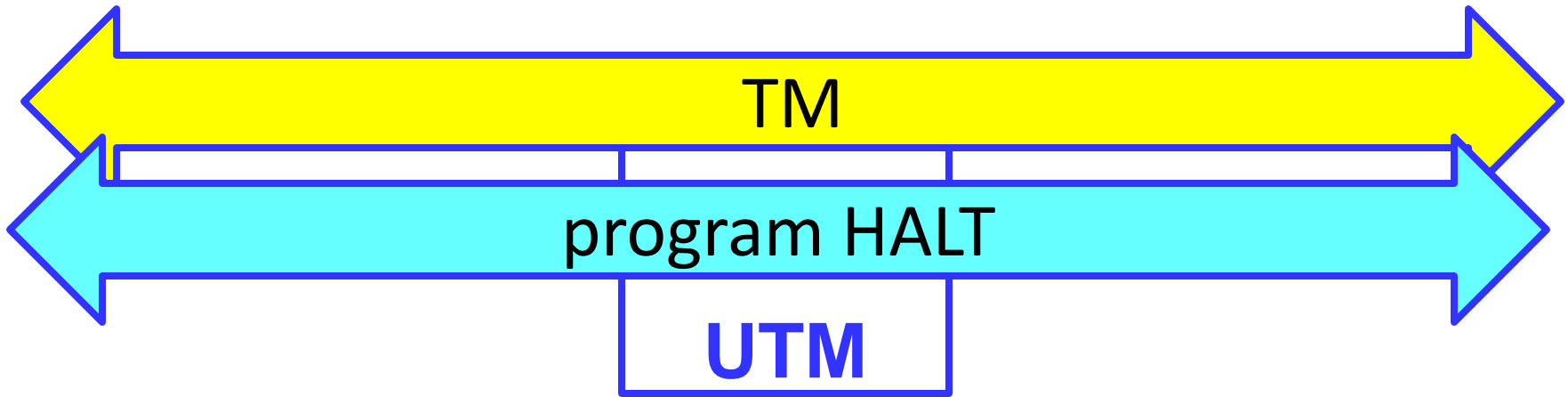
0. Virtual (TM) machines
1. hard limits, (un)decidability using standard model (TM)
- 2. Universal architecture achieving hard limits (UTM)**
3. Practical implementation in digital electronics (biology?)



Software
Hardware

2. Universal architecture achieving hard limits (UTM)

- Software: A Turing machine (TM) can be data for another Turing machine
- A Universal Turing Machine can run any TM
- A UTM is a virtual machine.
- There are lots of UTMs, differ only (but greatly) in speed and programmability (space assumed free)



The halting problem

- Given a TM (i.e. a computer program)
- Does it halt (or run forever)?
- Or do more or less anything in particular.
- Undecidable! There does not exist a special TM that can tell if any other TM halts.
- i.e. the program HALT does not exist. ☹️

Thm: TM H=HALT does not exist.

That is, there does not exist a program like this:

$$H(TM, input) \triangleq \begin{cases} 1 & \text{if } TM(input) \text{ halts} \\ 0 & \text{otherwise} \end{cases}$$

Proof is by contradiction. Sorry, don't know any alternative. And Turing is a god.

$$H(TM, input) \triangleq \begin{cases} 1 & \text{if } TM(input) \text{ halts} \\ 0 & \text{otherwise} \end{cases}$$

Thm: No such H exists.

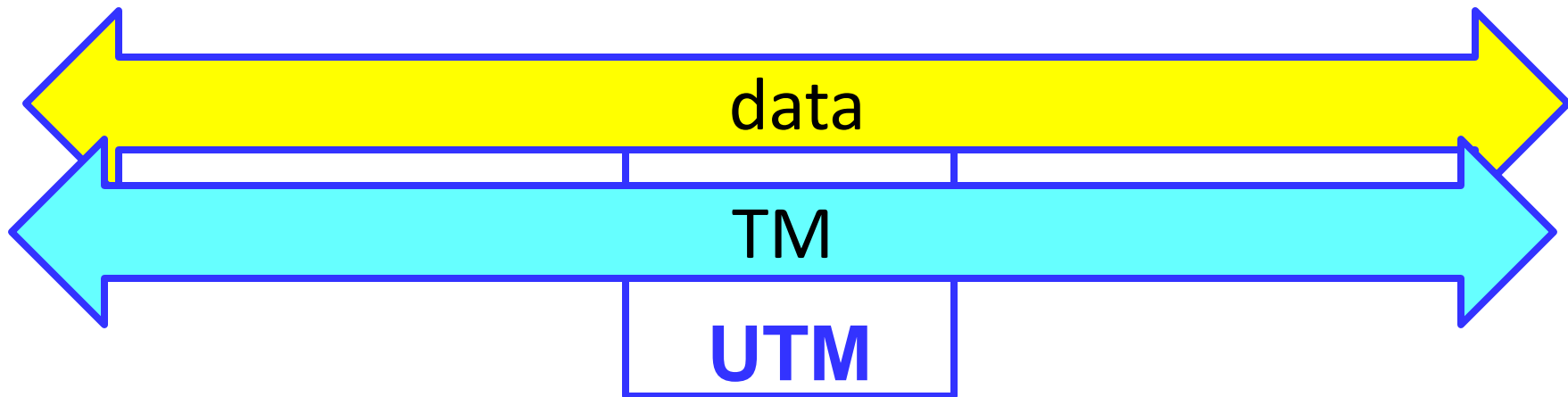
Proof: Suppose it does. Then define 2 more programs:

$$H'(TM, input) \triangleq \begin{cases} 1 & \text{if } H(TM, input) = 0 \\ \text{loop forever} & \text{otherwise} \end{cases}$$

$$H^*(TM) \triangleq H'(TM, TM)$$

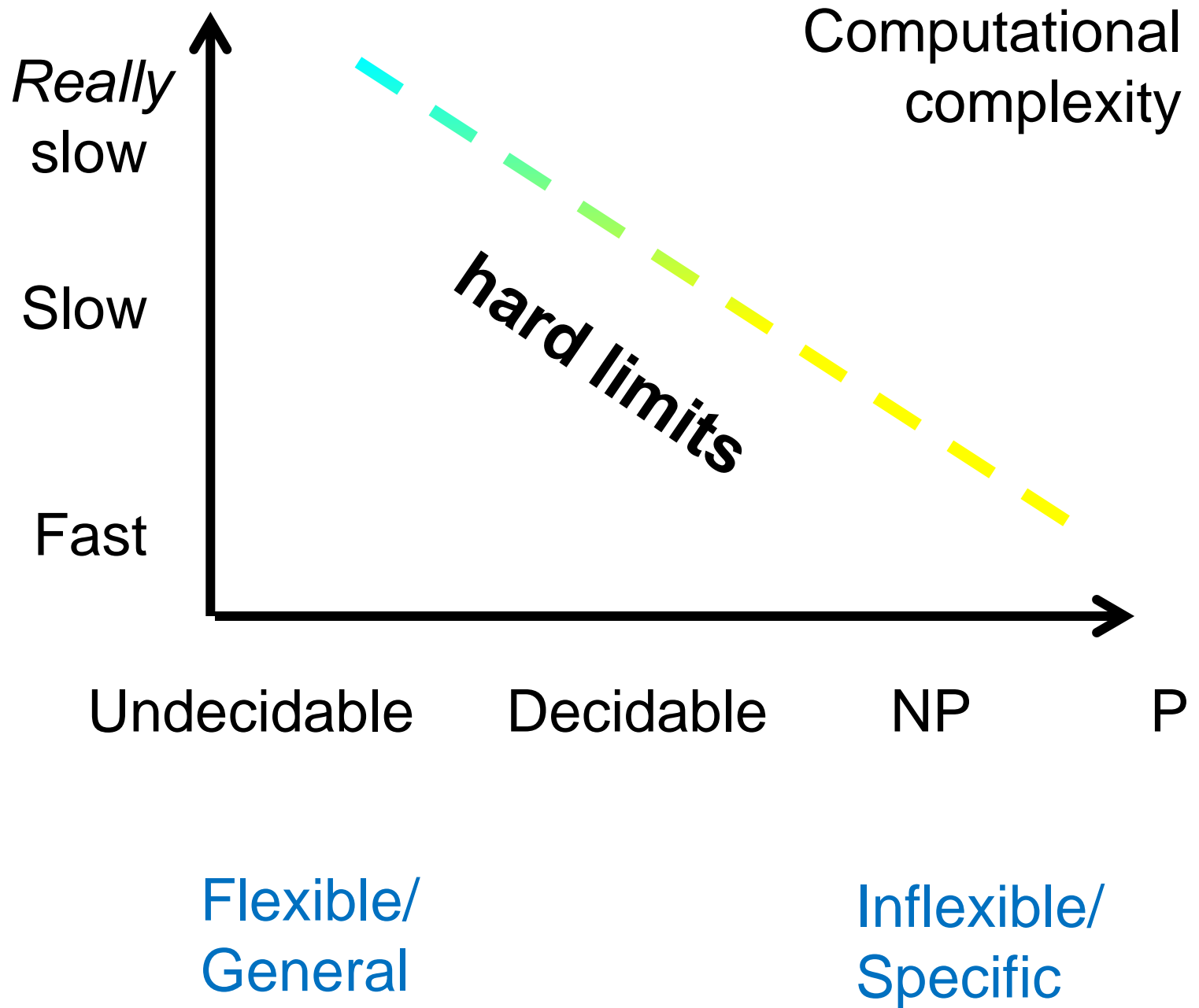
$$\begin{aligned} \text{Run } H^*(H^*) &= H'(H^*, H^*) \\ &= \begin{cases} \text{halt} & \text{if } H^*(H^*) \text{ loops forever} \\ \text{loop forever} & \text{otherwise} \end{cases} \end{aligned}$$

Contradiction!



Implications

- Large, thin, nonconvex everywhere...
- TMs and UTMs are perfectly repeatable
- But perfectly unpredictable
- Undecidable: Will a TM halt? Is a TM a UTM? Does a TM do X (for almost any X)?
- Easy to make UTMs, but hard to recognize them.
- Is anything decidable? Yes, questions NOT about TMs.

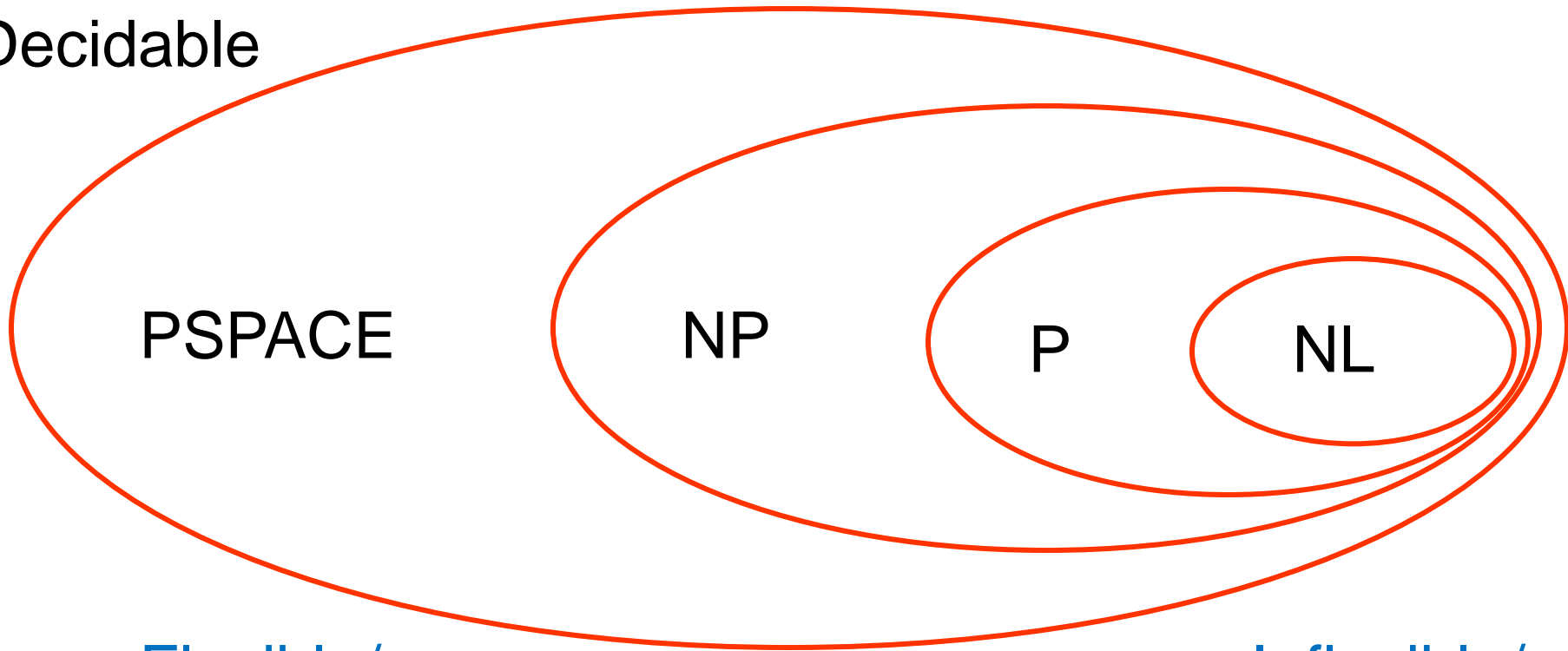


$PSPACE \subset NP \subset P \subset NL$
 $PSPACE \neq NL$

Computational complexity

Space is powerful and/or cheap.

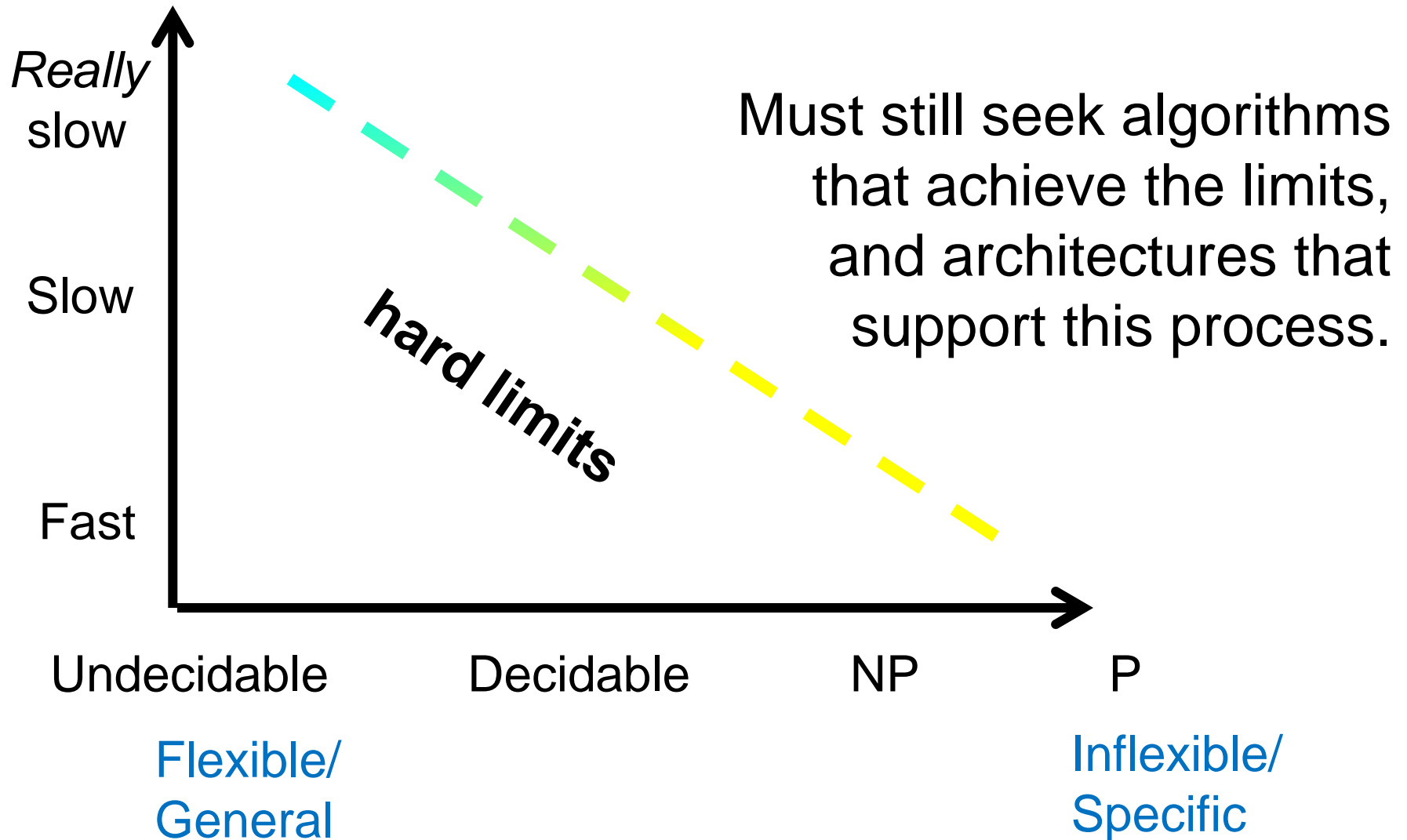
Decidable



Flexible/
General

Inflexible/
Specific

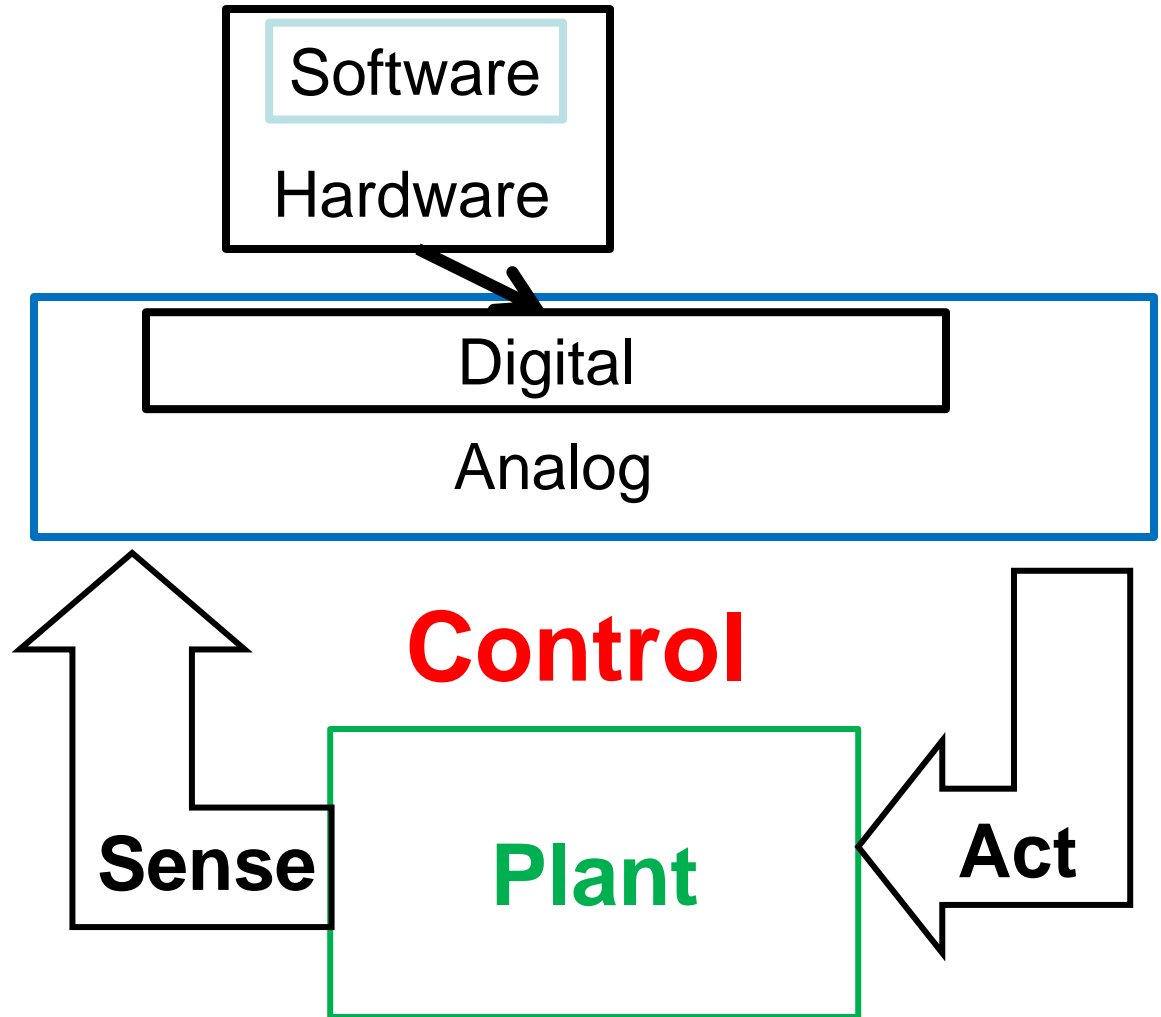
These are hard limits on the *intrinsic* computational complexity of *problems*.



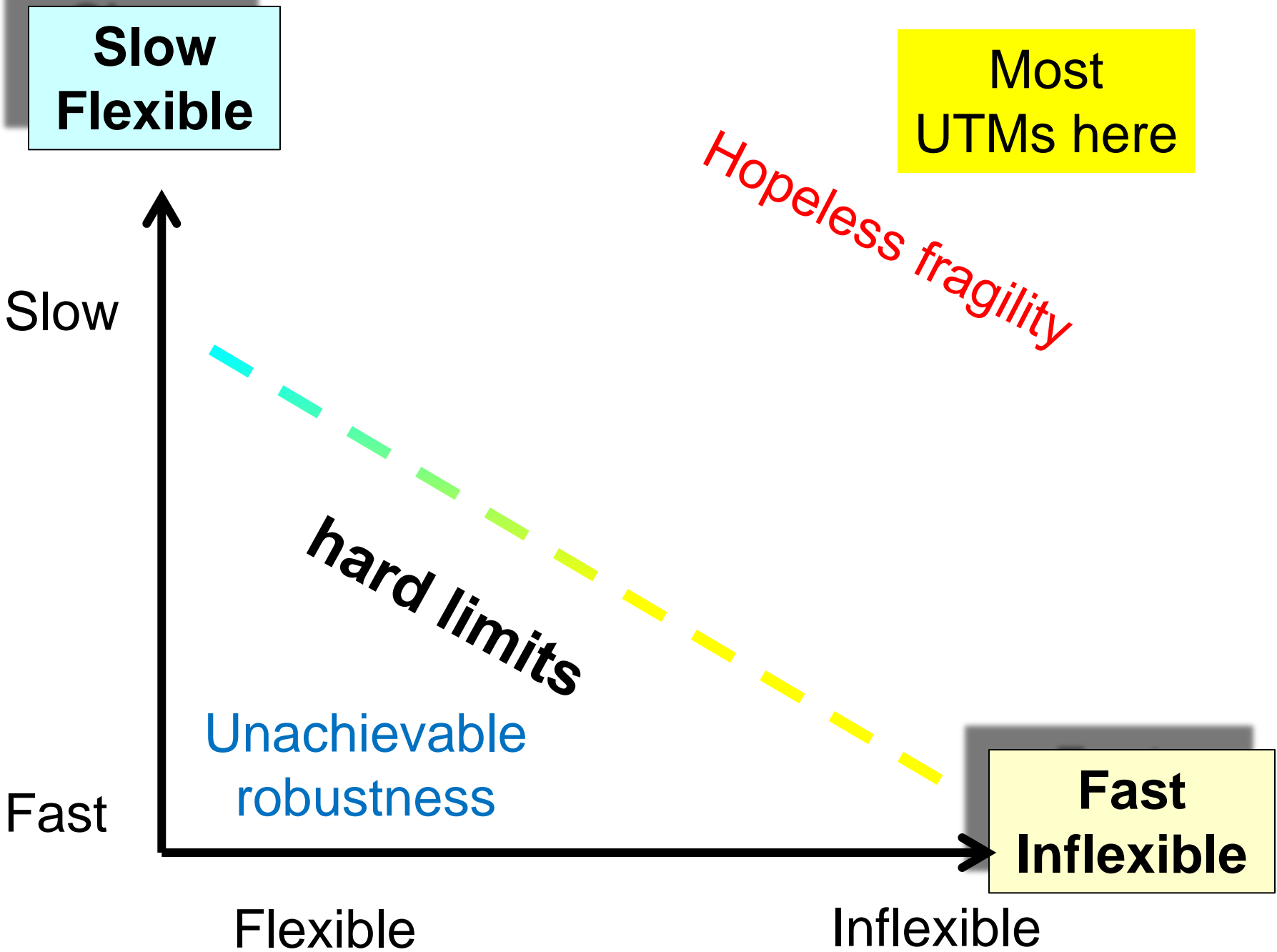
Compute

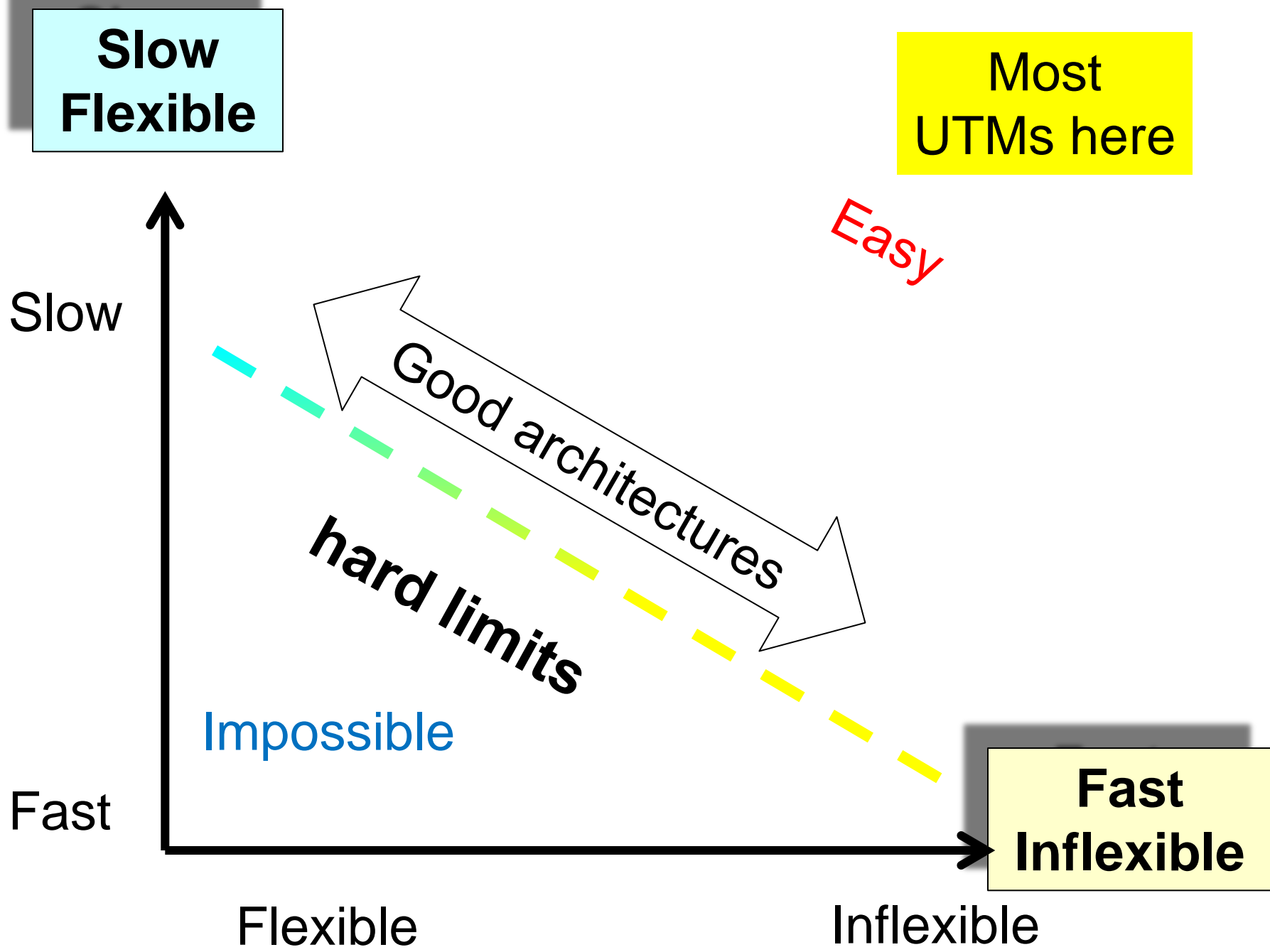
- Computational complexity of
- **Designing** control algorithms
 - **Implementing** control algorithms

**Delay is
even more
important
in control**



Control





Issues for engineering

- Turing remarkably relevant for 76 years
- UTMs are \approx implementable
 - Differ only (but greatly) in speed and programmability
 - Time/speed/delay is most critical resource
 - Space (memory) almost free for most purposes
- Read/write random access memory hierarchies
- Further gradations of decidable (P/NP/coNP)
- **Most crucial:**
 - UTMs differ vastly in speed, usability, and programmability
 - You can fix bugs but it is hard to automate finding/avoiding them

Issues for engineering

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 - You can fix bugs but it is hard to automate finding/avoiding them

Conjectures, biology

- Memory potential $\approx \infty$
- Examples
 - Insects
 - Scrub jays
 - Autistic Savants

Gallistel and King

C.R. Gallistel and
Adam Philip King



Memory and the
Computational Brain

Why Cognitive Science Will Transform Neuroscience

WILEY-BLACKWELL

- But why so rare and/or accidental?
- Large memory, computation of limited value?
- Selection favors fast robust **action**?
- Brains are distributed (not studied by Gallistel)

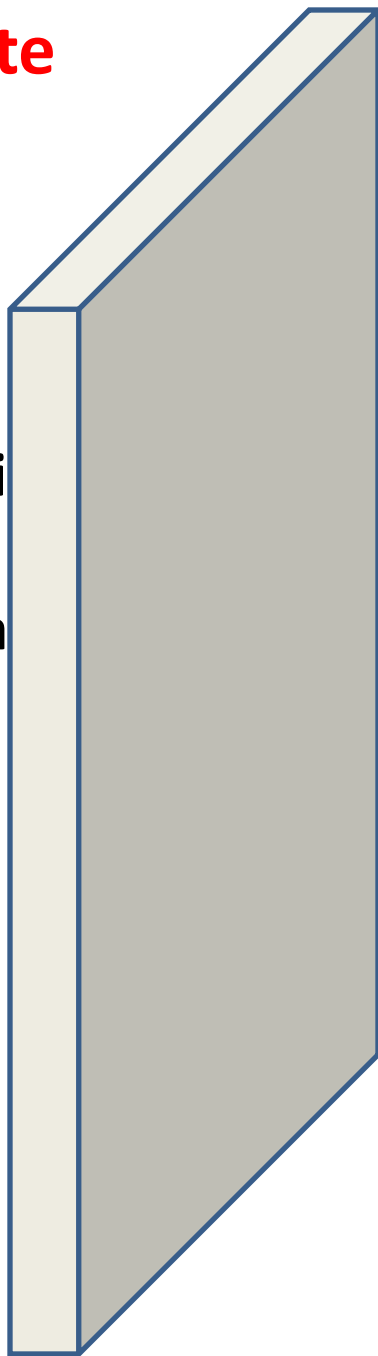
Compute

Turing

Delay is
most
important

Bode

Control,



Communicate

Shannon

Delay is
least
important

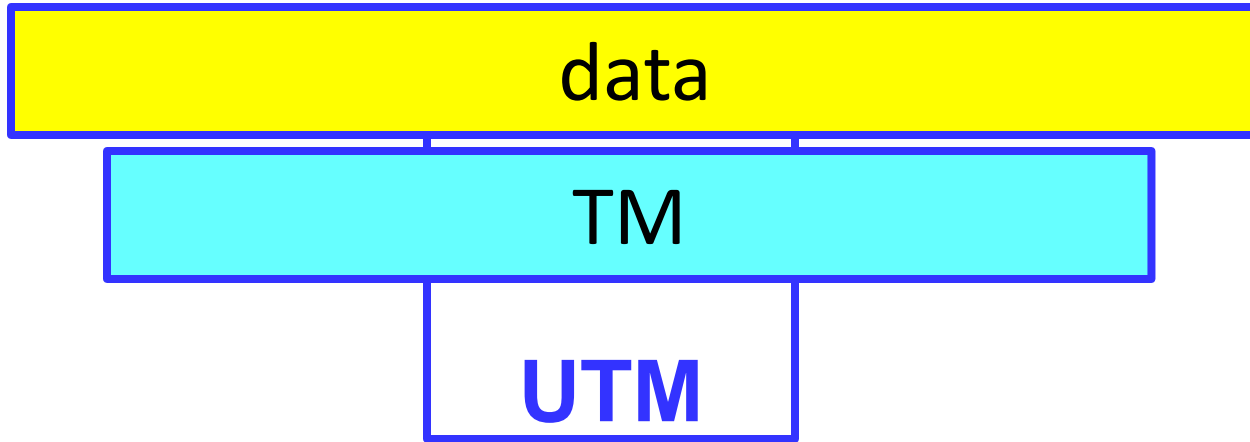
Carnot

Boltzmann

Heisenberg

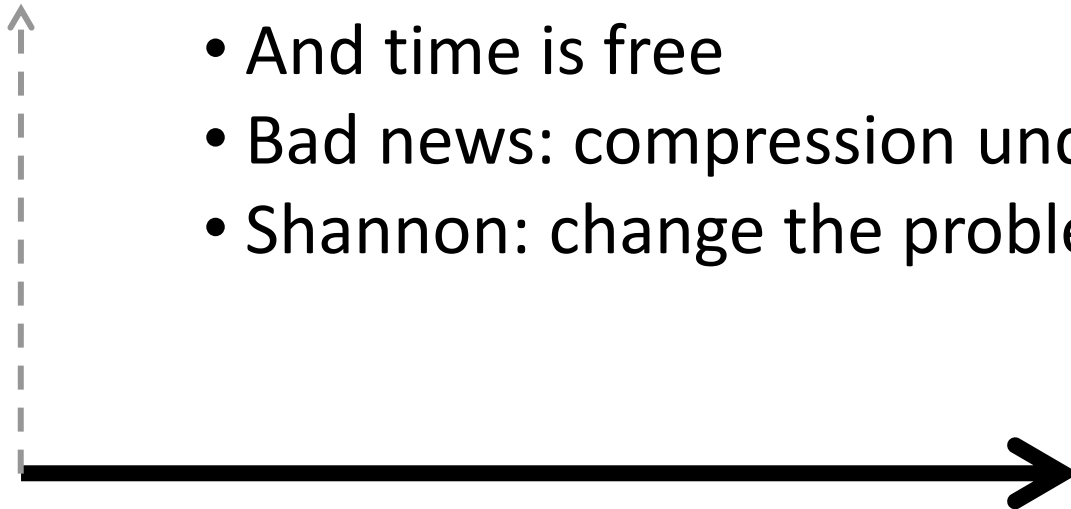
Physics

Einstein



- Suppose we only care about space?
- And time is free
- Bad news: compression undecidable.
- Shannon: change the problem!

time



space

Communications

Shannon

Shannon's brilliant insight

- Forget time
- Forget files, use *infinite random ensembles*

Good news

- Laws and architecture!
- Info theory most popular and accessible topic in systems engineering
- *Fantastic* for some engineering problems

Communications

Shannon

Shannon's brilliant insight

- Forget time
- Forget files, use *infinite random ensembles*

Bad news

- Laws and architecture very brittle

- Less than zero impact on internet architecture
- Almost useless for biology (But see Lestas et al, 2010)
- Mised, distracted generations of biologists (and neuroscientists)

Compute

Communicate

Turing

Lowering the barrier

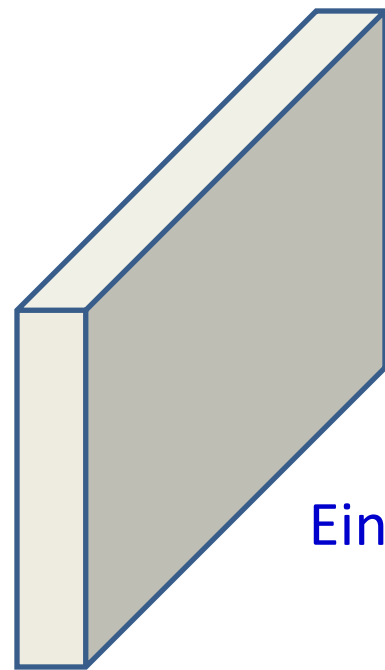
Shannon

**Delay is
most
important**

New progress!



**Delay is
~~least~~
important**



Bode

Carnot

Boltzmann

Control, OR

Heisenberg

Einstein

Physics

System

Architecture
=Constraints

“Emergent”:
“Nontrivial”
consequences
of other
constraints

data

TM

UTM

Protocols

Components

Systems requirements:
Algorithm to solve problem

(Un)decidable

data

TM

UTM

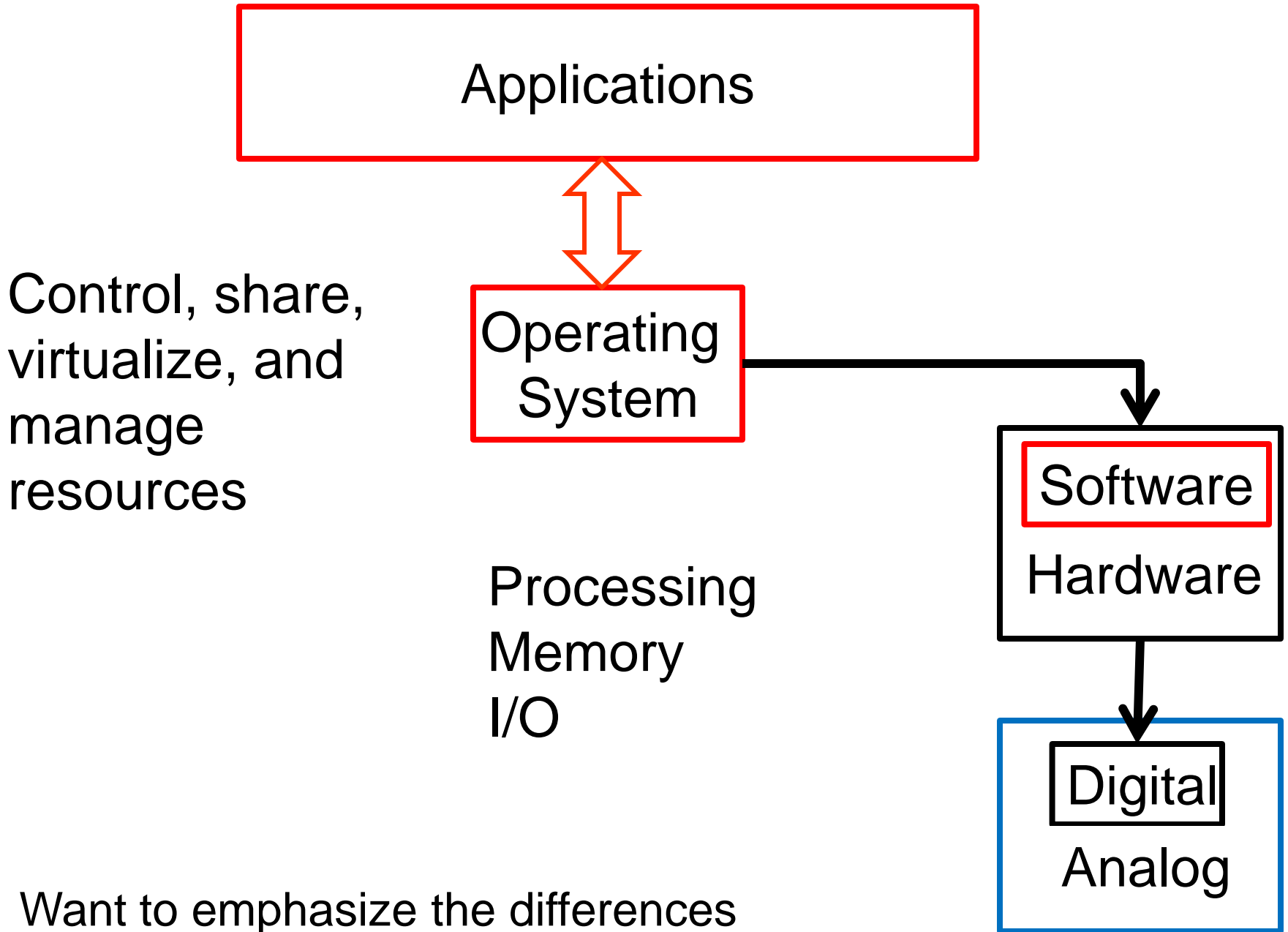
UTM

Constraints

Components and materials:
Automata + ∞ memory

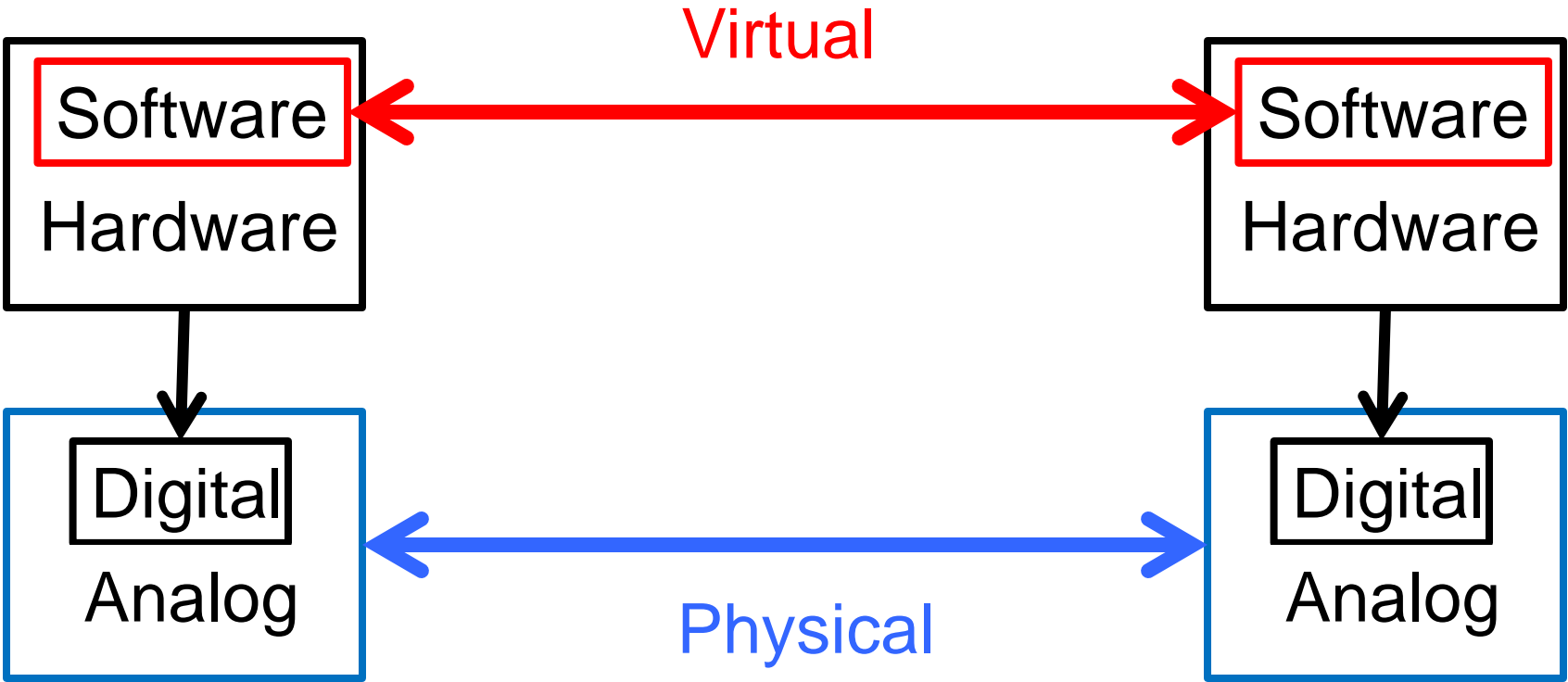
Universal architectures

What can go wrong?

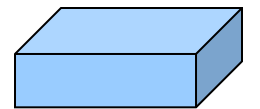
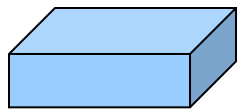
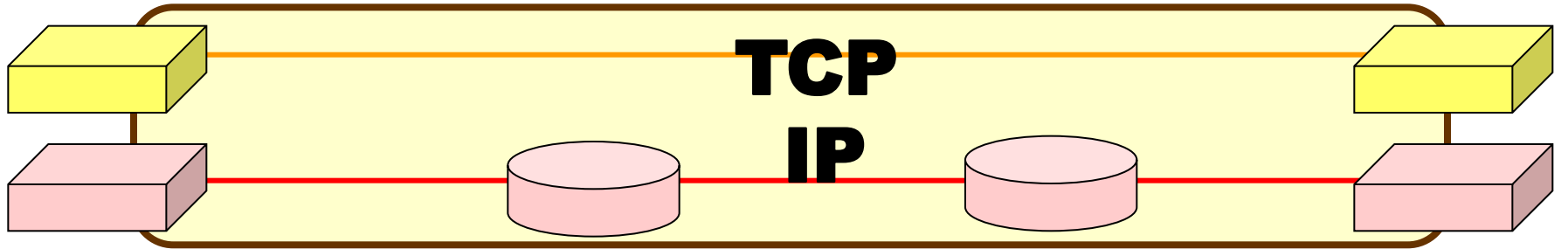
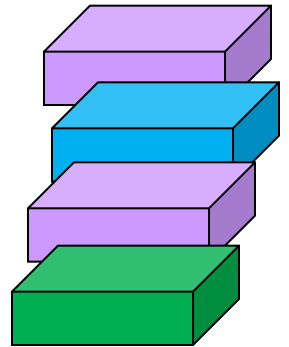
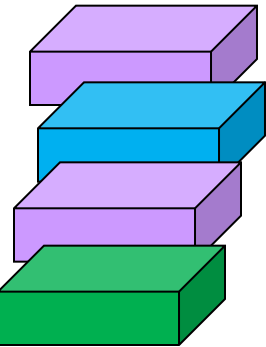


Want to emphasize the differences between these two types of layering.

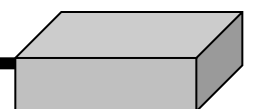
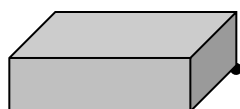
Networking



Diverse applications (HMT)



Diverse



Physical



IPC



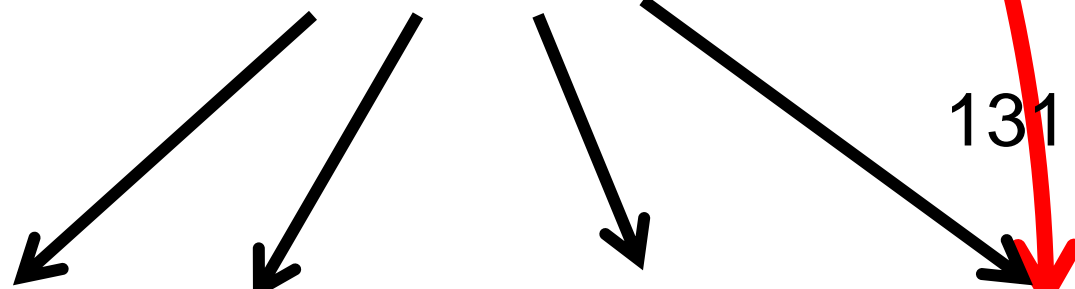
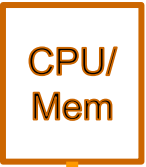
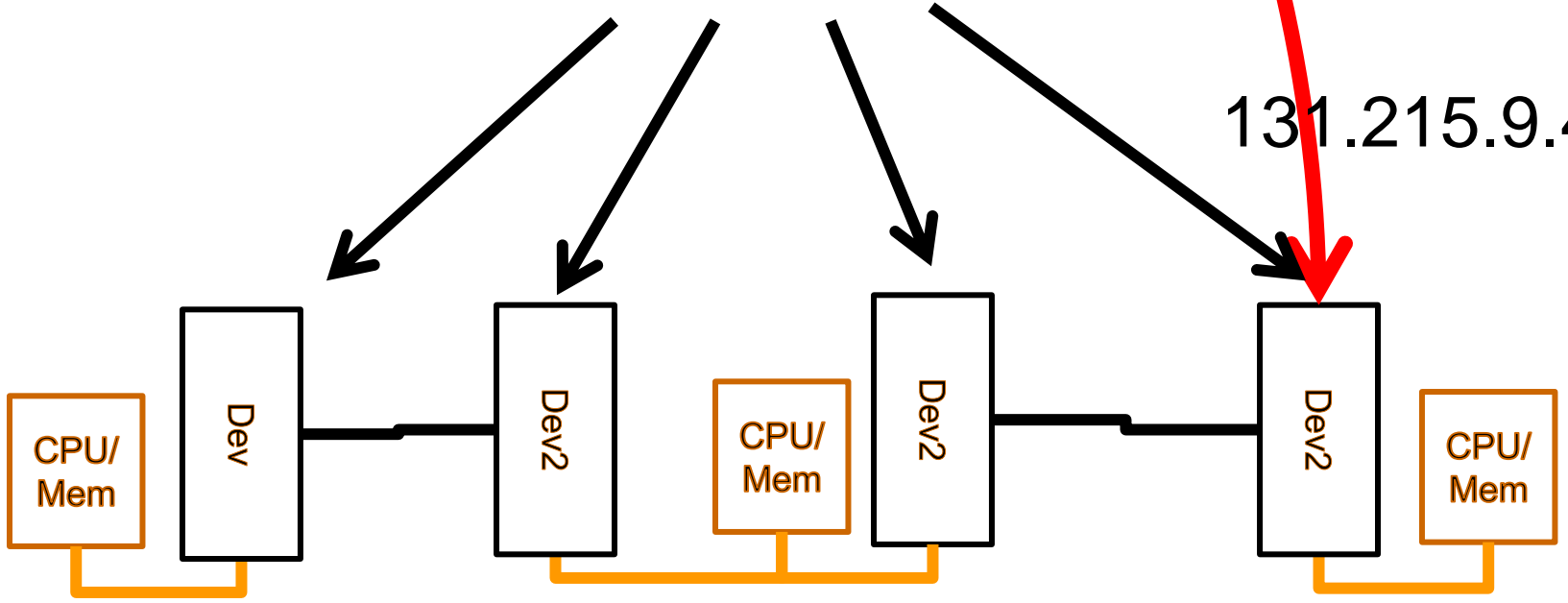
caltech.edu?

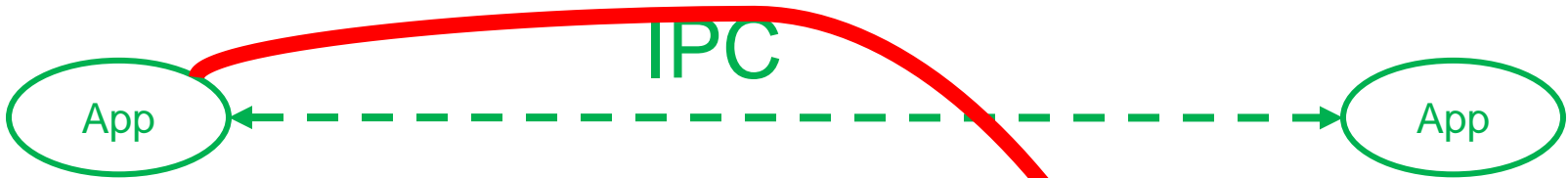
DNS

Global and direct access to physical address!

IP addresses interfaces (not nodes)

131.215.9.49





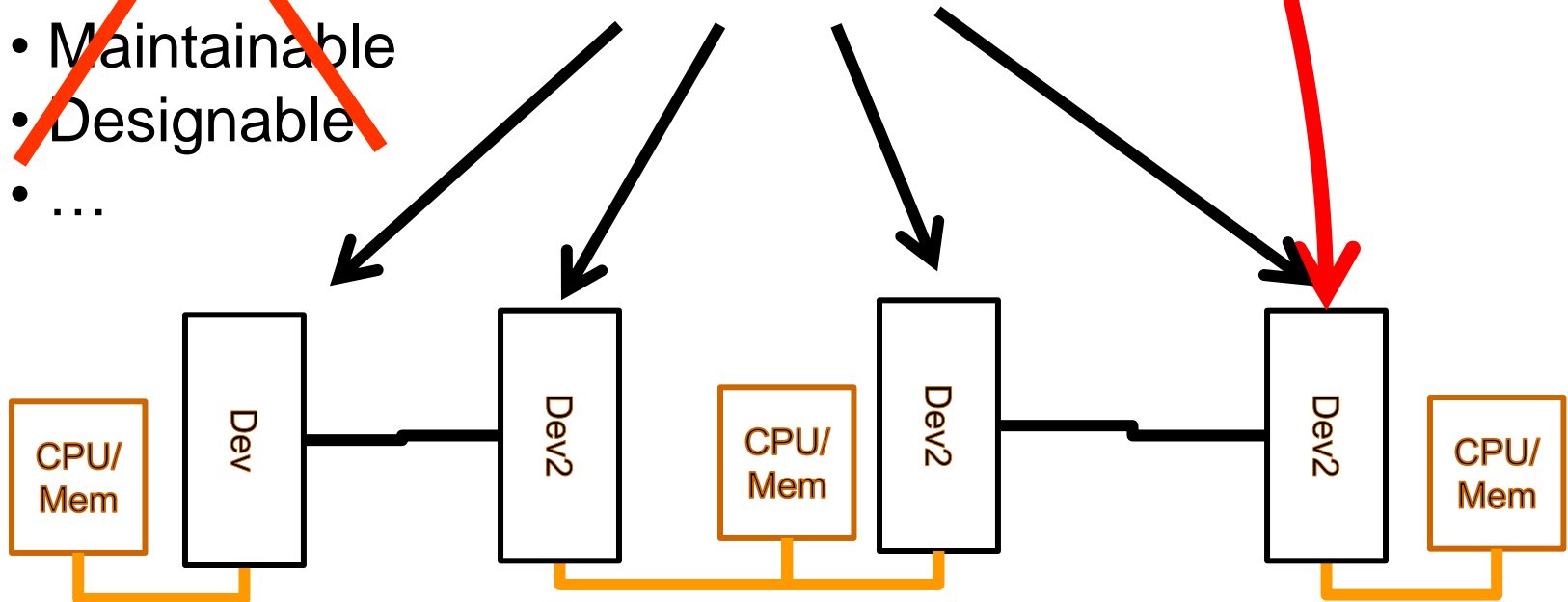
DNS

Global
and direct
access to
physical
address!

~~Robust?~~

- ~~• Secure~~
- ~~• Scalable~~
- ~~• Verifiable~~
- ~~• Evolvable~~
- ~~• Maintainable~~
- ~~• Designable~~
- ~~• ...~~

**IP addresses
interfaces
(not nodes)**

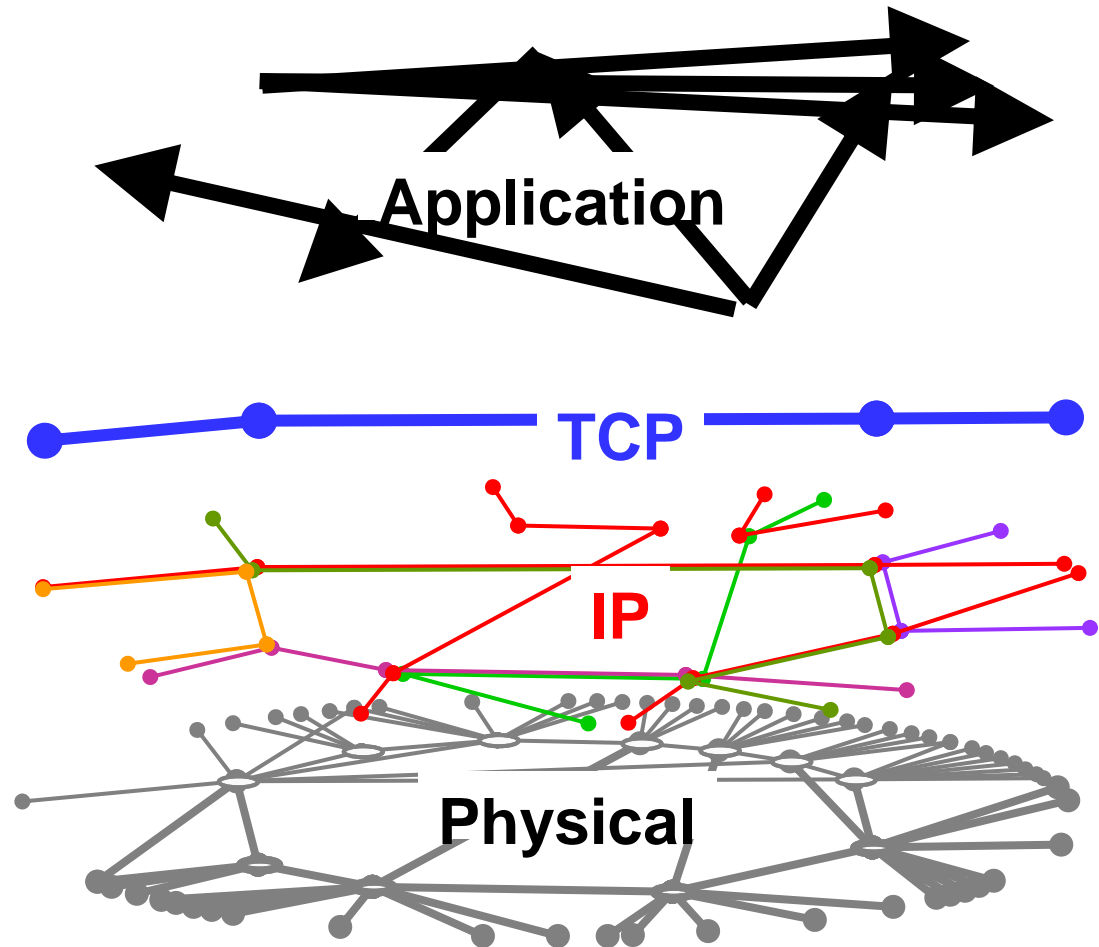


Naming and addressing need to have **scope** and

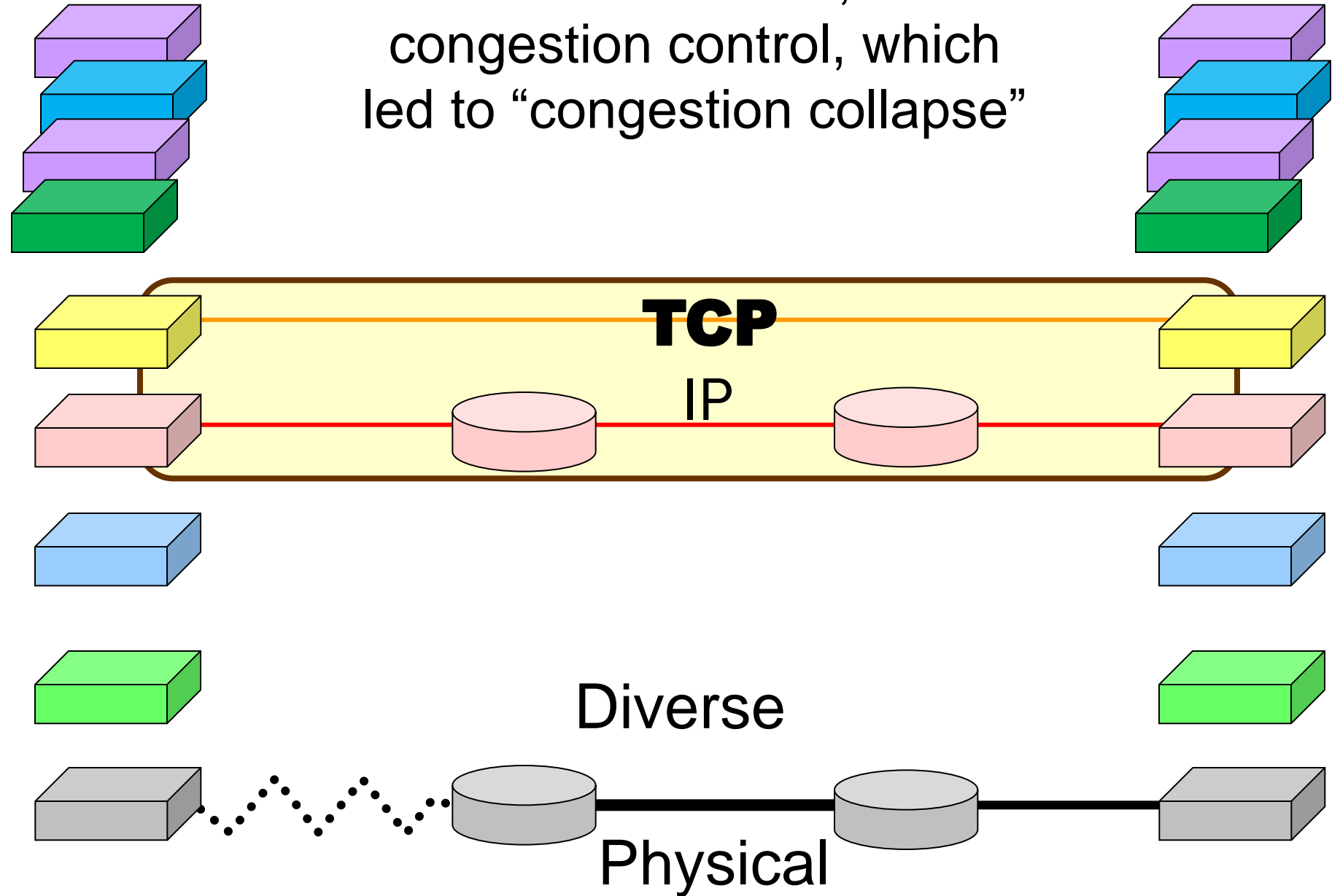
- resolved within layer
- translated between layers
- not exposed outside of layer

Related “issues”

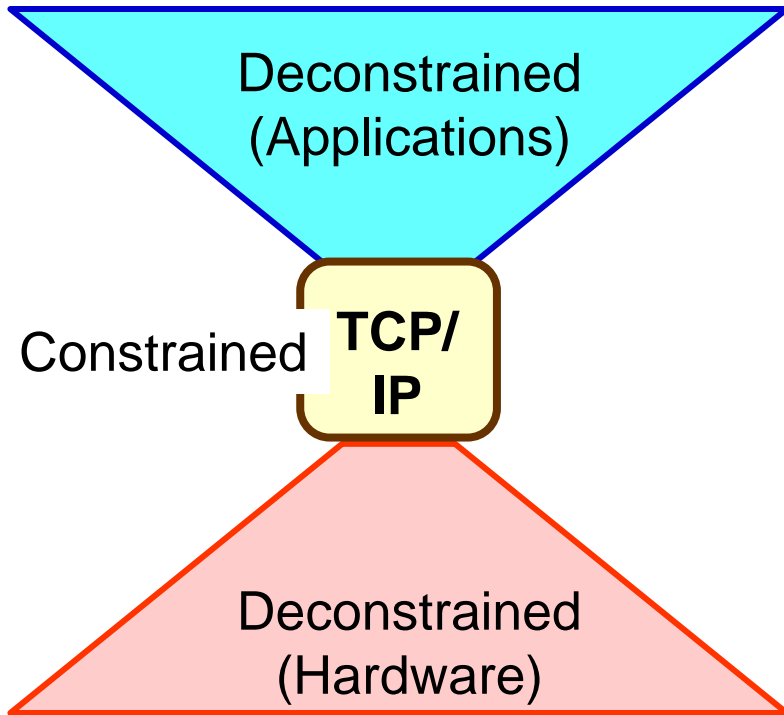
- VPNs
- NATS
- Firewalls
- Multihoming
- Mobility
- Routing table size
- Overlays
- ...



Until late 1980s, no congestion control, which led to “congestion collapse”



Original design challenge?



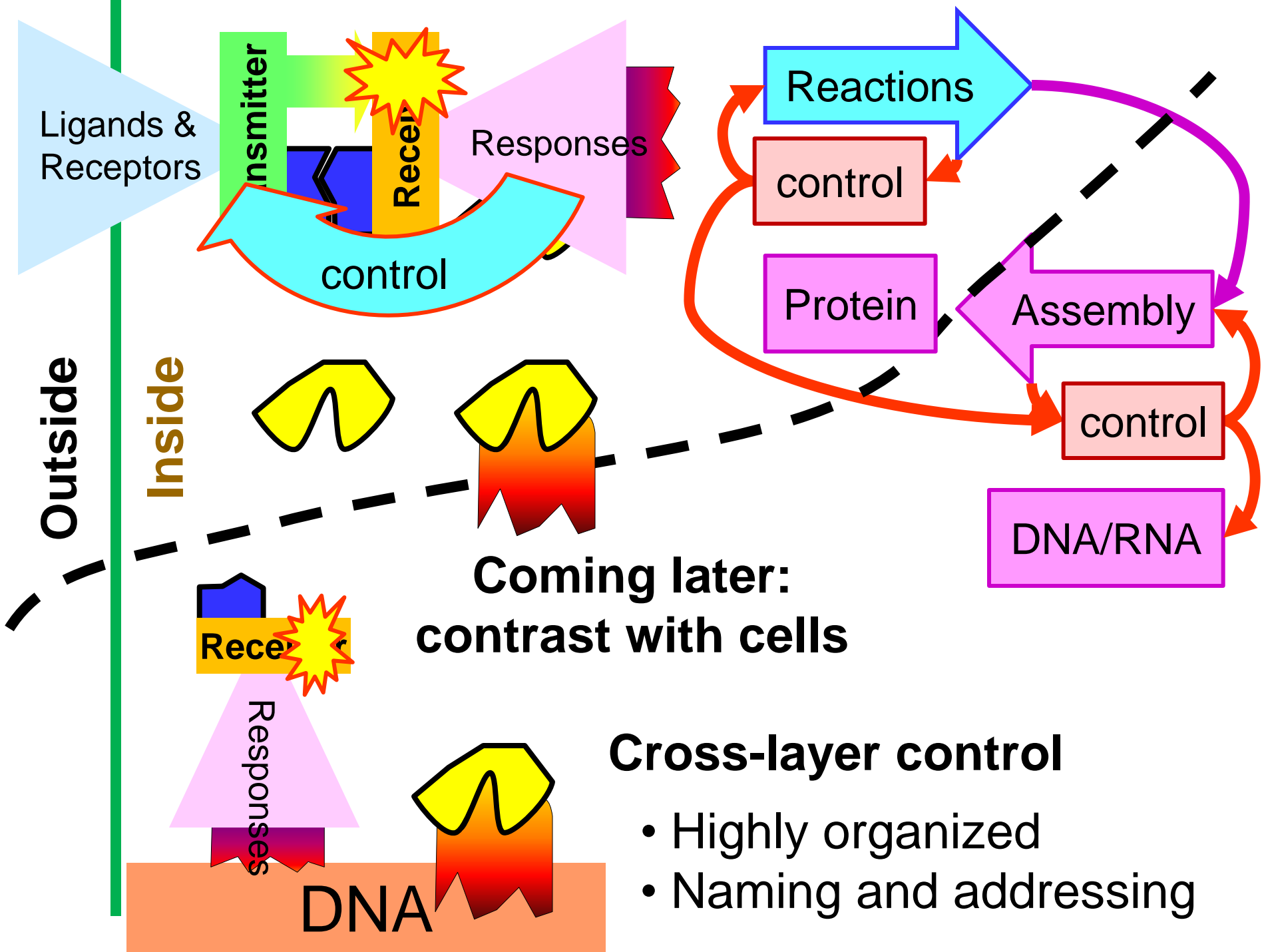
Networked OS

- Expensive mainframes
- Trusted end systems
- Homogeneous
- Sender centric
- Unreliable comms

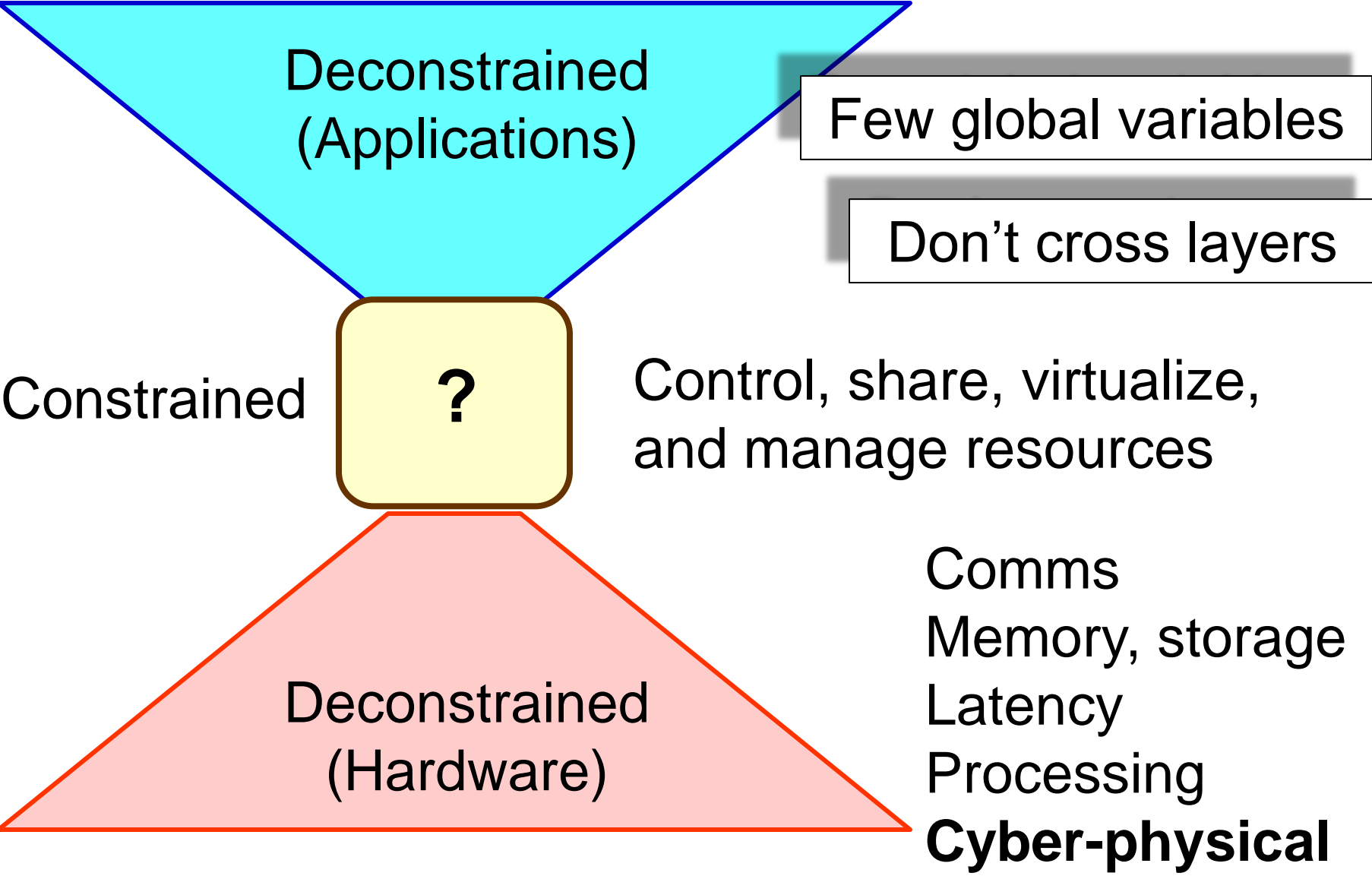
Facilitated wild evolution

Created

- whole new ecosystem
- completely opposite



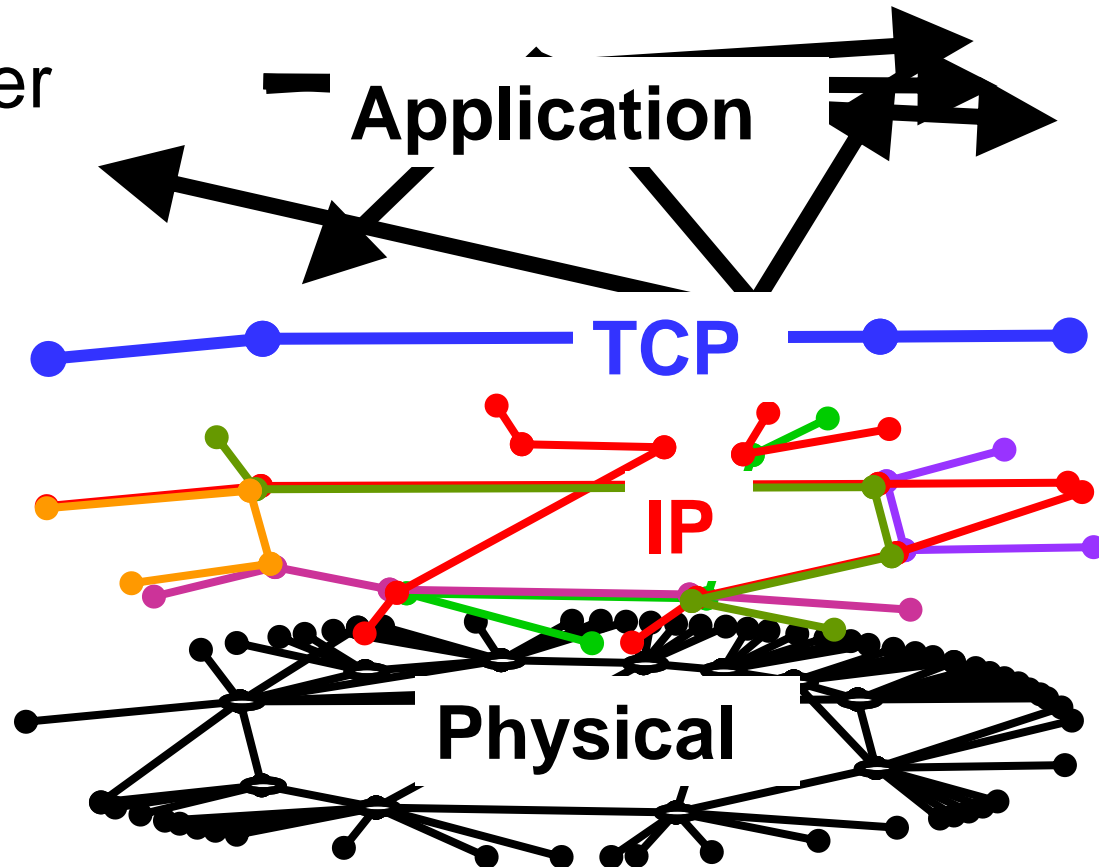
Next layered architectures



**Persistent errors
and confusion
("network science")**

Architecture is *least*
graph topology.

Every layer
has
different
diverse
graphs.



Architecture
facilitates
arbitrary
graphs.

The “robust yet fragile” nature of the Internet

John C. Doyle^{*†}, David L. Alderson^{*}, Lun Li^{*}, Steven Low^{*}, Matthew Roughan[‡], Stanislav Shalunov[§], Reiko Tanaka[¶], and Walter Willinger^{||}

^{*}Engineering and Applied Sciences Division, California Institute of Technology, Pasadena, CA 91125; [‡]Applied Mathematics, University of Adelaide, South Australia 5005, Australia; [§]Internet2, 3025 Boardwalk Drive, Suite 200, Ann Arbor, MI 48108; [¶]Bio-Mimetic Control Research Center, Institute of Physical and Chemical Research, Nagoya 463-0003, Japan; and ^{||}AT&T Labs–Research, Florham Park, NJ 07932

Edited by Robert M. May, University of Oxford, Oxford, United Kingdom, and approved August 29, 2005 (received for review February 18, 2005)

The search for unifying properties of complex networks is popular, challenging, and important. For modeling approaches that focus on

no self-loops or parallel edges) having the same graph degree. We will say that graphs $g \in G(D)$ have scaling-degree sequen-

Notices of the AMS, 2009

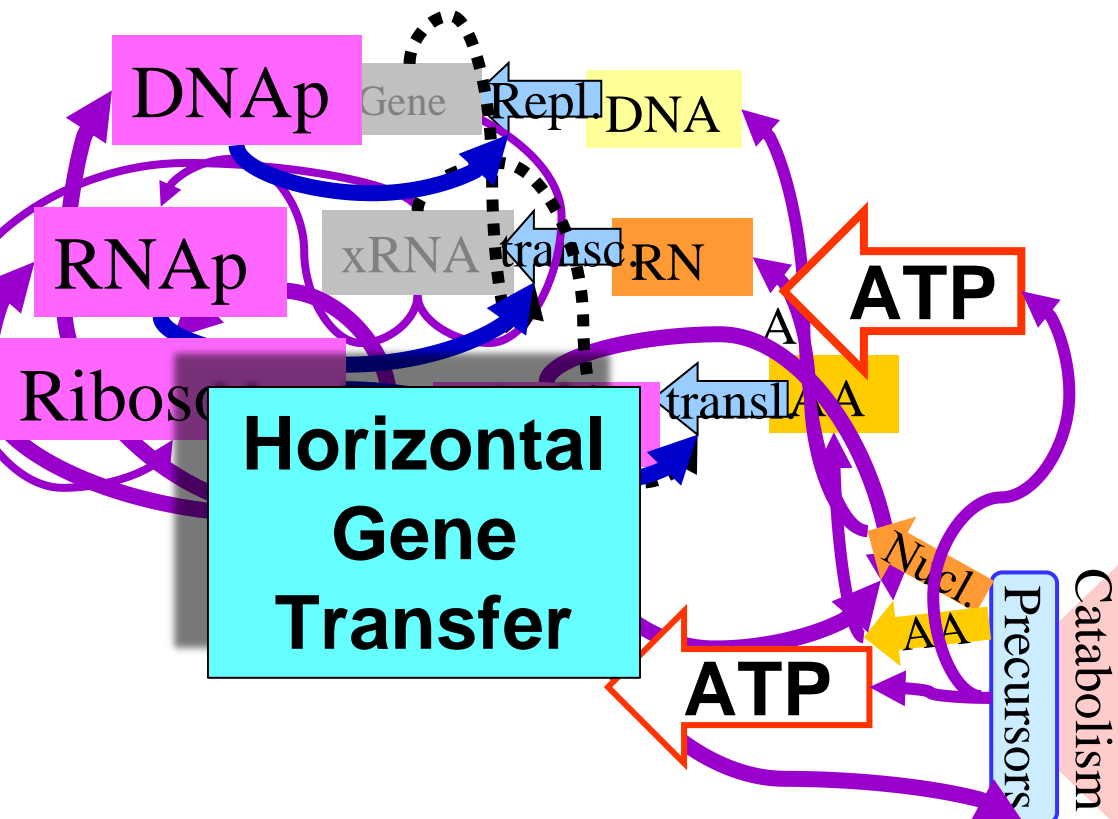
Mathematics and the
Internet: A Source of
Enormous Confusion
and Great Potential

Walter Willinger, David Alderson, and John C. Doyle

Who and what

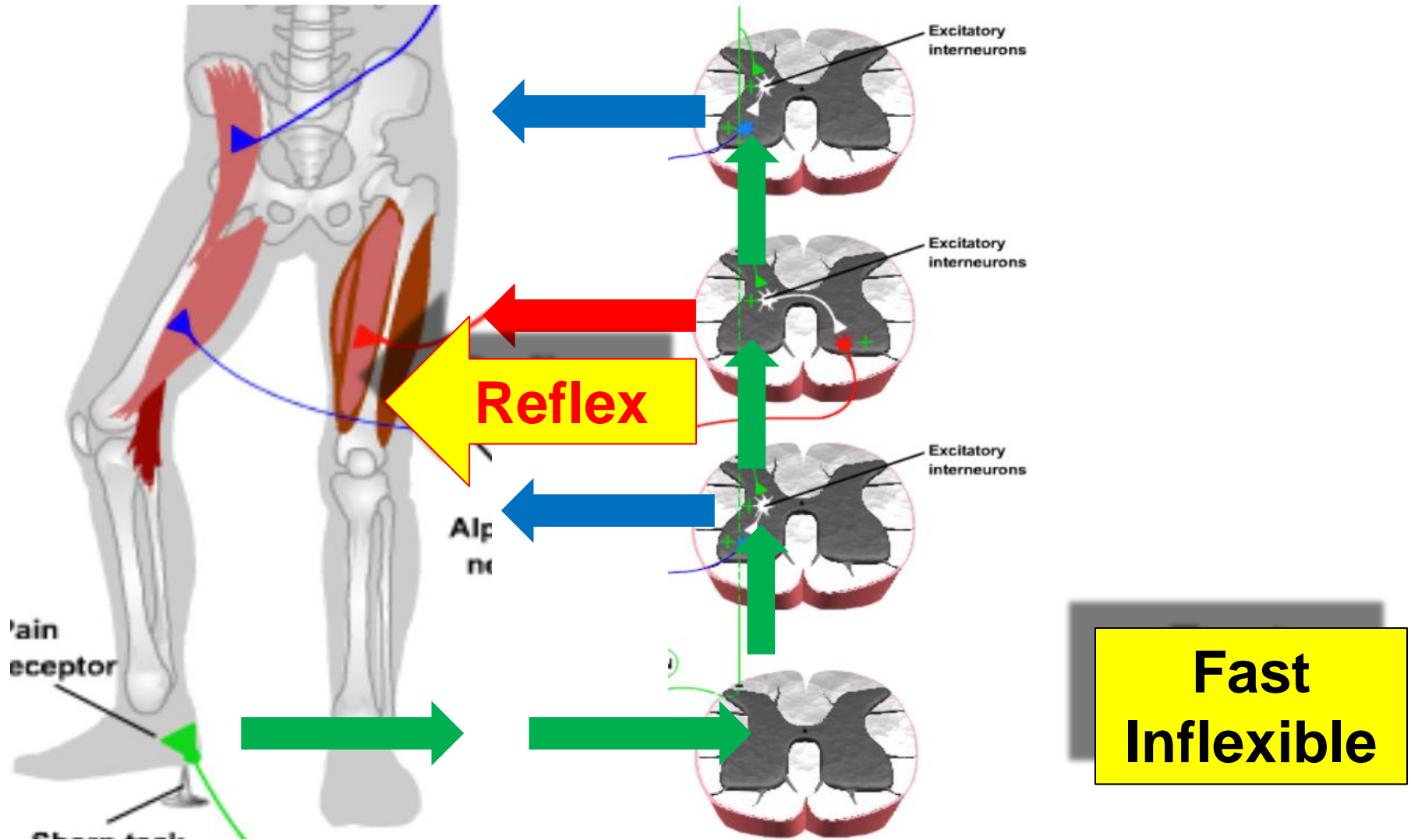
Sequence ~100 E Coli (*not* chosen randomly)

- ~ 4K genes per cell
- ~20K *different* genes in total
- ~ 1K universally shared genes
- ~ 300 essential (minimal) genes



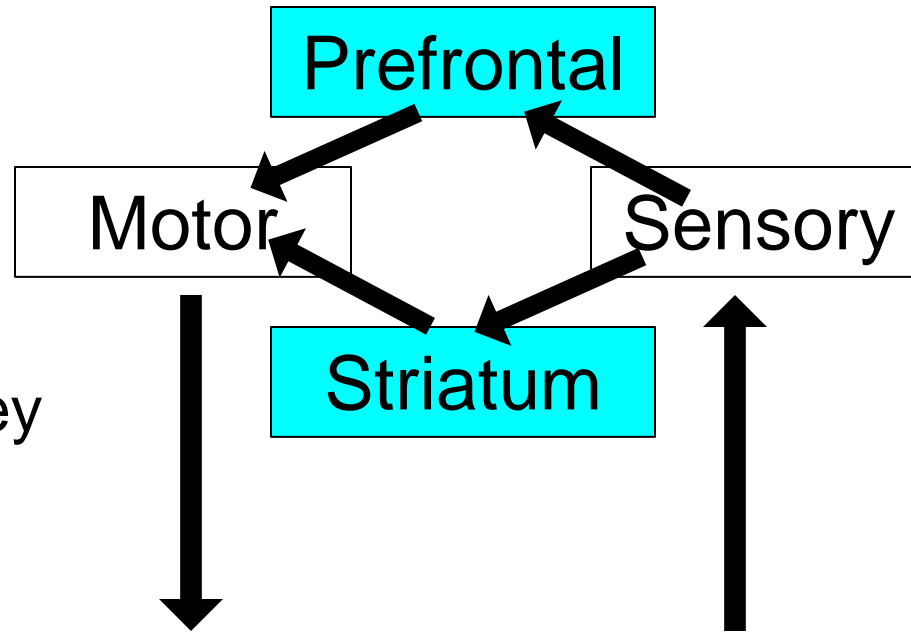
See slides on
bacterial
biosphere

Neuro motivation



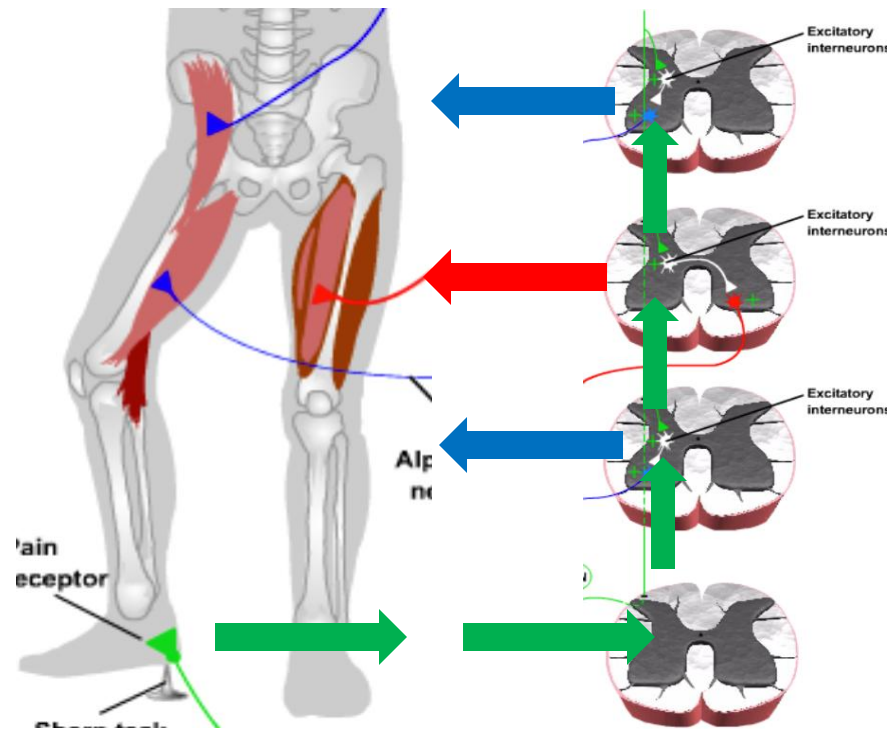
Learning

**Slow
Flexible**



Ashby & Crossley

- **Acquire**
- **Translate/
integrate**
- **Automate**



Thanks to
Bassett & Grafton

**Slow
Flexible**

Prefrontal

Motor ← Sensory

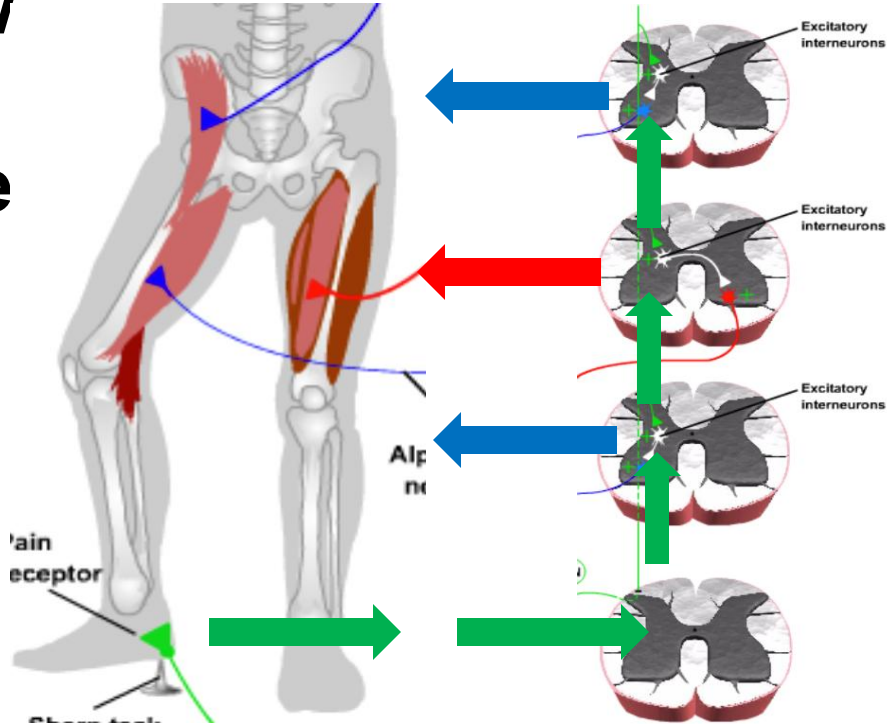
Striatum

Learning

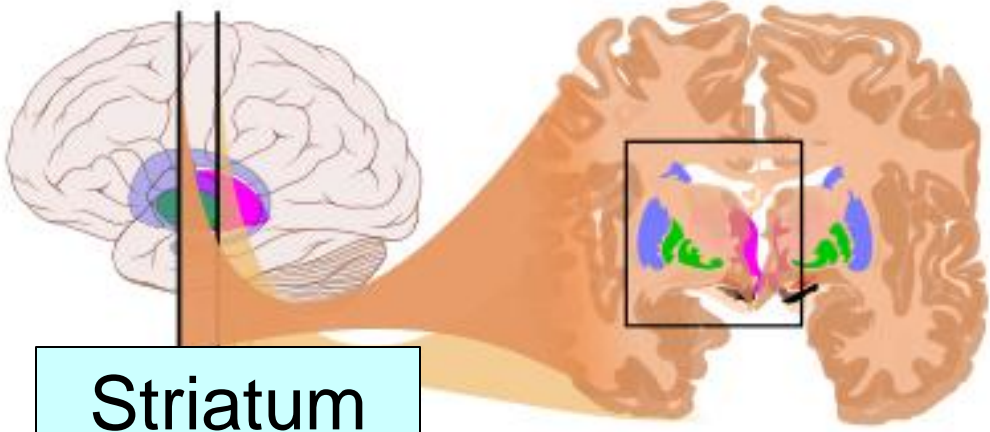
**Fast
Inflexible**

Ashby & Crossley

- Acquire
- **Translate/
integrate**
- **Automate**



**Slow
Flexible**



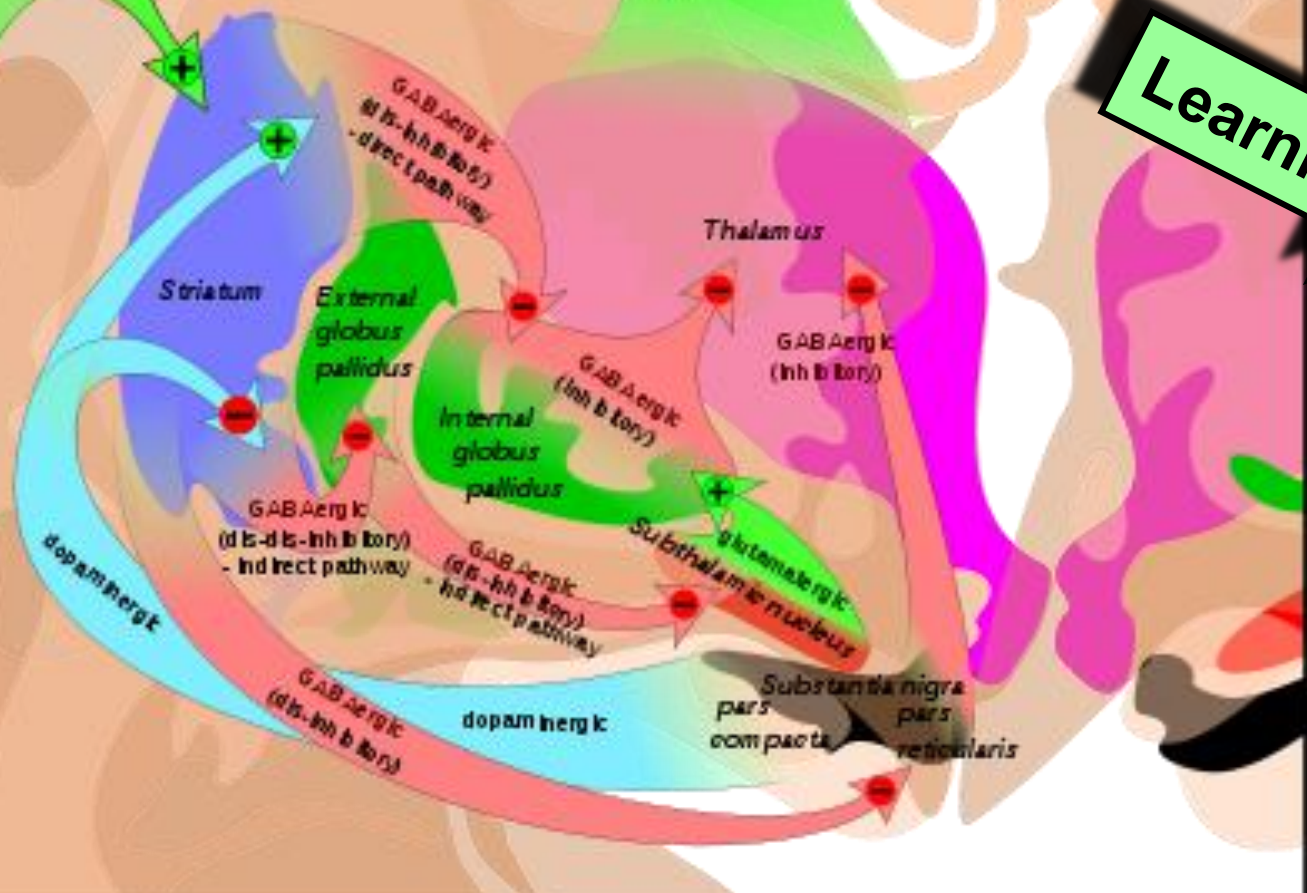
Striatum

from cortex
glutamatergic
(excitatory)

back to cortex
glutamatergic
(excitatory)

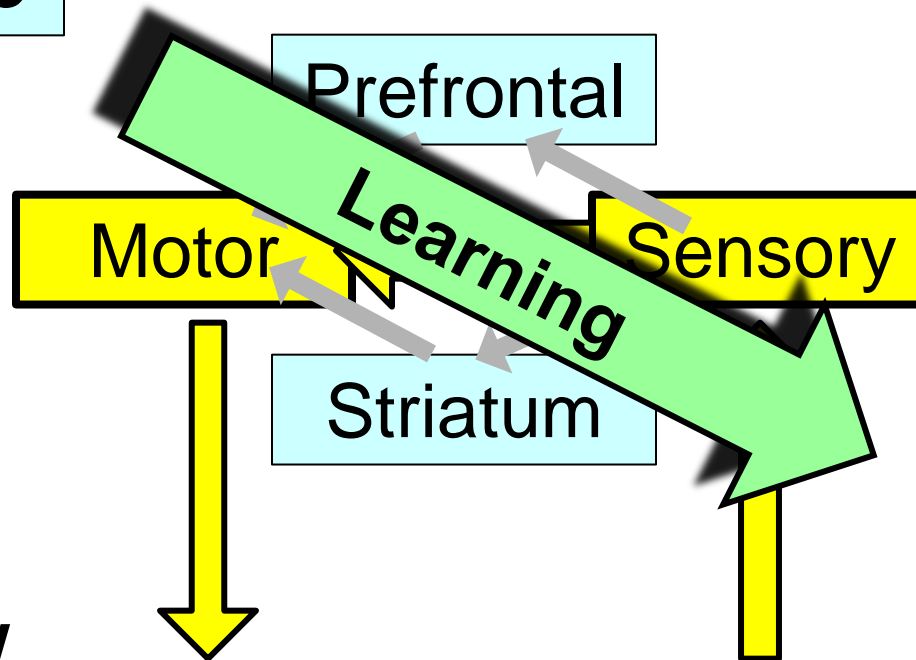


**Fast
Inflexible**



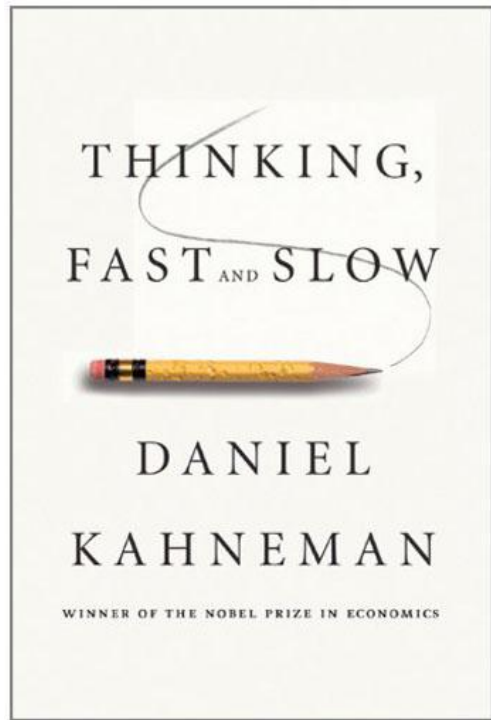
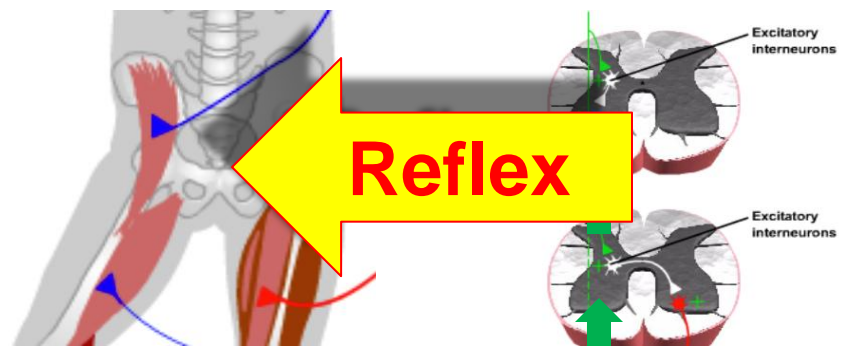
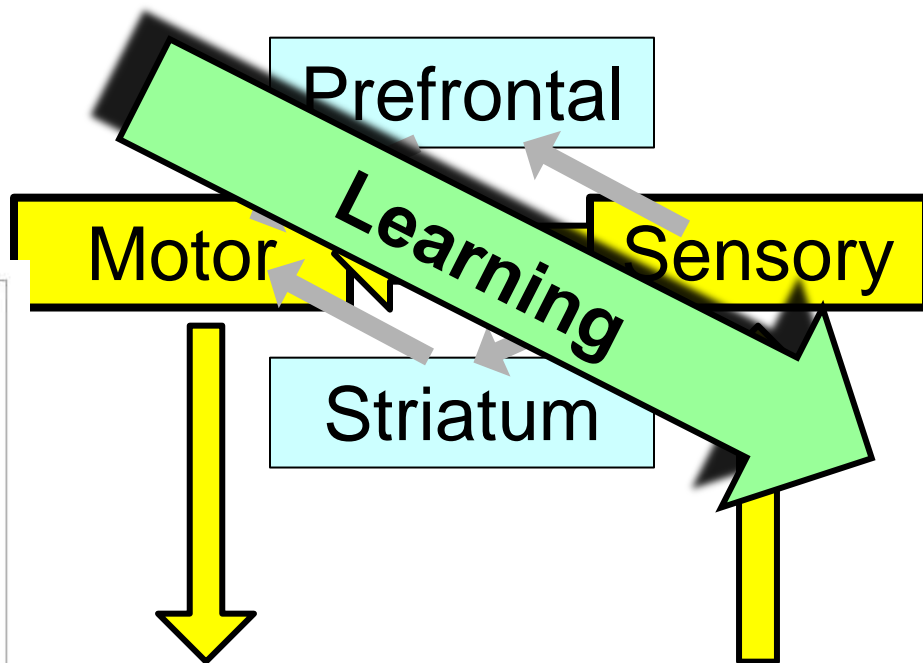
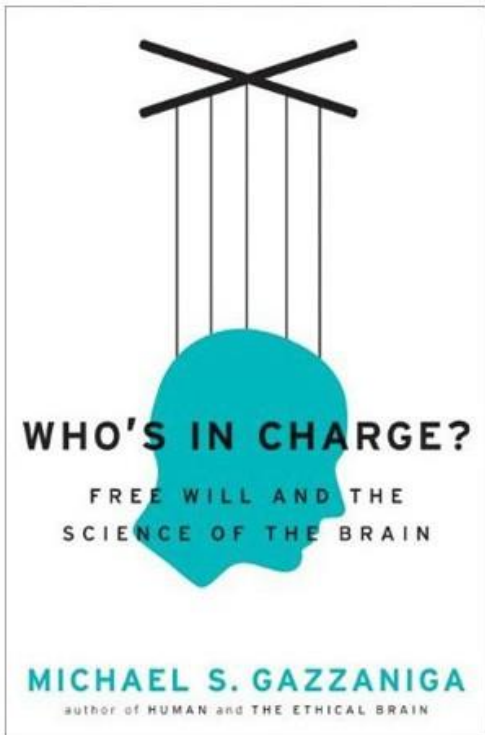
Build on Turing to show what is *necessary* to make this work.

**Slow
Flexible**

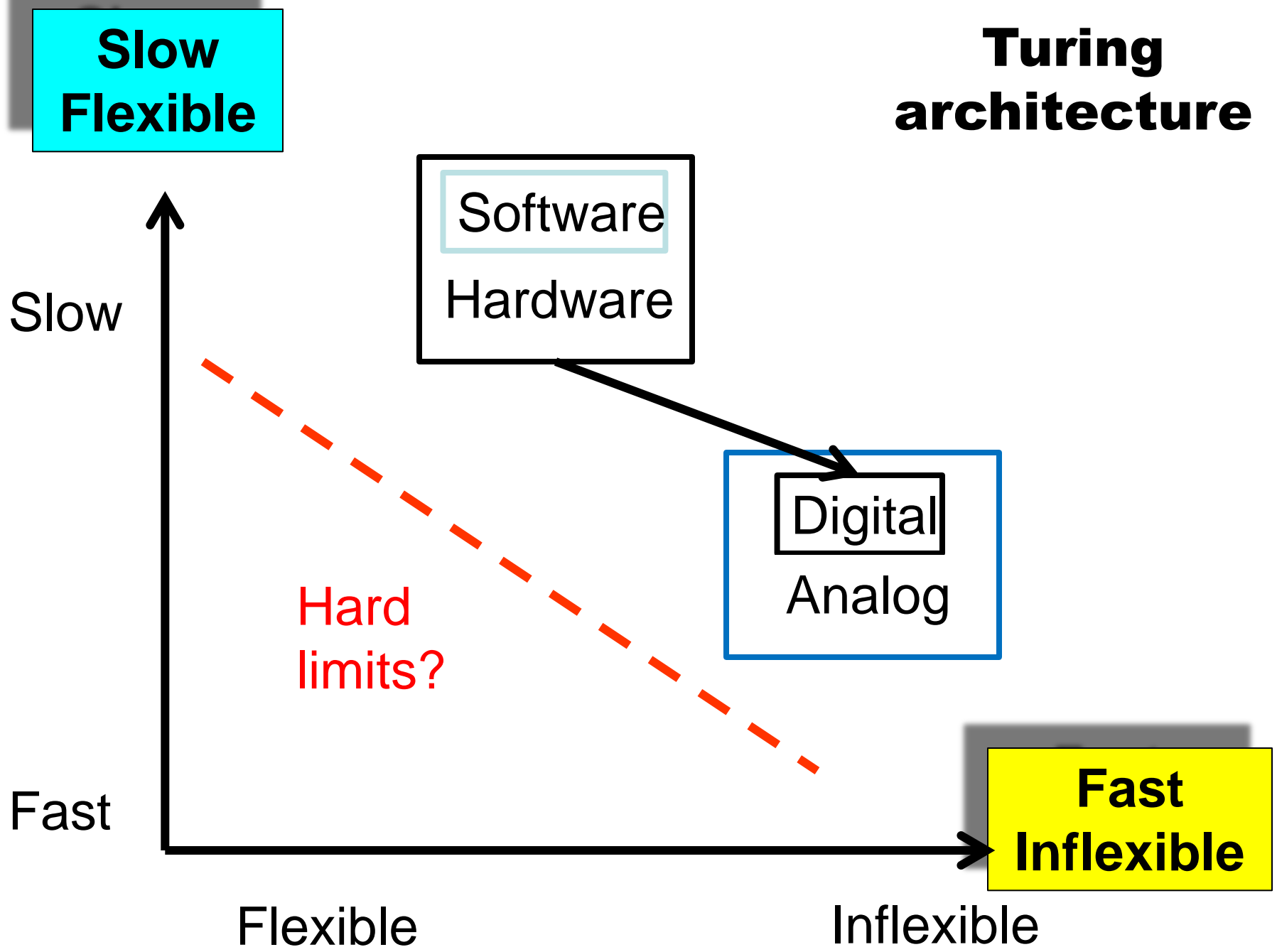


**Fast
Inflexible**

- Acquire
- Translate/
integrate
- Automate



Turing architecture



Slow Flexible

Slow

Fast

Flexible

Inflexible

Software
Hardware

Digital
Analog

Hard
limits?

Fast Inflexible

Flexible

General purpose
Large uncertainties
Diverse problems

Solve problems
Make decisions
Take actions

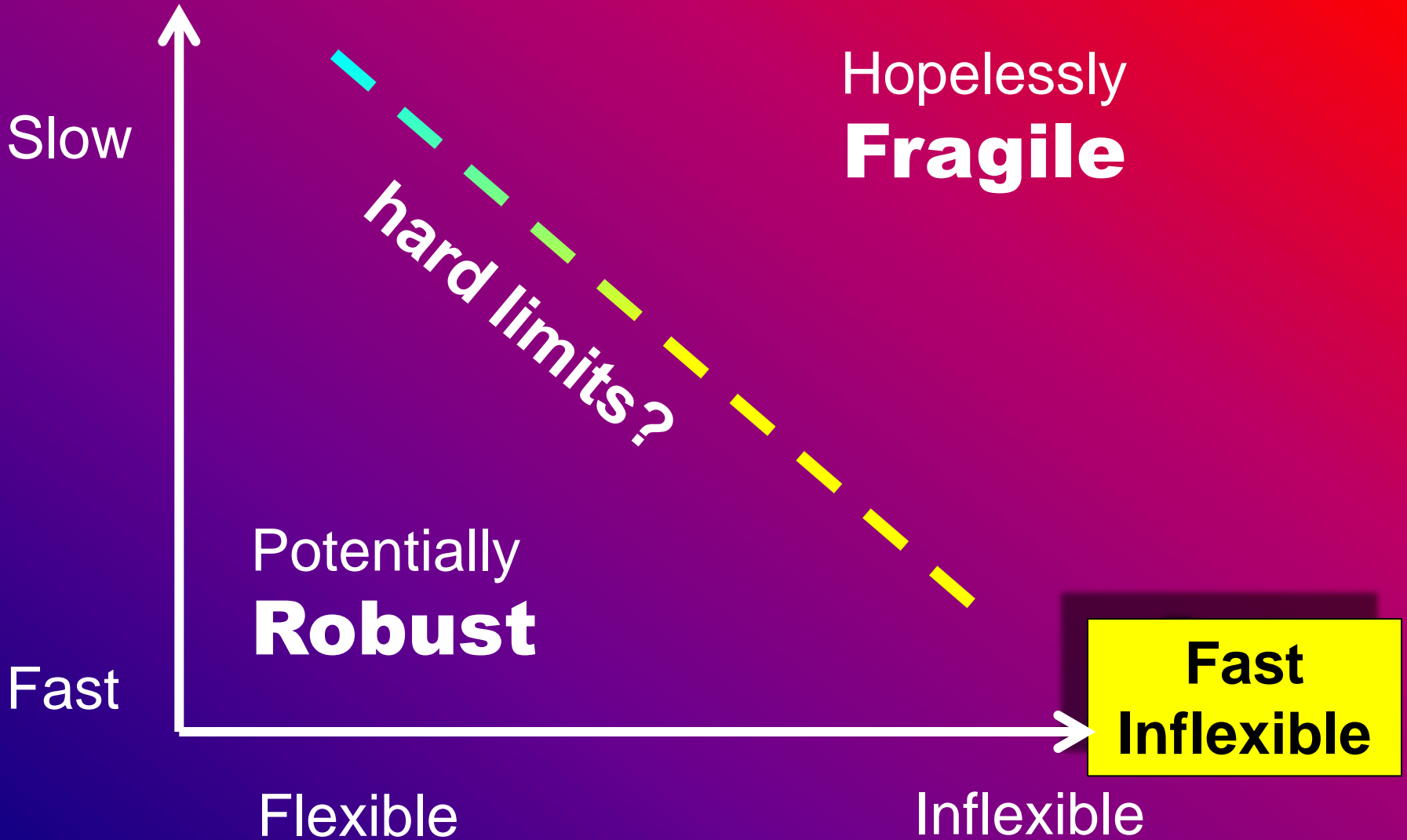
Low latency/delay

Fast

Fast

Flexible

**Slow
Flexible**



Hopelessly
Fragile

hard limits?

Potentially
Robust

**Fast
Inflexible**

Flexible

Inflexible

Human complexity

Robust

- ☺ Metabolism
- ☺ Regeneration & repair
- ☺ Healing wound /infect

Fragile

- ☹ Obesity, diabetes
- ☹ Cancer
- ☹ AutoImmune/Inflame

Start with physiology

Lots of triage

Benefits

Robust

- ☺ Metabolism
- ☺ Regeneration & repair
- ☺ Healing wound /infect

- ☺ Efficient
- ☺ Mobility
- ☺ Survive uncertain food supply
- ☺ Recover from moderate trauma and infection

Mechanism?

Robust

- ☺ Metabolism
- ☺ Regeneration & repair
- ☺ Healing wound /infect
- ☹ Fat accumulation
- ☹ Insulin resistance
- ☹ Proliferation
- ☹ Inflammation

Fragile

- ☹ Obesity, diabetes
- ☹ Cancer
- ☹ AutoImmune/Inflame
- ☹ Fat accumulation
- ☹ Insulin resistance
- ☹ Proliferation
- ☹ Inflammation

What's the difference?

Robust

- 😊 Metabolism
- 😊 Regeneration & repair
- 😊 Healing wound /infect

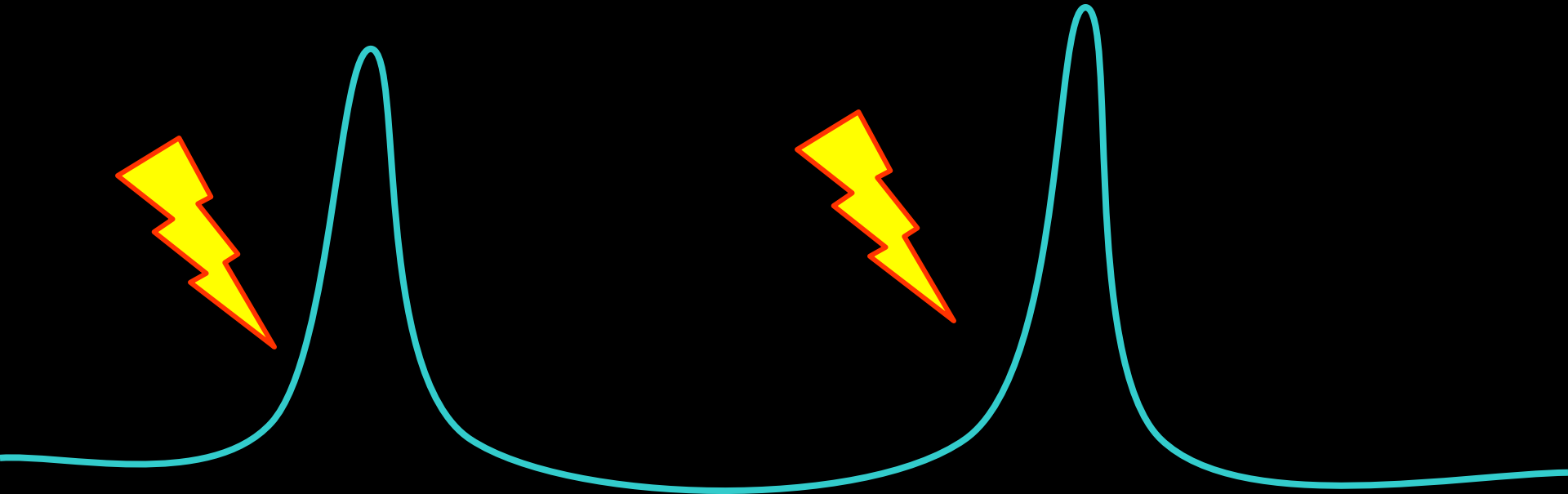
Fragile

- 😞 Obesity, diabetes
- 😞 Cancer
- 😞 AutoImmune/Inflame

- 😞 Fat accumulation
- 😞 Insulin resistance
- 😞 Proliferation
- 😞 Inflammation

Controlled
Dynamic

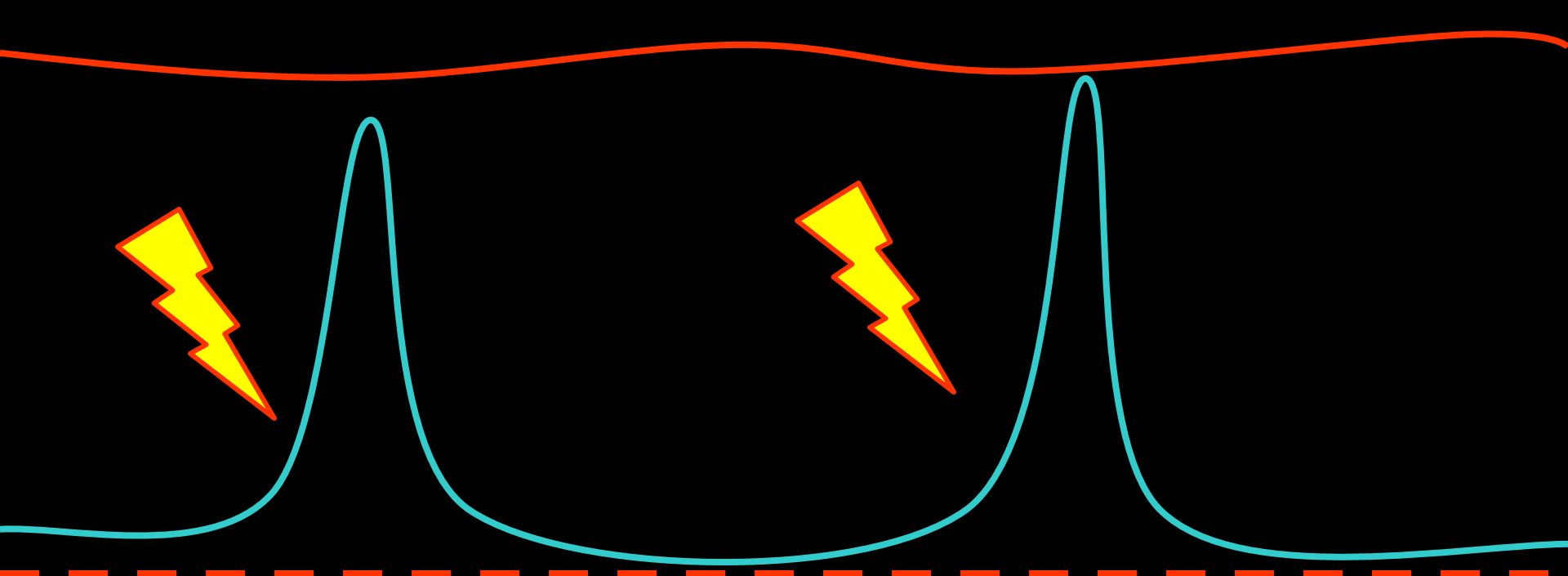
Uncontrolled
Chronic



- ☹ Fat accumulation
- ☹ Insulin resistance
- ☹ Proliferation
- ☹ Inflammation

Controlled
Dynamic

Low mean
High variability



Death

- ☹ Fat accumulation
- ☹ Insulin resistance
- ☹ Proliferation
- ☹ Inflammation

Controlled
Dynamic

Low mean
High variability

Uncontrolled
Chronic

High mean
Low variability

Restoring robustness?

Robust

- 😊 Metabolism
- 😊 Regeneration & repair
- 😊 Healing wound /infect

- ☹ Fat accumulation
- ☹ Insulin resistance
- ☹ Proliferation
- ☹ Inflammation

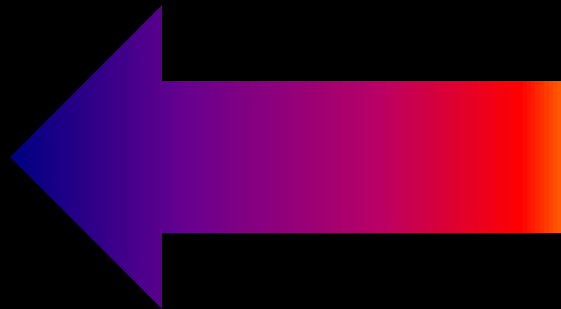
Fragile

- ☹ Obesity, diabetes
- ☹ Cancer
- ☹ AutoImmune/Inflame

- ☹ Fat accumulation
- ☹ Insulin resistance
- ☹ Proliferation
- ☹ Inflammation

Controlled
Dynamic

Low mean
High variability



Uncontrolled
Chronic

High mean
Low variability

Human complexity

Robust

- ☺ Metabolism
- ☺ Regeneration & repair
- ☺ Immune/inflammation
- ☺ Microbe symbionts
- ☺ Neuro-endocrine
- 📄 Complex societies
- 📄 Advanced technologies
- 📄 Risk “management”

Yet Fragile

- ☹ Obesity, diabetes
- ☹ Cancer
- ☹ AutoImmune/Inflame
- ☹ Parasites, infection
- ☹ Addiction, psychosis,...
- ☠ Epidemics, war,...
- 💣 Disasters, global &!%\$#
- 💣 Obfuscate, amplify,...

Accident or necessity?

Robust

☺ Metabolism

☺ Regenerati

☺ Healing wo

Fragile

☹ Obesity, diabetes

☹ Fat accumulation

☹ Insulin resistance

☹ Proliferation

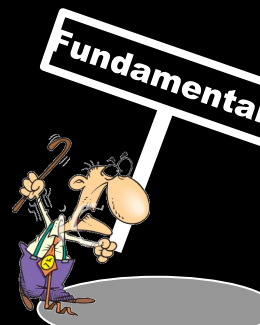
☹ Inflammation

une/Inflame

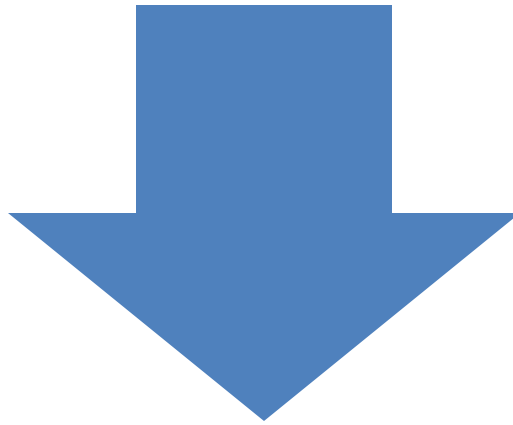
- Fragility ← Hijacking, side effects, unintended...
- Of mechanisms evolved for robustness
- Complexity ← control, robust/fragile tradeoffs
- Math: robust/fragile constraints (“conservation laws”)

Both

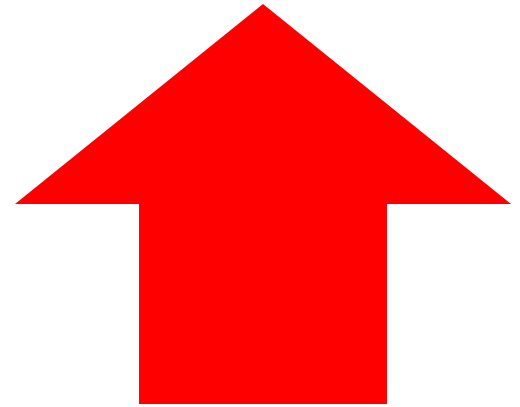
Accident or necessity?



fragile



**Some features
robust to some
perturbations**



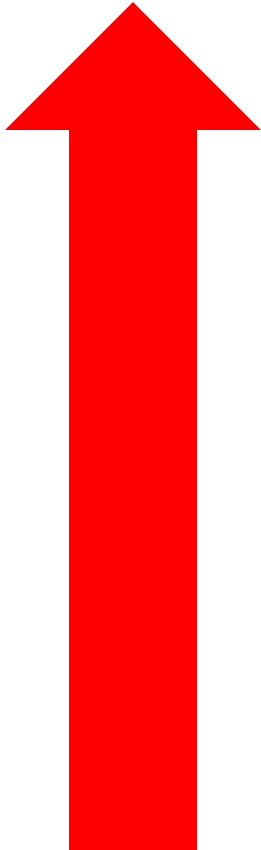
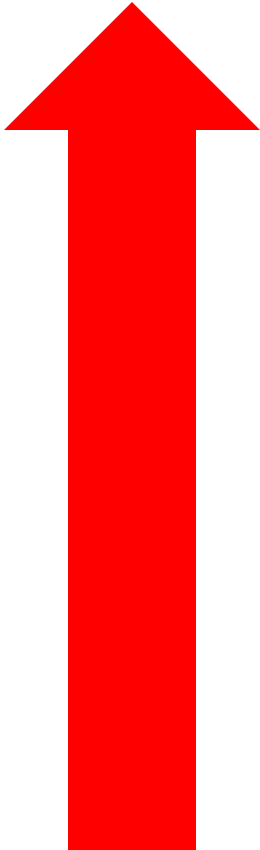
**Other features or
other
perturbations**

robust



Increased complexity?

fragile



robust

**Some features
robust to some
perturbations**

**Other features or
other
perturbations**

Robust

Modular

Simple

Plastic

Evolvable

and

~~**xor**~~

Fragile

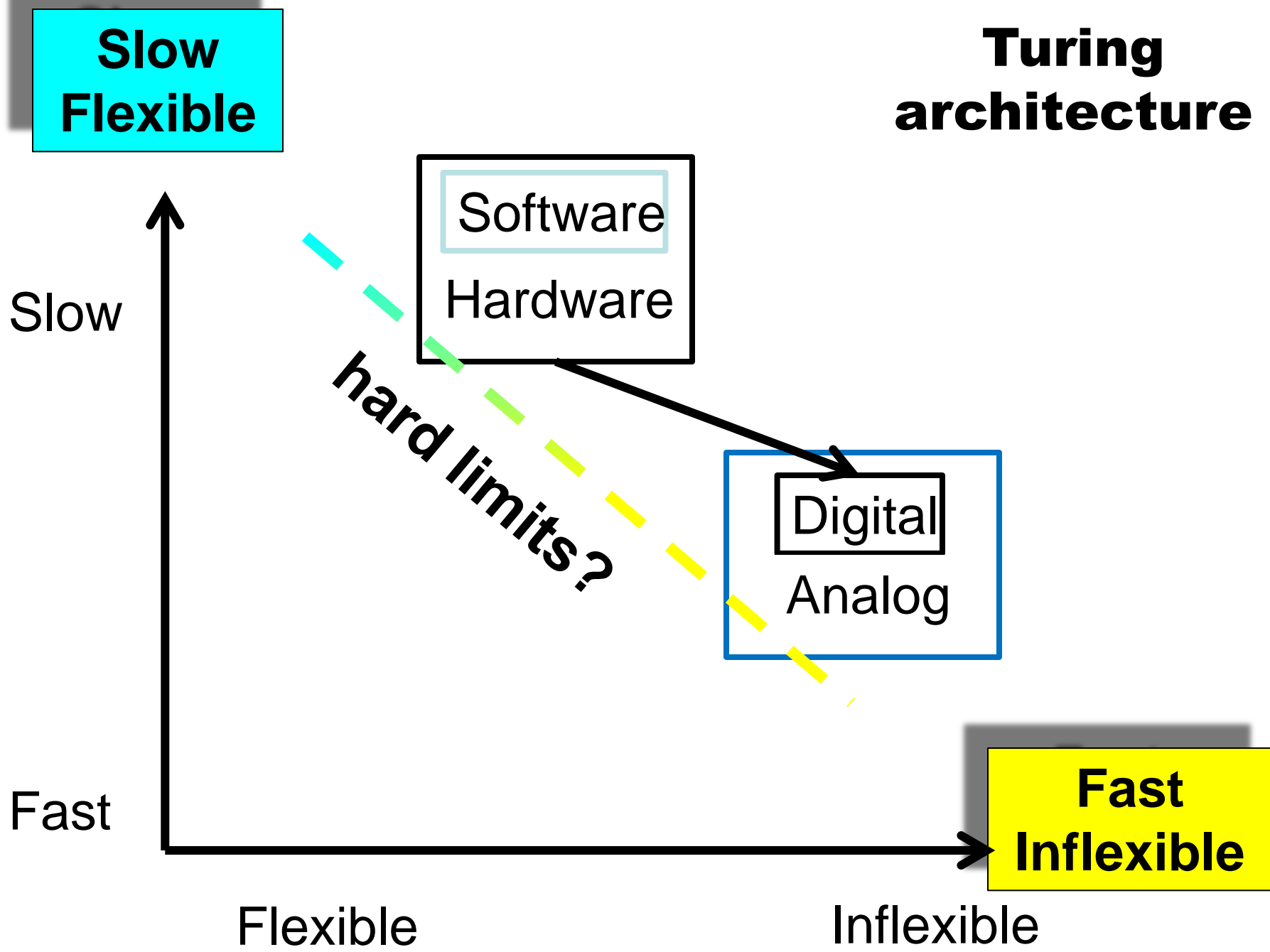
Distributed

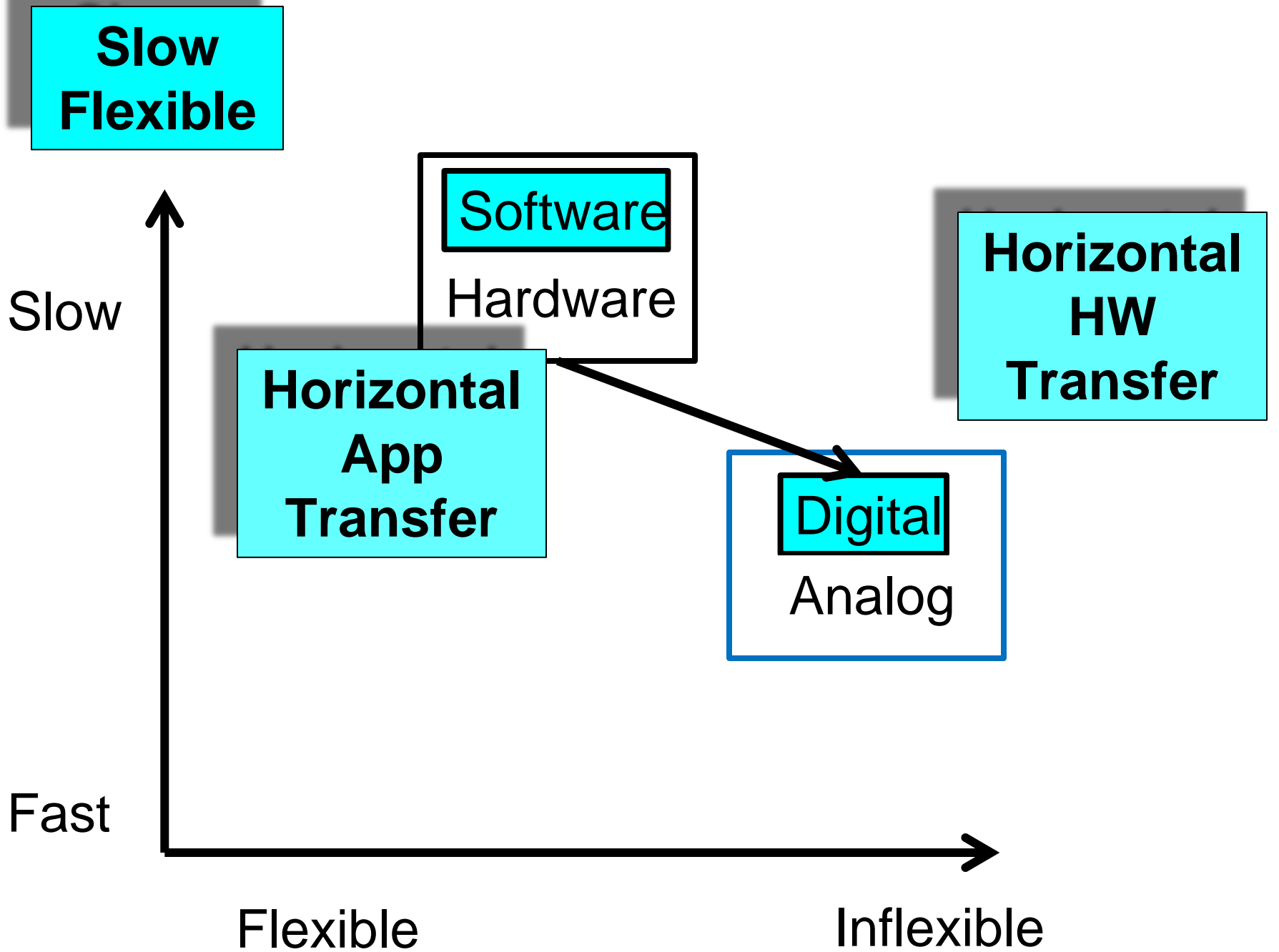
Complex

Frozen

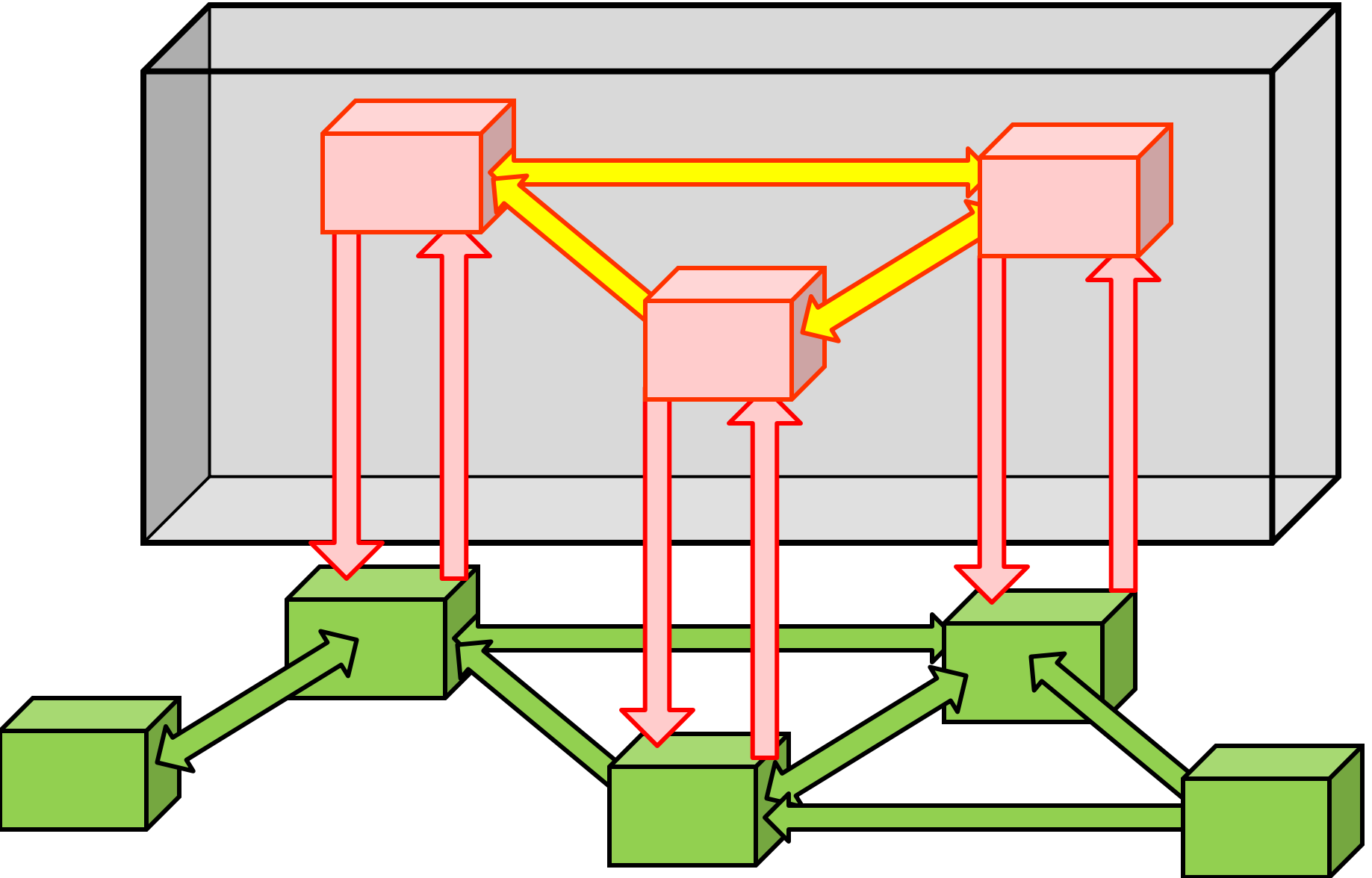
Frozen

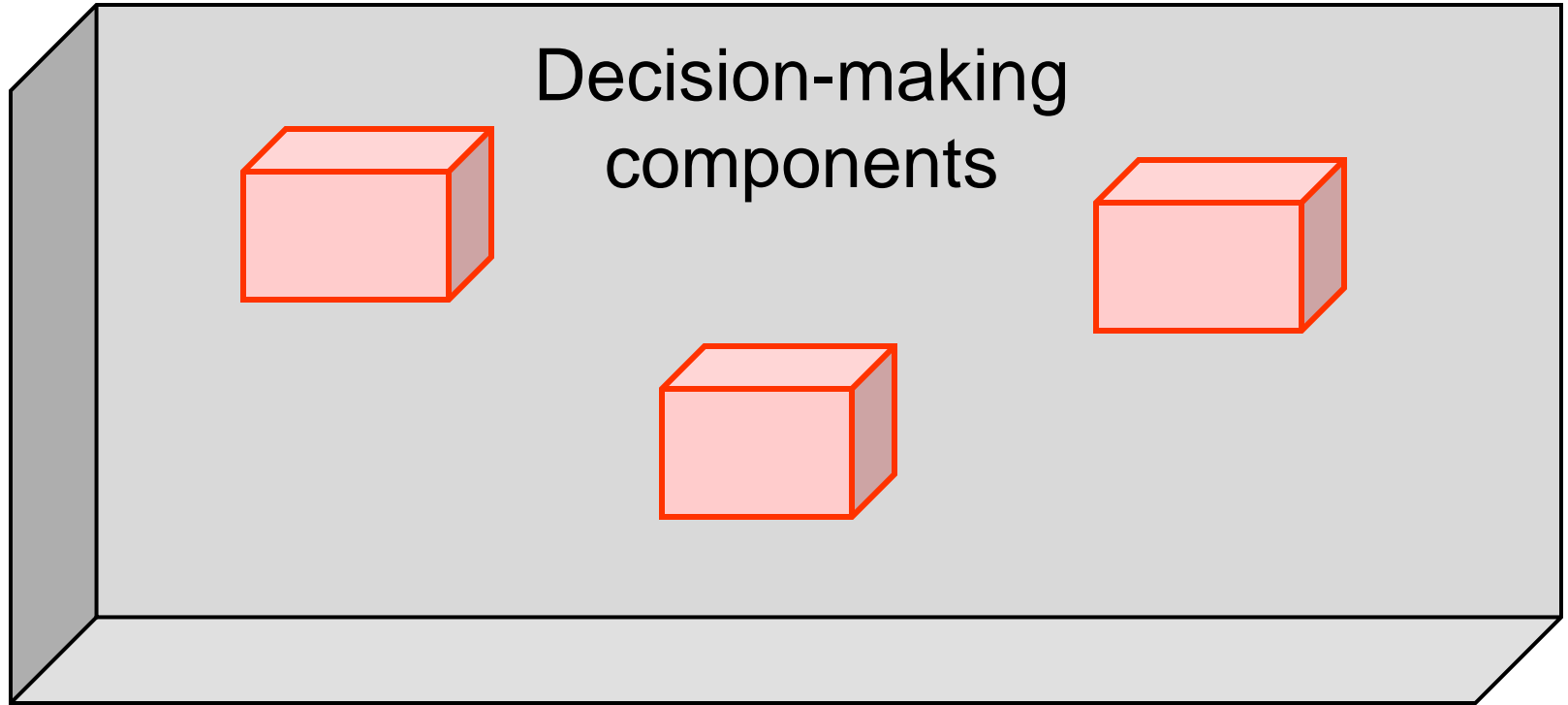
tradeoffs



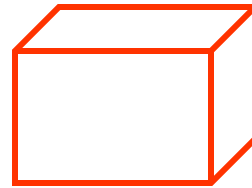
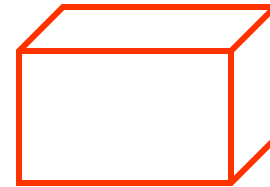
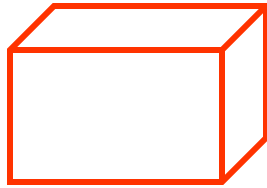


Cyber-physical: decentralized control with internal delays.

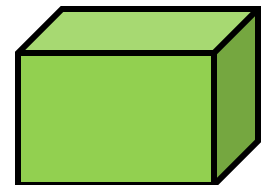
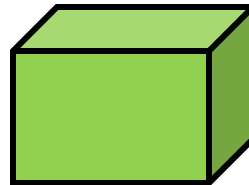
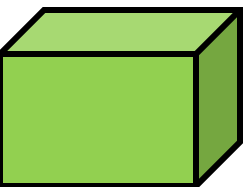
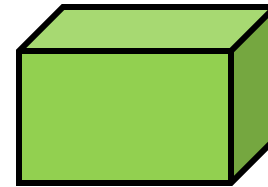
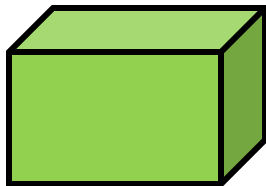




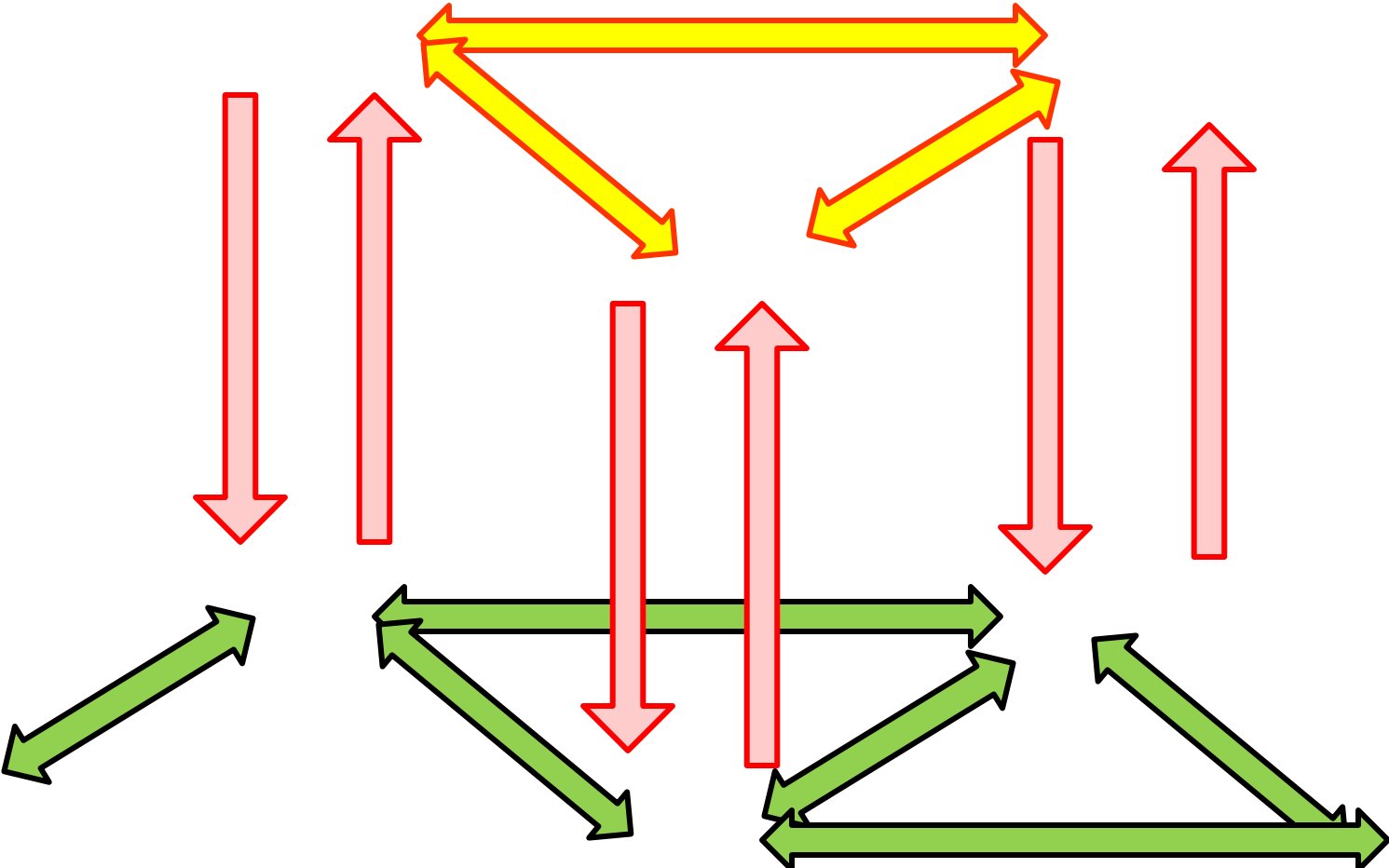
Decentralized, but initially assume computation is fast and memory is abundant.



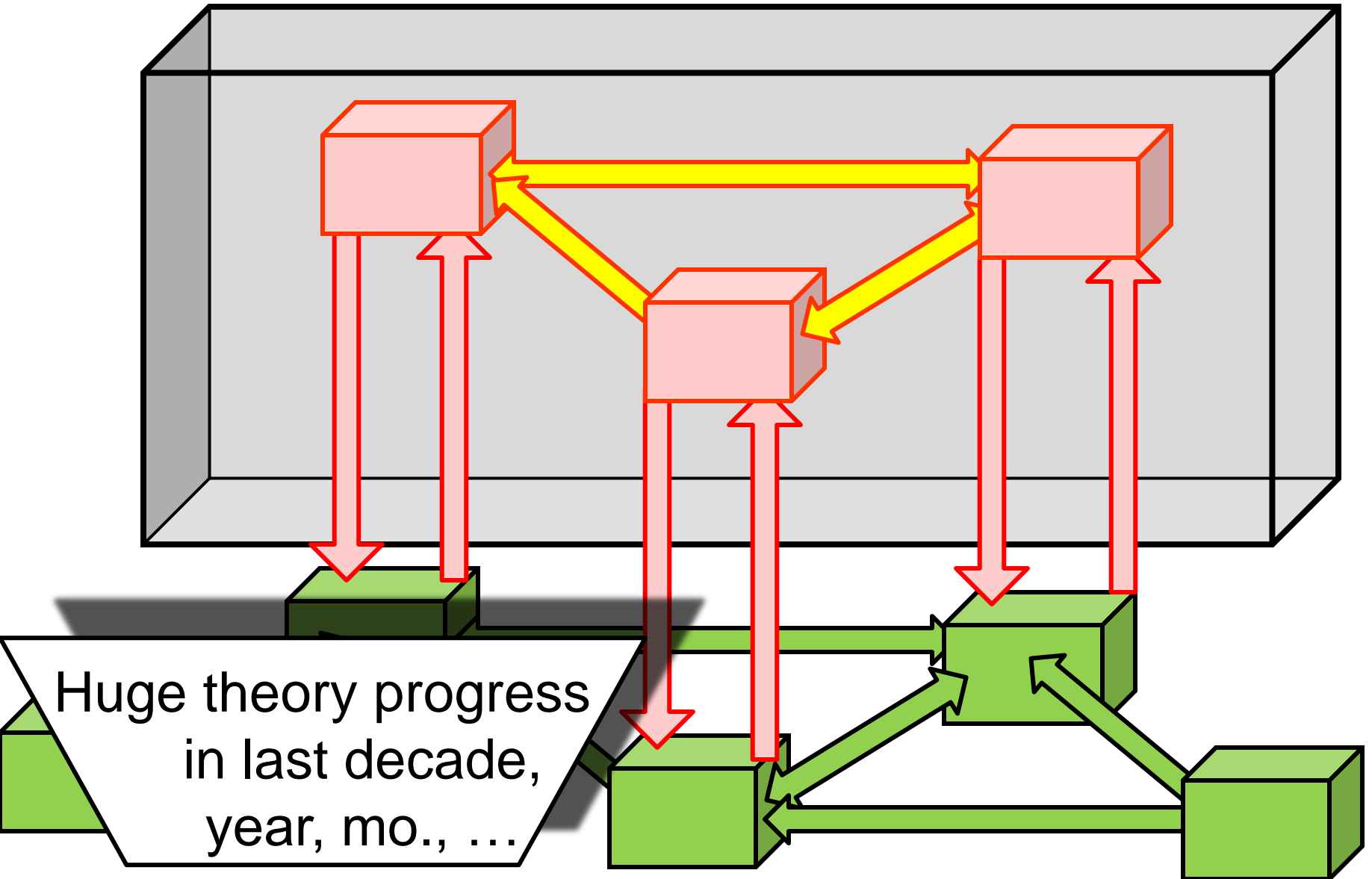
Plant is also distributed with its own component dynamics



Internal delays between components, and their sensor and actuators, and also externally between plant components

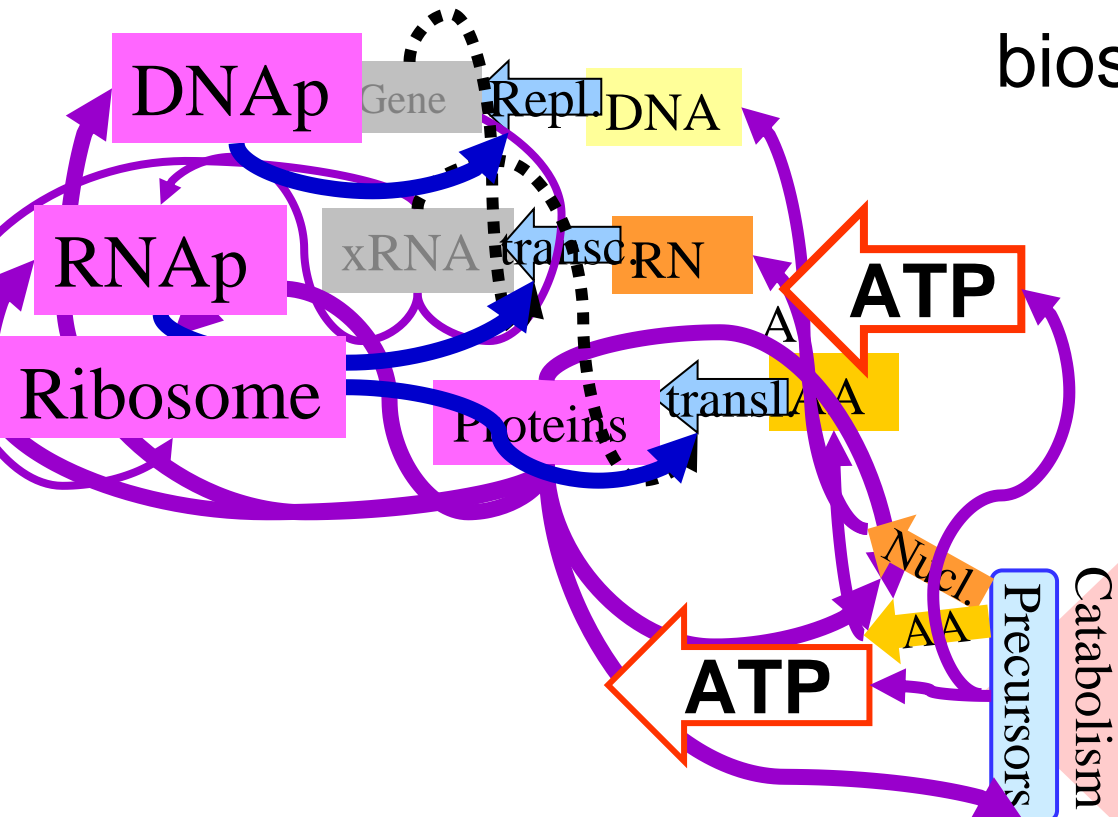


Going beyond black box: control is decentralized with internal delays.



The best case study so far

Layered architecture of the bacterial biosphere



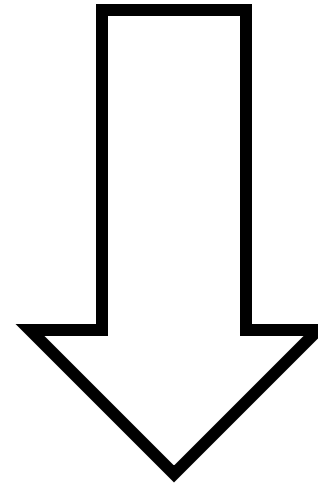
Not done here in detail, see slides elsewhere

How?

Universal architectures

Slow execution
Flexible reprogramming

Faster execution
Less flexible



Modern technology gives lots of intermediate alternatives.

Software

Software

Hardware

Digital

Analog

Applications



Operating System



Software
Hardware



Digital
Analog

Control, share,
virtualize, and
manage
resources

Processing
Memory
I/O

Want to emphasize the differences
between these two types of layering.

**Horizontal
App
Transfer**

Applications



Operating
System



Software

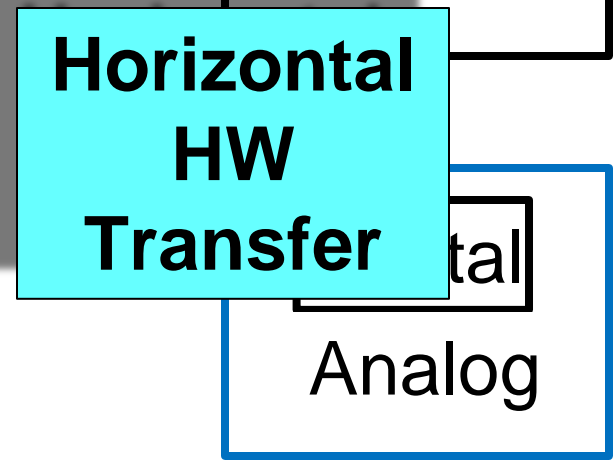
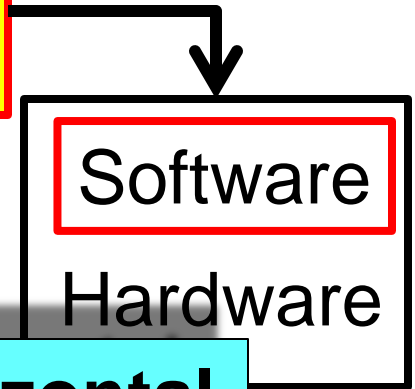
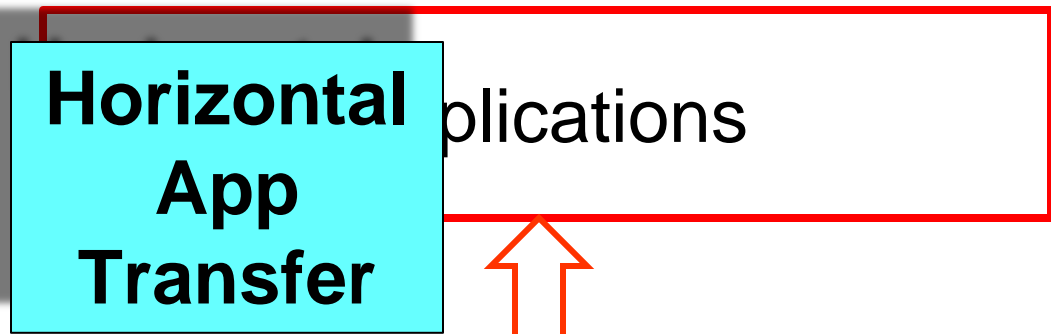
Hardware

**Horizontal
HW
Transfer**

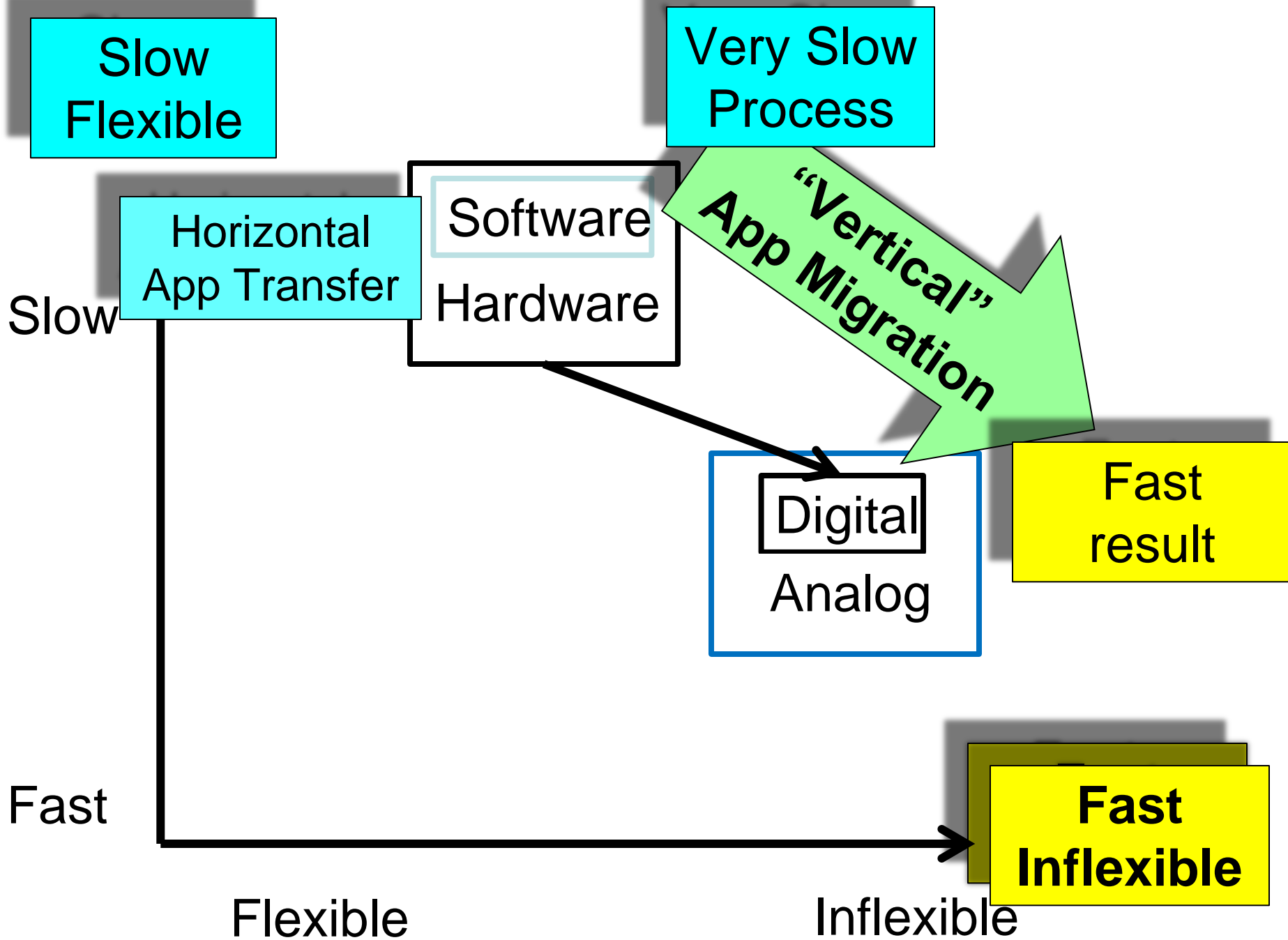


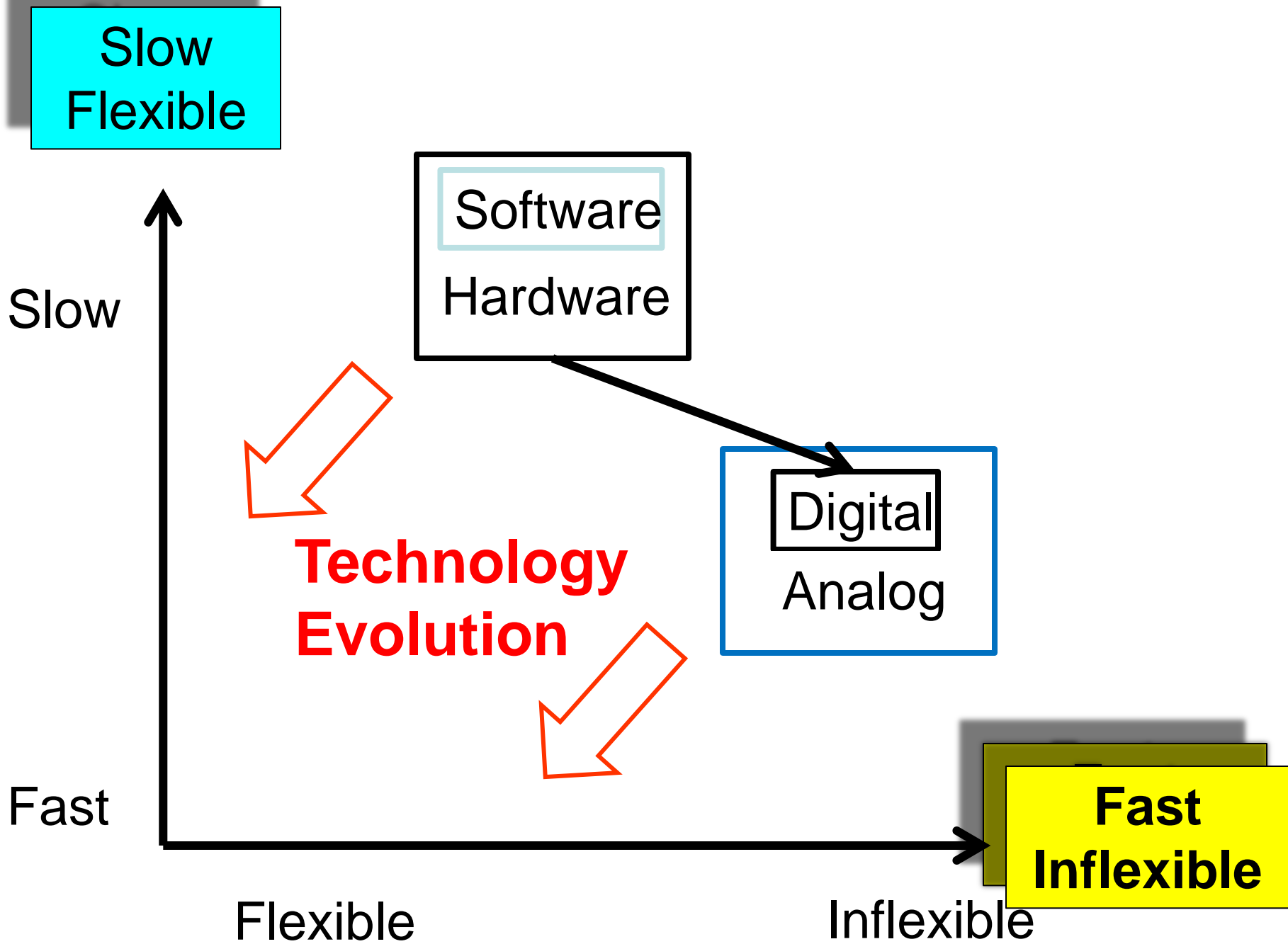
Digital
Analog

**What
matters is
the OS.**



- Some people write apps and build hardware
- But most software and hardware is acquired by “horizontal” transfer from others
- Similarly, most new ideas (humans) and new genes (bacteria) are acquired horizontally





Horizontal
Meme
Transfer

Very Slow
Process

Slow
Flexible

“Vertical”
App Migration

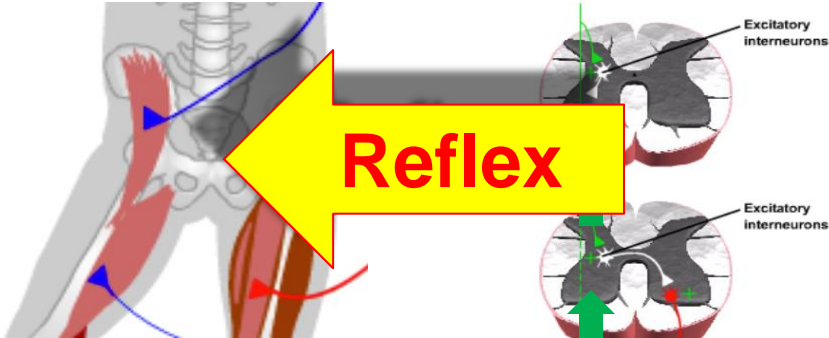
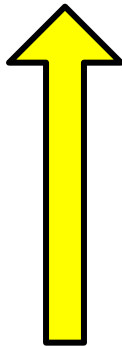
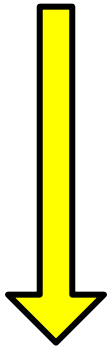
Prefrontal

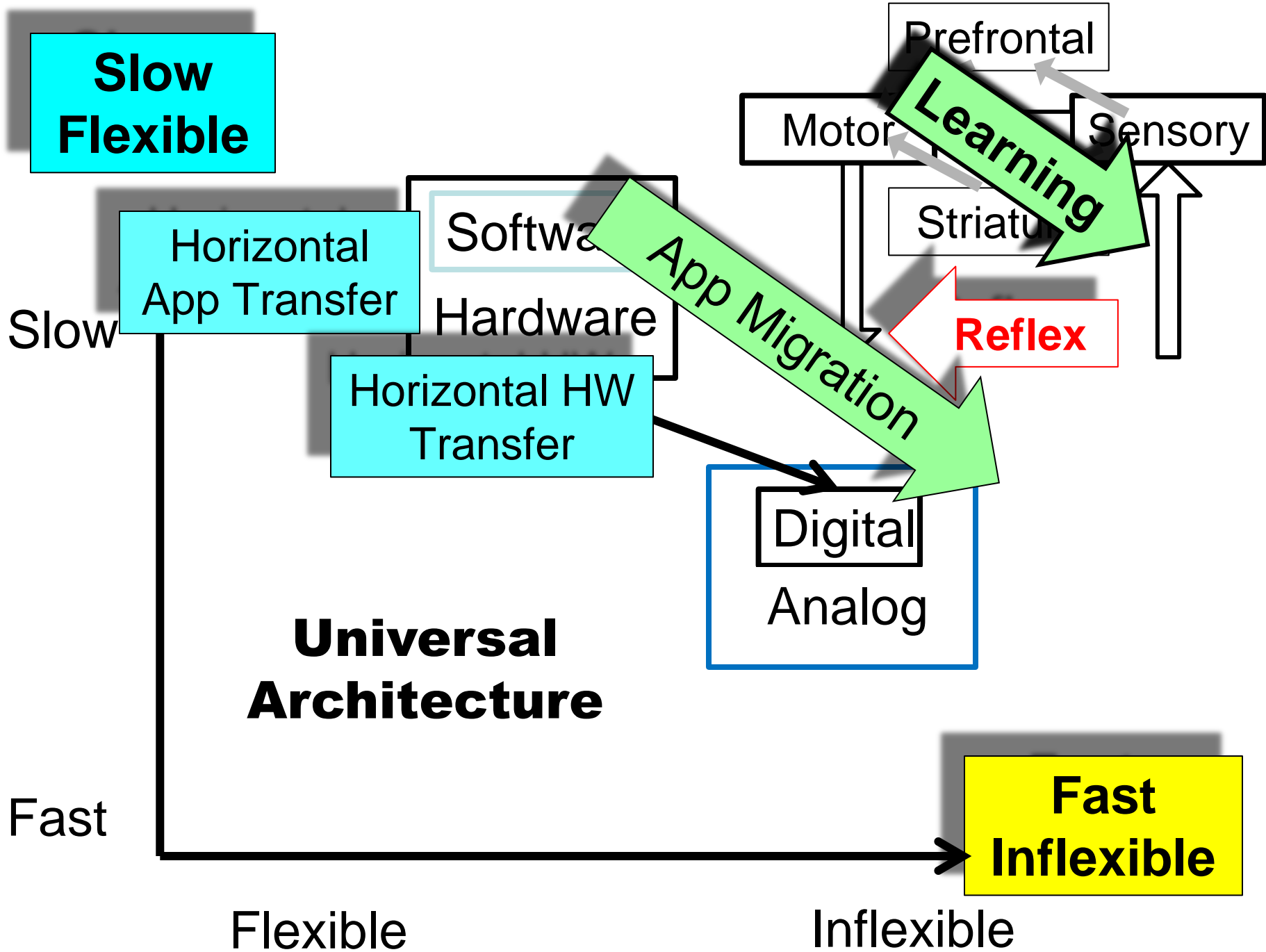
Motor ← Sensory

Striatum

Fast
Inflexible

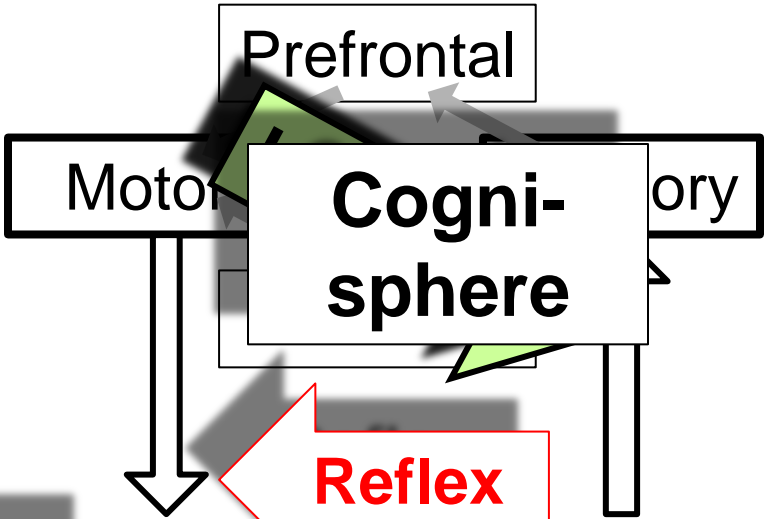
- Acquire
- Translate/
integrate
- Automate





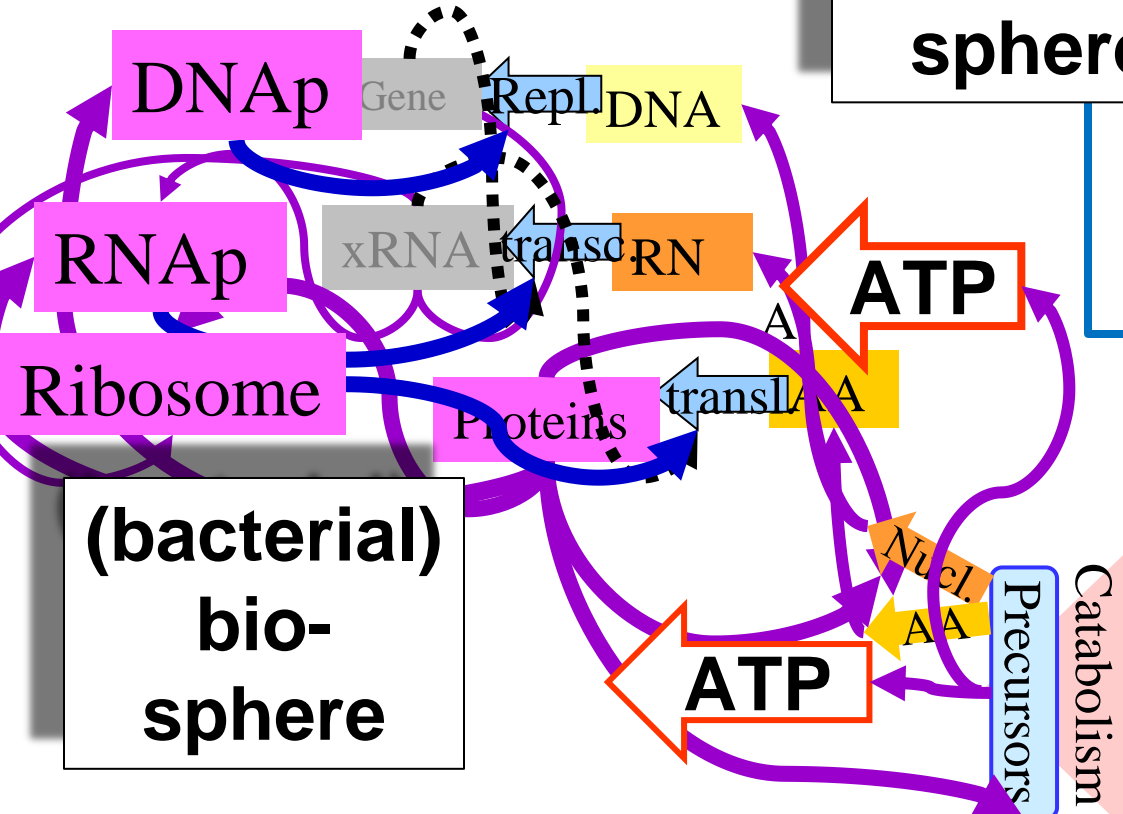
**Slow
Flexible**

Software
Hardware



**Techno-
sphere**

Digital
Analog



**(bacterial)
bio-
sphere**

**Fast
Inflexible**

**Flexible/
Adaptable/
Evolvable**

**Horizontal
Meme
Transfer**

frontal

Sensory

Learning

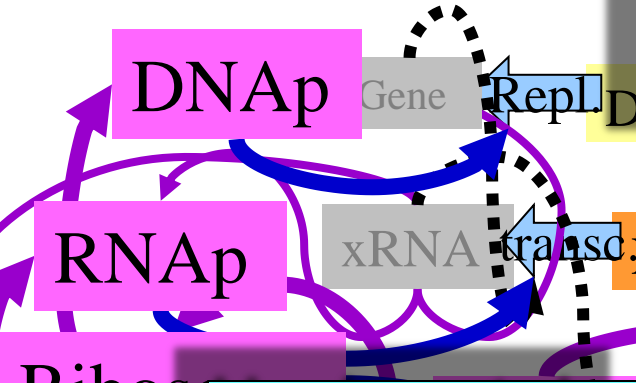
Striatu

Reflex

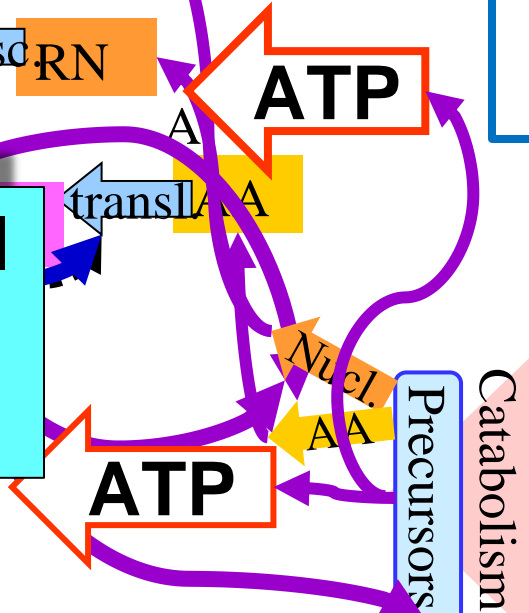
Software
Hardware

**Horizontal
App
Transfer**

Digital
Analog



**Horizontal
Gene
Transfer**



**Depends
crucially on
layered
architecture**

**Horizontal
Meme
Transfer**

**Horizontal
App
Transfer**

**Horizontal
Gene
Transfer**

Most

- software and hardware
- new ideas (humans)
- new genes (bacteria)

is acquired by “horizontal” transfer,
though sometimes it is evolved locally

**Exploiting
layered
architecture**

**Horizontal
Bad Meme
Transfer**



**Horizontal
Bad App
Transfer**

Fragility?

**Horizontal
Bad Gene
Transfer**



**Parasites &
Hijacking**

Build on Turing to show what is *necessary* to make this work.

Depends
crucially on
layered
architecture

- Acquire
- Translate/
integrate
- Automate

Horizontal
Meme
Transfer

**Horizontal
App
Transfer**

Horizontal
Gene
Transfer

Amazingly
Flexible/
Adaptable

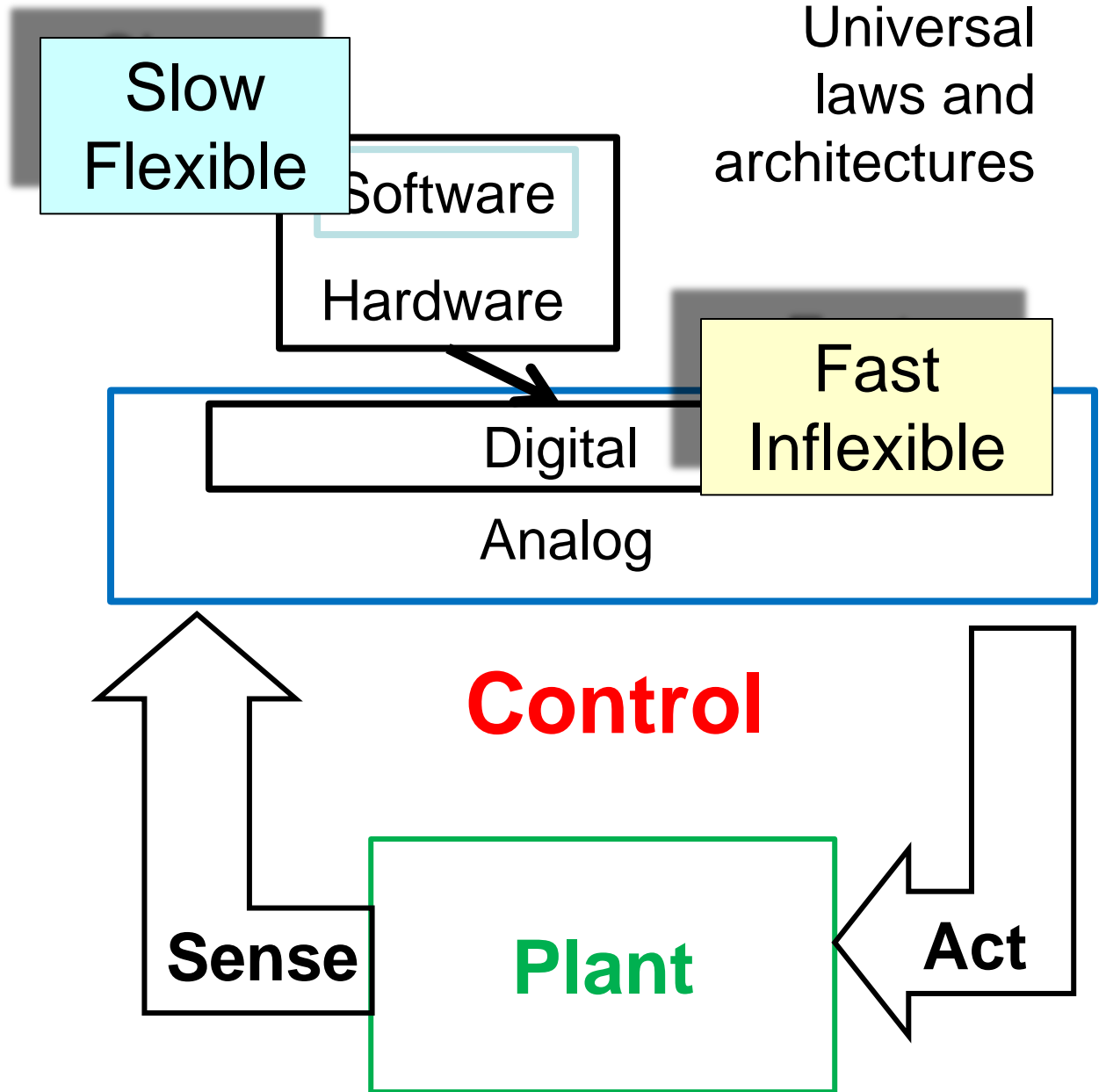
Compute

Turing

**Delay is
even more
important**

Bode

Control

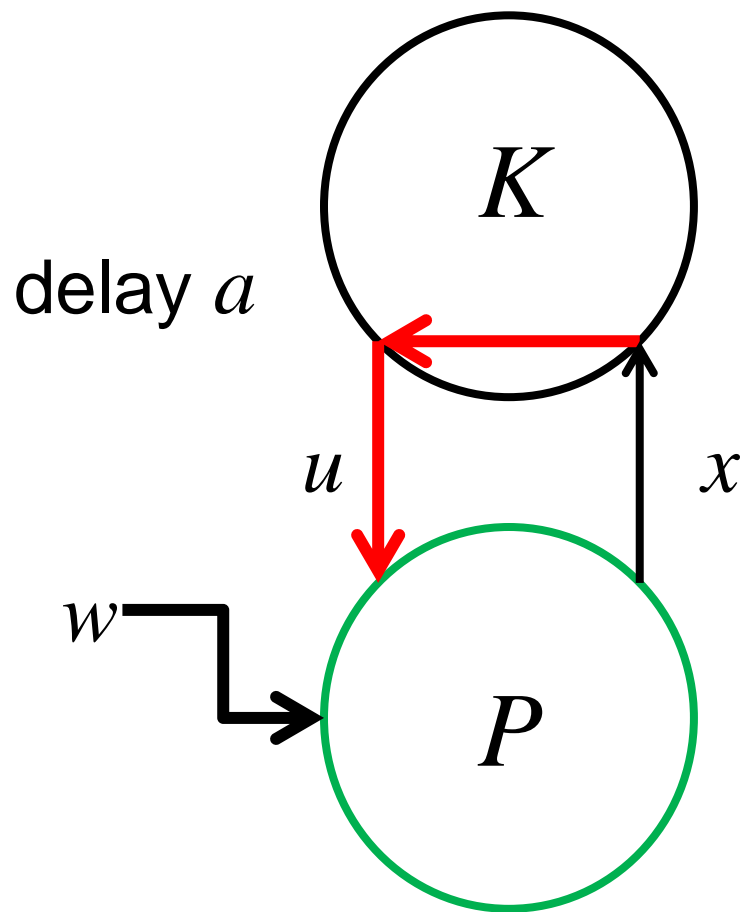


Compute

Turing

Why

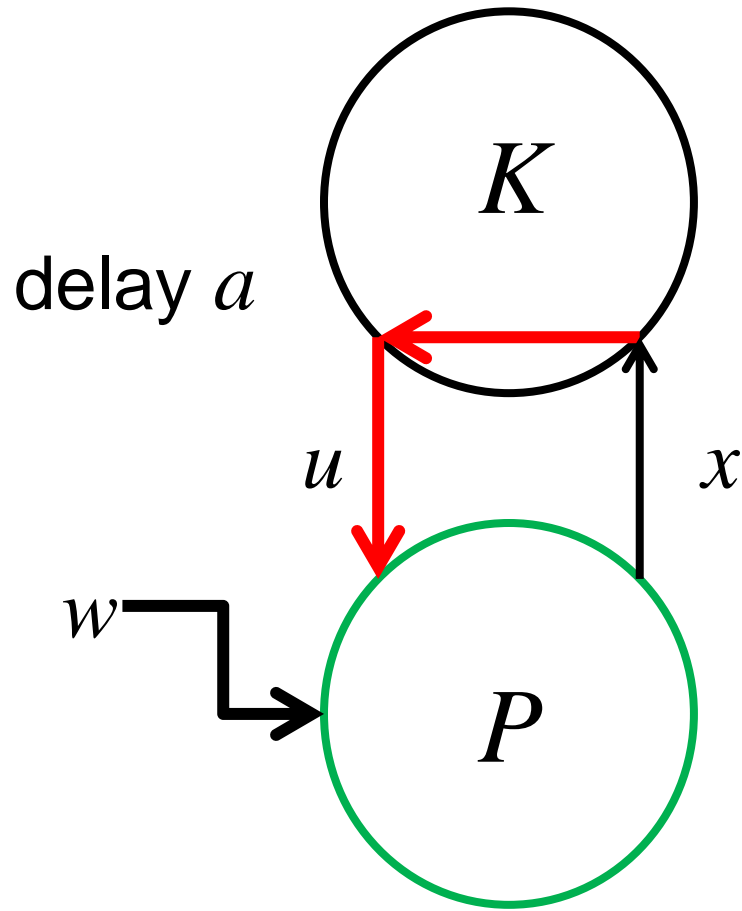
Necessity



$$x_{t+1} = px_t + w_t + u_{t-a}$$

$$p > 1$$

delay a



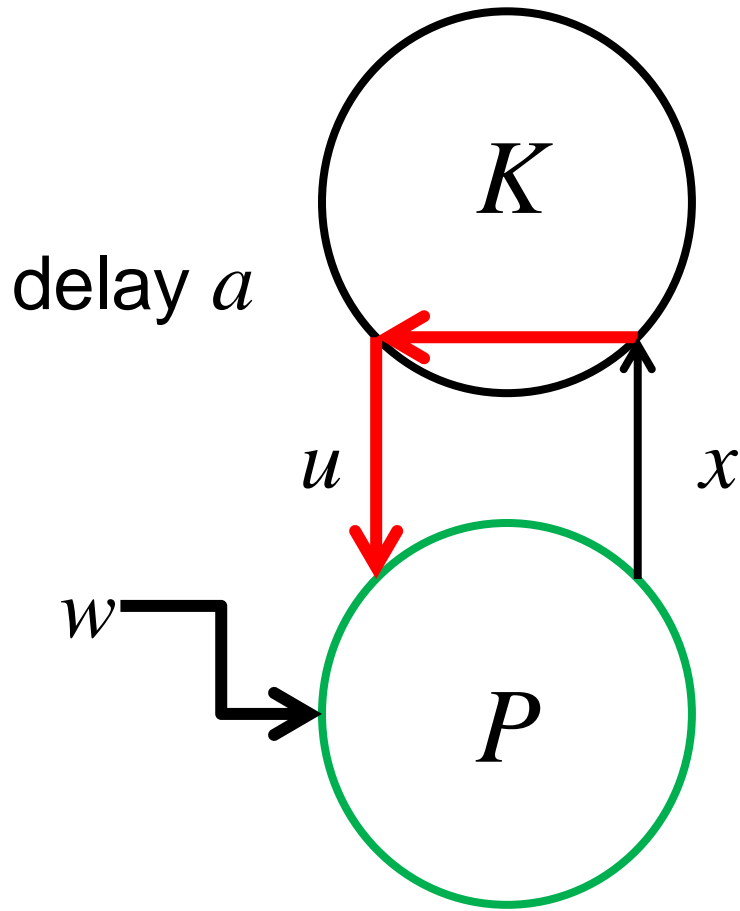
No delay or
no uncertainty

$$u_{t-a} = -(px_t + w_t)$$

$$\Rightarrow \|x\| \approx 0 \quad \|u\| \approx \|w\|$$

$$x_{t+1} = px_t + w_t + u_{t-a}$$

$$p > 1$$



No delay or
no uncertainty

$$u_{t-a} = -(px_t + w_t)$$

$$\Rightarrow \|x\| \approx 0 \quad \|u\| \approx \|w\|$$

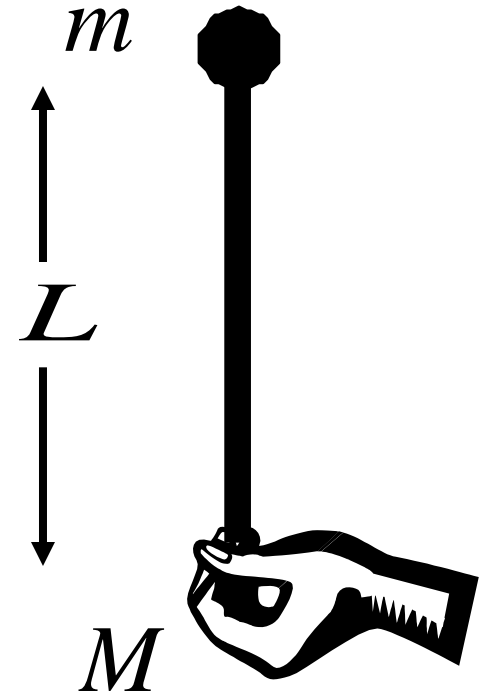
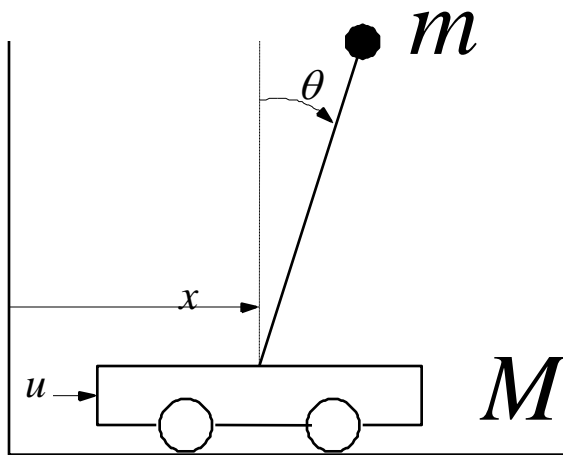
With delay **and**
uncertainty

$$x_{t+1} = px_t + w_t + u_{t-a}$$

$$p > 1$$

$$\Rightarrow \|x\| \approx \|u\| \approx p^a \|w\|$$

Linearized pendulum on a cart



$$\frac{d}{dt} \begin{bmatrix} x \\ \theta \\ \dot{x} \\ \dot{\theta} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & \frac{m^2 g l^2}{q} & \frac{-(J + m l^2) b}{q} & 0 \\ 0 & \frac{m g l (M + m)}{q} & \frac{-m l b}{q} & 0 \end{bmatrix} x + \begin{bmatrix} 0 \\ 0 \\ \frac{J + m l^2}{q} \\ \frac{m l}{q} \end{bmatrix} u$$

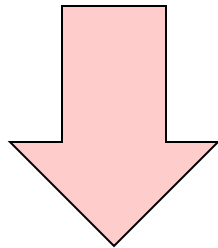
$$q = J(M + m) + M m l^2$$

$$(M + m)\ddot{x} + ml(\ddot{\theta} \cos \theta - \dot{\theta}^2 \sin \theta) = u$$

$$\ddot{x} \cos \theta + l\ddot{\theta} + g \sin \theta = 0$$

$$y = x + \alpha l \sin \theta$$

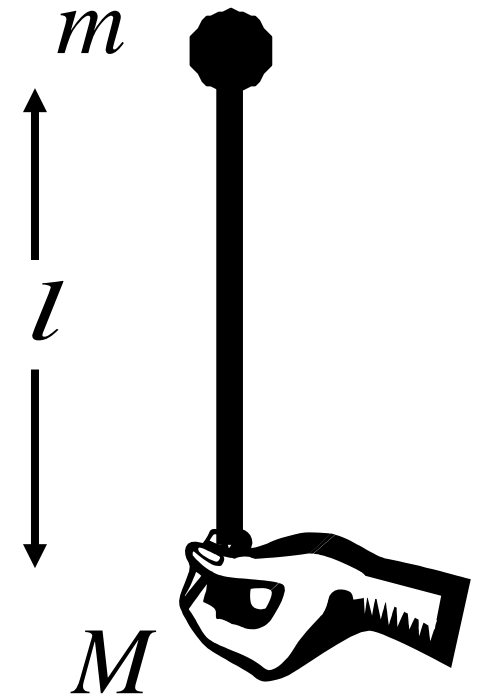
linearize



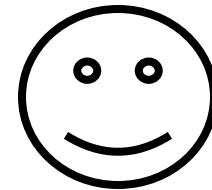
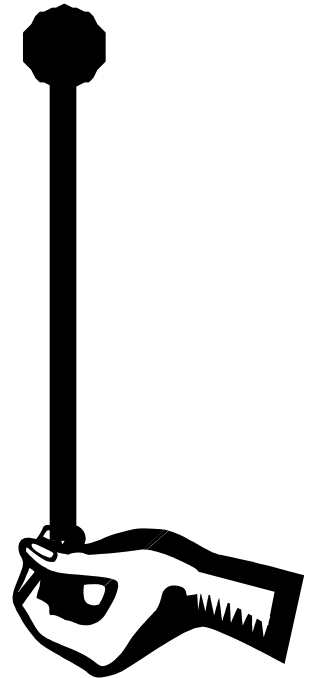
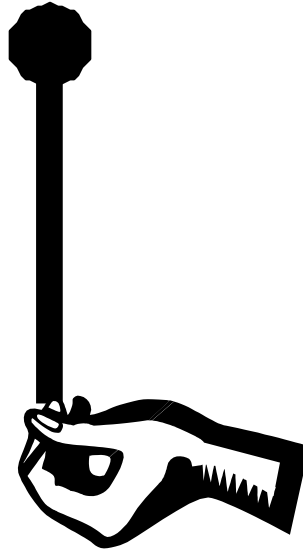
$$(M + m)\ddot{x} + ml\ddot{\theta} = u$$

$$\ddot{x} + l\ddot{\theta} \pm g\theta = 0$$

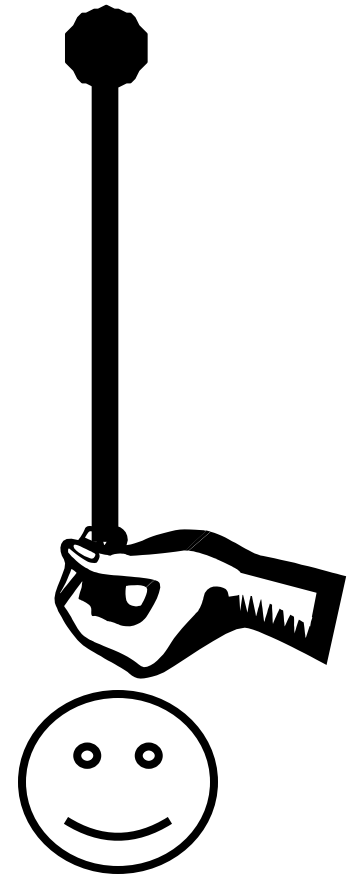
$$y = x + \alpha l \theta$$

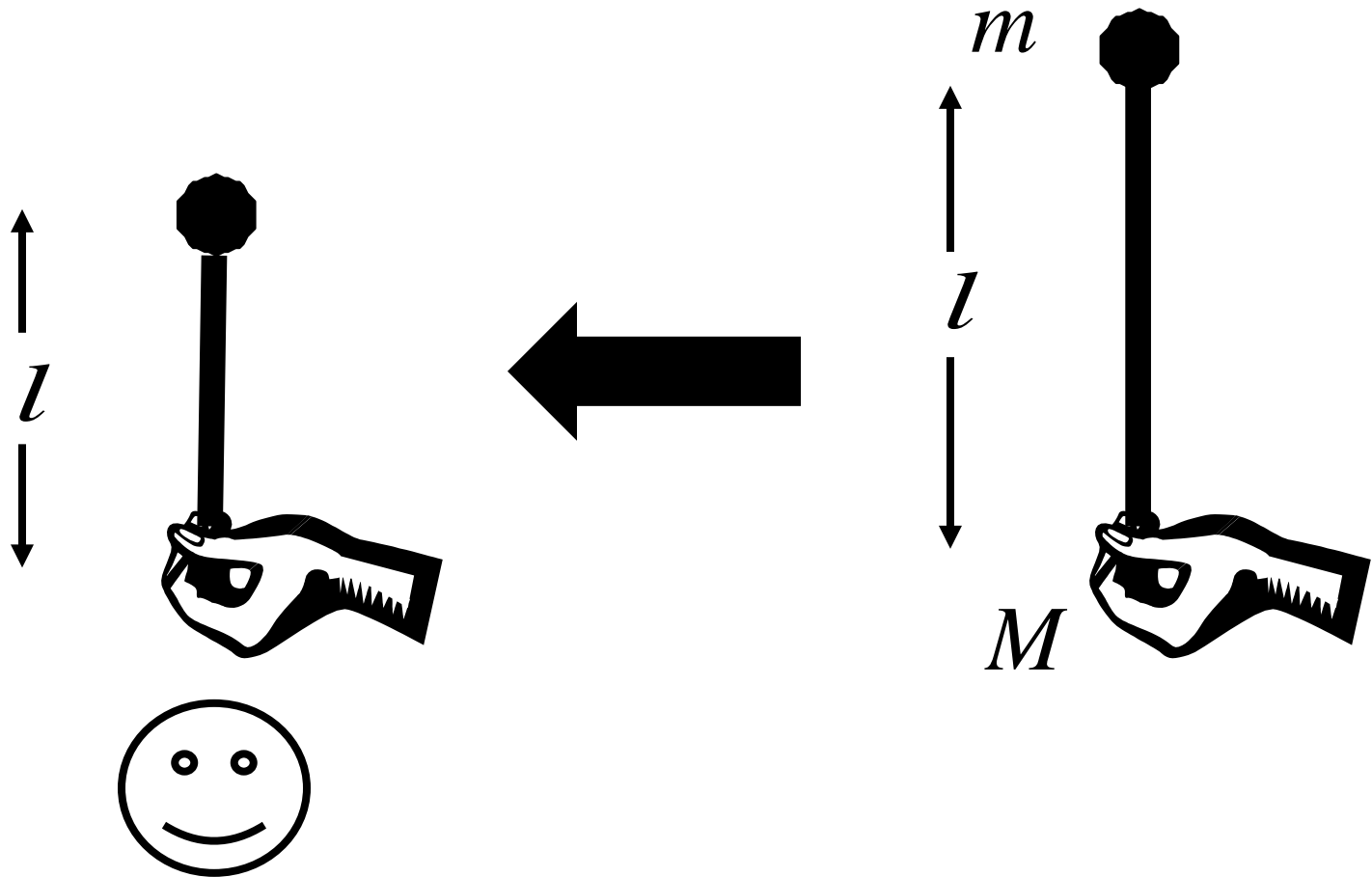


Robust
=agile and
balancing



Robust
=agile and
balancing





Efficient=length of
pendulum (artificial)

$$\begin{bmatrix} x \\ \theta \end{bmatrix} = \frac{1}{D(s)} \begin{bmatrix} ls^2 \pm g \\ -s^2 \end{bmatrix} u$$

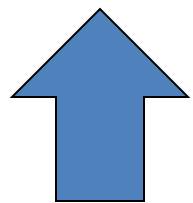
$$D(s) = s^2 (Mls^2 \pm (M + m)g)$$

$$y = x + \alpha l \theta = \frac{\varepsilon ls^2 \pm g}{D(s)}$$

$$\varepsilon = 1 - \alpha$$

$$p = \sqrt{\frac{g}{l}} \sqrt{1+r} \quad r = \frac{m}{M}$$

$$z = \sqrt{\frac{g}{l}} \sqrt{\frac{1}{\varepsilon}}$$

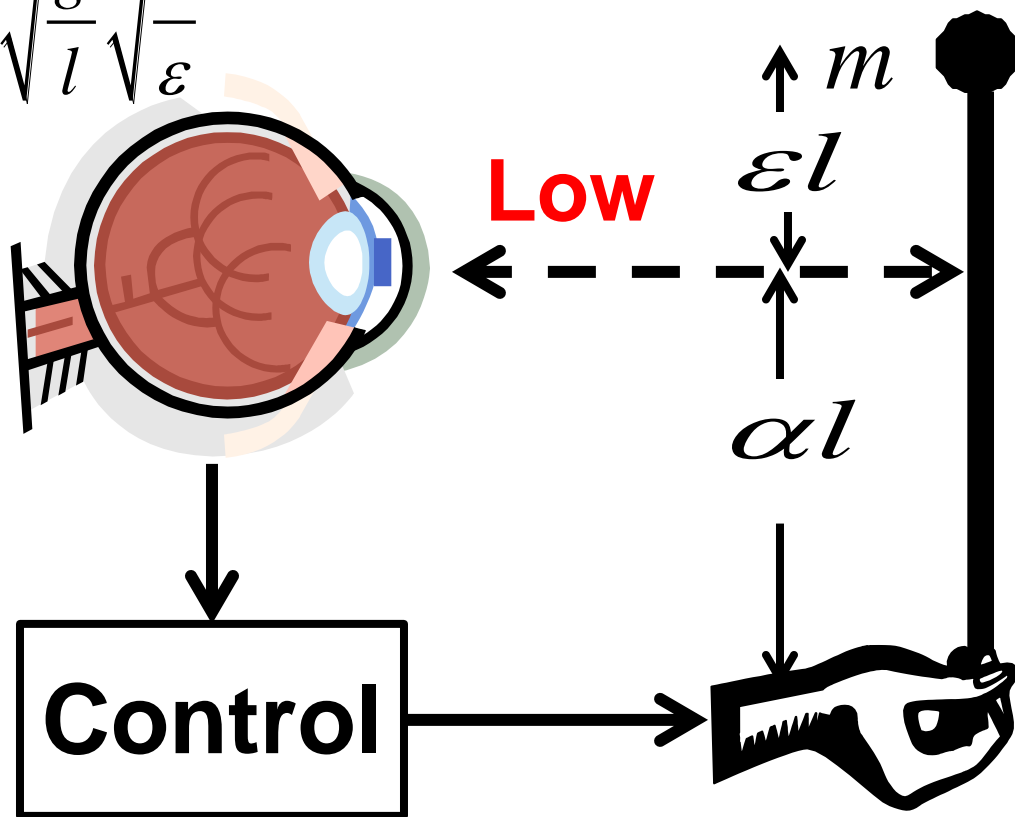


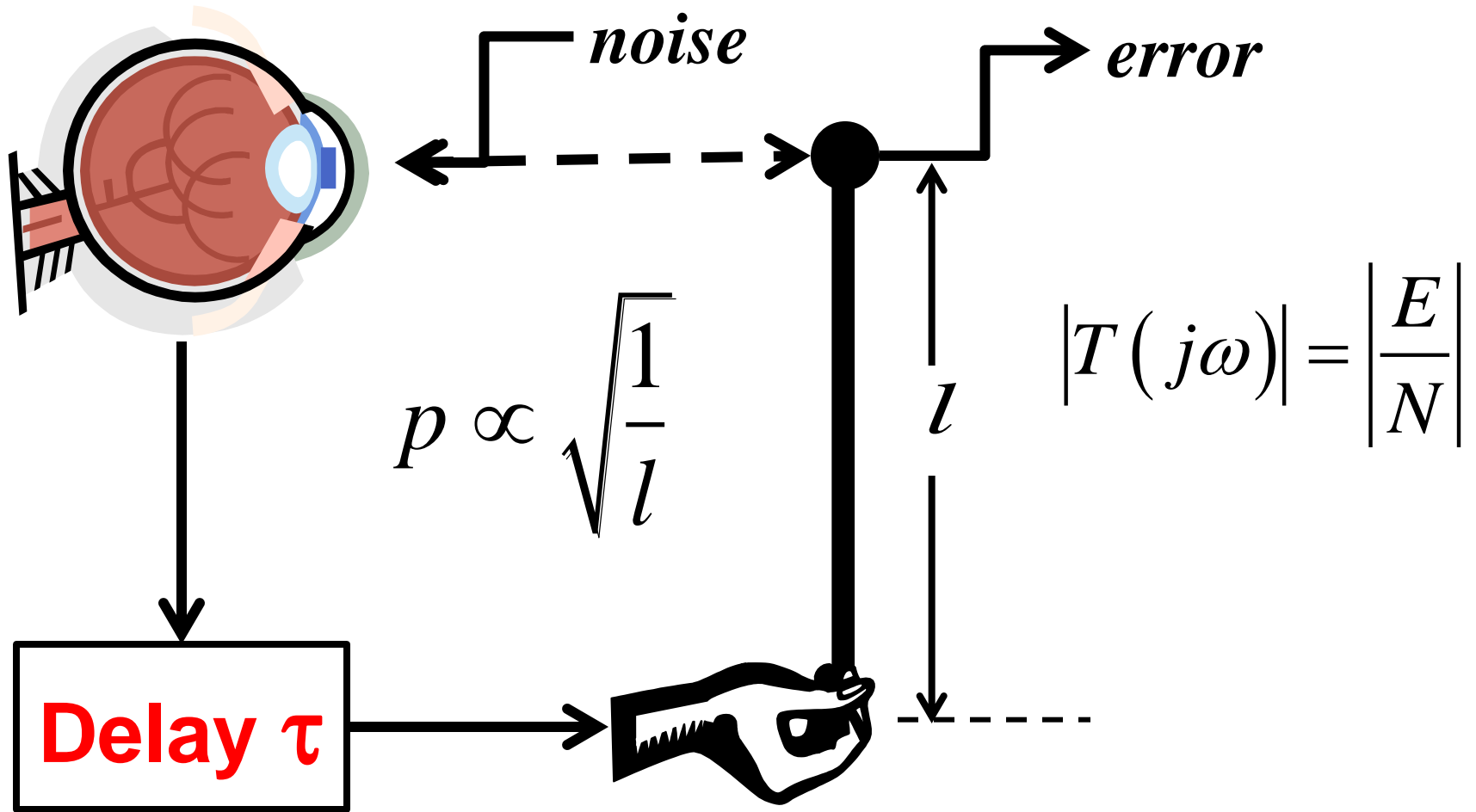
transform+
algebra

$$(M + m)\ddot{x} + ml\ddot{\theta} = u$$

$$\ddot{x} + l\ddot{\theta} \pm g\theta = 0$$

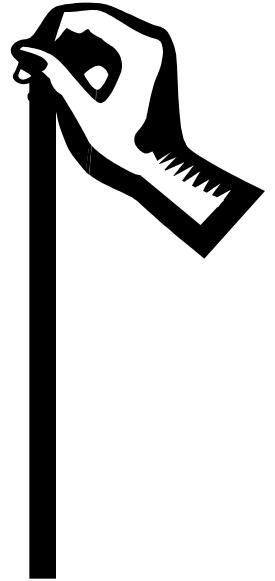
$$y = x + \alpha l \theta$$







$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| d\omega \geq 0$$

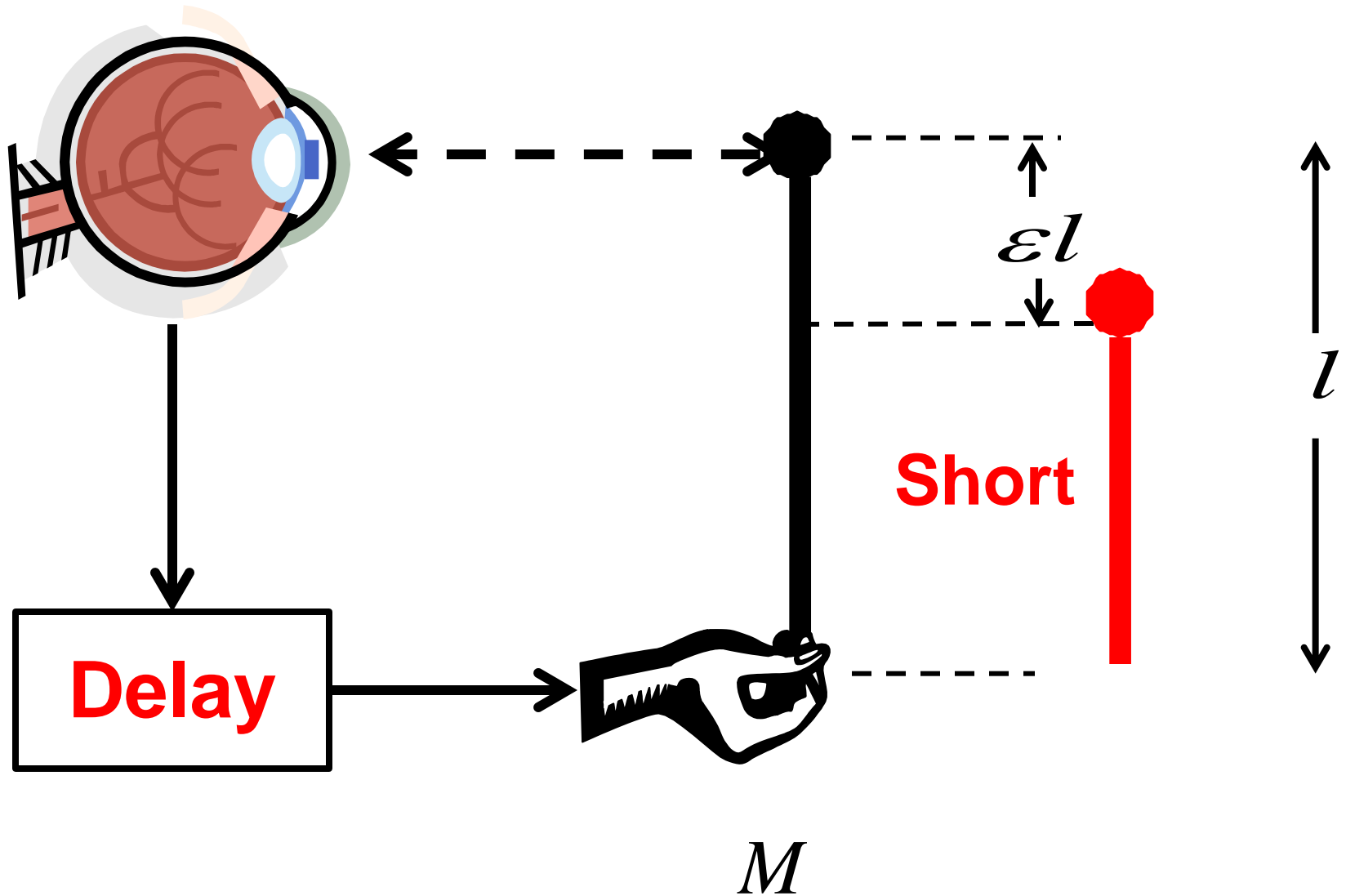


Easy, even with eyes closed
No matter what the length

Proof: Standard UG control theory:

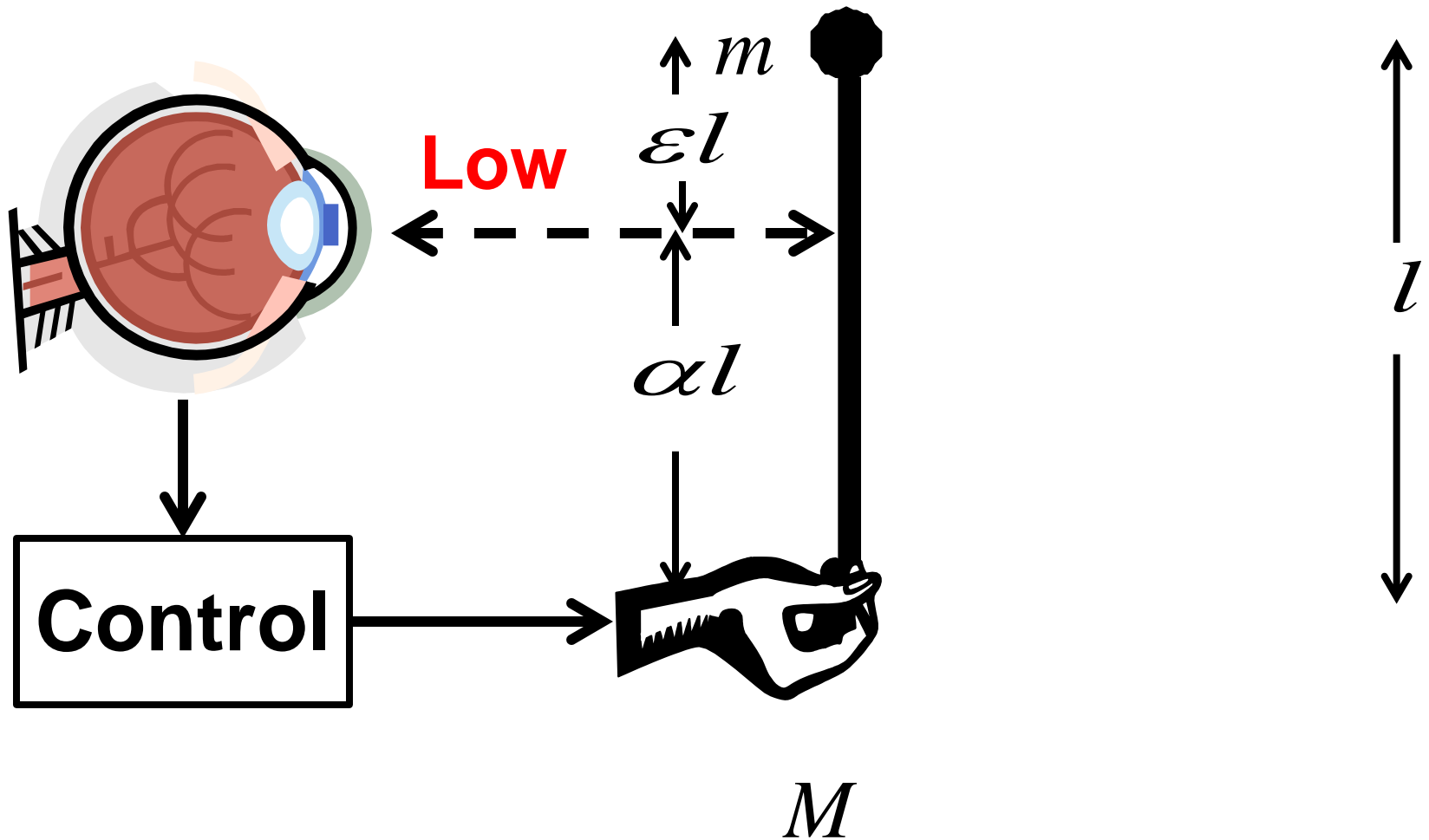
Easy calculus, easier contour integral,
easiest Poisson Integral formula

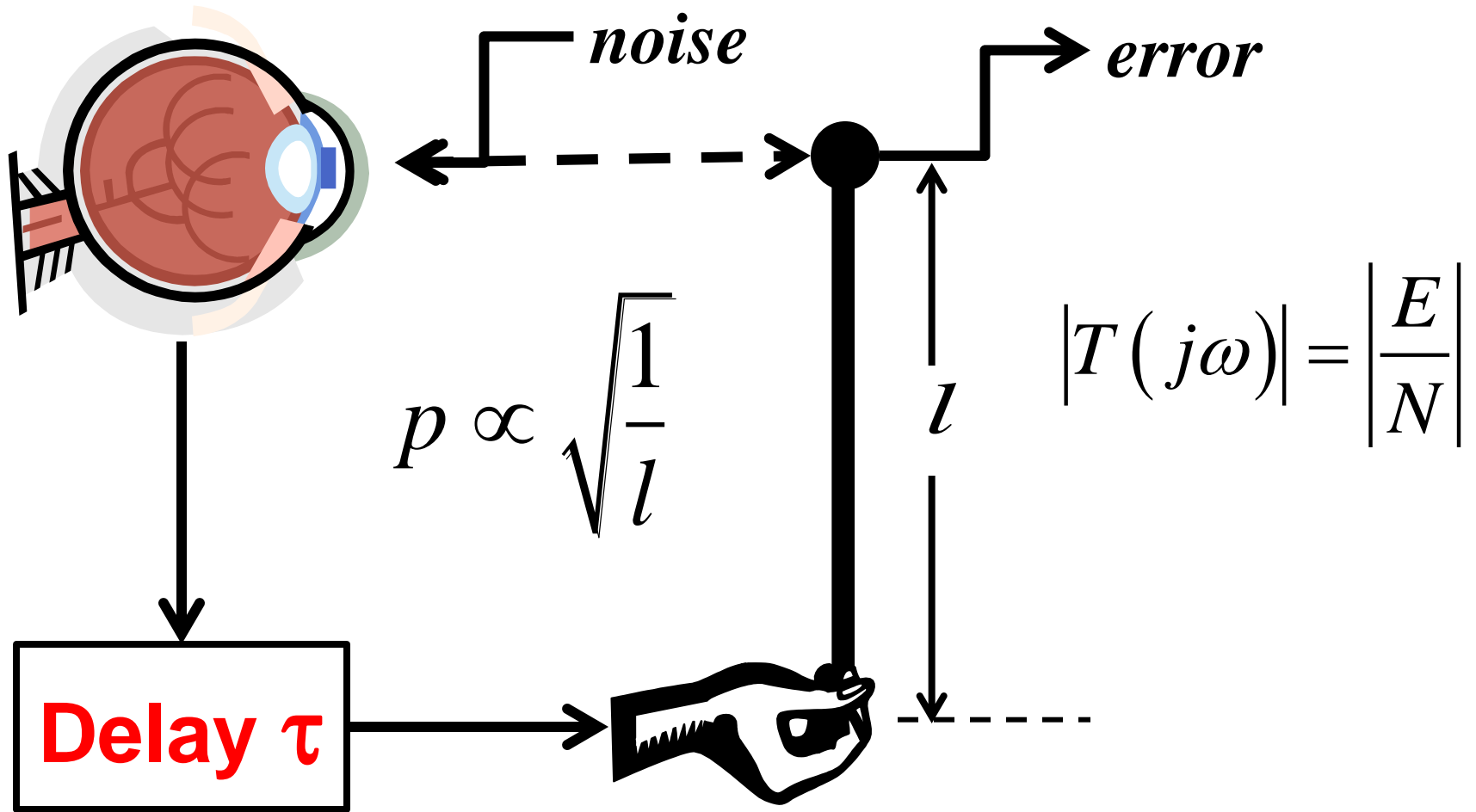
Harder if delayed or short

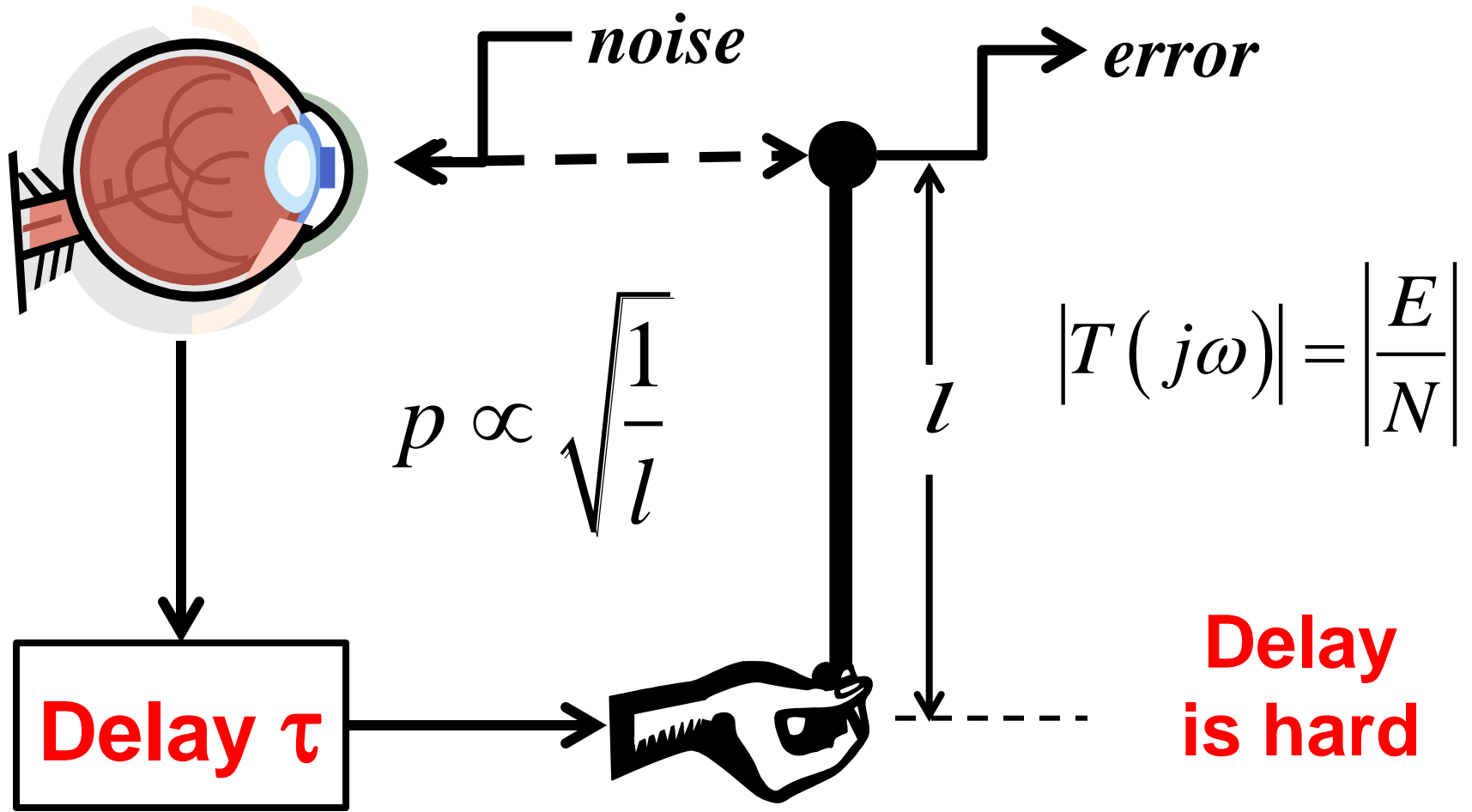


Also harder if sensed low

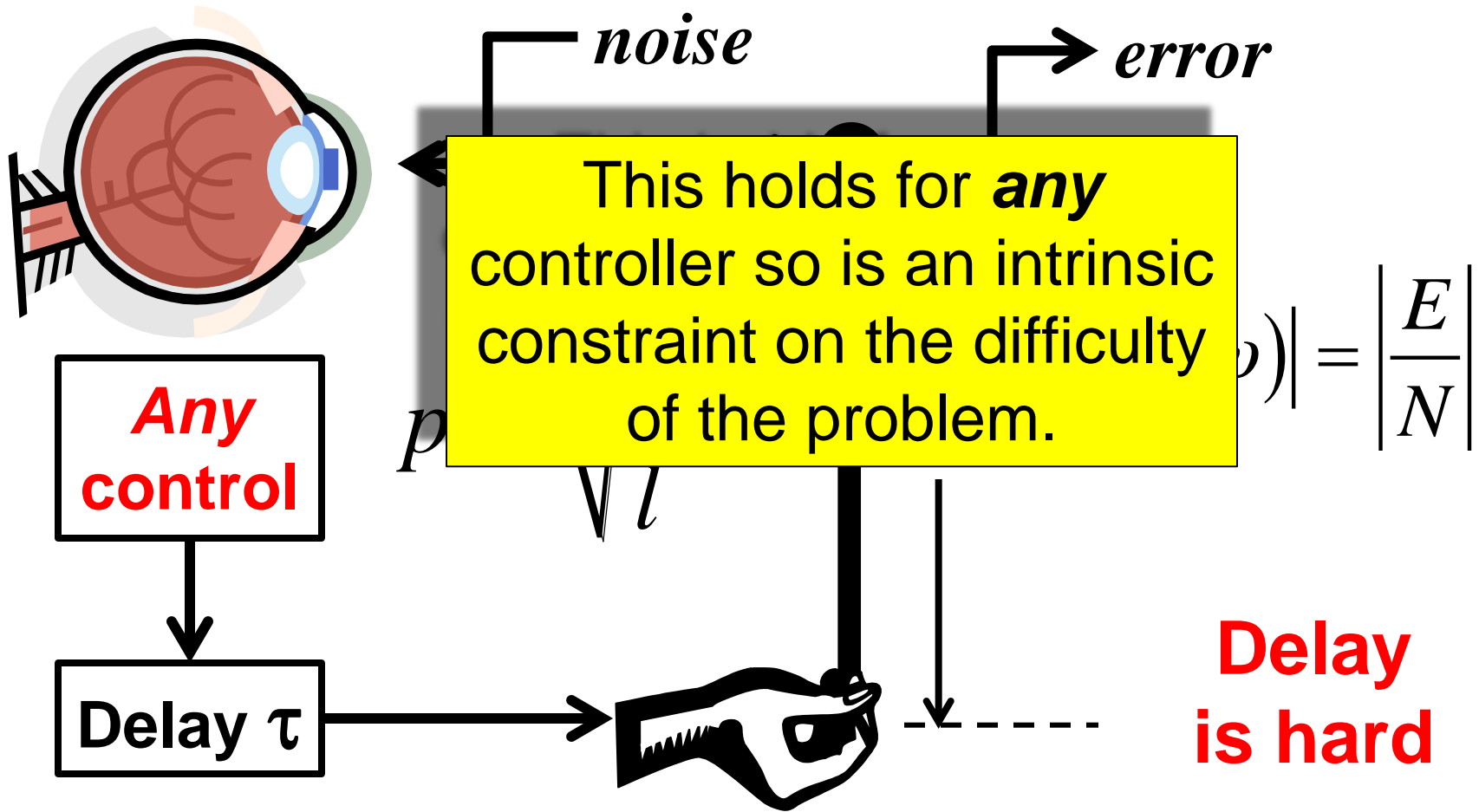
$$r = \frac{m}{M}$$







$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq \ln |T_{mp}(p)| = p\tau \propto \tau \sqrt{\frac{1}{l}}$$



$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq \ln |T_{mp}(p)| = p\tau \propto \tau \sqrt{\frac{1}{l}}$$

$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq p\tau \propto \tau \sqrt{\frac{1}{l}}$$

Fragility

$$\tau \sqrt{\frac{1}{l}}$$

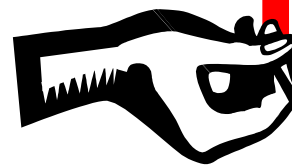
Too fragile

For fixed length

L

up

down



large τ
small $1/\tau$

small τ
large $1/\tau$

$1/\text{delay}$

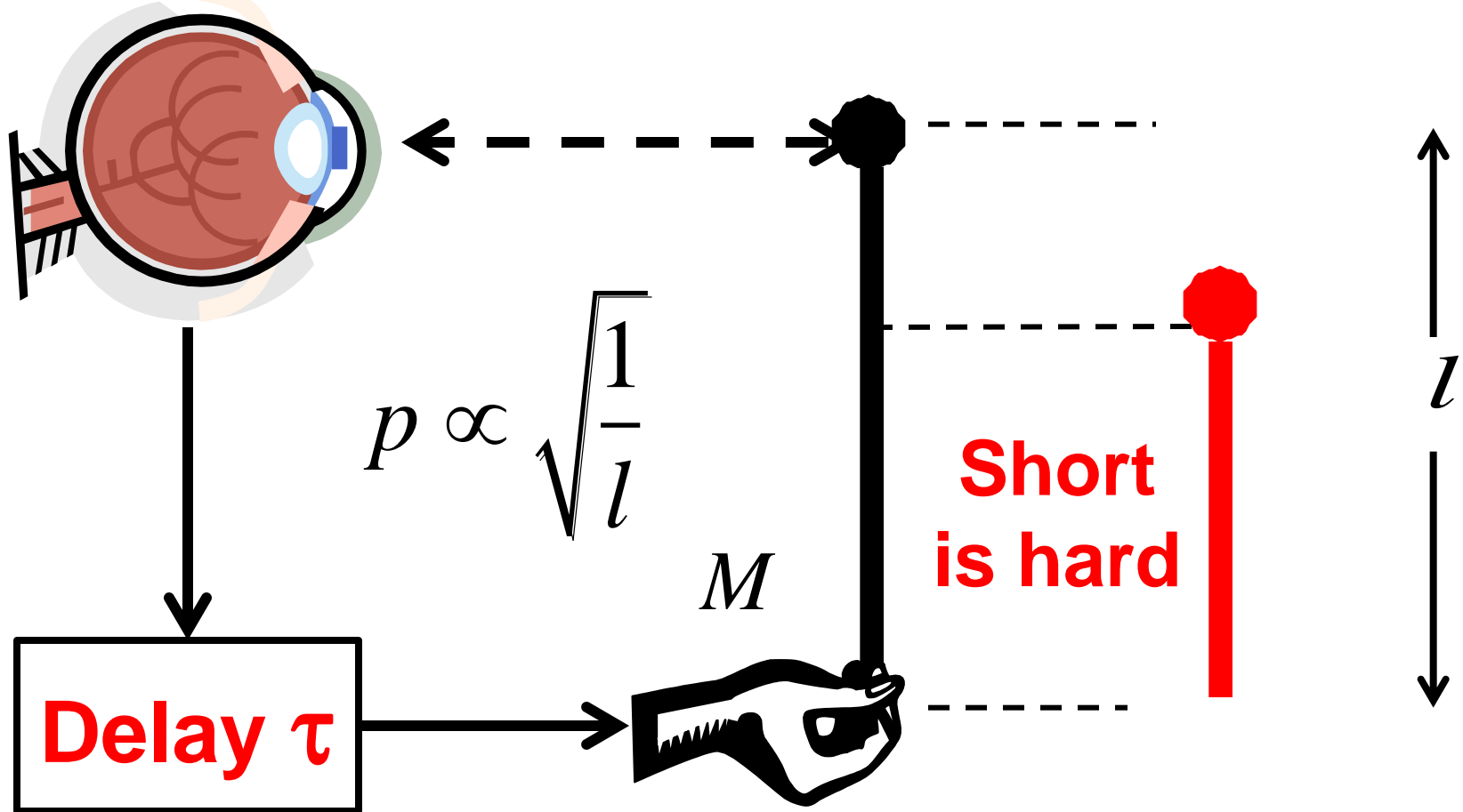
$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq p\tau \propto \tau \sqrt{\frac{1}{l}}$$

We would like to tolerate large delays (and small lengths), but large delays severely constrain the achievable robustness.



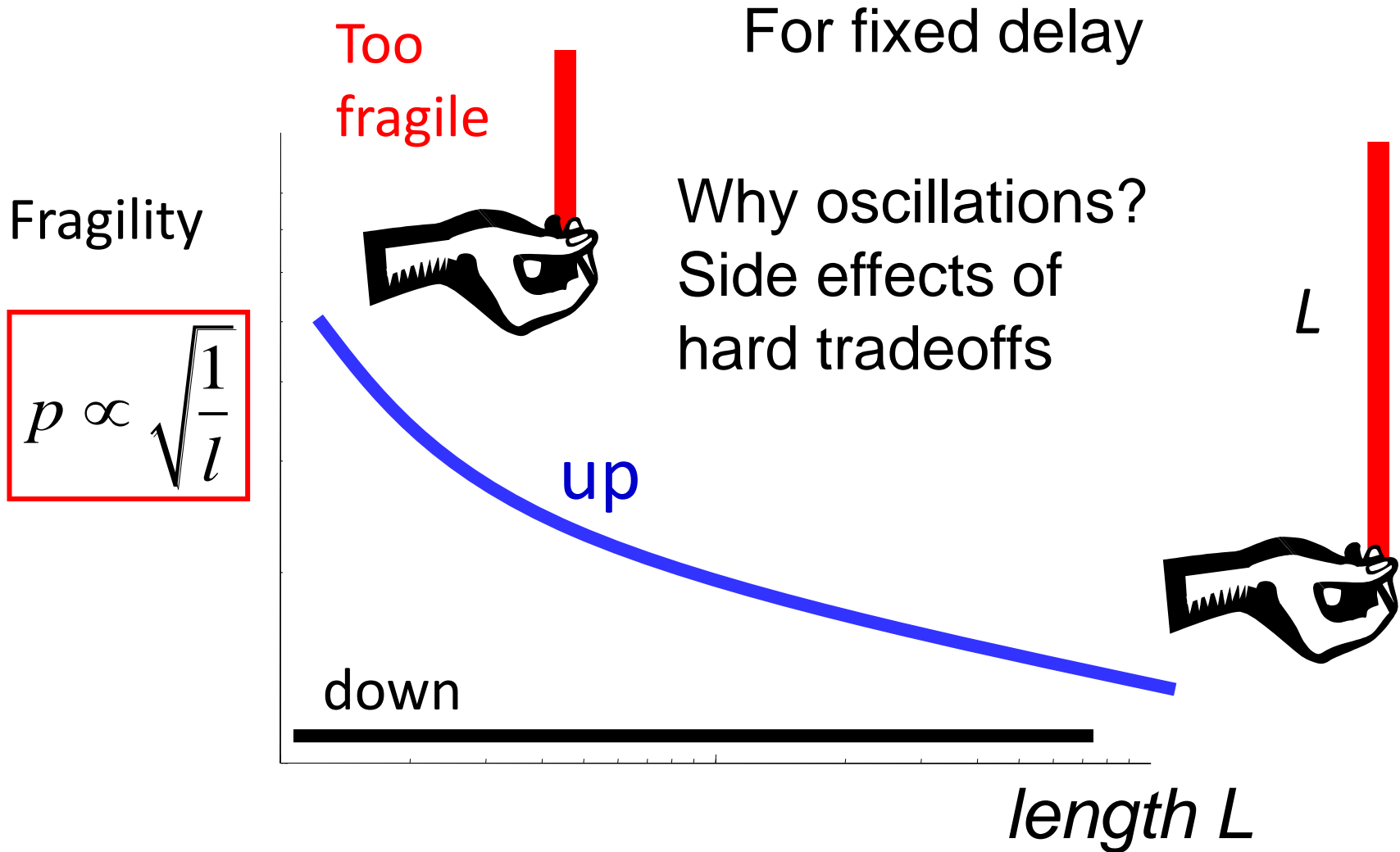
large τ
small $1/\tau$

small τ
large $1/\tau$

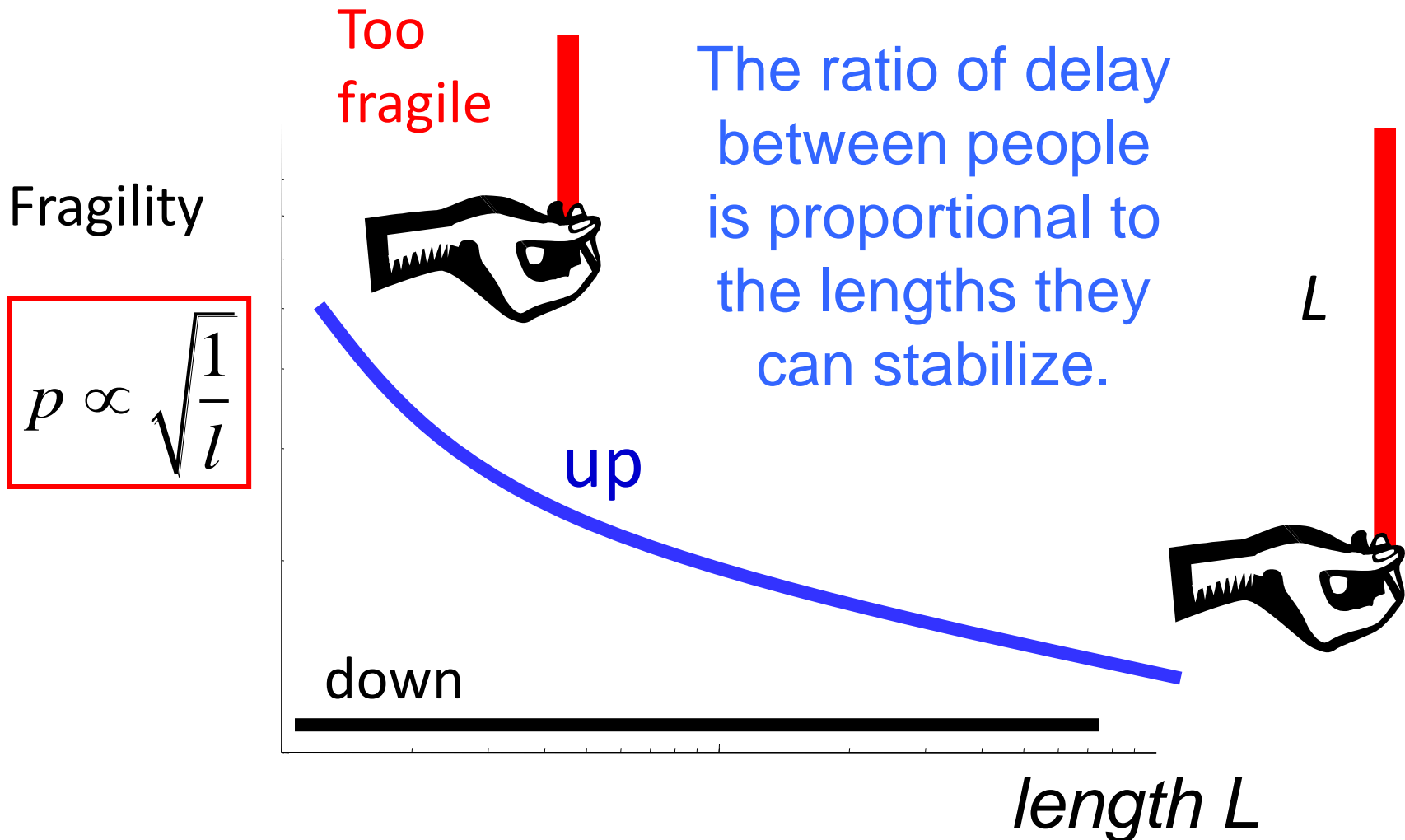


$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq \ln |T_{mp}(p)| = p\tau \propto \tau \sqrt{\frac{1}{l}}$$

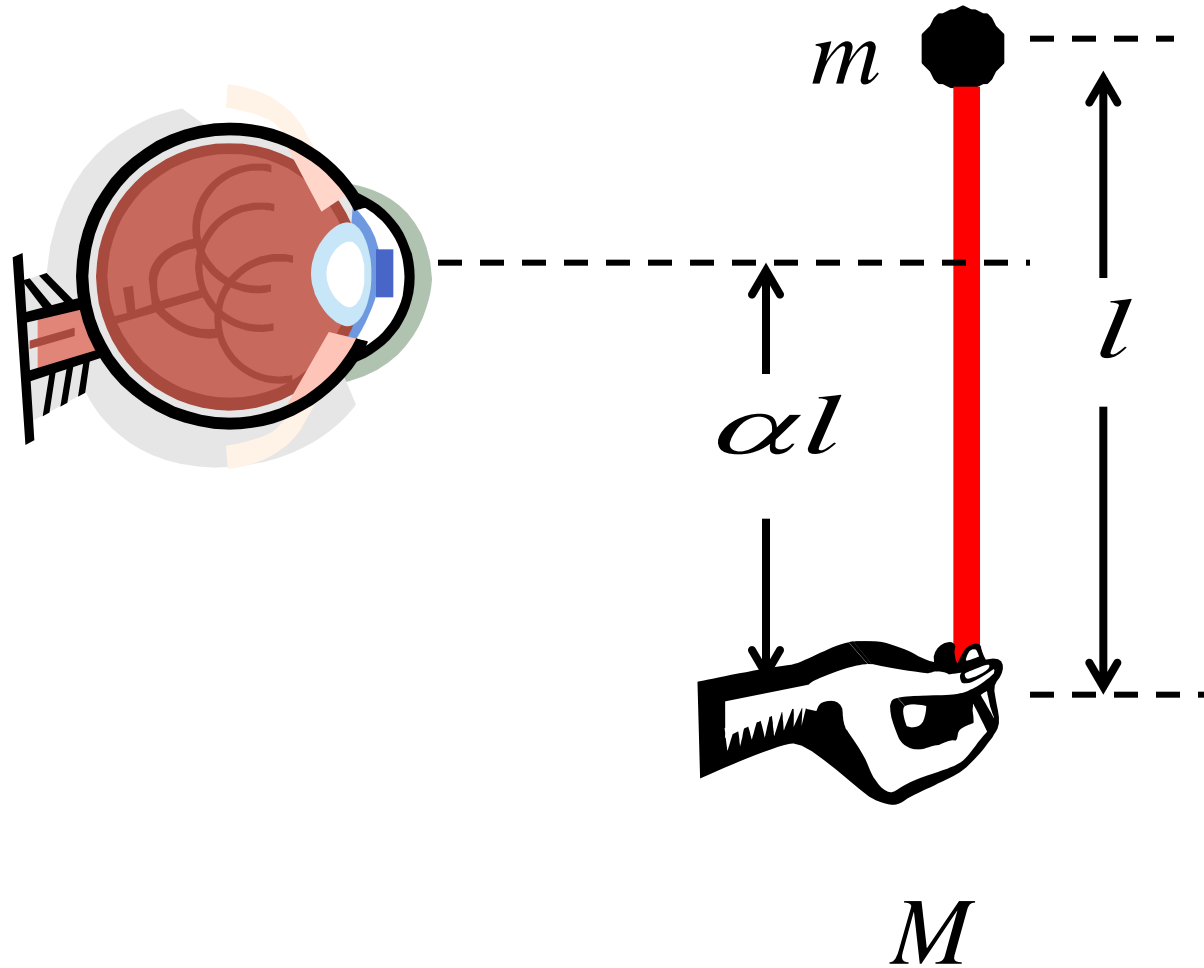
$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq \ln |T_{mp}(p)| = p\tau \propto \tau \sqrt{\frac{1}{l}}$$



$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq \ln |T_{mp}(p)| = p\tau \propto \tau \sqrt{\frac{1}{l}}$$

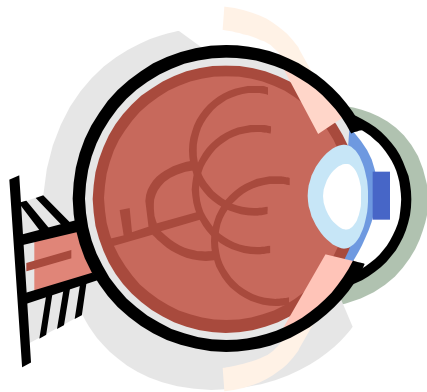


Eyes moved down is harder
(RHP zero)
Similar to delay

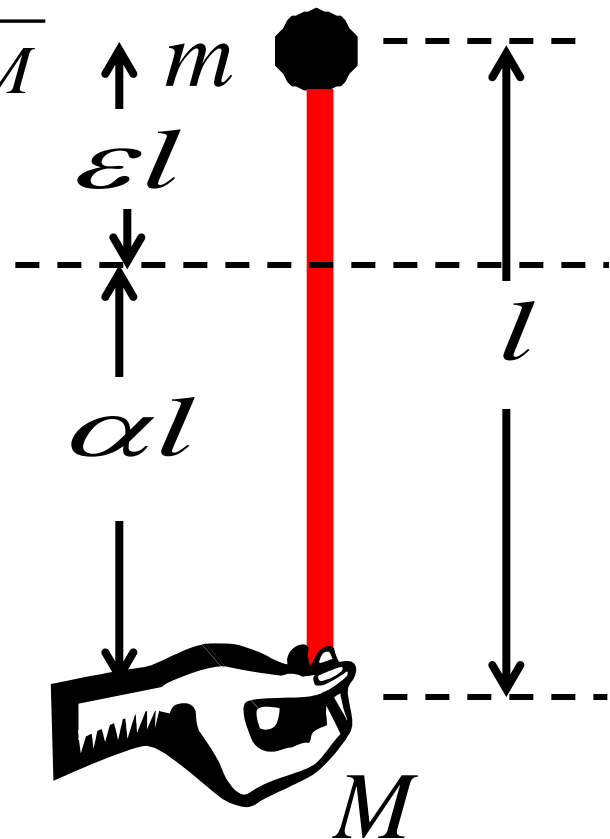


Suppose $r = \frac{m}{M} \ll 1$

Units $\Rightarrow M = g = 1$



$$r = \frac{m}{M}$$



$$y = x + \alpha l \theta = \frac{\varepsilon l s^2 \pm g}{s^2 (l s^2 \pm g)} \quad \varepsilon = 1 - \alpha$$

$$p \approx \sqrt{\frac{g}{l}} \quad z = \sqrt{\frac{g}{l}} \sqrt{\frac{1}{\varepsilon}} \Rightarrow \frac{z + p}{z - p} = \frac{1 + \sqrt{\varepsilon}}{1 - \sqrt{\varepsilon}}$$

Compare

$$p = \sqrt{\frac{g}{l(1-\varepsilon)}} \sqrt{1+r} = p_0 \sqrt{\frac{1}{(1-\varepsilon)}} \approx p_0 \left(1 + \frac{\varepsilon}{2}\right)$$

Move eyes

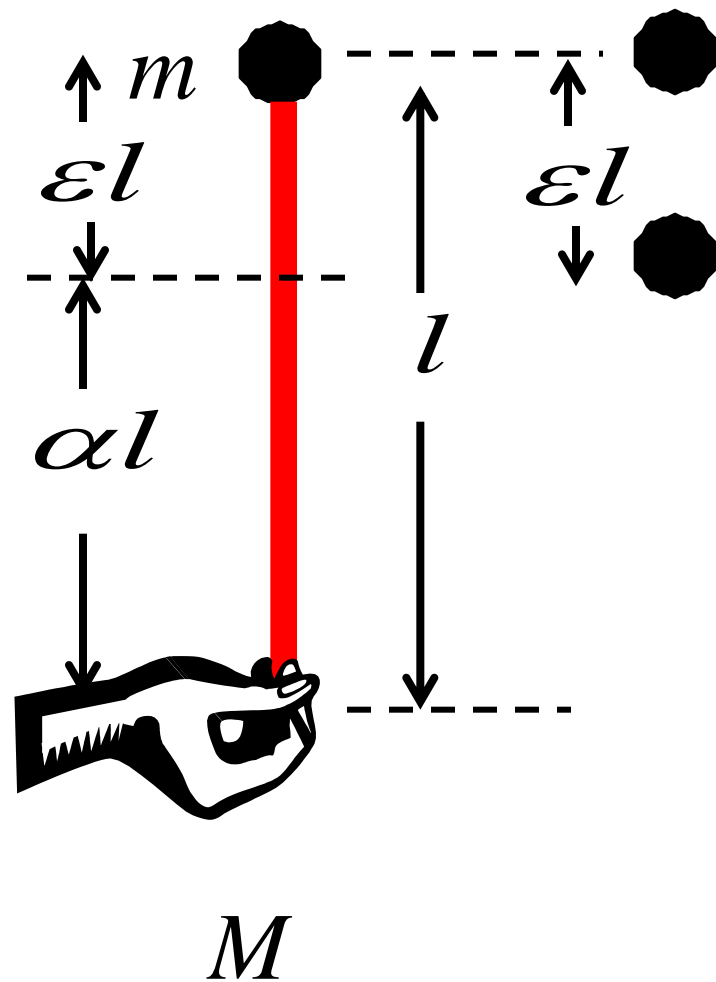
$$p = \sqrt{\frac{g}{l}} \sqrt{1+r} \quad r = \frac{m}{M} \quad z = \sqrt{\frac{g}{l}} \sqrt{\frac{1}{\varepsilon}}$$

$$p = z \Rightarrow 1+r = \frac{1}{\varepsilon} \Rightarrow \varepsilon = \frac{1}{1+r}$$

$$p \left(1 + \frac{1}{3} \frac{p^2}{z^2}\right) = \sqrt{\frac{g}{l}} \sqrt{1+r} \left(1 + \frac{1}{3} \varepsilon\right) = p \left(1 + \frac{\varepsilon}{3}\right)$$

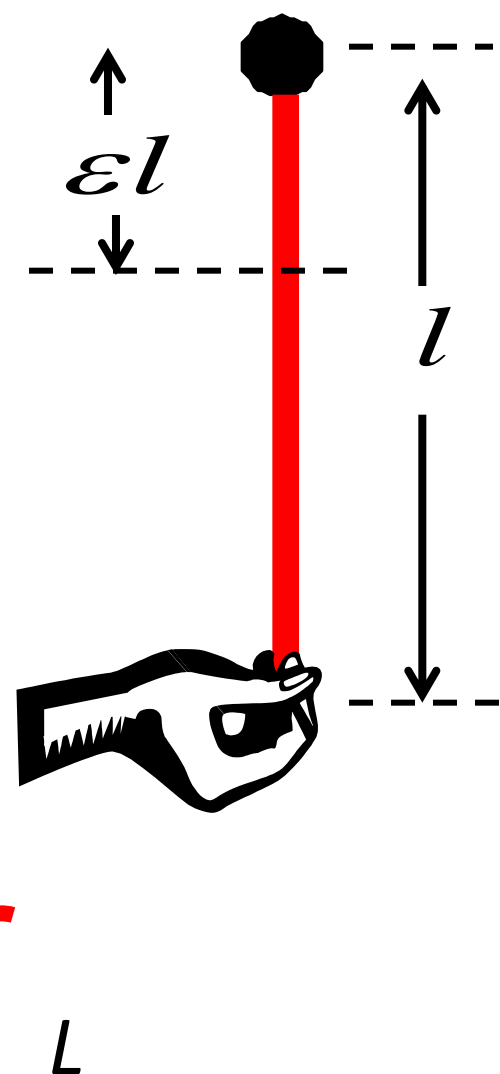
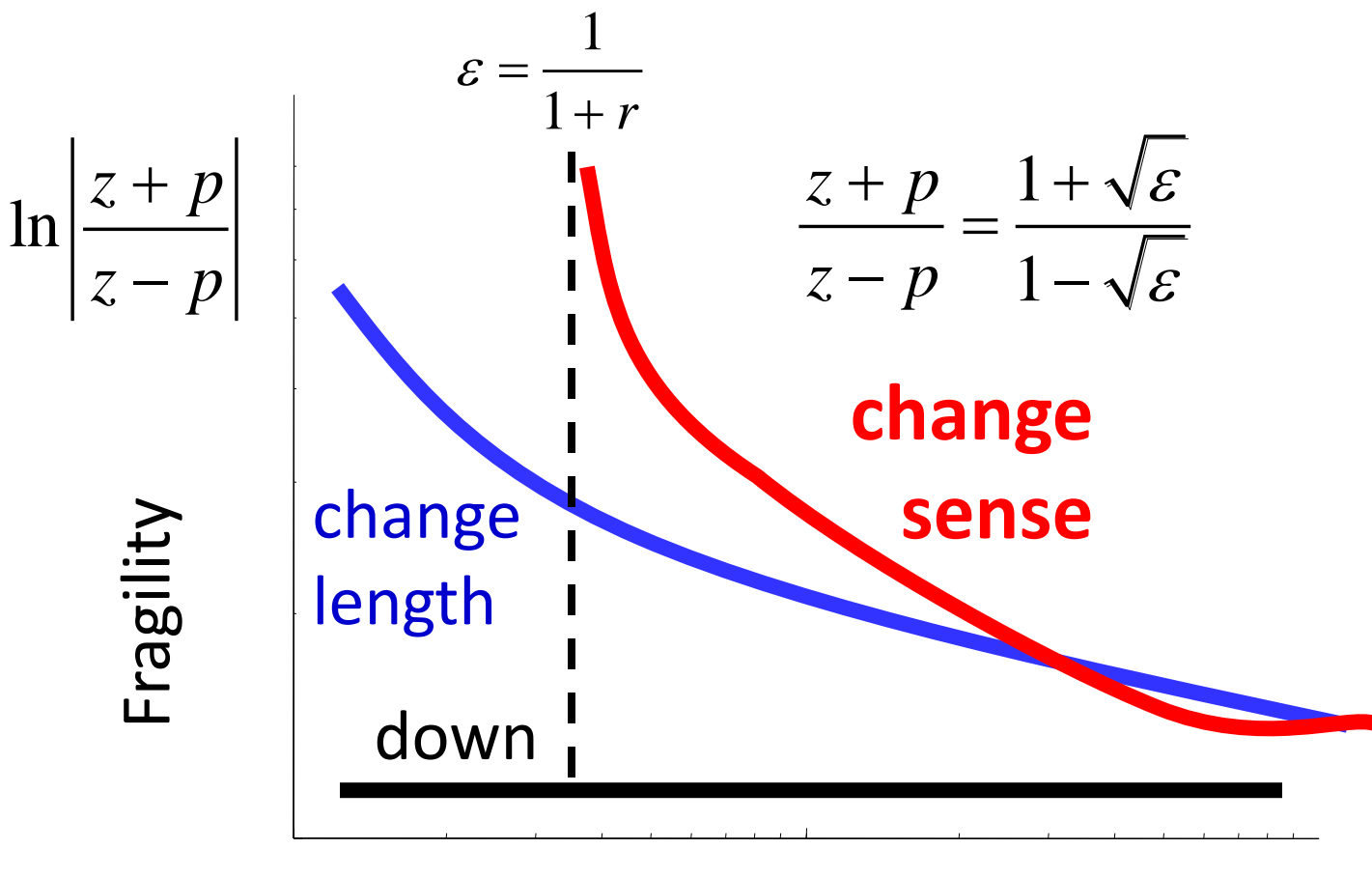
$$= p \left(1 + \frac{1-\alpha}{3}\right)$$

$$r = \frac{m}{M}$$



$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{2z}{z^2 + \omega^2} \right) d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$

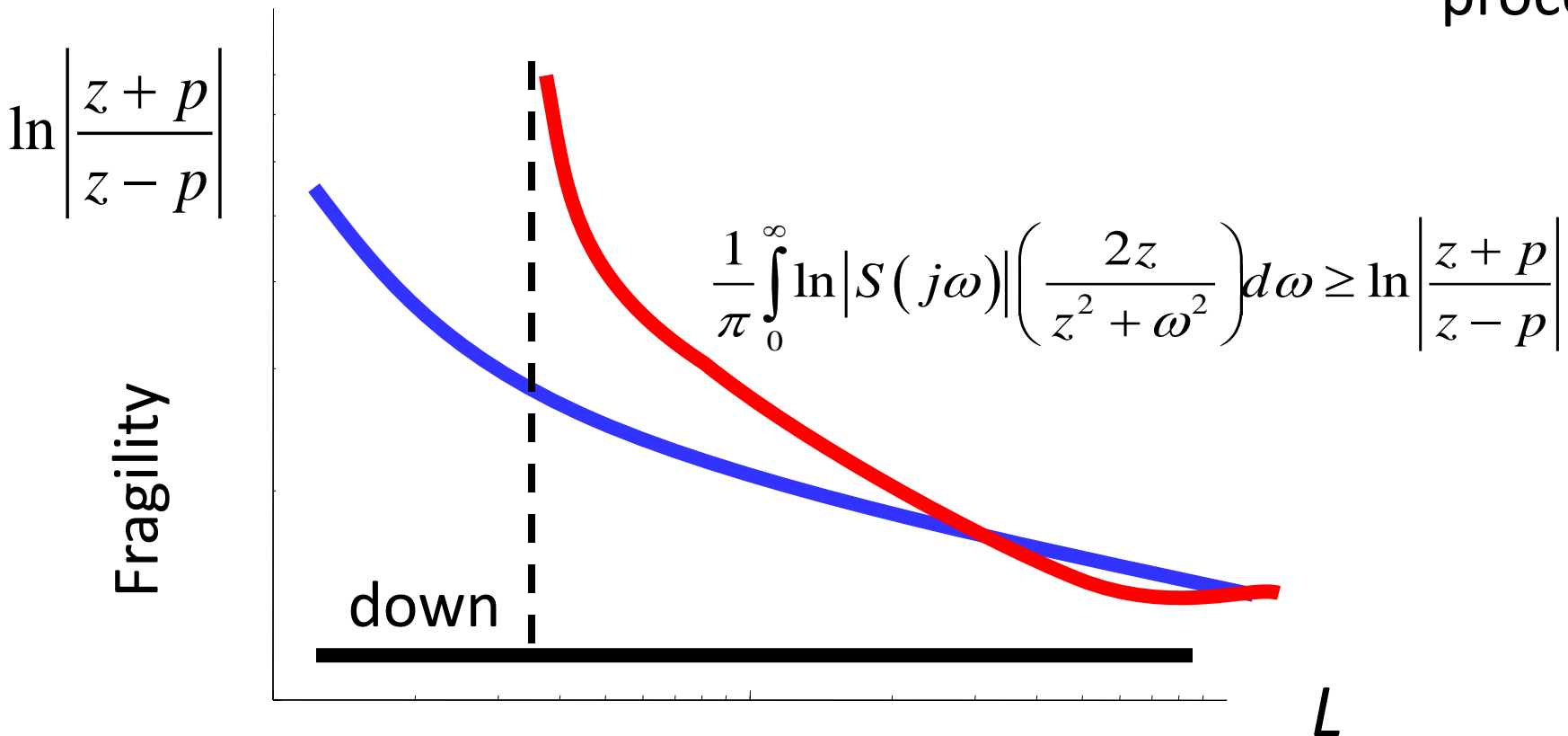
$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \left(\frac{2p}{p^2 + \omega^2} \right) d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$



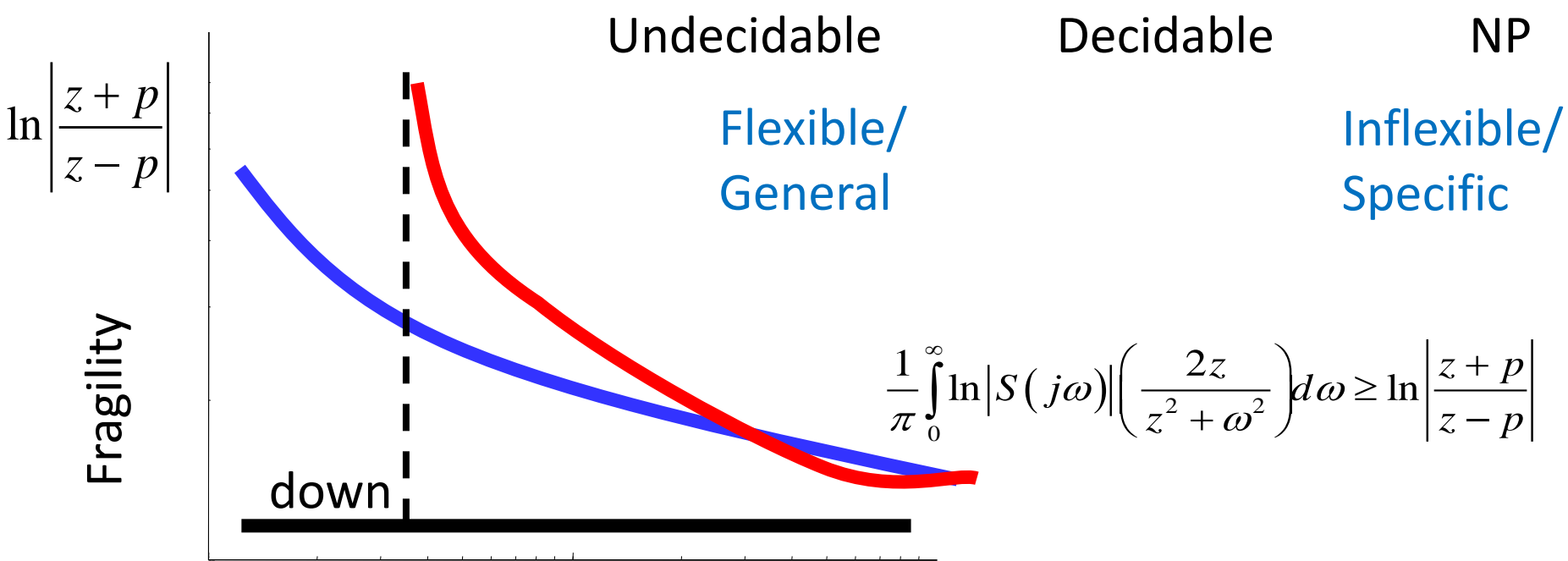
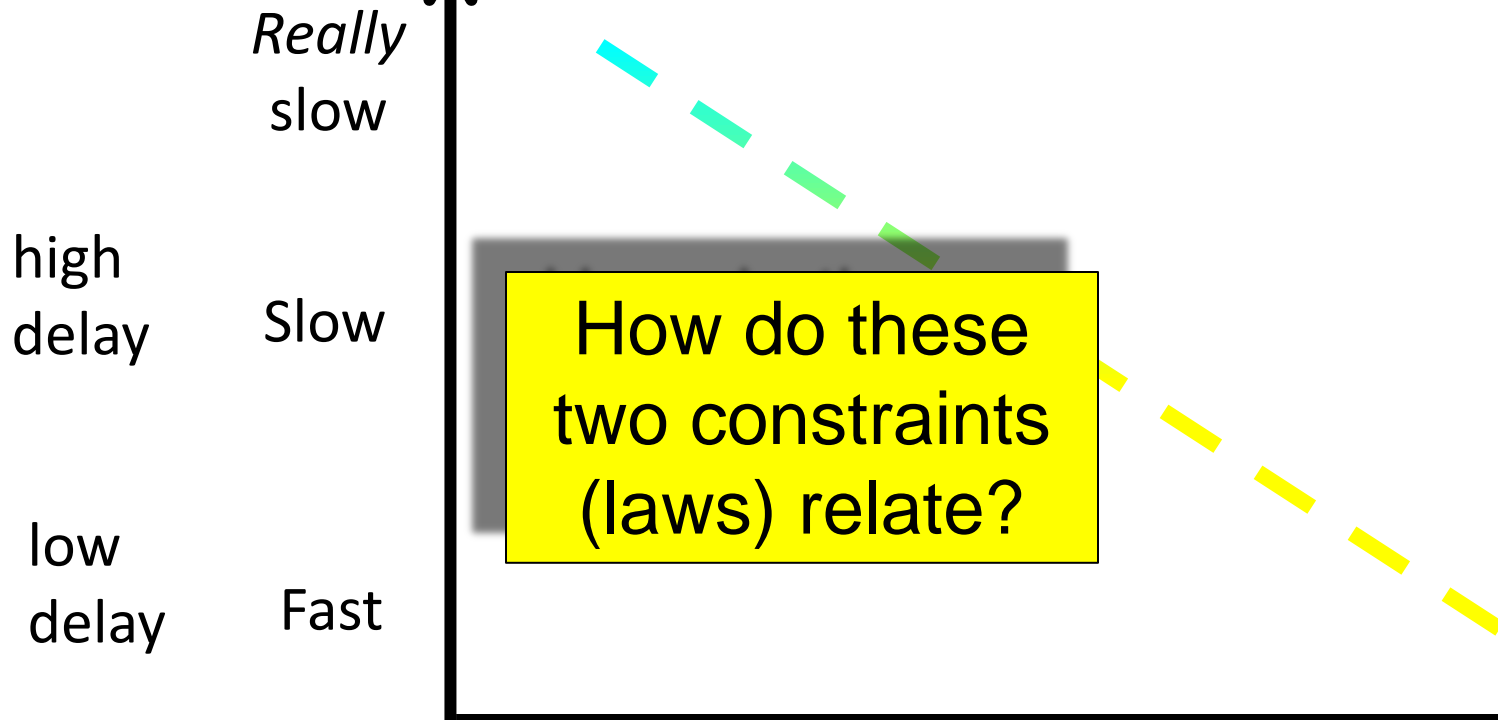
This is a cartoon, but can be made precise.

Hard limits on the *intrinsic* robustness of control *problems*.

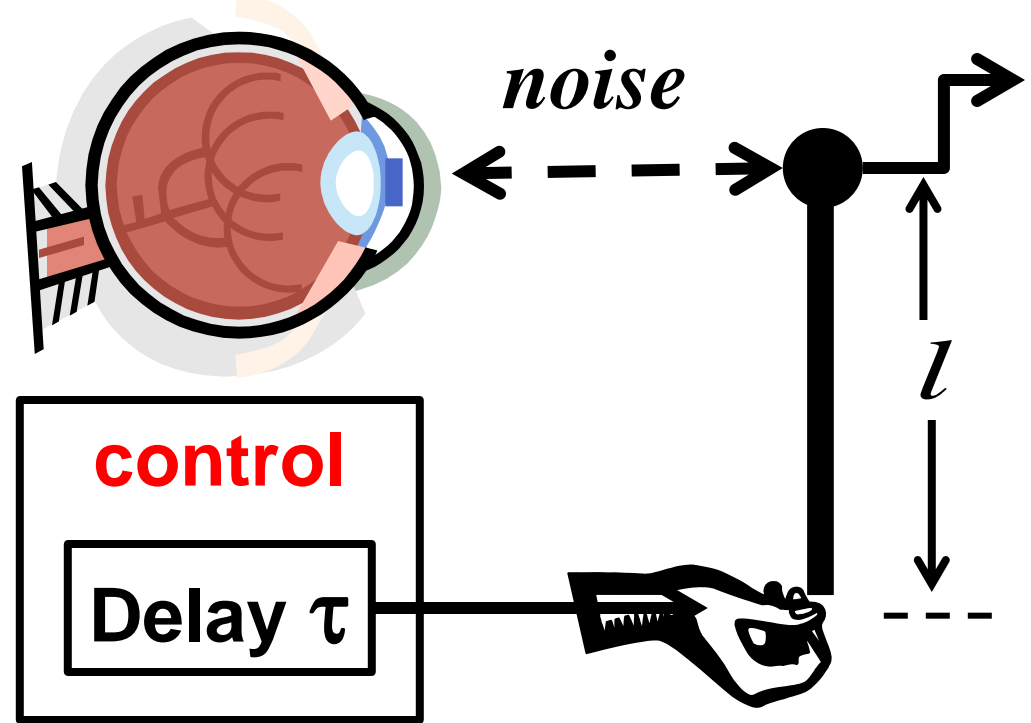
Must (and do) have algorithms that achieve the limits, and architectures that support this process.



This is a cartoon, but can be made precise.

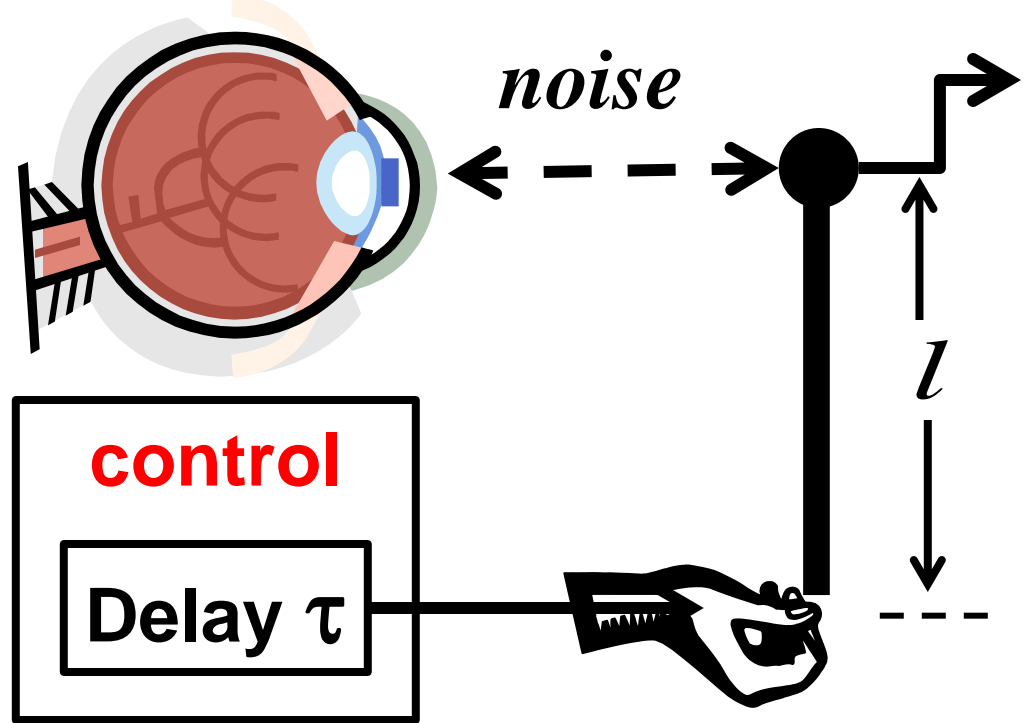


Delay comes from sensing, communications, computing, and actuation. Delay limits robust performance.



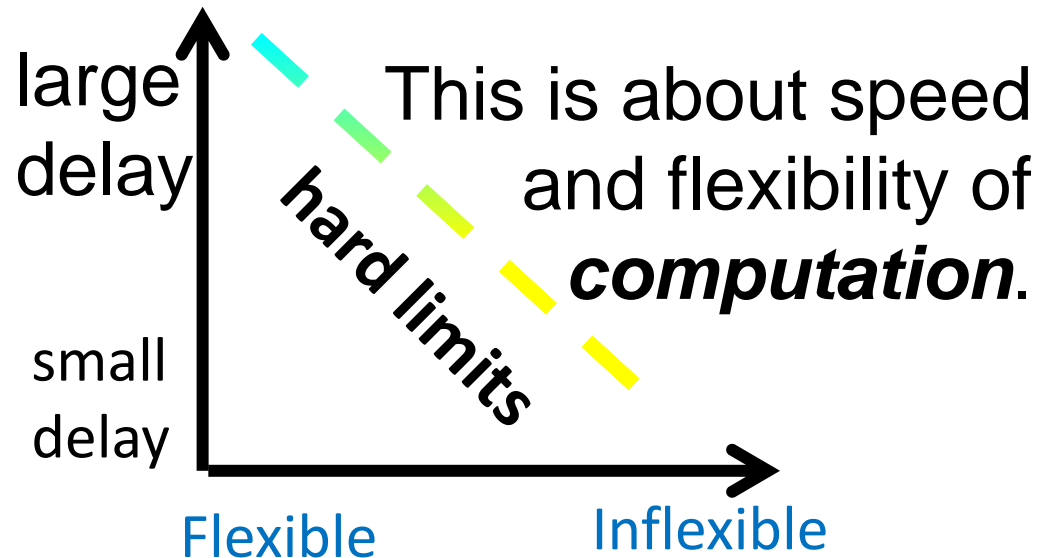
$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq \ln |T_{mp}(p)| = p\tau \propto \tau \sqrt{\frac{1}{l}}$$

How do these two constraints (laws) relate?



Computation delay adds to total delay.

Computation is a component in control.



Delay makes control hard.

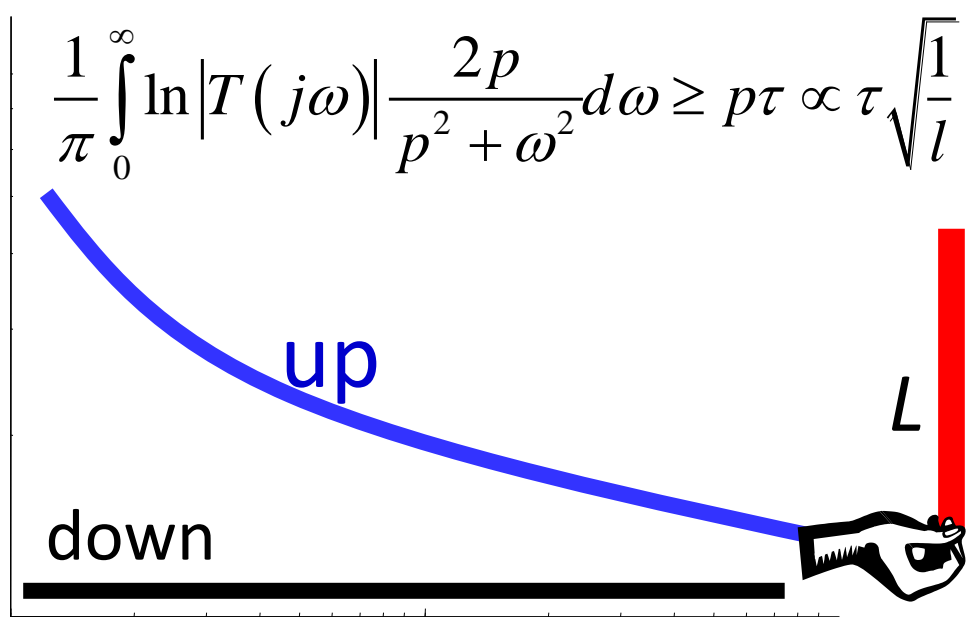


Computation delay adds to total delay.

Computation is a component in control.

Fragility

$$\tau \sqrt{\frac{1}{l}}$$



large τ

small τ

large delay

small delay

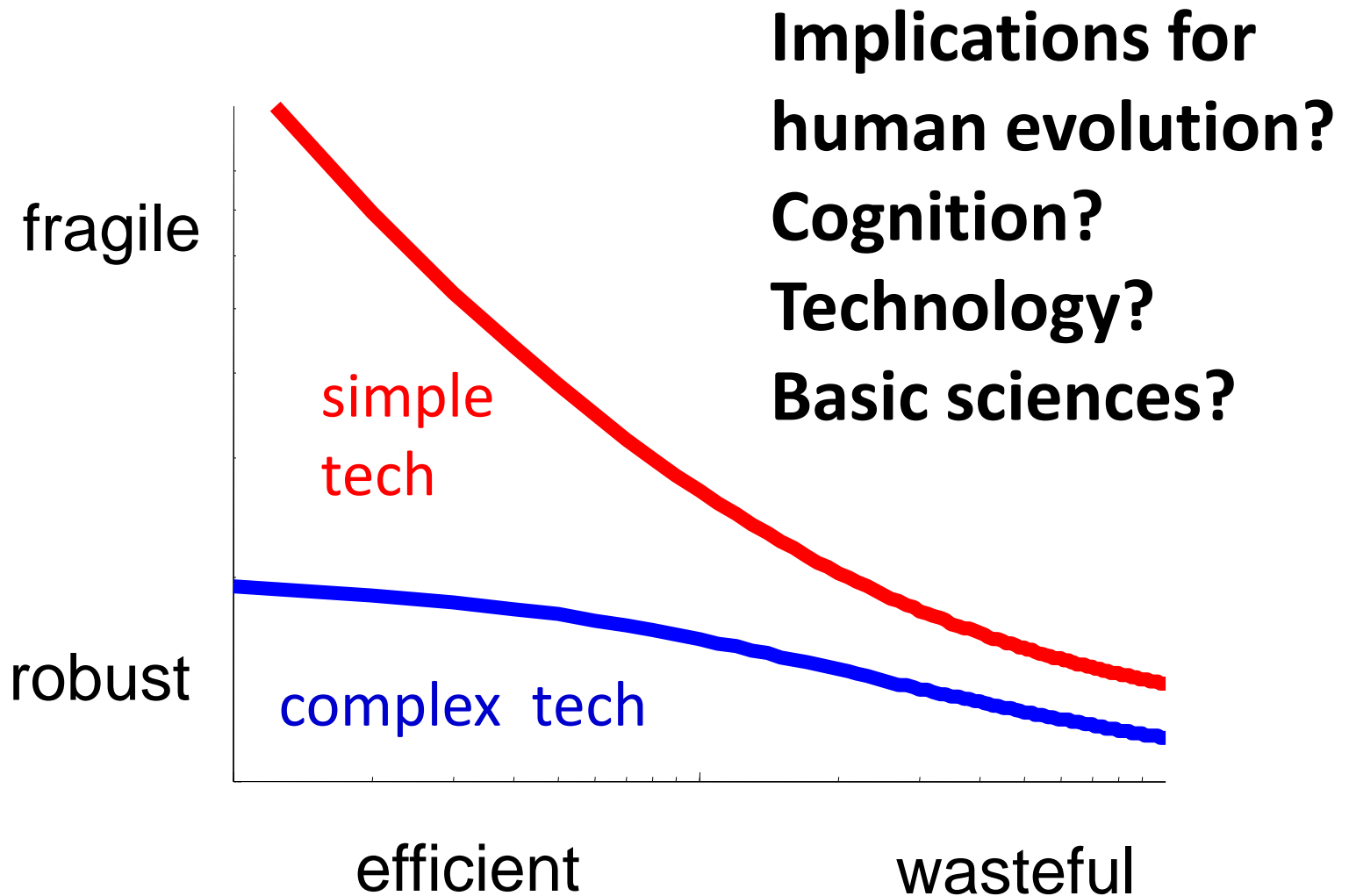
Flexible

Inflexible

hard limits

computation

How general is this picture?



Viruses' Life History: Towards a Mechanistic Basis of a Trade-Off between Survival and Reproduction among Phages

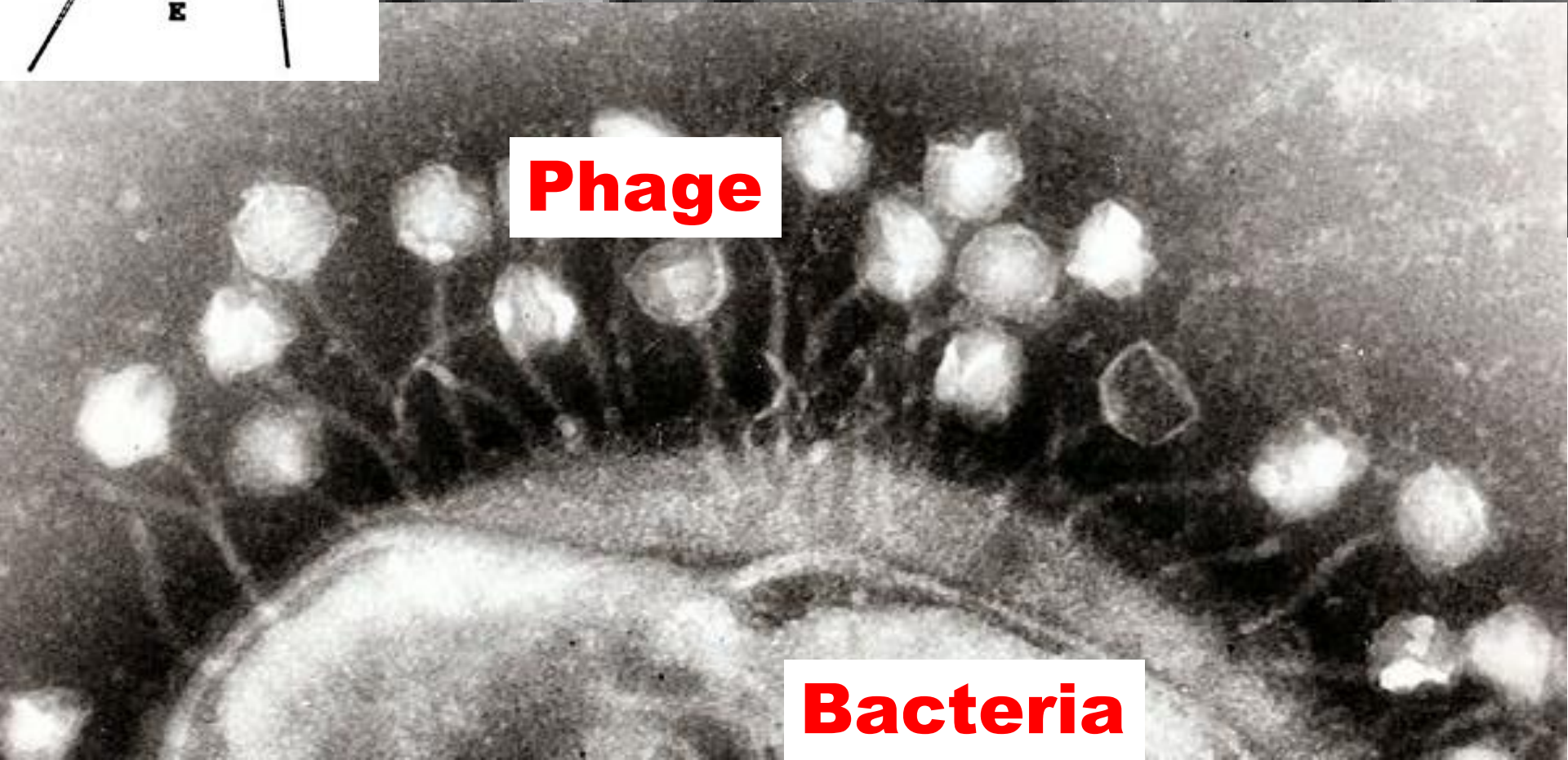
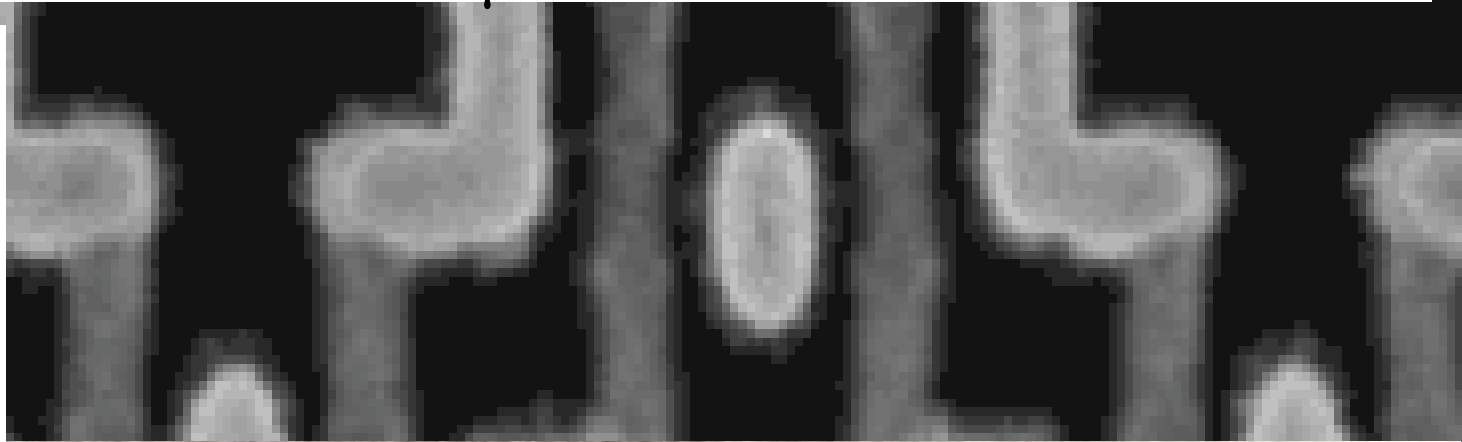
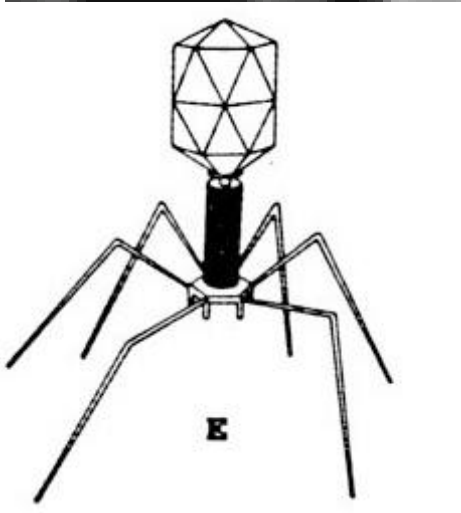
Marianne De Paepe, François Taddei*

Laboratoire de Genetique Moleculaire, Evolutive et Medicale, University of Paris 5, INSERM, Paris, France

July 2006 | Volume 4 | Issue 7 | e193

I recently found this paper, a rare example of exploring an explicit tradeoff between robustness and efficiency. This seems like an important paper but it is rarely cited.

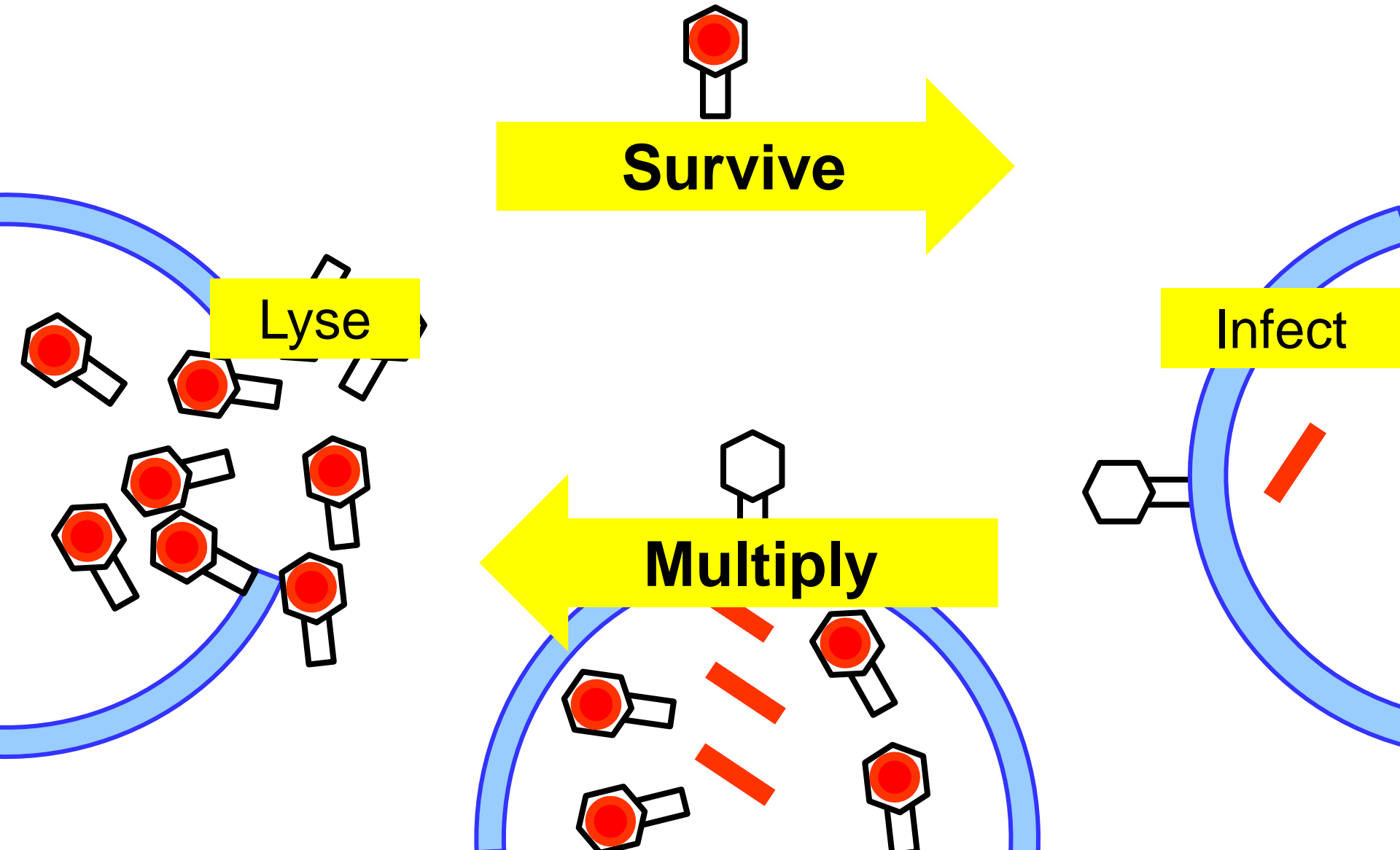
1 μm

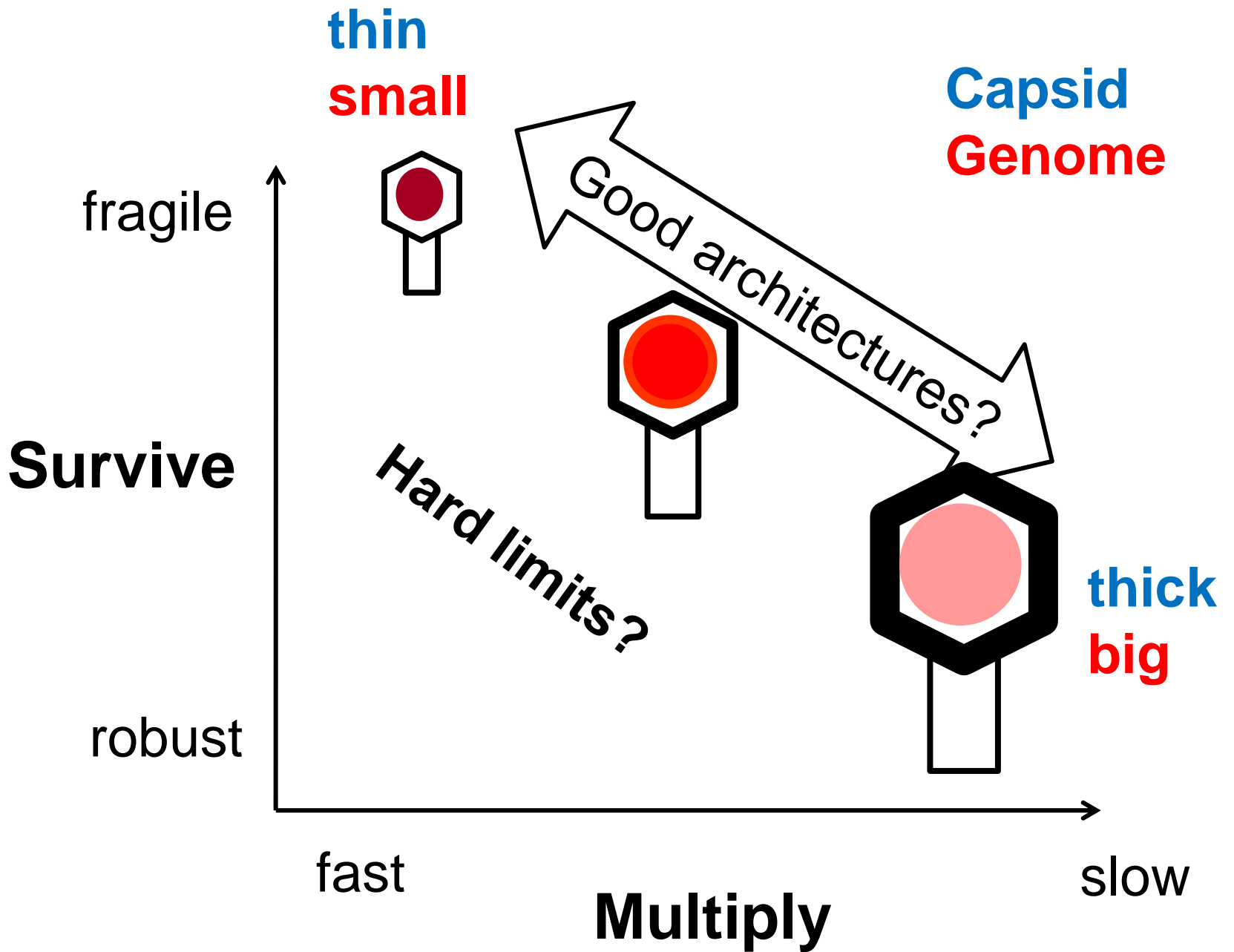


Phage

Bacteria

Phage lifecycle





Glycolytic Oscillations and Limits on Robust Efficiency

Fiona A. Chandra,^{1*} Gentian Buzi,² John C. Doyle²

Both engineering and evolution are constrained by trade-offs between efficiency and robustness, but theory that formalizes this fact is limited. For a simple two-state model of glycolysis, we explicitly derive analytic equations for hard trade-offs between robustness and efficiency with oscillations as an inevitable side effect. The model describes how the trade-offs arise from individual parameters, including the interplay of feedback control with autocatalysis of network products necessary to power and catalyze intermediate reactions. We then use control theory to prove that the essential features of these hard trade-off “laws” are universal and fundamental, in that they depend minimally on the details of this system and generalize to the robust efficiency of any autocatalytic network. The theory also suggests worst-case conditions that are consistent with initial experiments.

Chandra, Buzi, and Doyle

Most important paper so far.

UG biochem, math, control theory

the cell's use of ATP. In glycolysis, two ATP molecules are consumed upstream and four are produced downstream, which normalizes to $q = 1$ (each y molecule produces two downstream) with kinetic exponent $a = 1$. To highlight essential trade-offs with the simplest possible analysis, we normalize the concentration such that the unperturbed ($\delta = 0$) steady states are $\bar{y} = 1$ and $\bar{x} = 1/k$ [the system can have one additional steady state, which is unstable when $(1, 1/k)$ is stable]. [See the supporting online material (SOM) part I]. The basal rate of the PFK reaction and the consumption rate have been normalized to 1 (the 2 in the numerator and feedback coefficients of the reactions come from these normalizations). Our results hold for more general systems as discussed below and in SOM, but the analysis



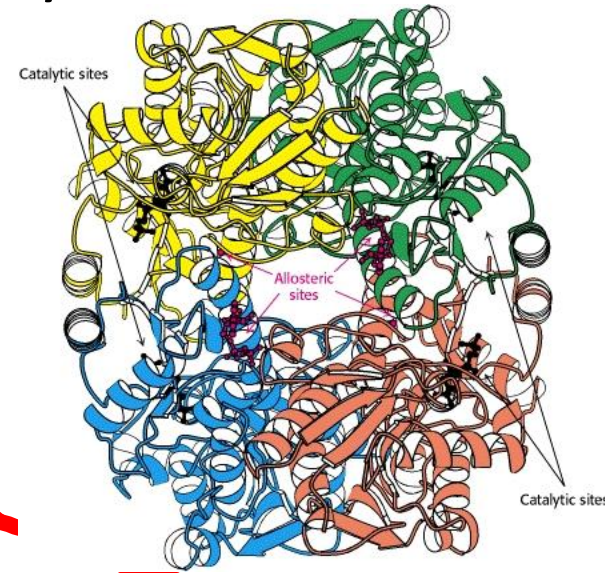
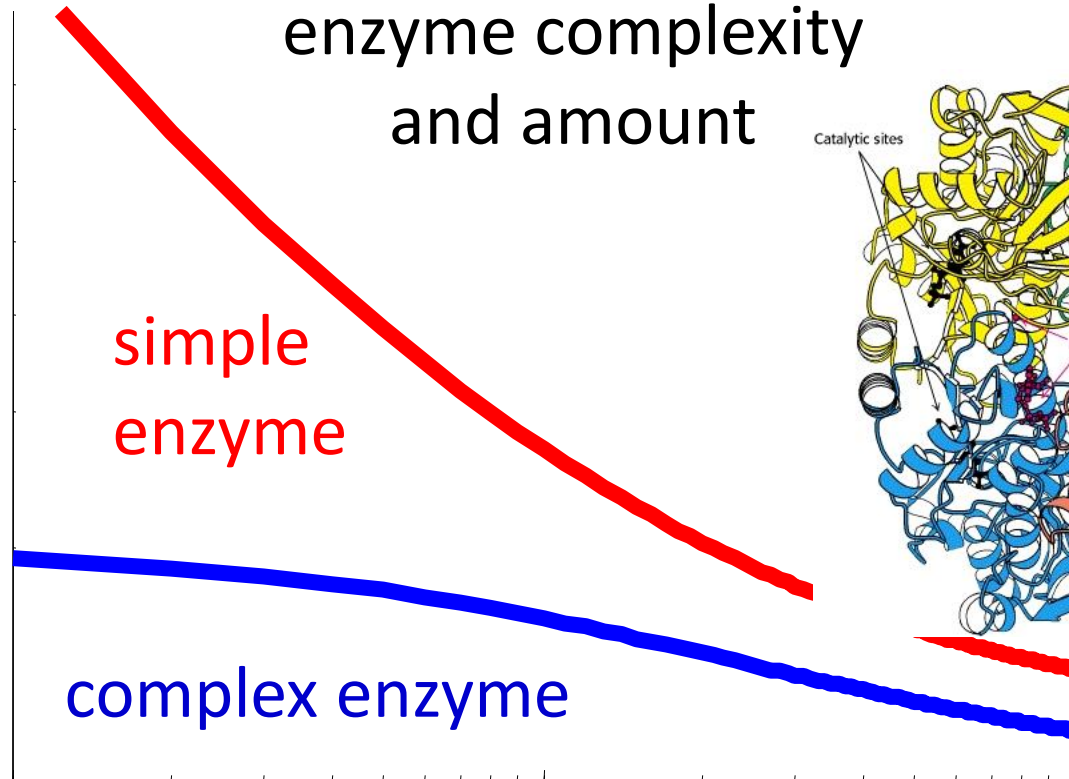
Theorem!

$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$

z and p functions of enzyme complexity and amount

Fragility

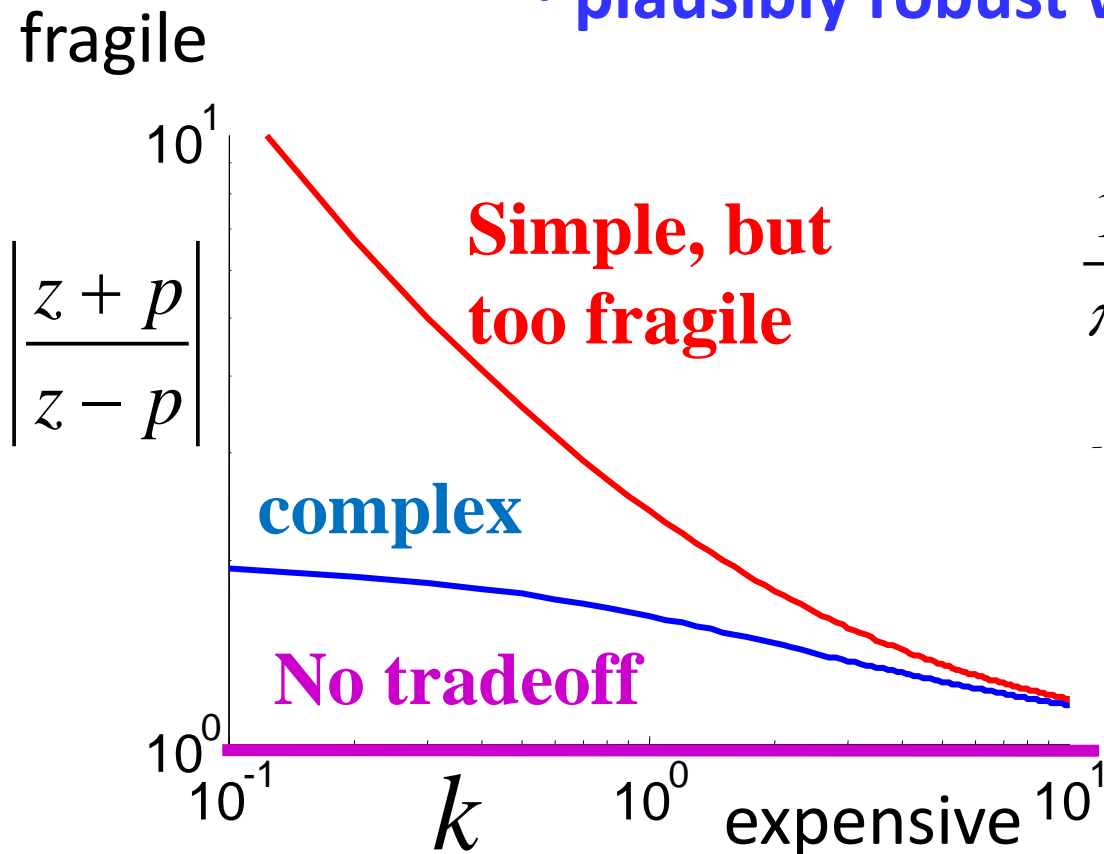
$$\ln \left| \frac{z+p}{z-p} \right|$$



Enzyme amount

Hard tradeoff in glycolysis is

- **robustness vs efficiency**
- **absent without autocatalysis**
- **too fragile with simple control**
- **plausibly robust with complex control**



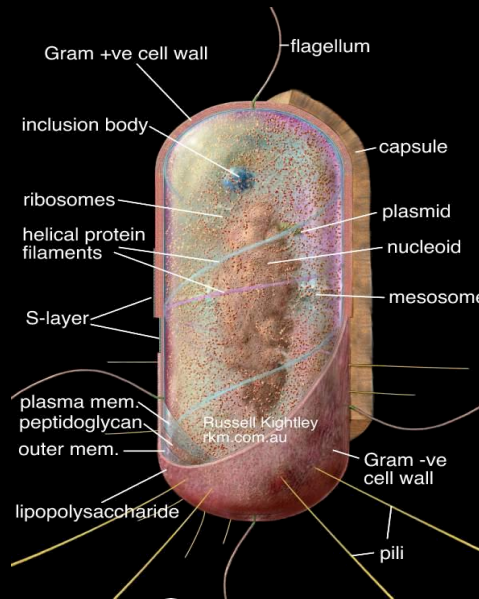
$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega$$

$$\geq \ln \left| \frac{z+p}{z-p} \right|$$

System

“Emergent”:
“Nontrivial”
consequences
of other
constraints

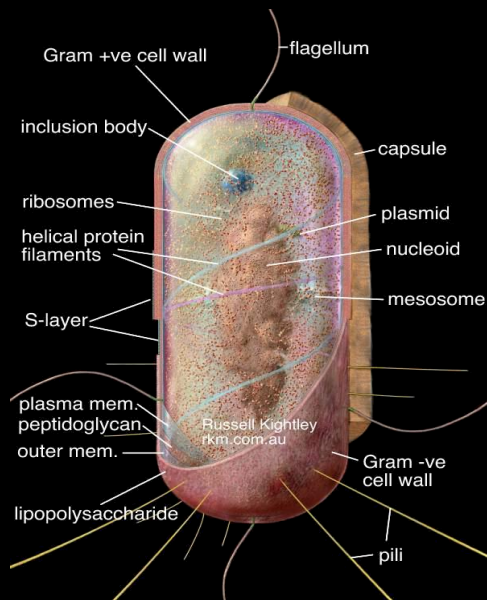
Architecture =Constraints



Protocols

Components

Systems requirements: Survive in hostile environments



Constraints

Components and materials: “Chemistry”

Constrained (“conserved”):

Moieties

1. NAD
2. Adenylate
3. Carbon
4. phosphate
5. oxygen
6. Oxidized state of metabolites
7. Reduced state of metabolites
8. High energy potential release

Constraints

**Components and materials:
“Chemistry”**

Bacterial biosphere

- carriers: ATP, NADH, etc
- Precursors, ...
- Enzymes
- Translation
- Transcription
- Replication
- ...



Protocols

Architecture = protocols
= “constraints that deconstrain”

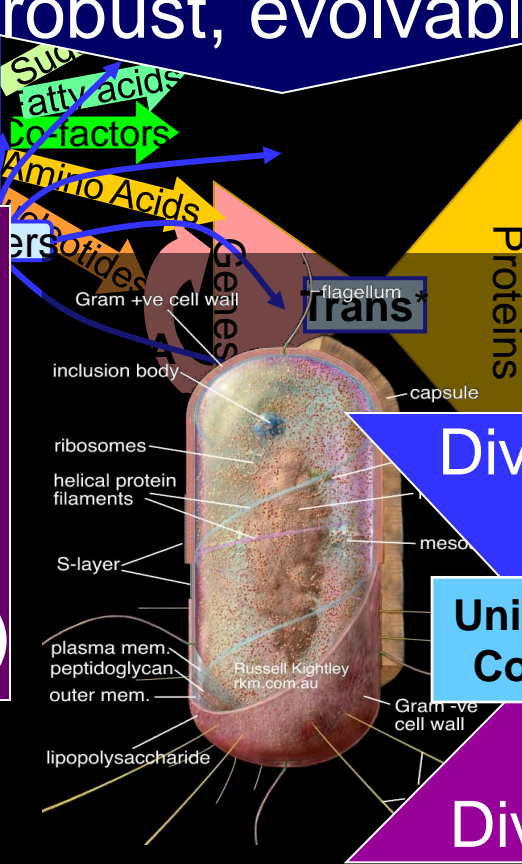
Systems requirements:
functional, efficient,
robust, evolvable

Hard constraints:
Thermo (Carnot)
Info (Shannon)
Control (Bode)
Compute (Turing)

Constraints

Components and materials:
Energy, moieties

Protocols



Systems requirements:
functional, efficient,
robust, evolvable

Constrained (“conserved”):
Moieties

1. NAD
2. Adenylate
3. Carbon
4. phosphate
5. oxygen
6. Oxidized state of metabolites
7. Reduced state of metabolites
8. High energy potential release

Protocols

$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega$$
$$\geq \ln \left| \frac{z+p}{z-n} \right|$$

Constraints

Components and materials:
Energy, moieties

Inside every cell

Catabolism

Precursors

ATP

AA

Nucl.

Enzymes

almost

Macro-layers

Building Blocks

AA

transl.

Proteins

ATP

Ribosome

RNA

transc.

xRNA

RNAP

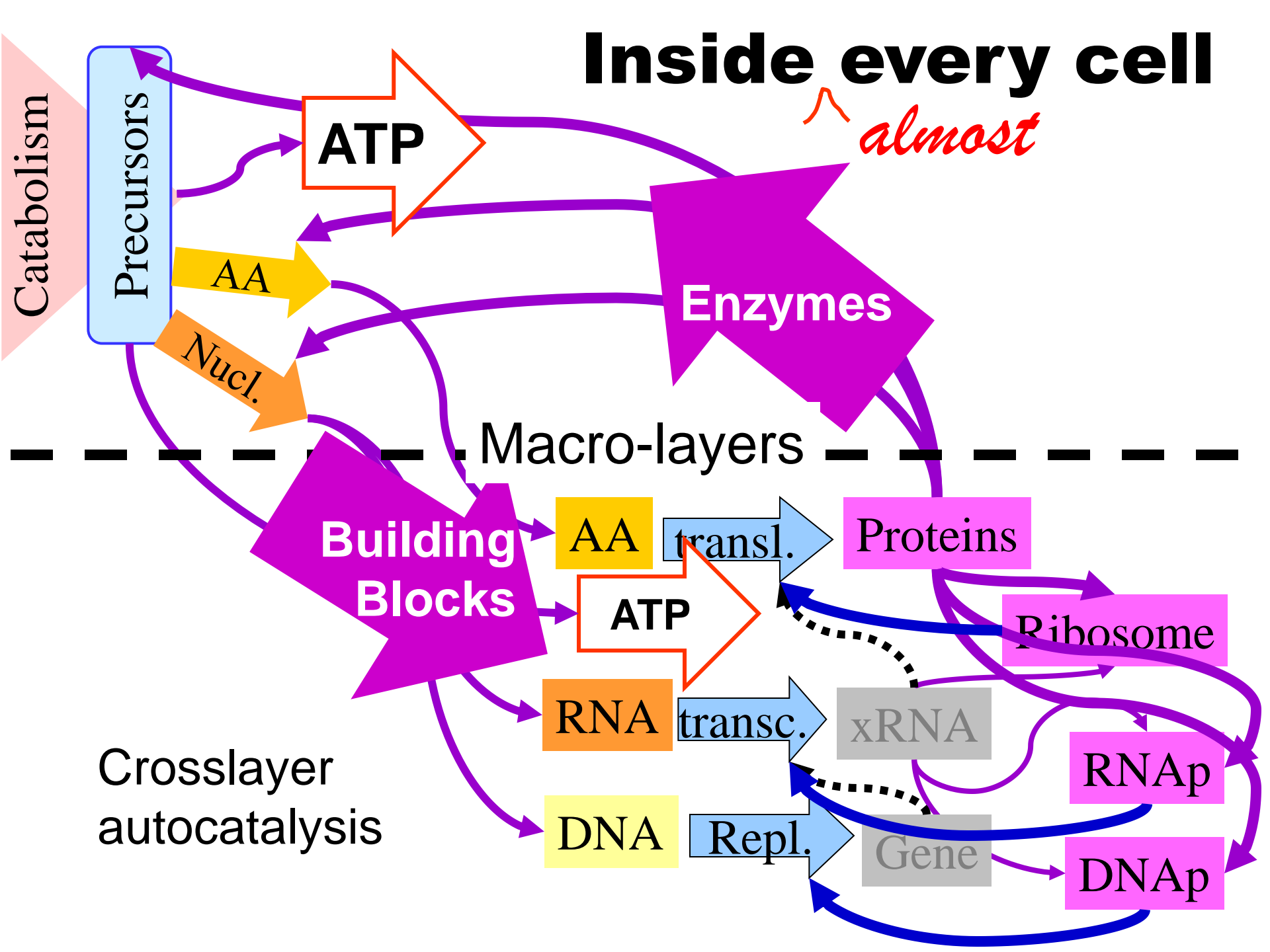
DNA

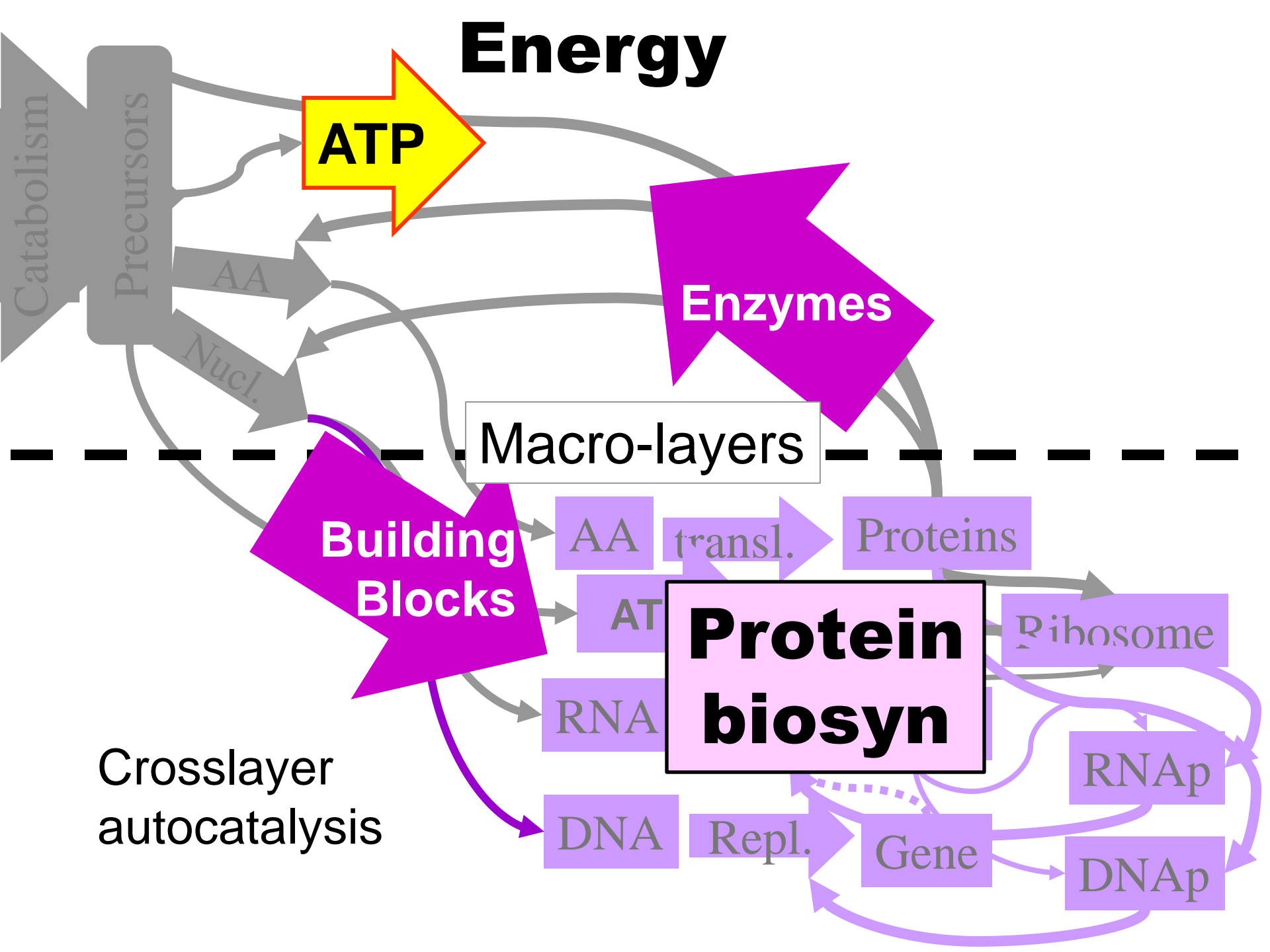
Repl.

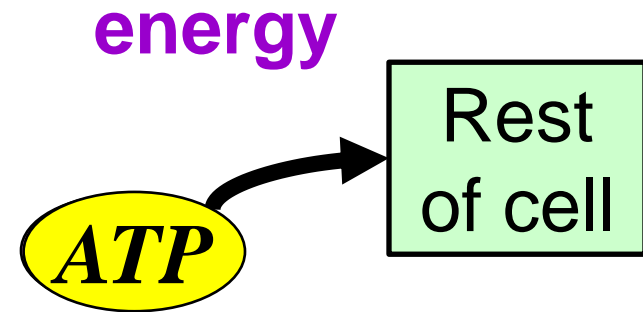
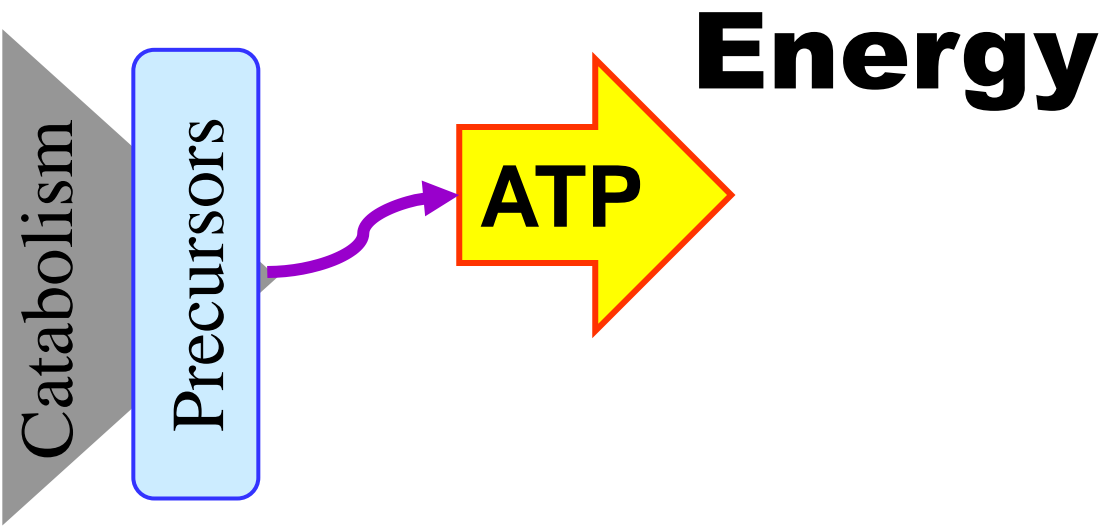
Gene

DNAP

Crosslayer autocatalysis

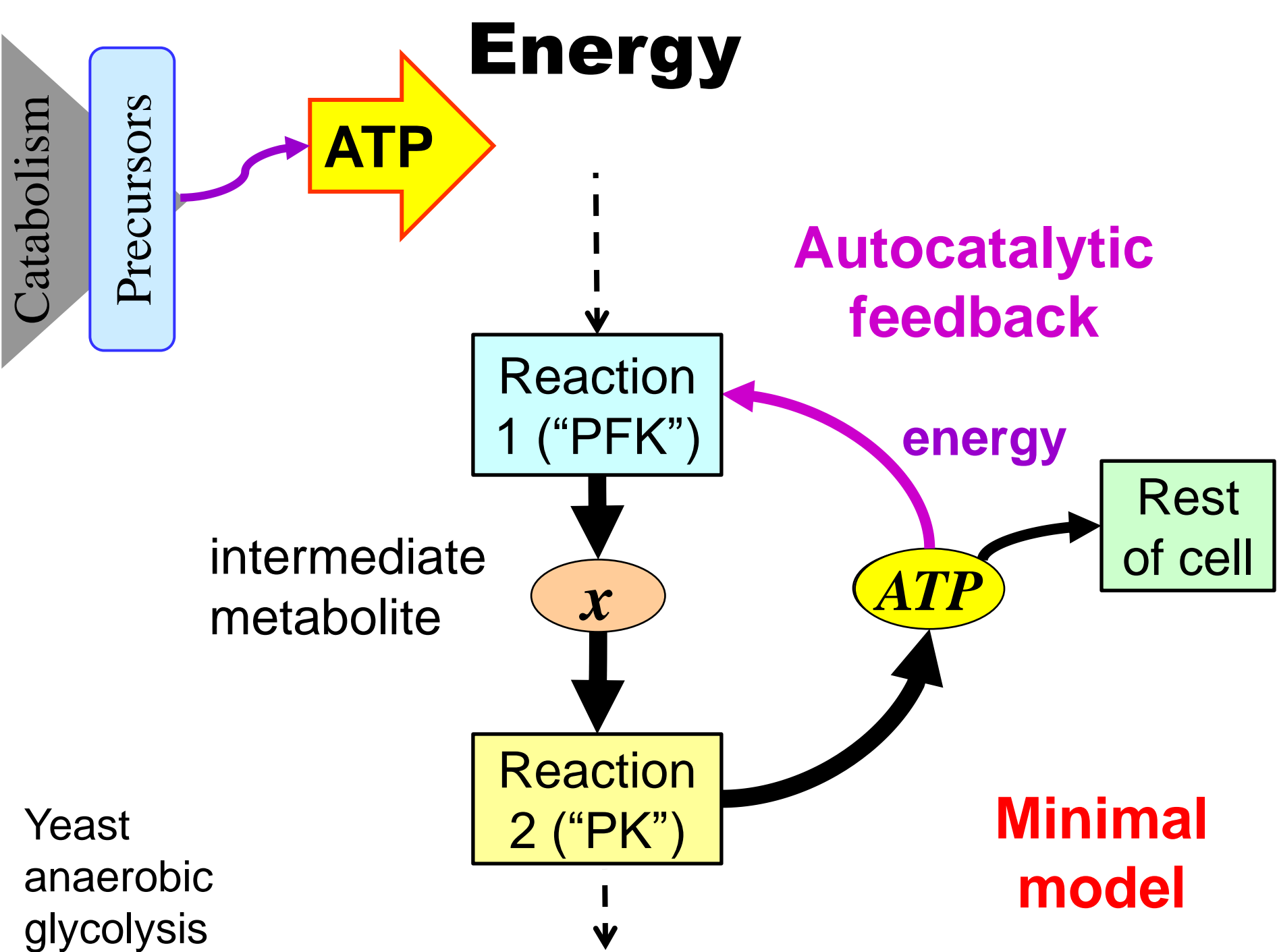




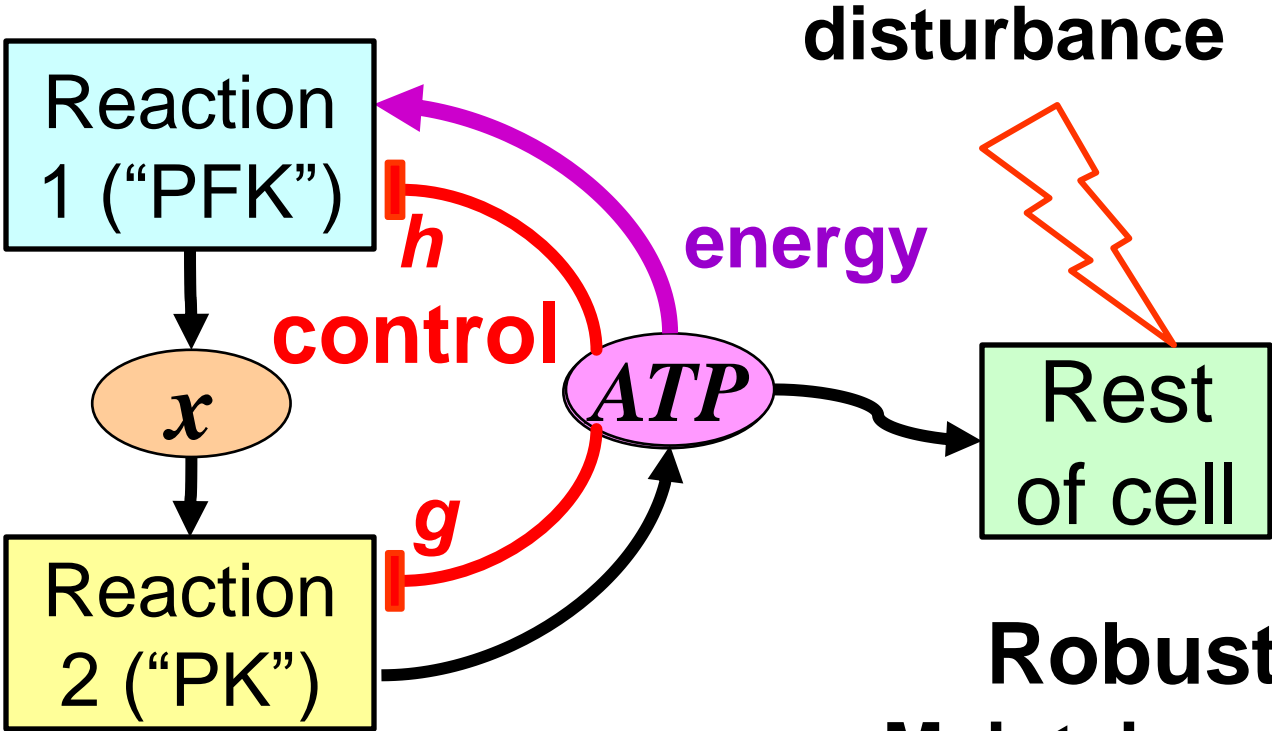


Yeast
anaerobic
glycolysis

**Minimal
model**

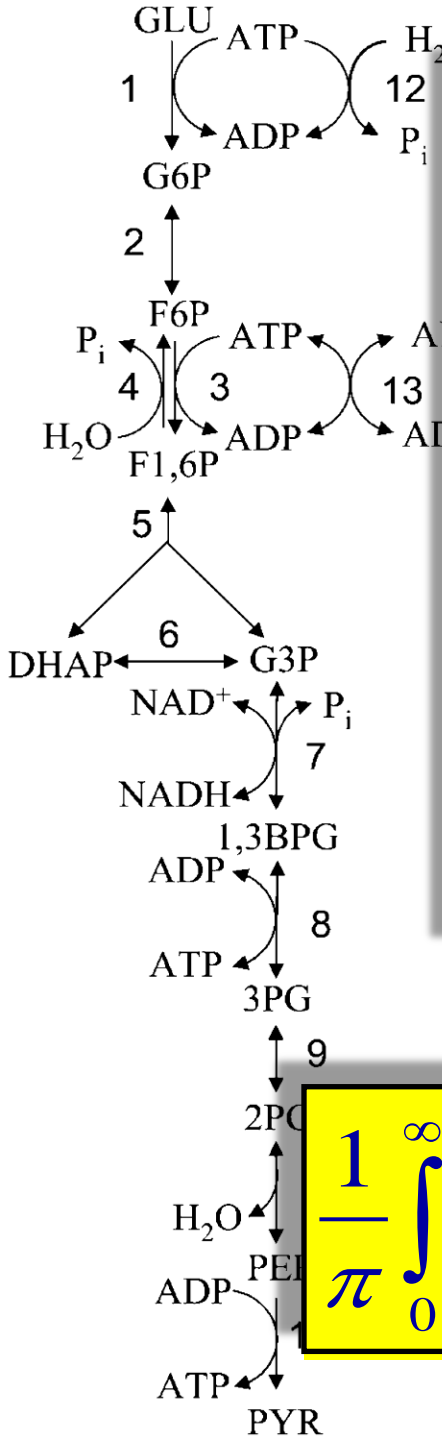


control feedback



**Robust =
Maintain energy
(ATP concentration)
despite demand fluctuation**

Tight control creates "weak linkage"
between power supply and demand



(P1) Total NAD moiety: [NAD⁺] + [NADH]

Constrained (“conserved”): Moieties

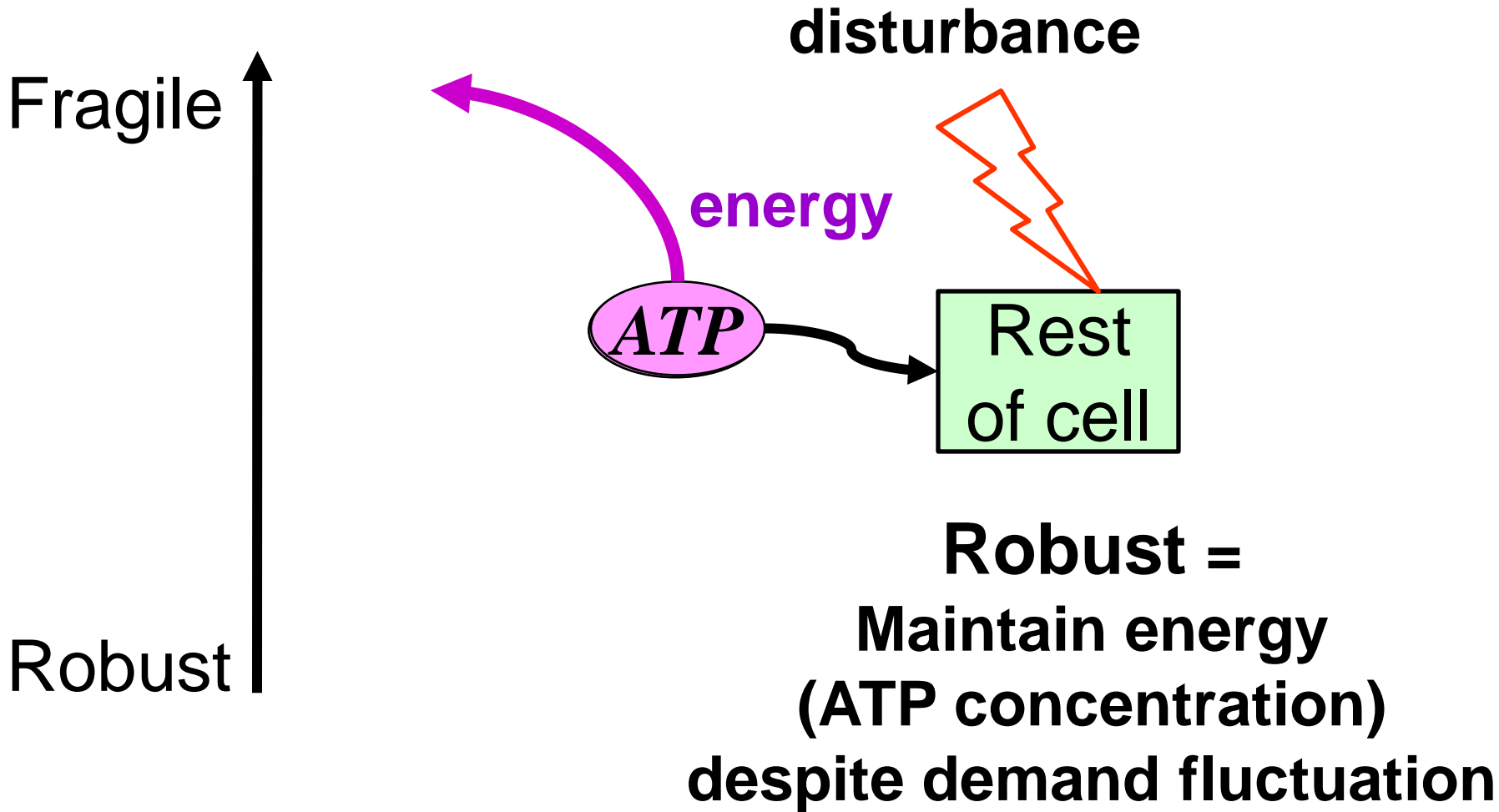
1. NAD
2. Adenylate
3. Carbon
4. phosphate
5. oxygen
6. Oxidized state of metabolites
7. Reduced state of metabolites
8. High energy potential release

[F1,6P] + [DHAP] +
[2PG] + [PEP] + [PYR]
[DHAP] + [G3P] +
+ [PEP] +
[DHAP] + [P_i]
[P_i] + [H₂O]
+
+ [PEP] + [PYR] + [NAD⁺]

$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$

+ [PYR] + [ADP] + 2[AMP] + [H₂O]

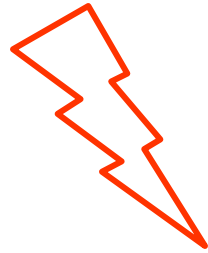
Hard tradeoff in glycolysis



disturbance

Accurate vs
sloppy

Fragile



What makes this hard?

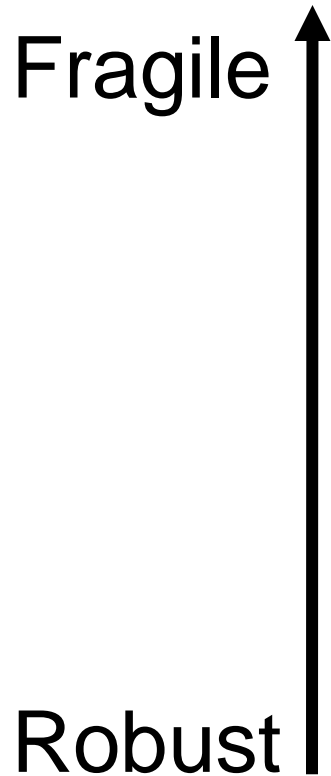
1. Instability (autocatalysis)
2. Delay (enzyme amount)

Robust

Robust

≈ Disturbance rejection

≈ Accurate



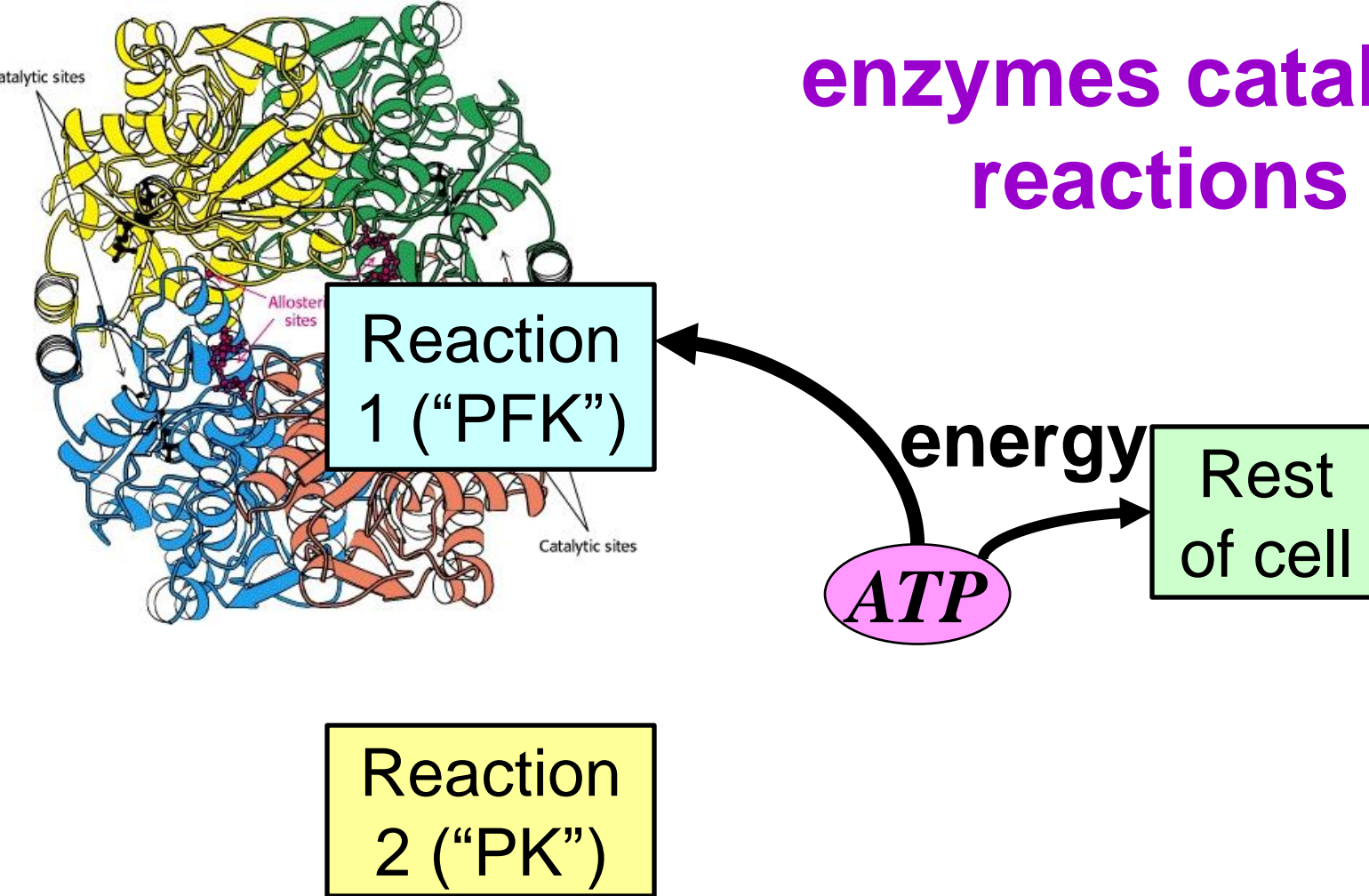
What makes this hard?

1. Instability
2. Delay

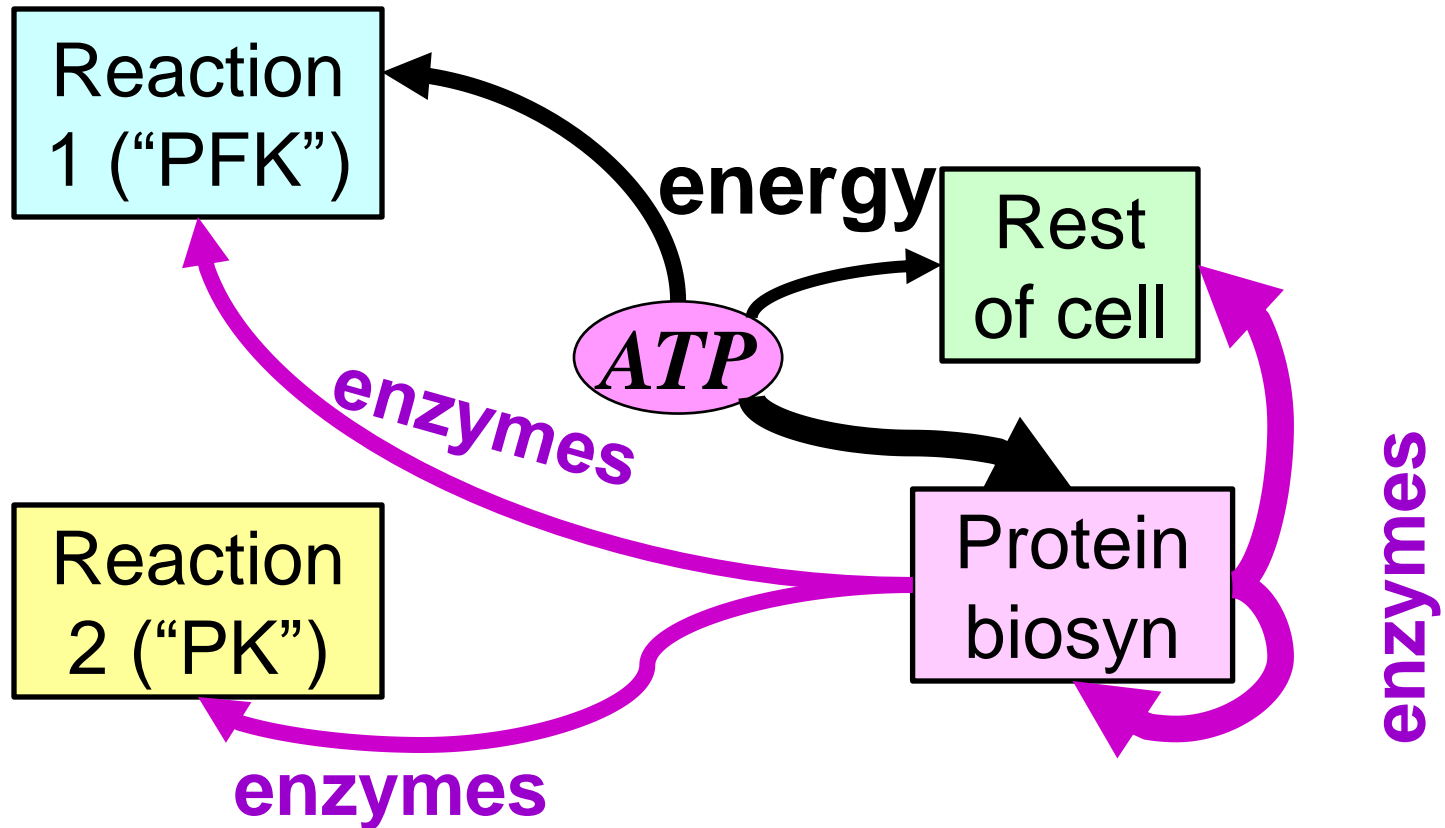
The CNS must cope with both

Today's important point

enzymes catalyze reactions



enzymes catalyze reactions, another source of autocatalysis



Efficient =

**low metabolic overhead
≈ low enzyme amount**

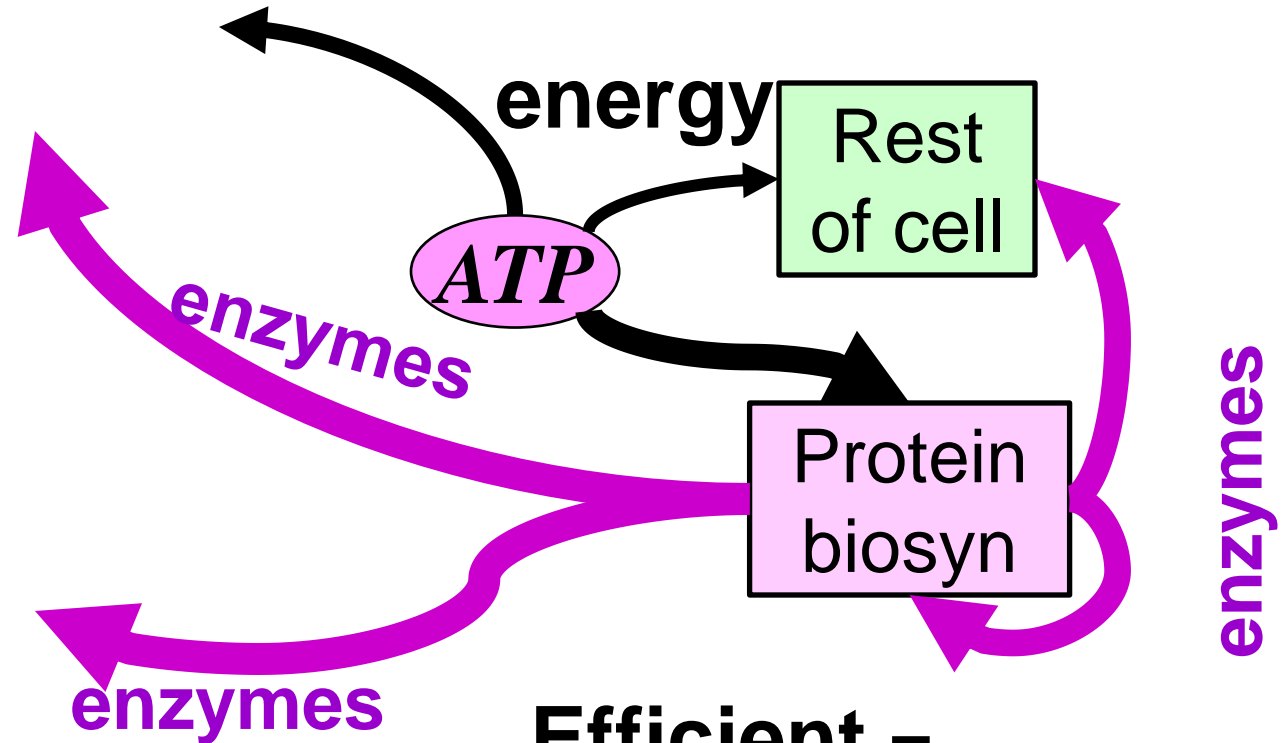
enzymes catalyze reactions, another source of autocatalysis

reaction rates

\propto

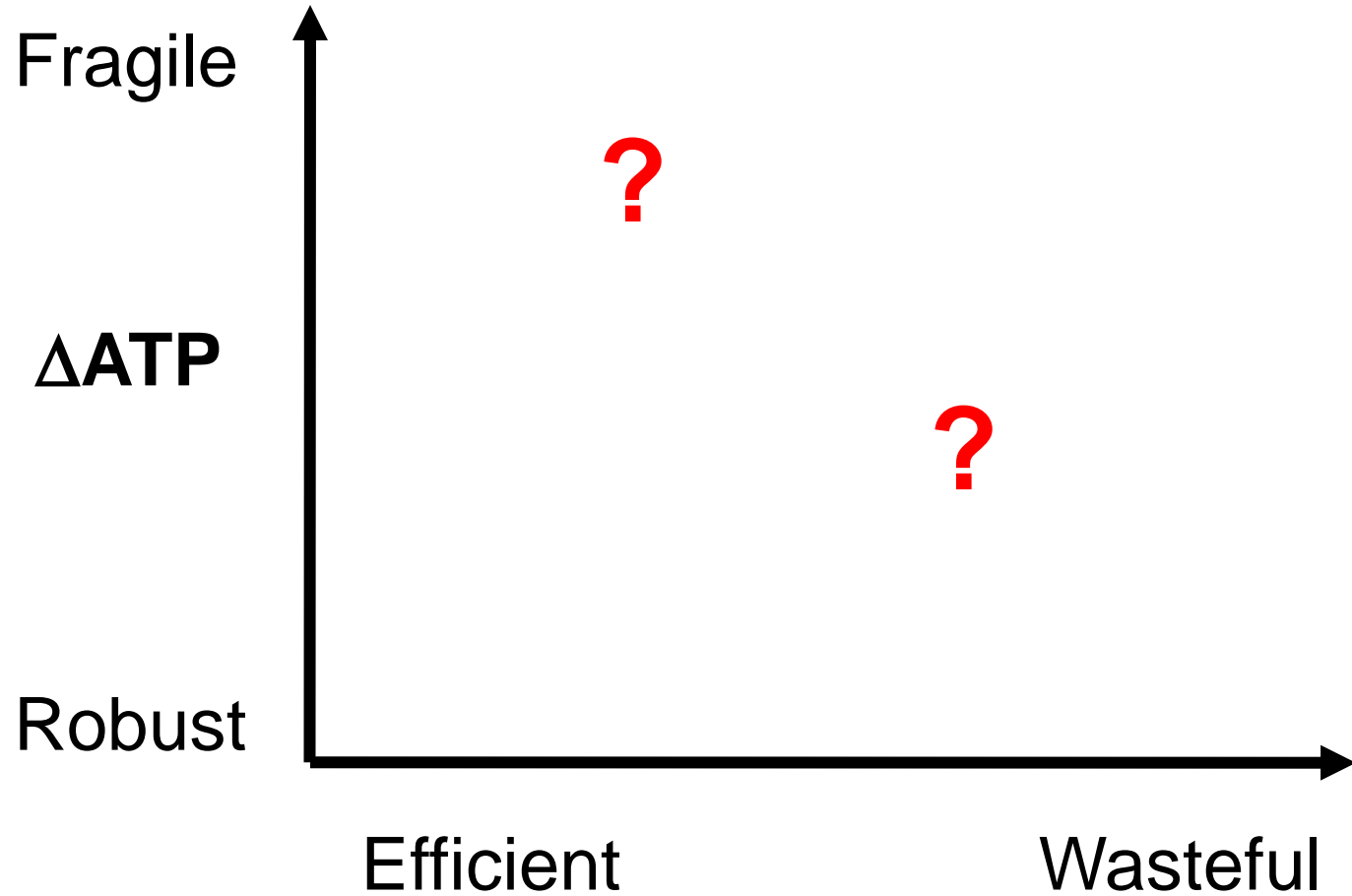
enzyme amount

Can't make too many enzymes here, need to supply rest of the cell.



Efficient =
low metabolic overhead
 \approx low enzyme amount
(\Rightarrow **slow reactions**)

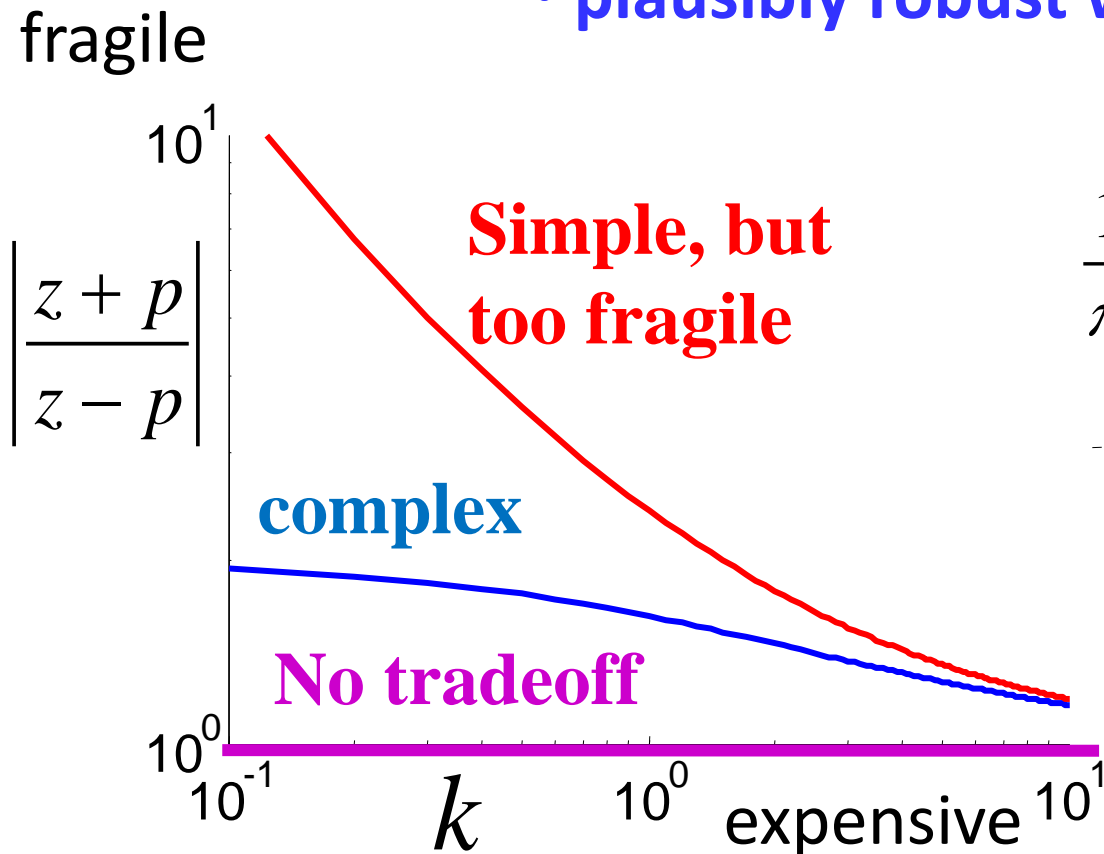
**Robust =
Maintain
ATP**



**Efficient =
low enzyme amount
(\Rightarrow slow reactions)**

Hard tradeoff in glycolysis is

- **robustness vs efficiency**
- **absent without autocatalysis**
- **too fragile with simple control**
- **plausibly robust with complex control**



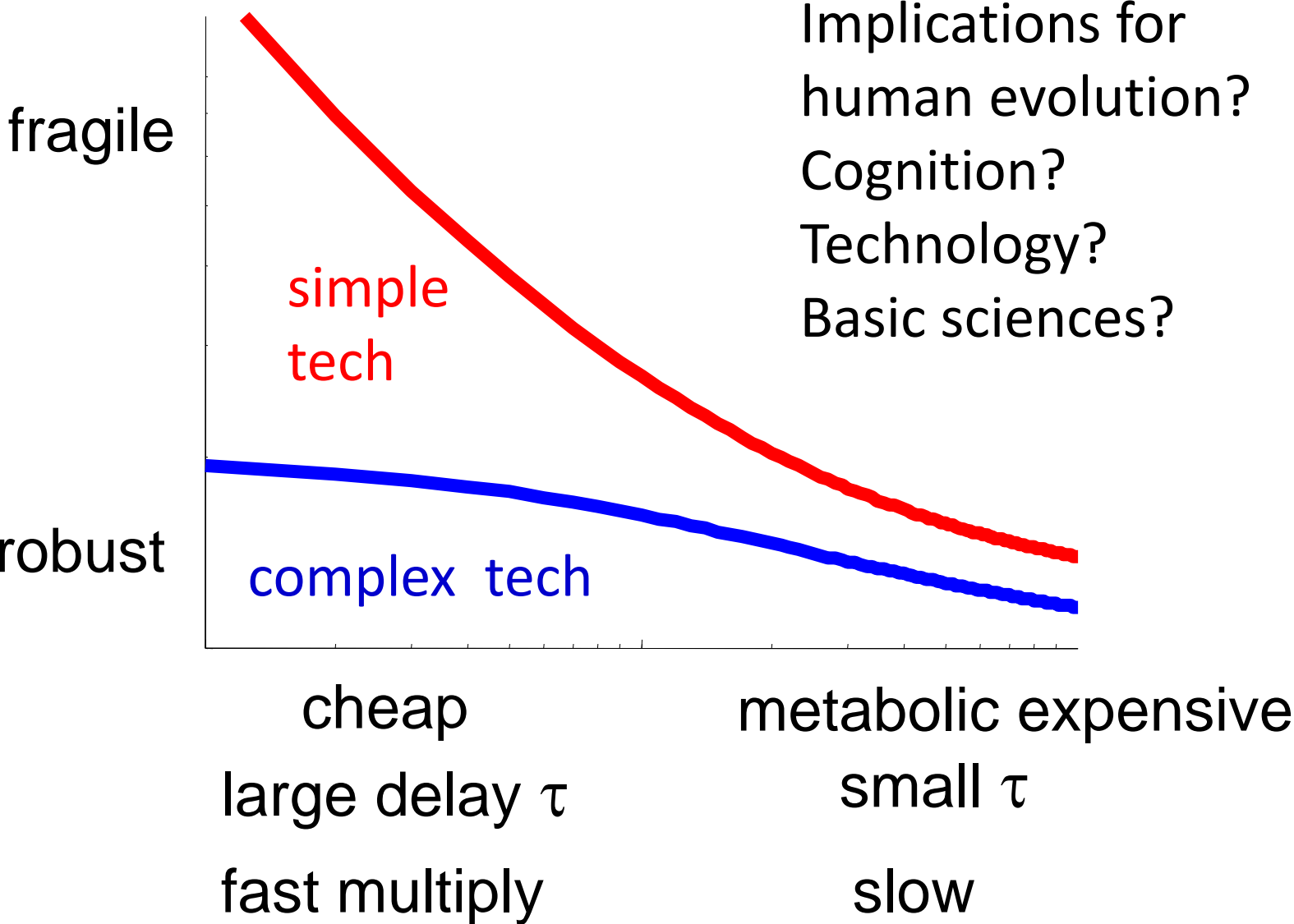
$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega$$

$$\geq \ln \left| \frac{z+p}{z-p} \right|$$

What (some) reviewers say

- “...to establish universality for all biological and physiological systems is **simply wrong**. It cannot be done...
- ... a mathematical scheme **without any real connections to biological or medical...**
- ...universality is well justified in physics... for biological and physiological systems **...a dream that will never be realized**, due to the vast diversity in such systems.
- **...does not seem to understand or appreciate** the vast diversity of biological and physiological systems...
- ...a high degree of abstraction, which ...make[s] **the model useless ...**

This picture is very general



This picture is very general

Domain specific costs/tradeoffs

metabolic
overhead

cheap



metabolic
expensive

CNS reaction
time τ (delay)

large τ



small τ

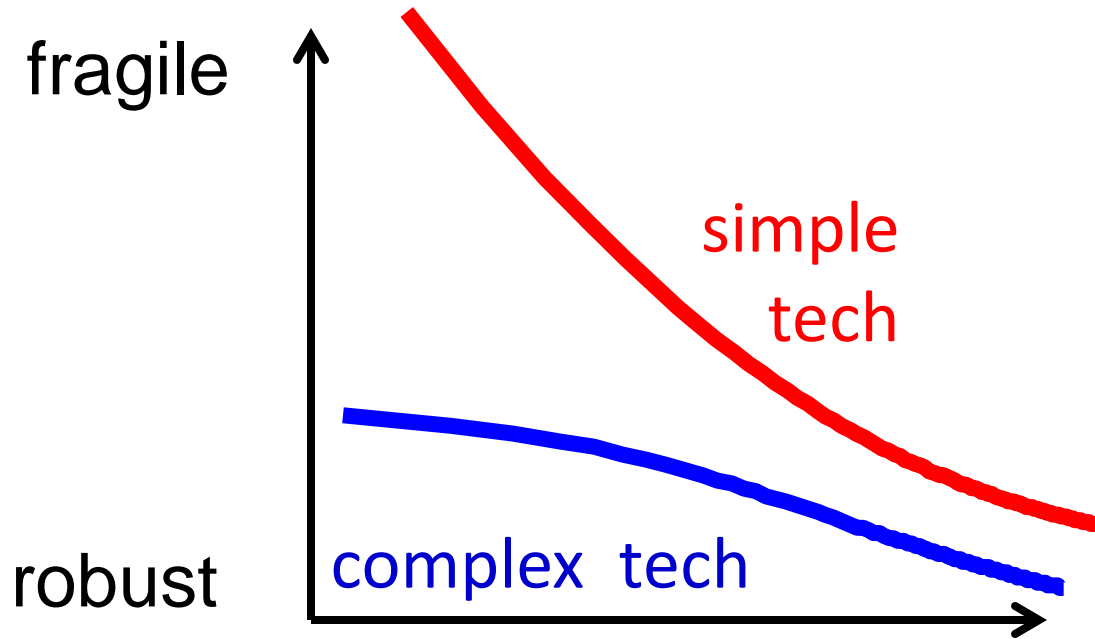
phage
multiplication
rate

fast
multiply



slow

This picture is very general



metabolic cost

cheap



expensive

reaction time τ

large τ



small τ

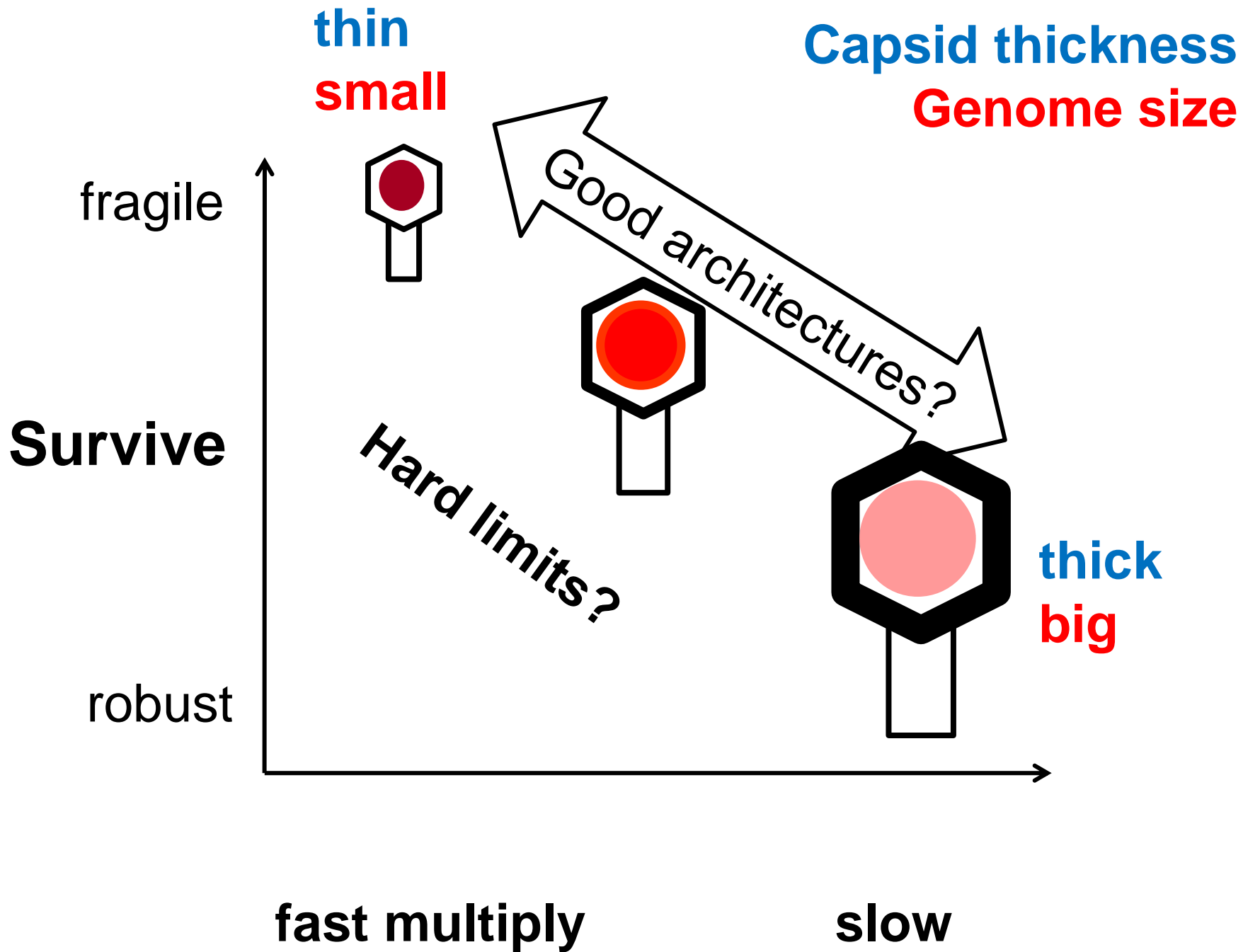
phage x rate

fast



slow

Domain specific costs/tradeoffs



$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq p\tau \propto \tau \sqrt{\frac{1}{l}}$$

Fragility

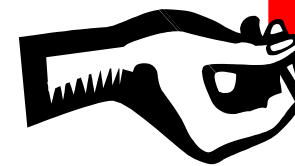
$$\tau \sqrt{\frac{1}{l}}$$

Too fragile

For fixed length

L

up



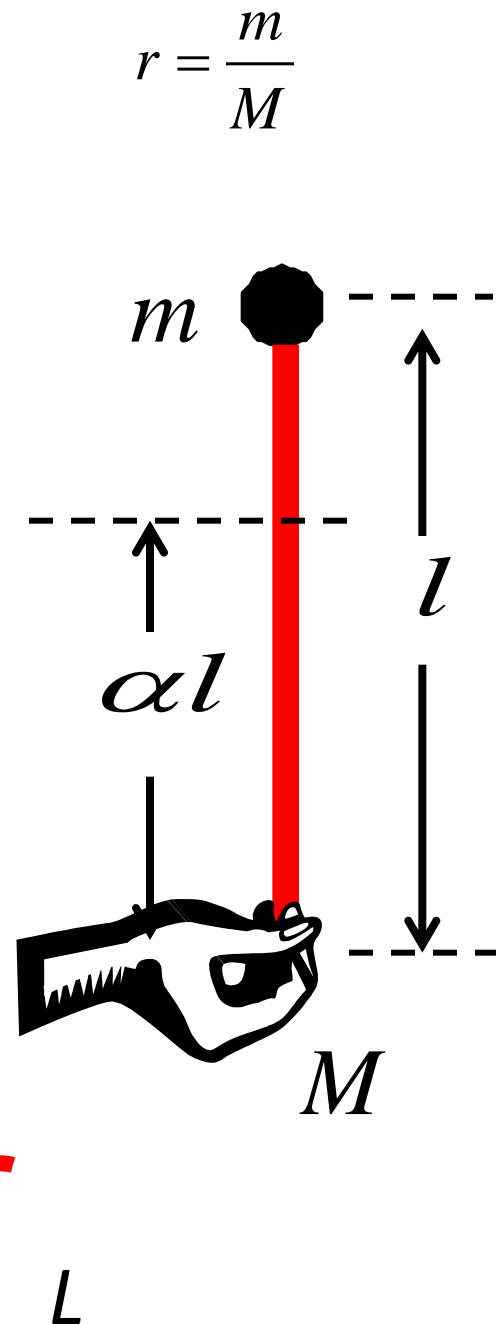
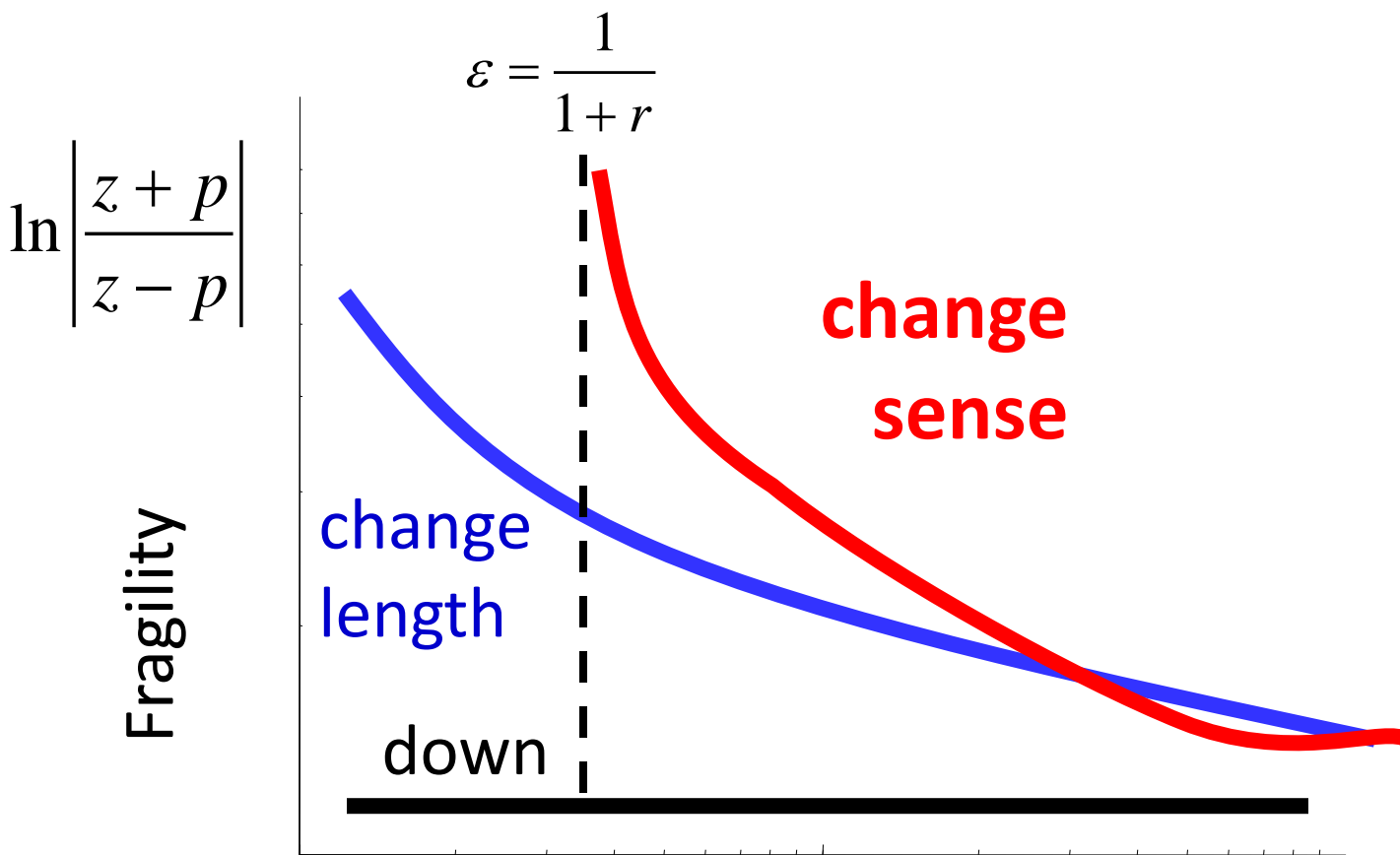
down

large τ
small $1/\tau$

small τ
large $1/\tau$

$1/\text{delay}$

$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{2z}{z^2 + \omega^2} \right) d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$

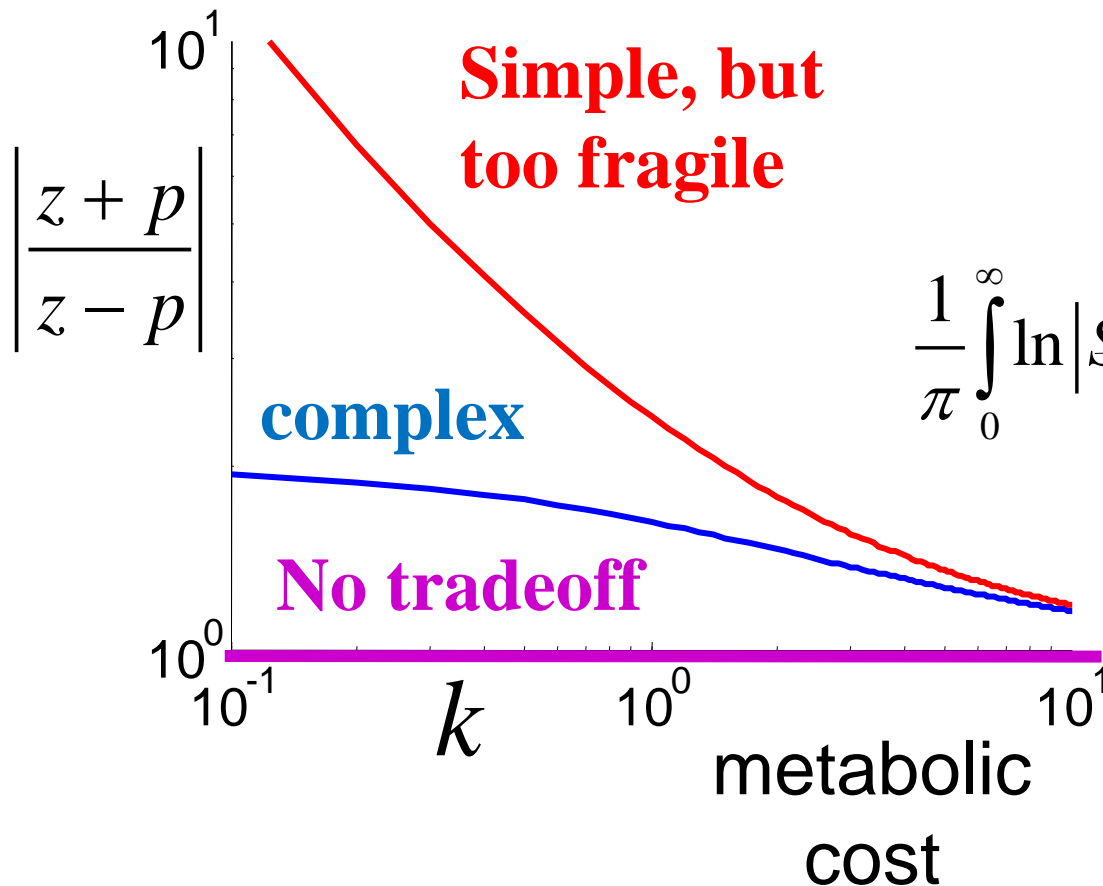


This is a cartoon, but can be made precise.

Hard tradeoff in glycolysis is

- **robustness vs efficiency**
- **absent without autocatalysis**
- **too fragile with simple control**
- **plausibly robust with complex control**

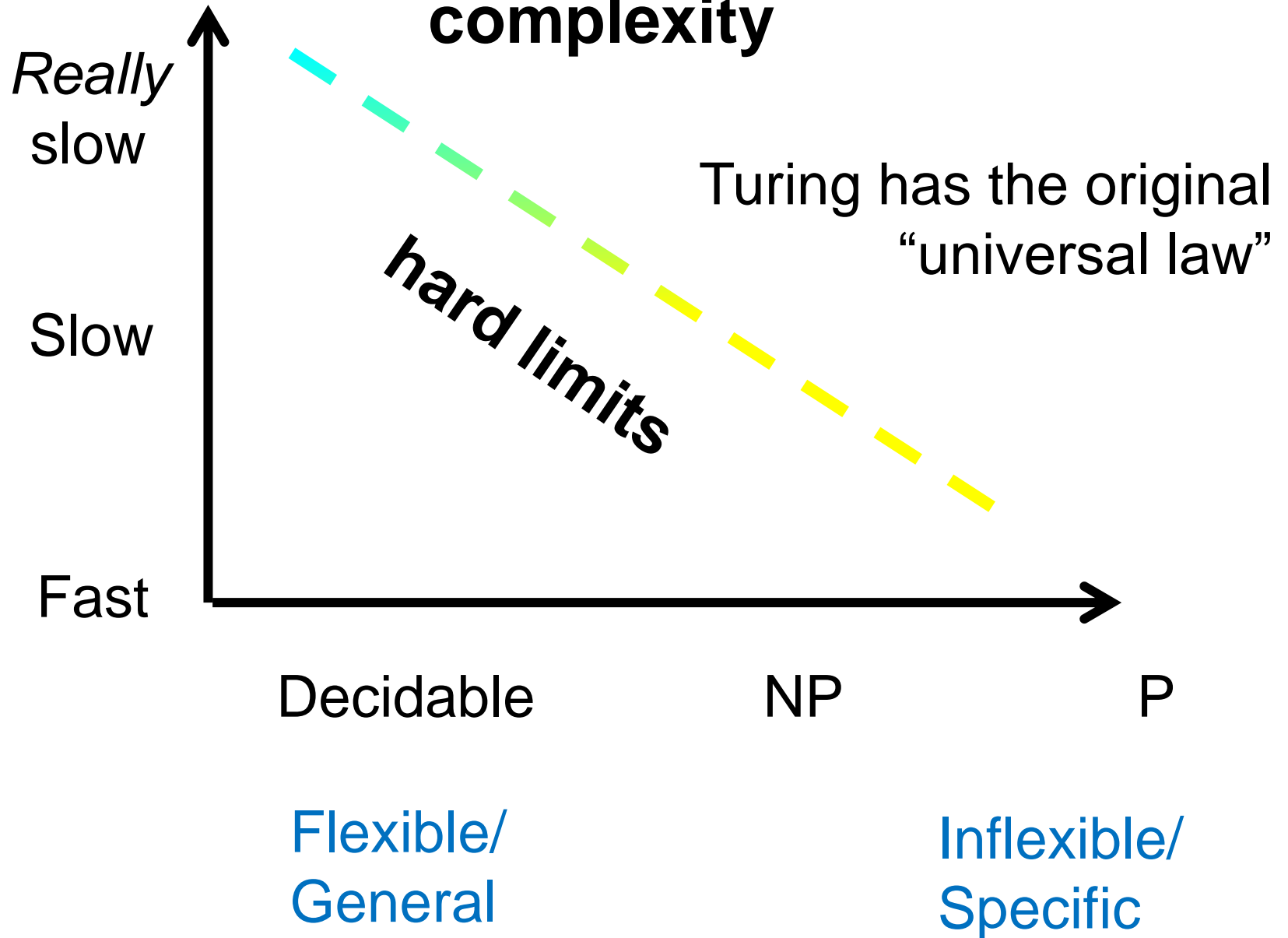
fragile



$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega$$

$$\geq \ln \left| \frac{z+p}{z-p} \right|$$

Computational complexity



Delay makes control hard.



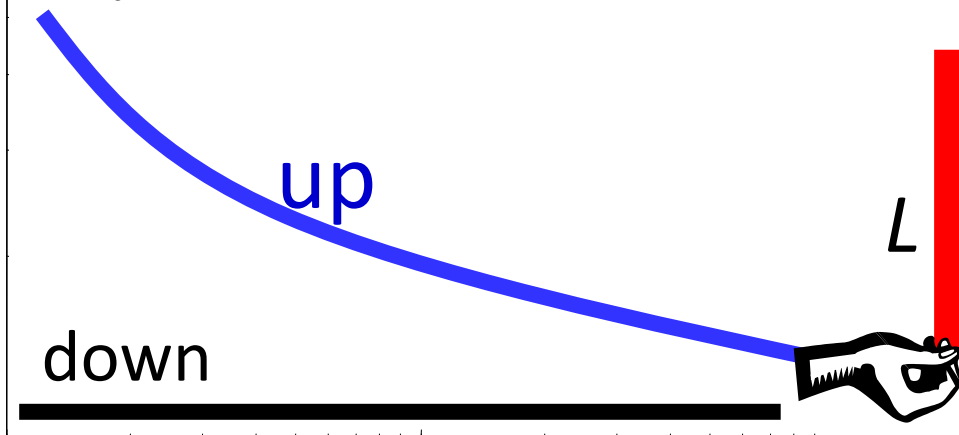
Computation delay adds to total delay.

Computation is a component in control.

Fragility

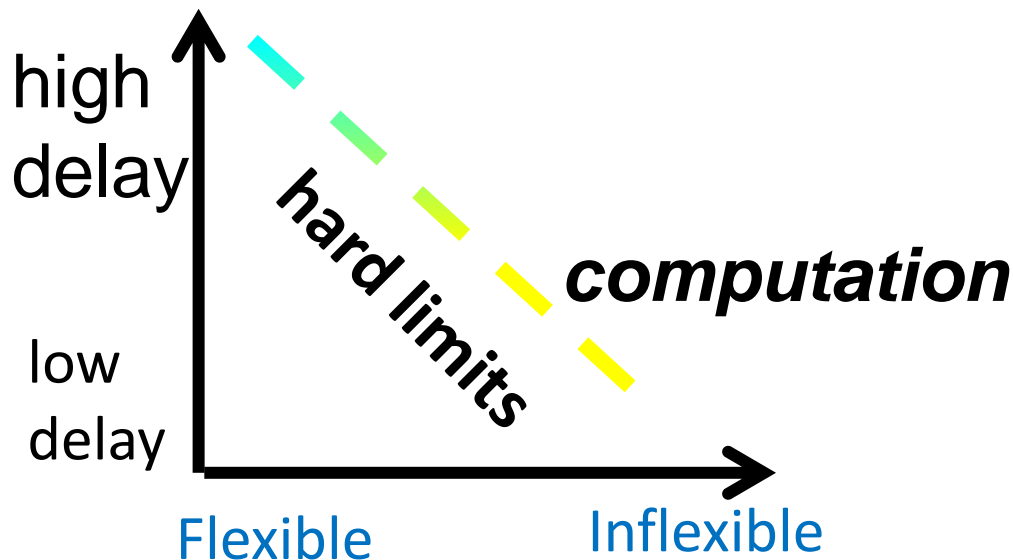
$$\tau \sqrt{\frac{1}{l}}$$

$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq p\tau \propto \tau \sqrt{\frac{1}{l}}$$



large τ

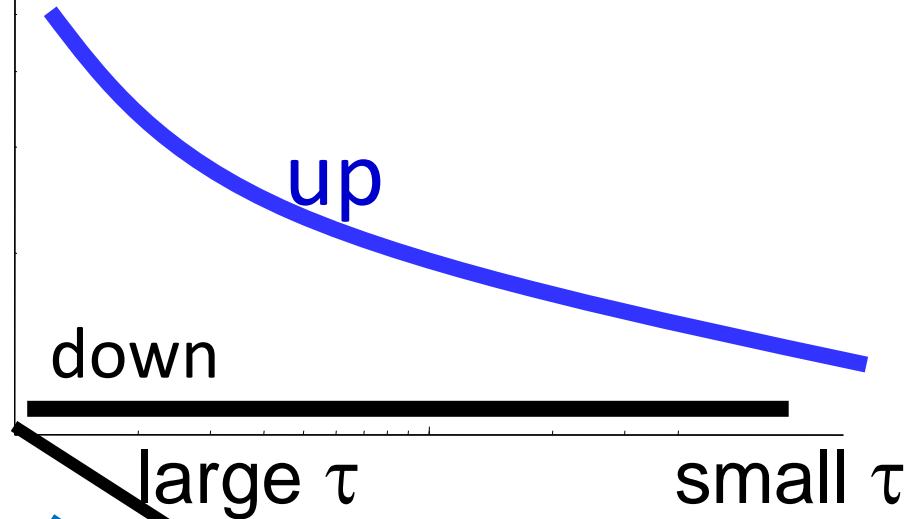
small τ



Fragility

$$\frac{1}{\pi} \int_0^{\infty} \ln |T(j\omega)| \frac{2p}{p^2 + \omega^2} d\omega \geq p\tau \propto \tau \sqrt{\frac{1}{l}}$$

$$\tau \sqrt{\frac{1}{l}}$$



This needs formalization:

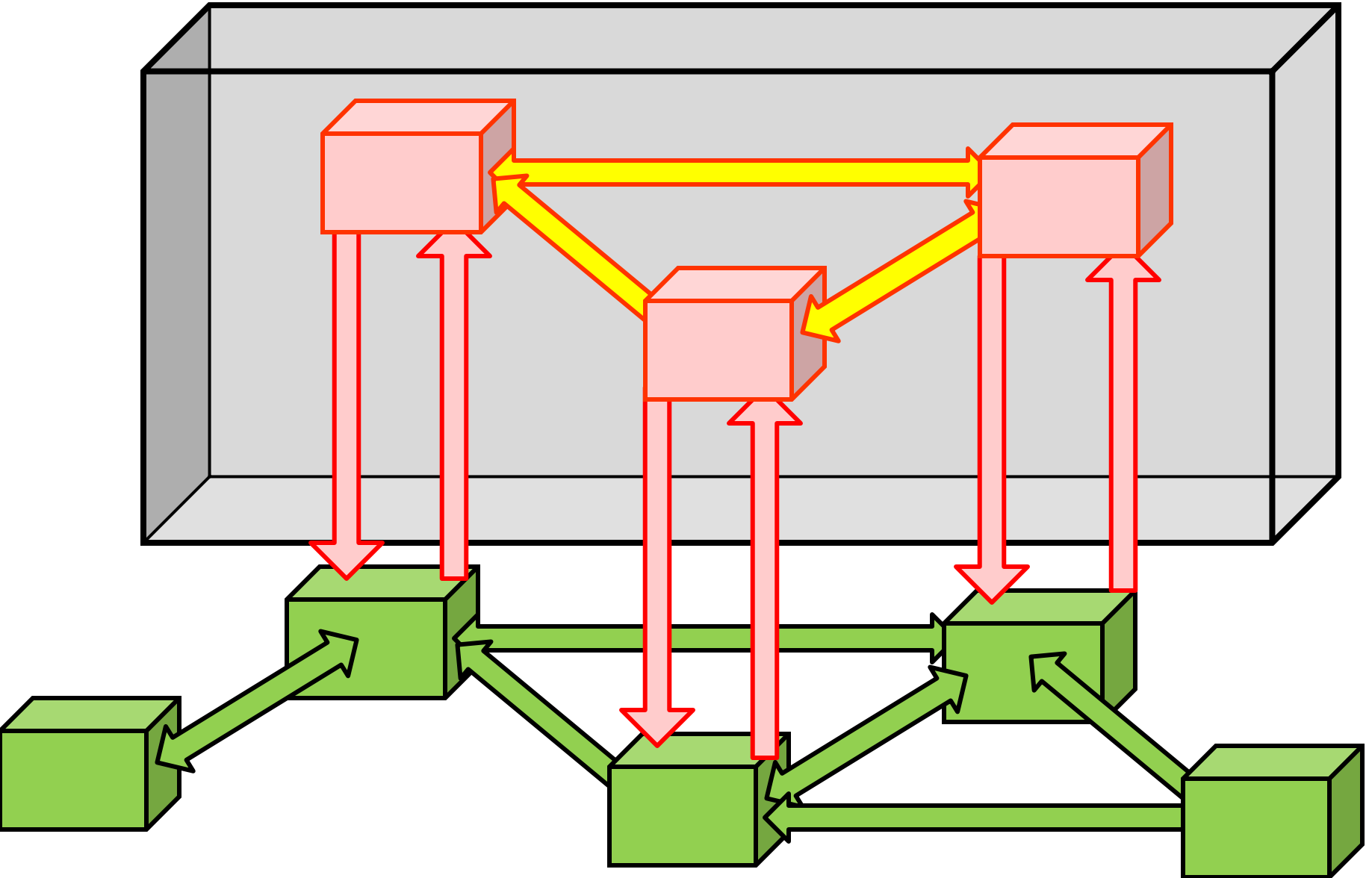
What **flexibility** makes control hard?

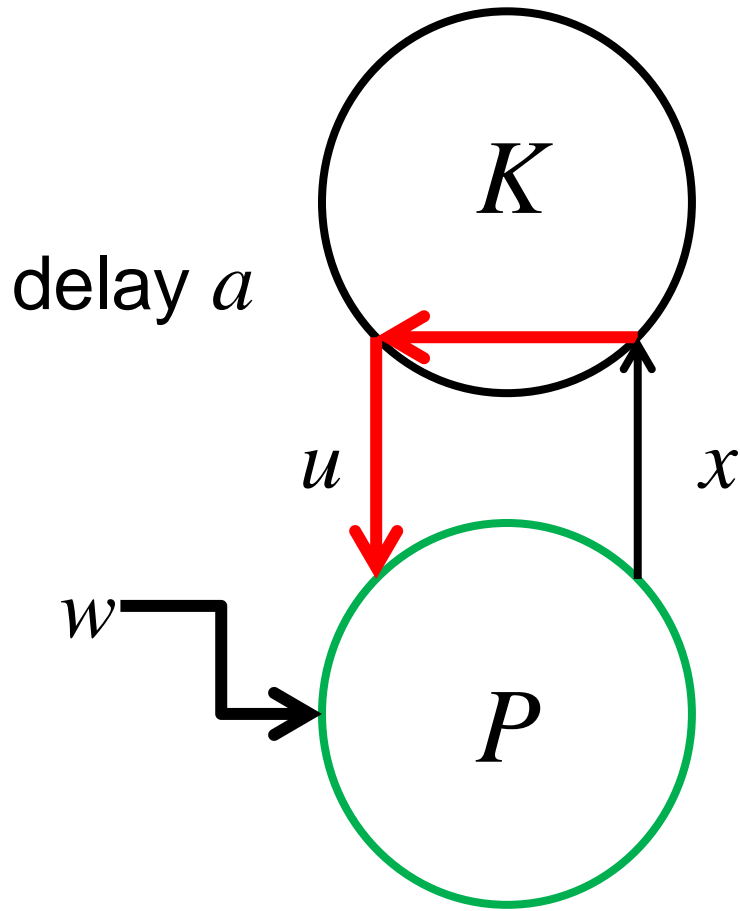
Large, structured uncertainty?

Flexible

Inflexible

What about: Cyber-physical: decentralized control with internal delays?





No delay or
no uncertainty

$$u_{t-a} = -(px_t + w_t)$$

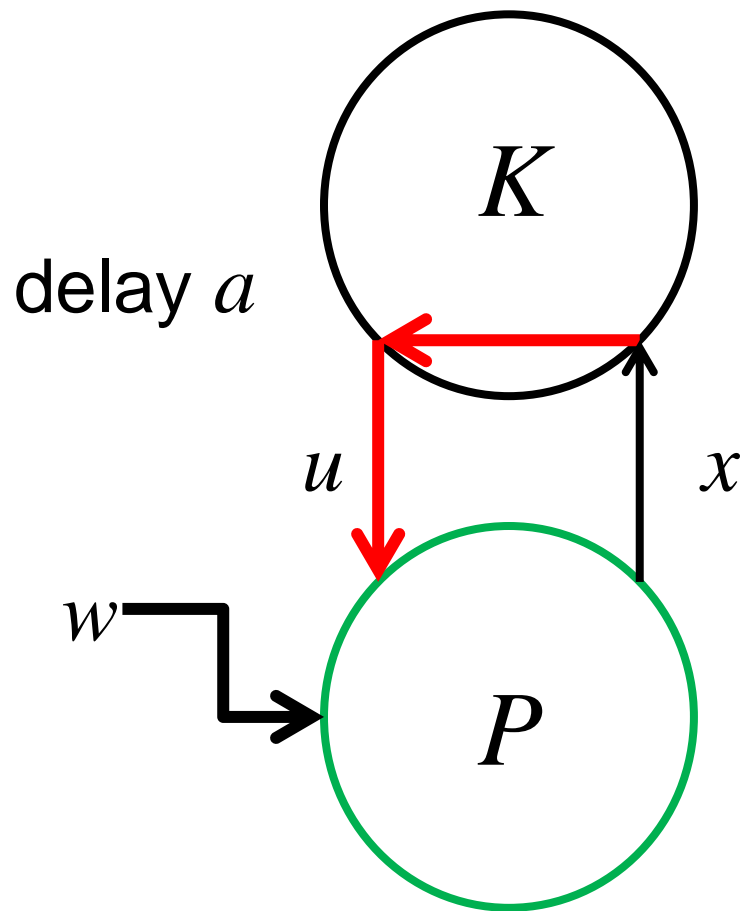
$$\Rightarrow \|x\| \approx 0 \quad \|u\| \approx \|w\|$$

With delay **and**
uncertainty

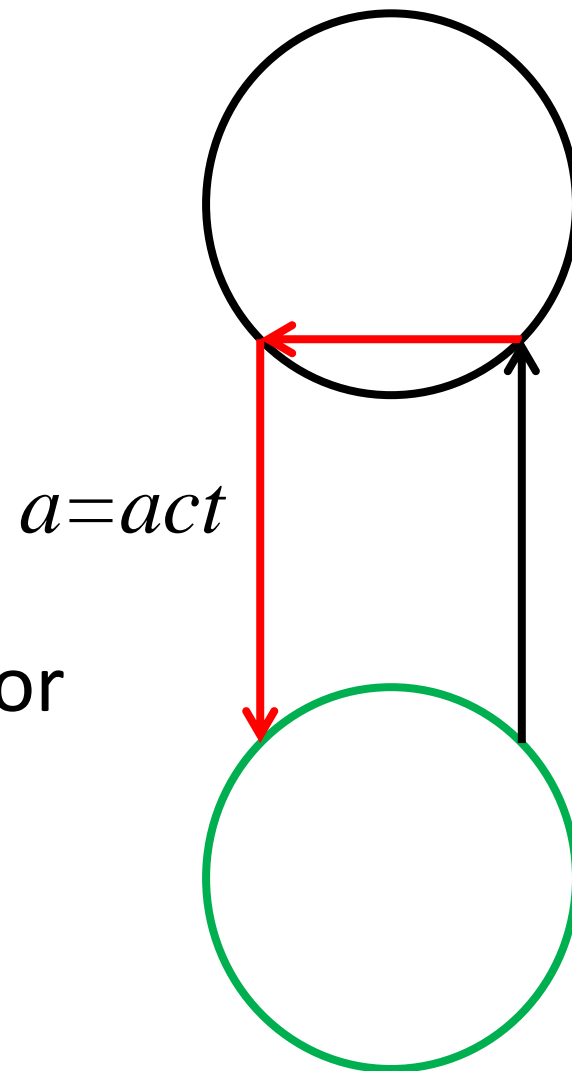
$$x_{t+1} = px_t + w_t + u_{t-a}$$

$$p > 1$$

$$\Rightarrow \|x\| \approx \|u\| \approx p^a \|w\|$$



Focus on delays

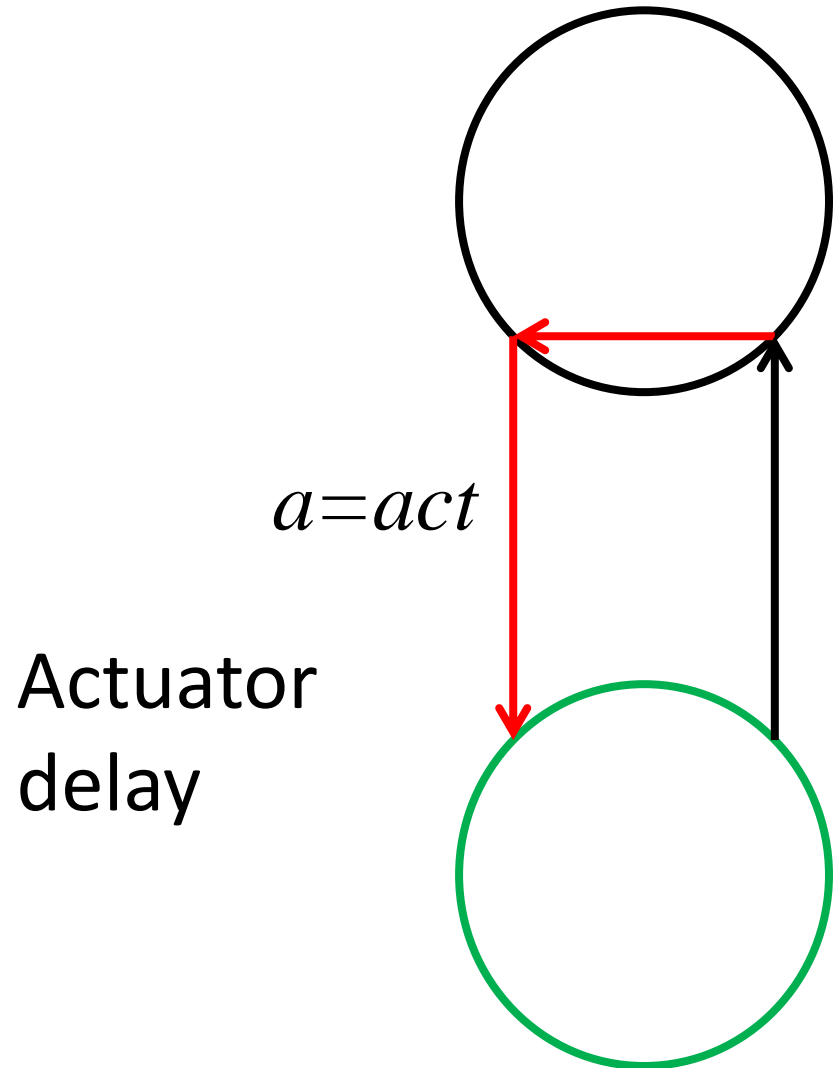


Actuator
delay

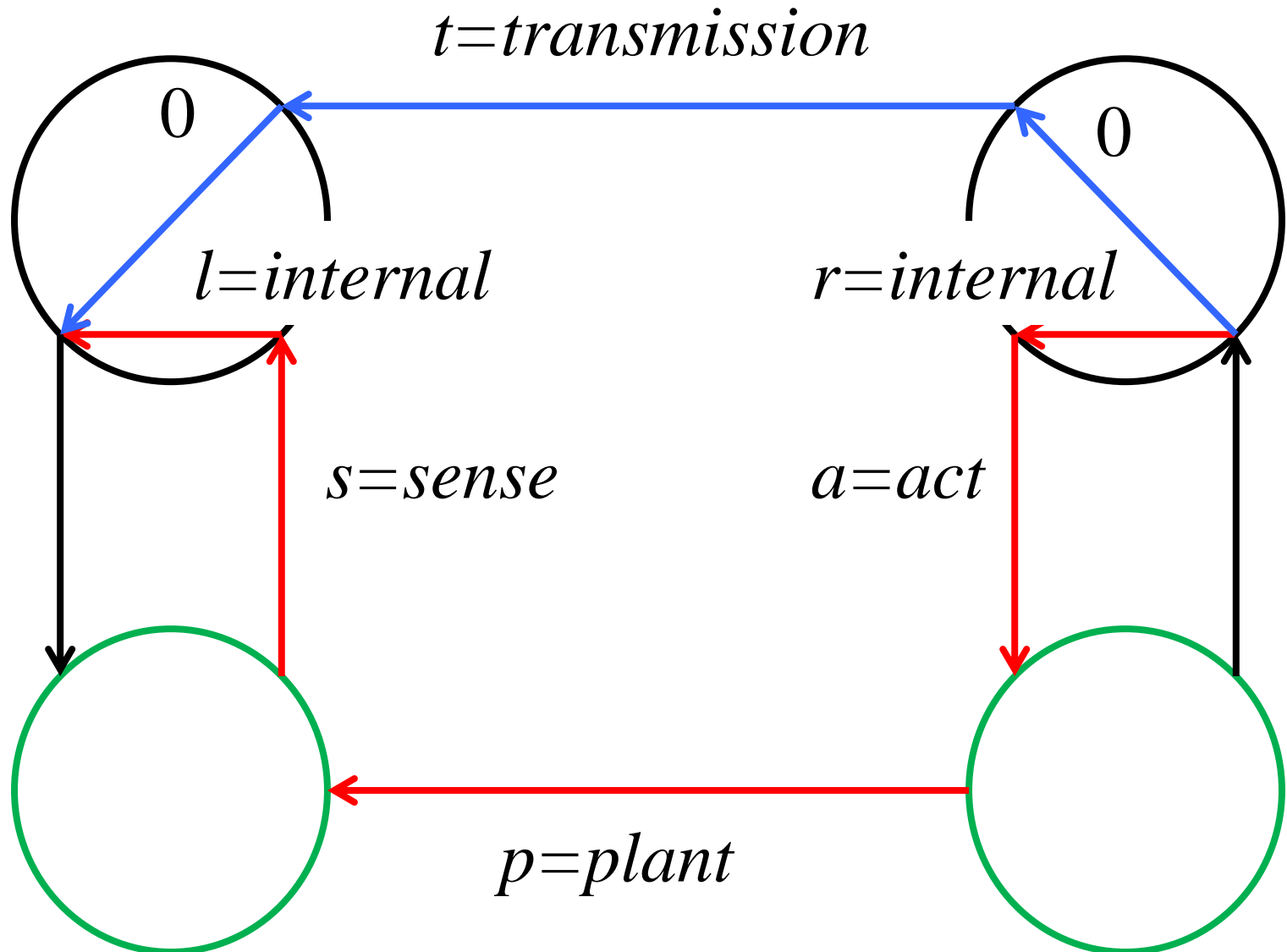
$$x_{t+1} = px_t + w_t + u_{t-a}$$

$$p > 1$$

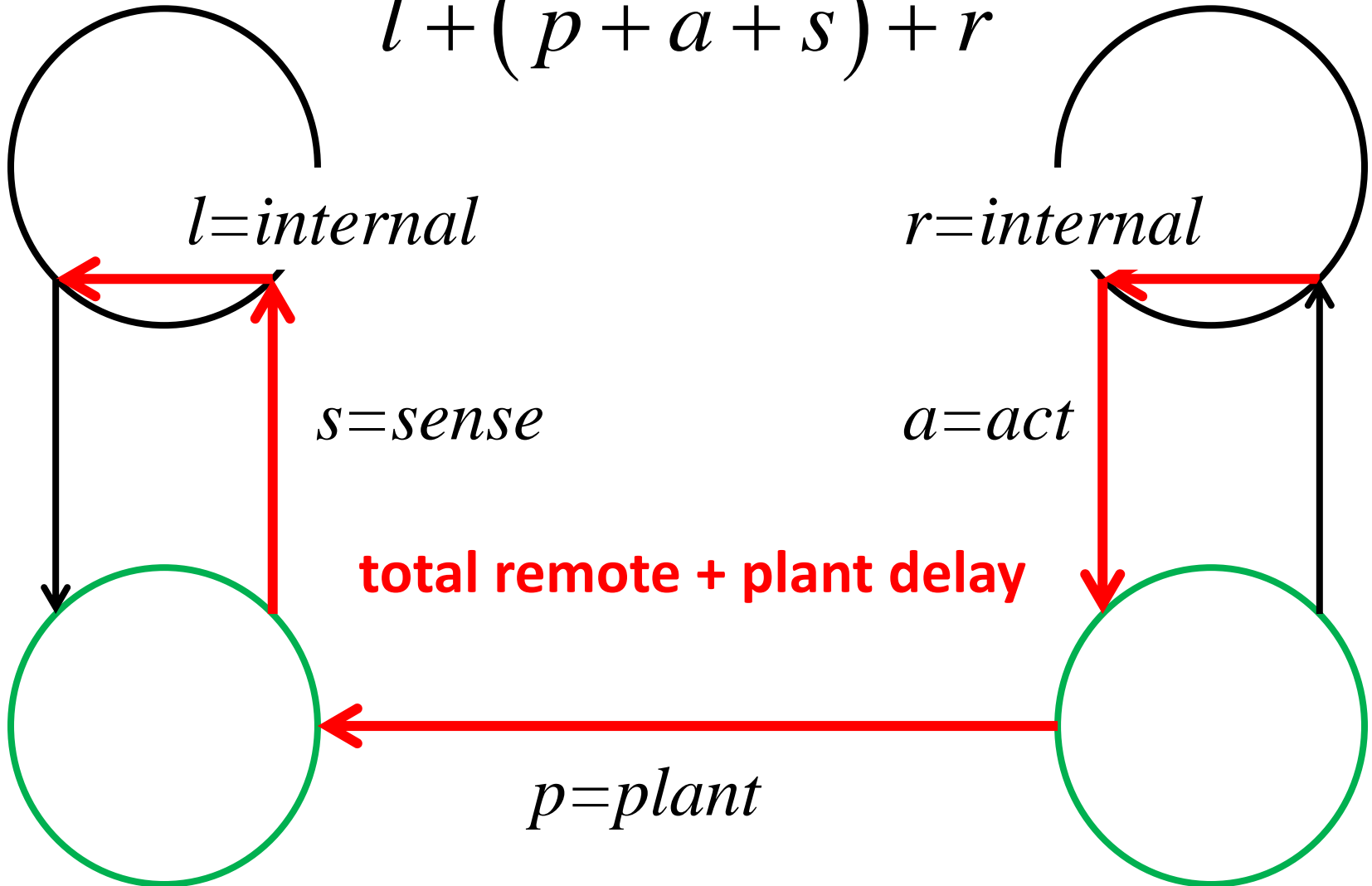
Focus on delays



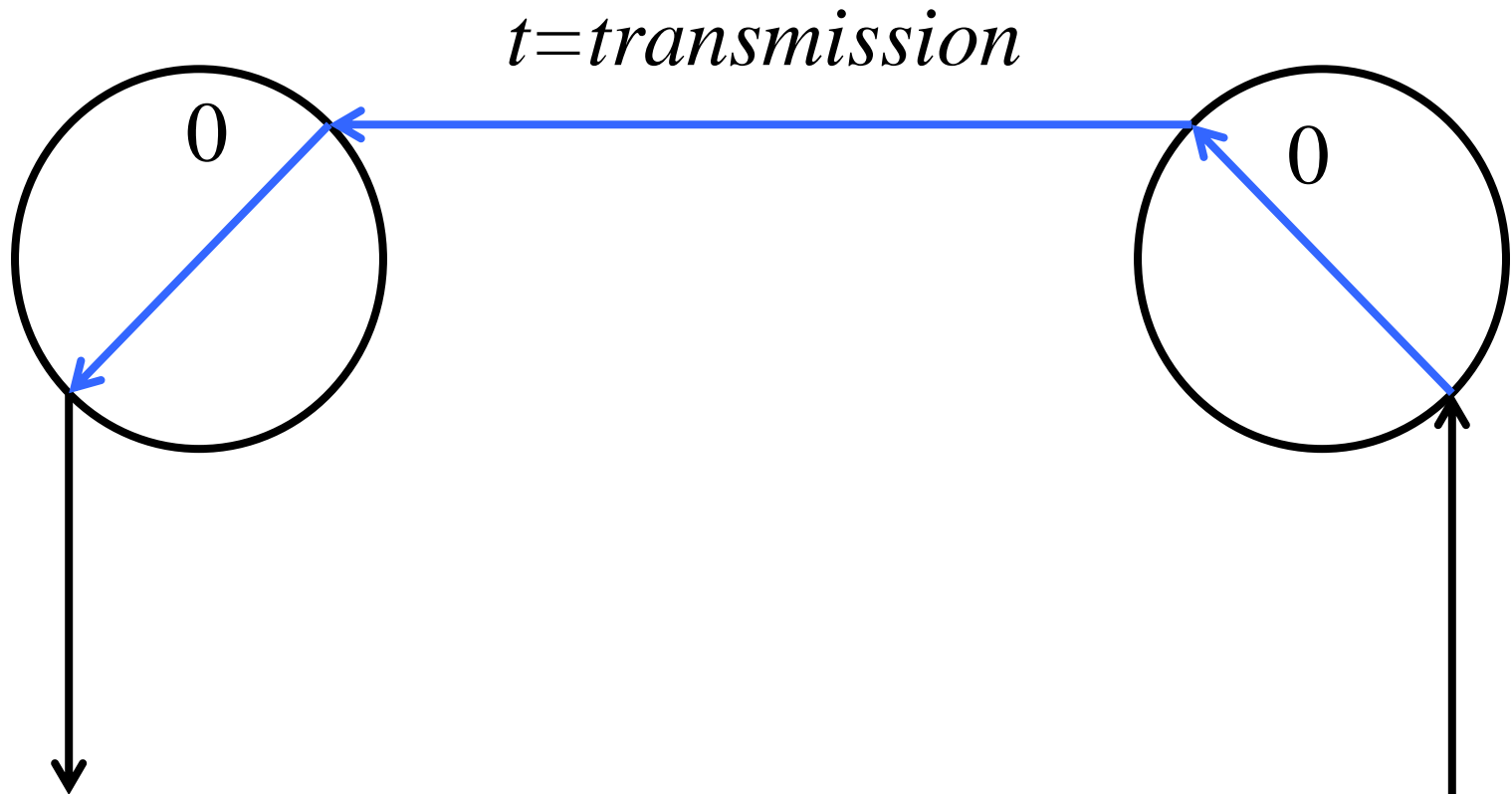
Decentralized control



$$l + (p + a + s) + r$$

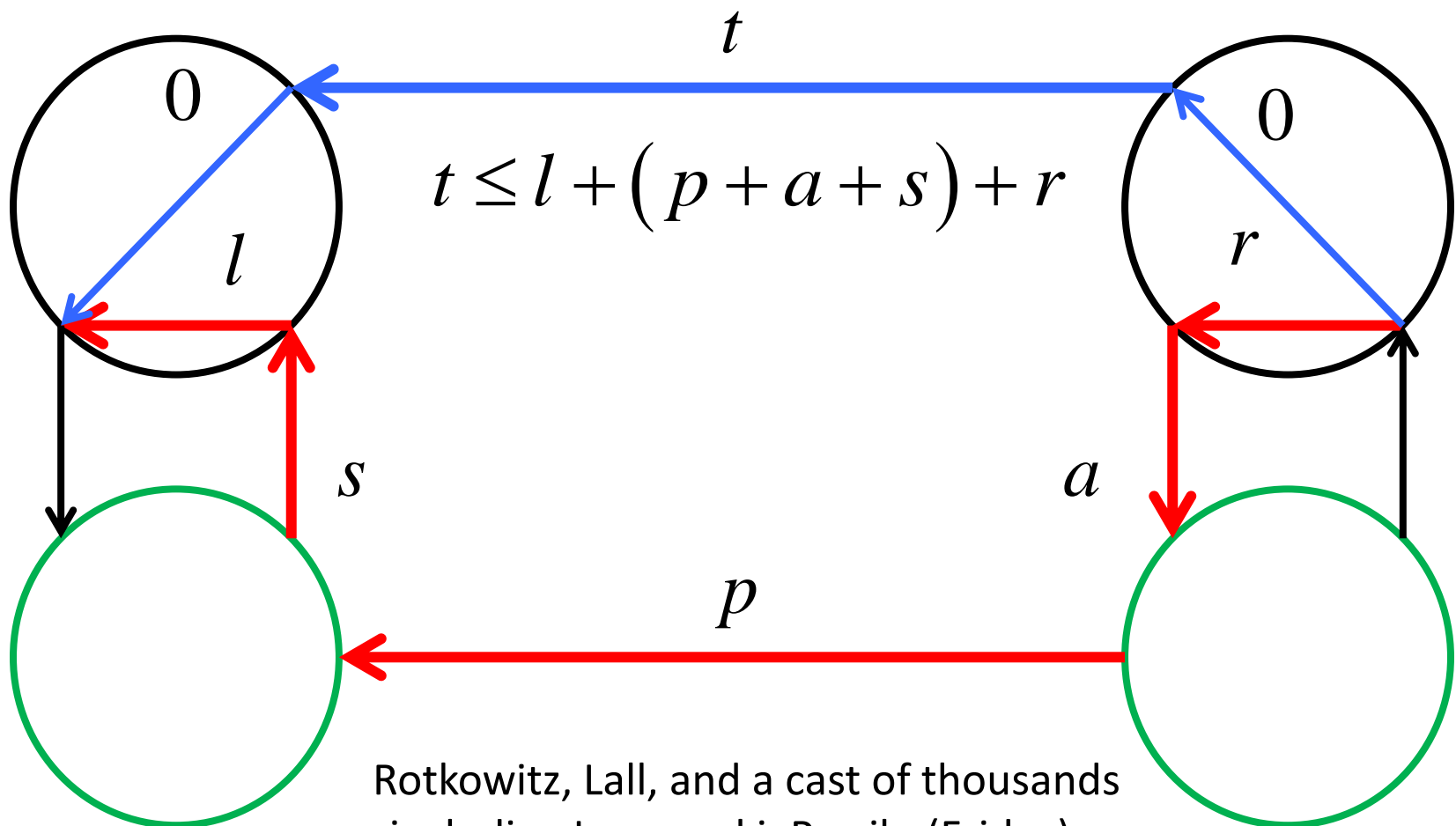


Communications delay



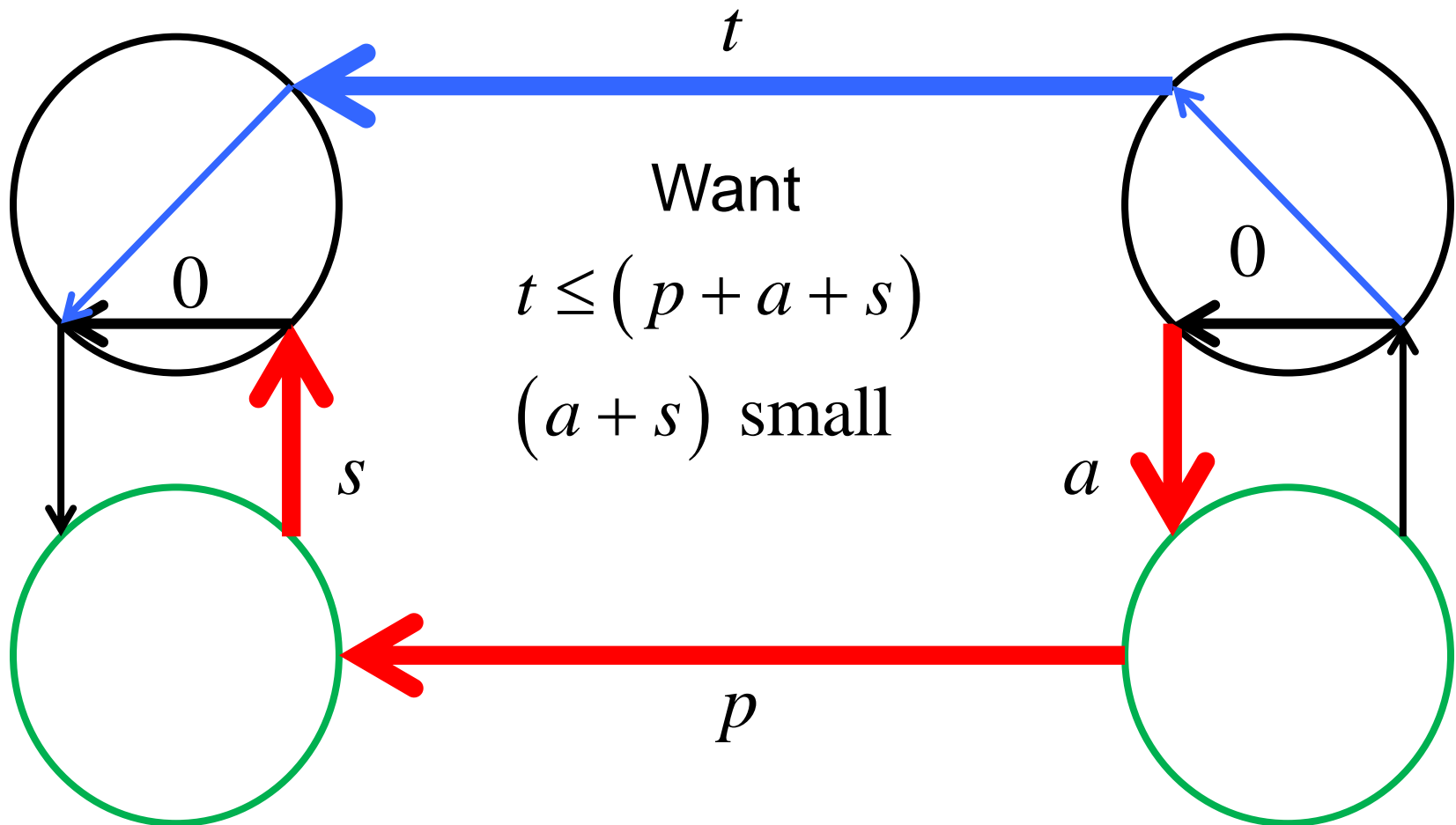
$$t \leq l + (p + a + s) + r$$

Then decentralized control design can be made **convex**



Rotkowitz, Lall, and a cast of thousands including Lamperski, Parrilo (Friday)...

A primary driver of human brain evolution?

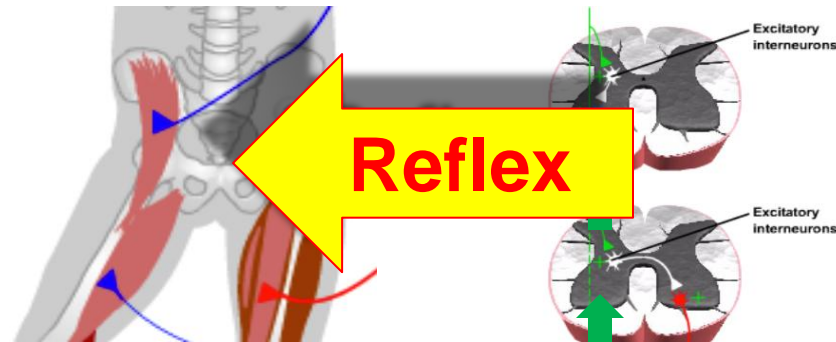


Wolpert, Grafton, etc

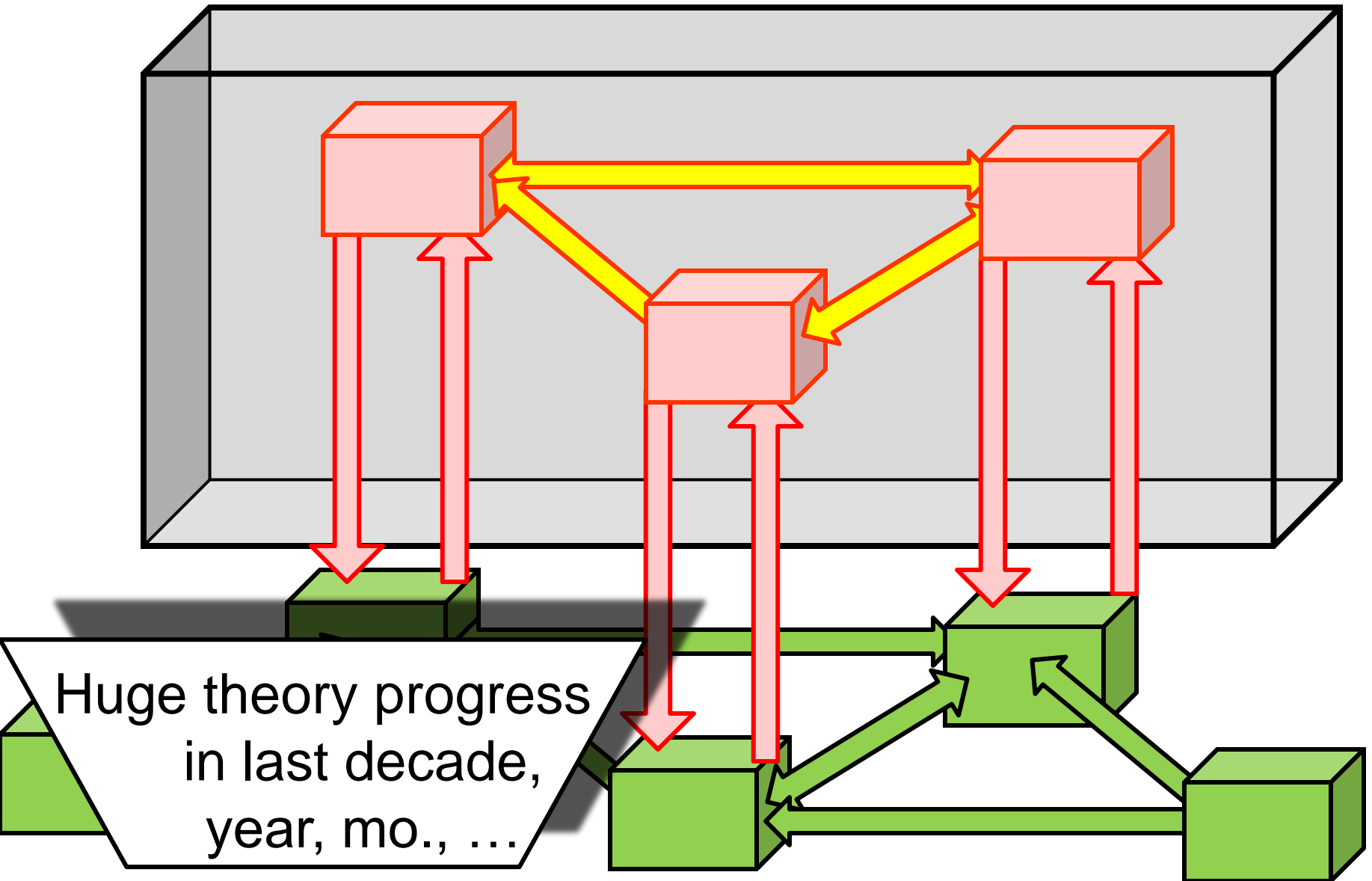
robust

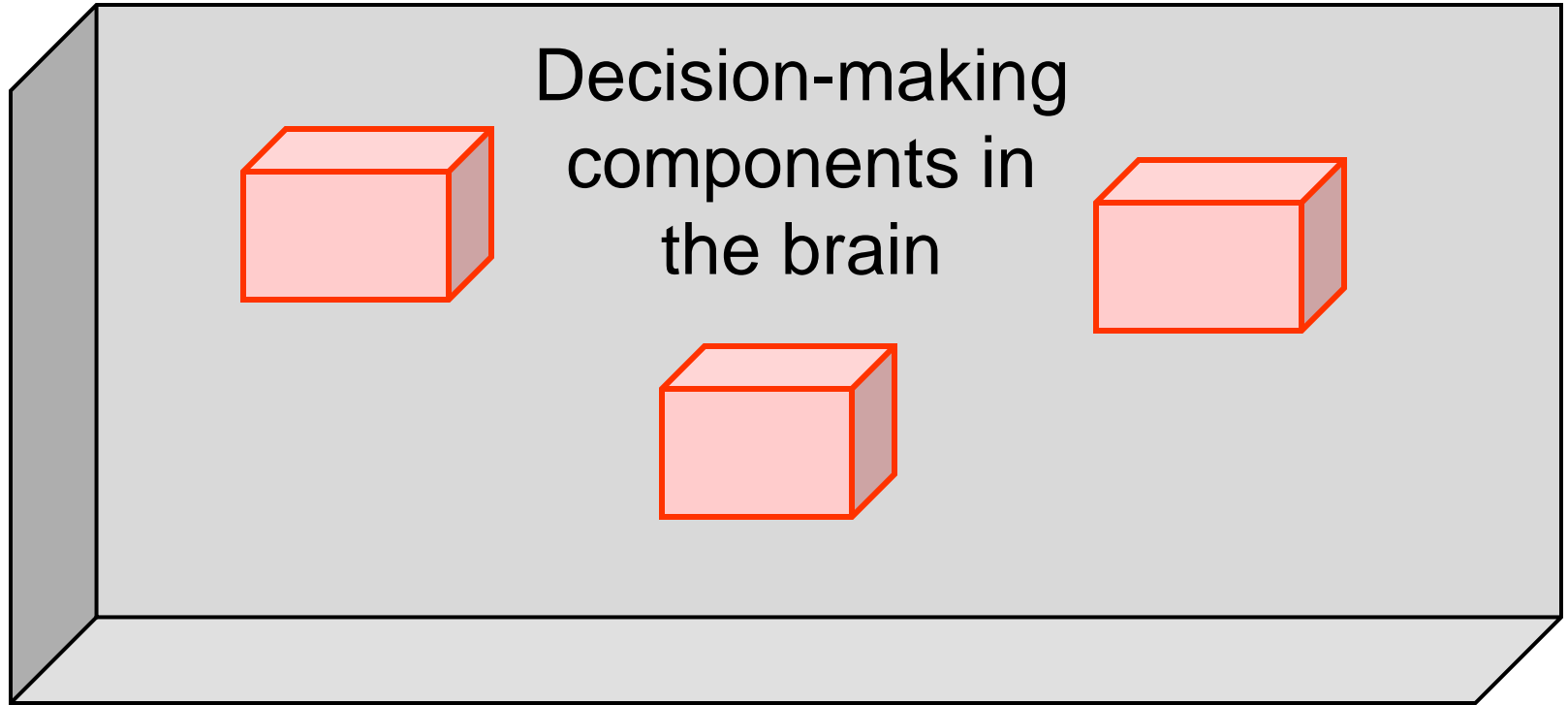
Brain as ~~optimal~~ controller

- Acquire
- Translate/
integrate
- **Automate**

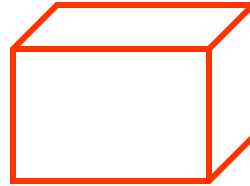
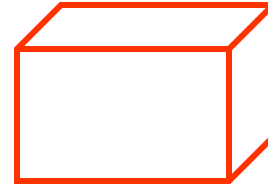
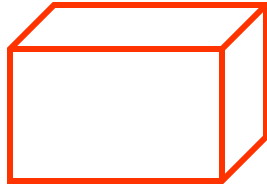


Going beyond black box: control is decentralized with internal delays.

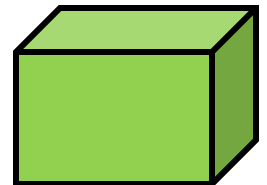
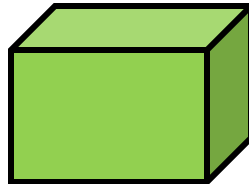
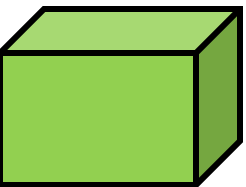
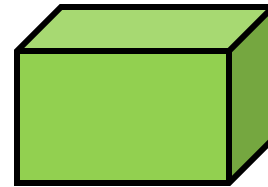
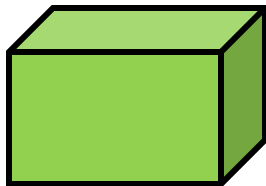




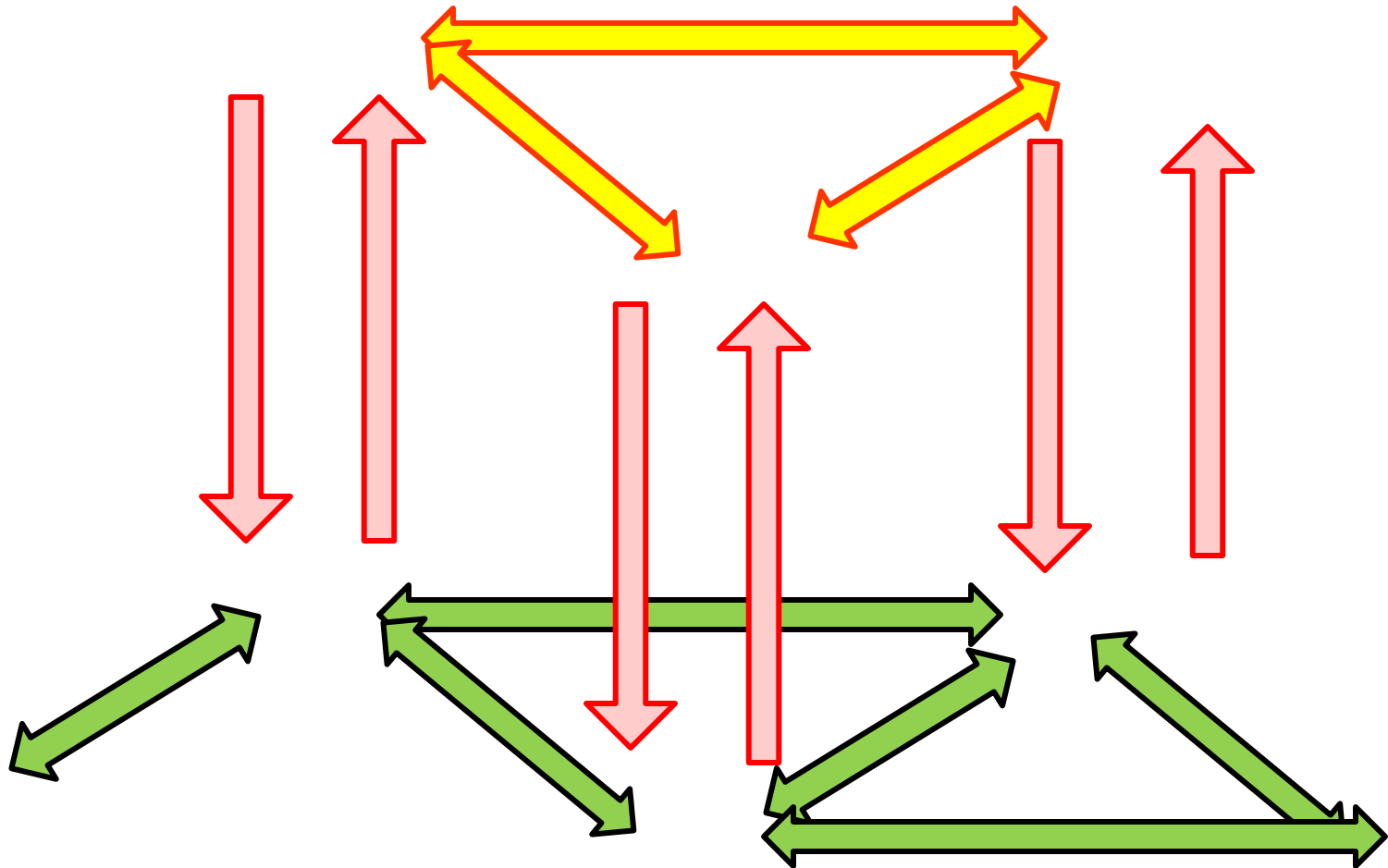
Decentralized, but initially assume
computation is fast and memory is abundant.



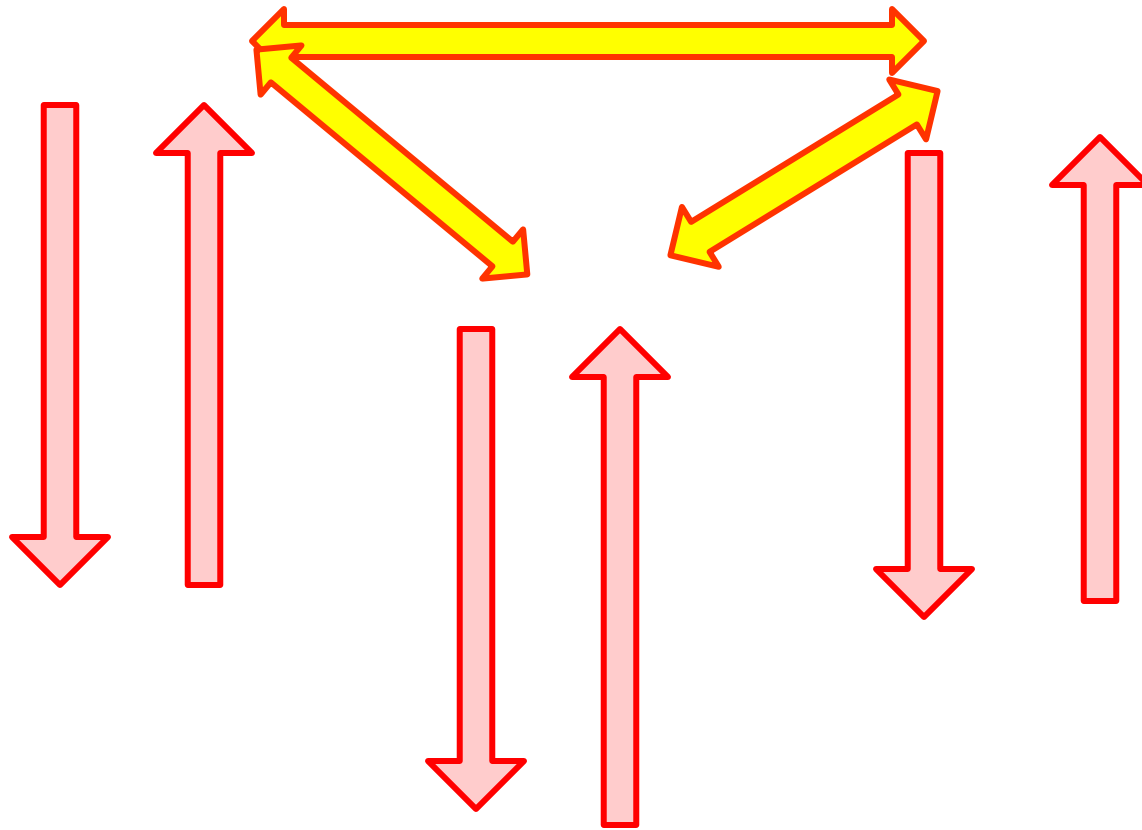
Plant is also distributed with its own component dynamics



Internal delays between brain components, and their sensor and actuators, and also externally between plant components



Internal delays involve both computation and communication latencies



Compute

Communicate

Turing

Shannon

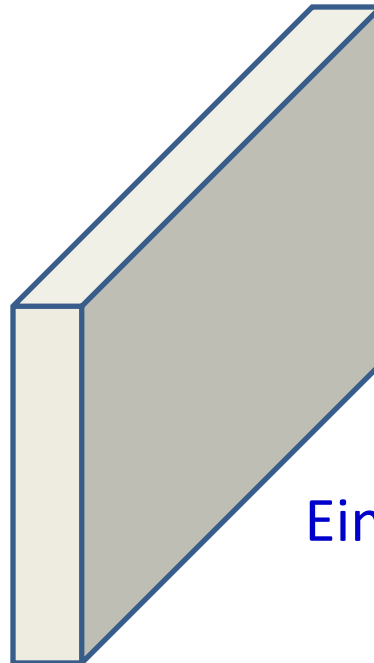
**This progress
is important.**

**Delay is
most
important**

New progress!



**Delay is
~~*least*~~
important**



Carnot

Bode

Boltzmann

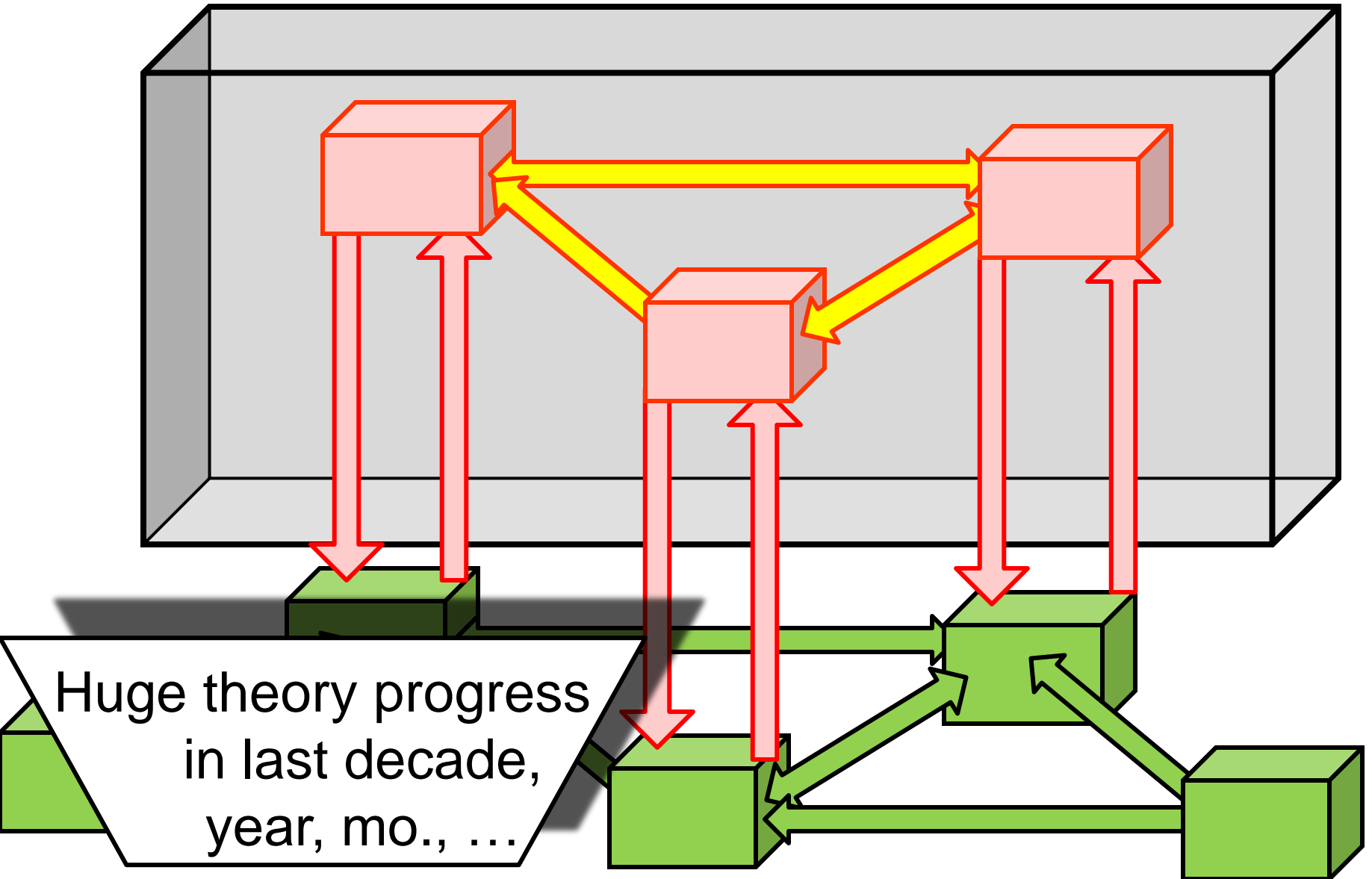
Control, OR

Heisenberg

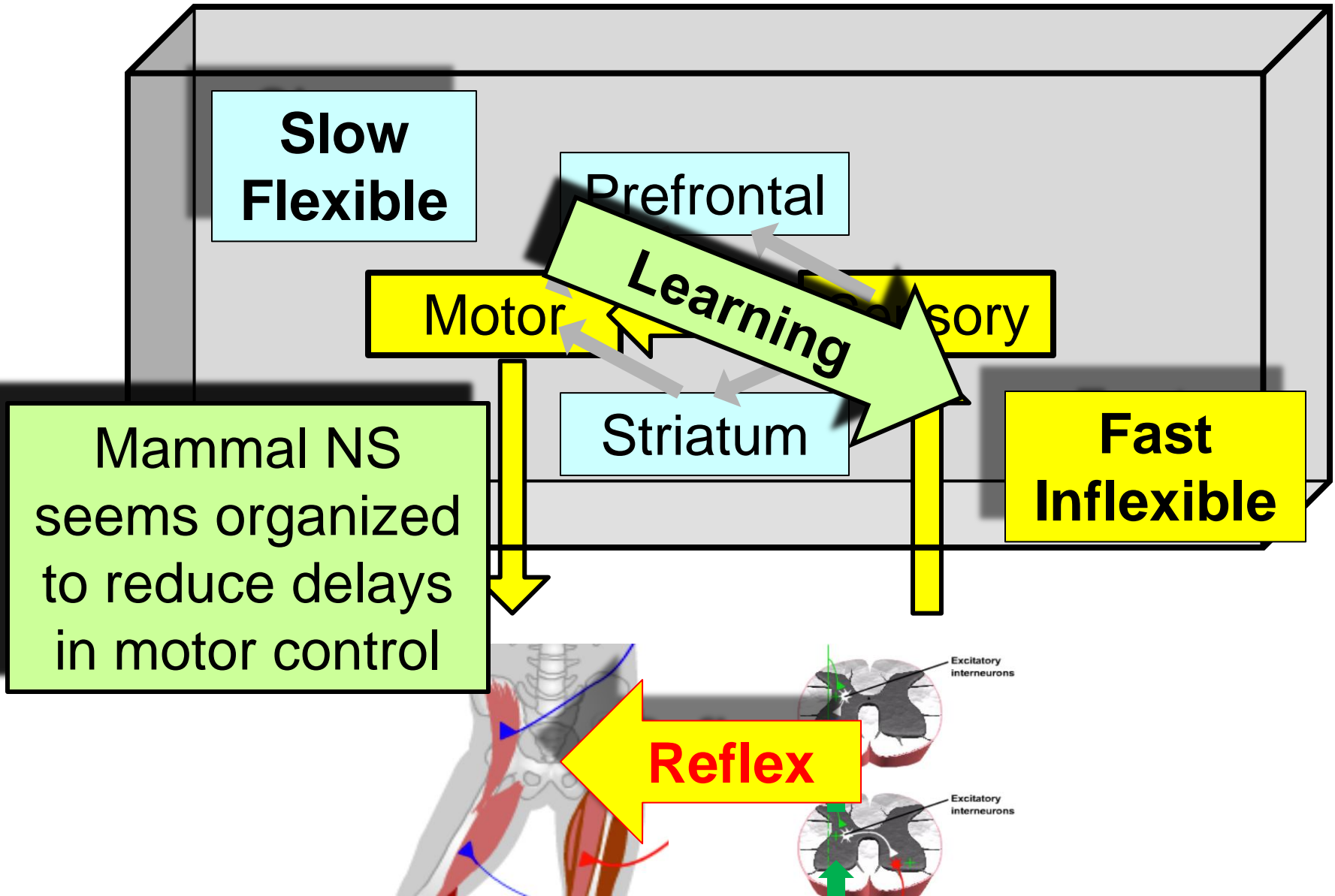
Einstein

Physics

Going beyond black box: control is decentralized with internal delays.



Going beyond black box: control is decentralized with internal delays.



Universal architectures

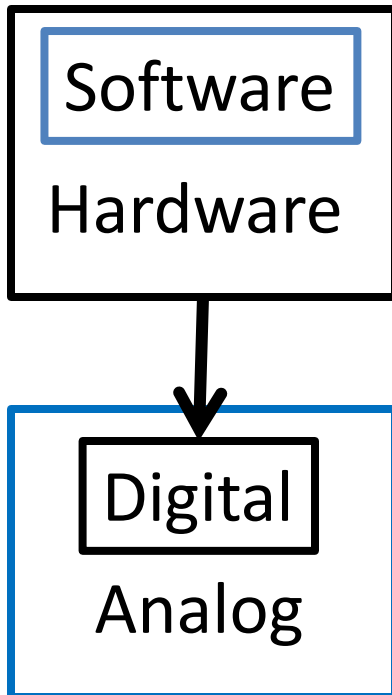
Implications

(Layered architectures discussed elsewhere)

Turing as
“new”
starting
point?

Essentials:

0. Model
1. Universal laws
- 2. Universal architecture**
3. Practical implementation



Turing’s 3 step research:

0. Virtual (TM) machines
1. hard limits, (un)decidability using standard model (TM)
- 2. Universal architecture achieving hard limits (UTM)**
3. Practical implementation in digital electronics (biology?)

**Horizontal
App
Transfer**

Applications

Operating
System

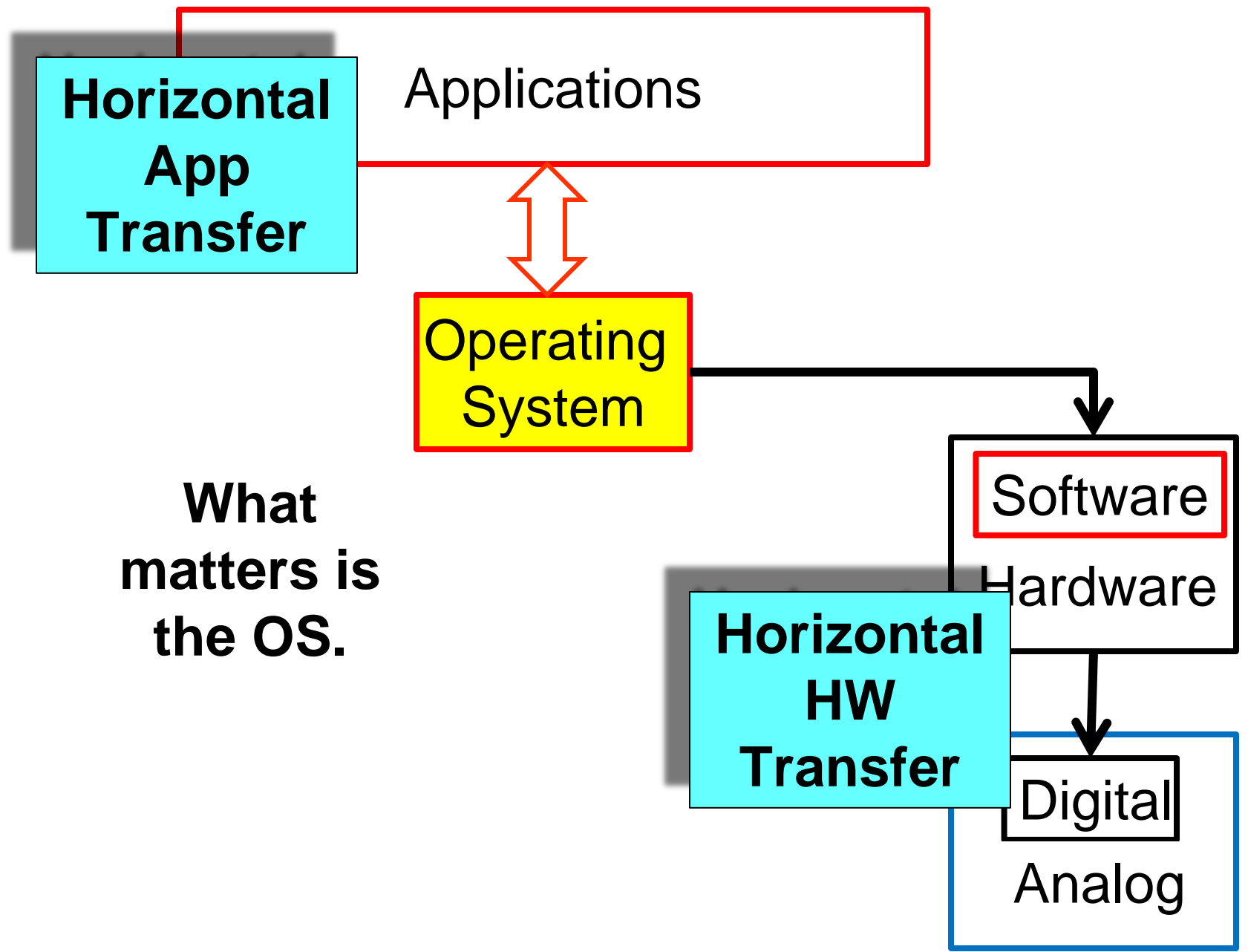
Software

Hardware

**Horizontal
HW
Transfer**

Digital
Analog

**What
matters is
the OS.**



**Flexible/
Adaptable/
Evolvable**

**Horizontal
Meme
Transfer**

frontal

Sensory

Learning

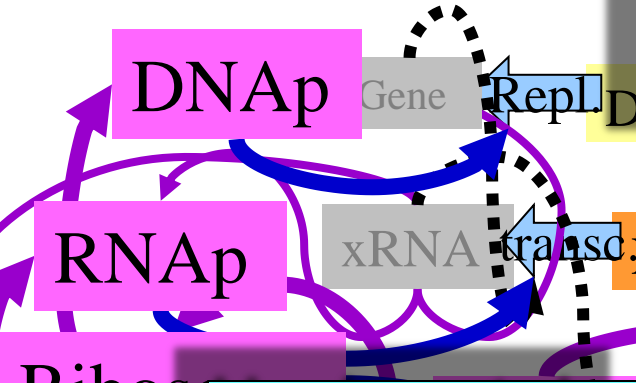
Striatu

Reflex

Software
Hardware

**Horizontal
App
Transfer**

Digital
Analog

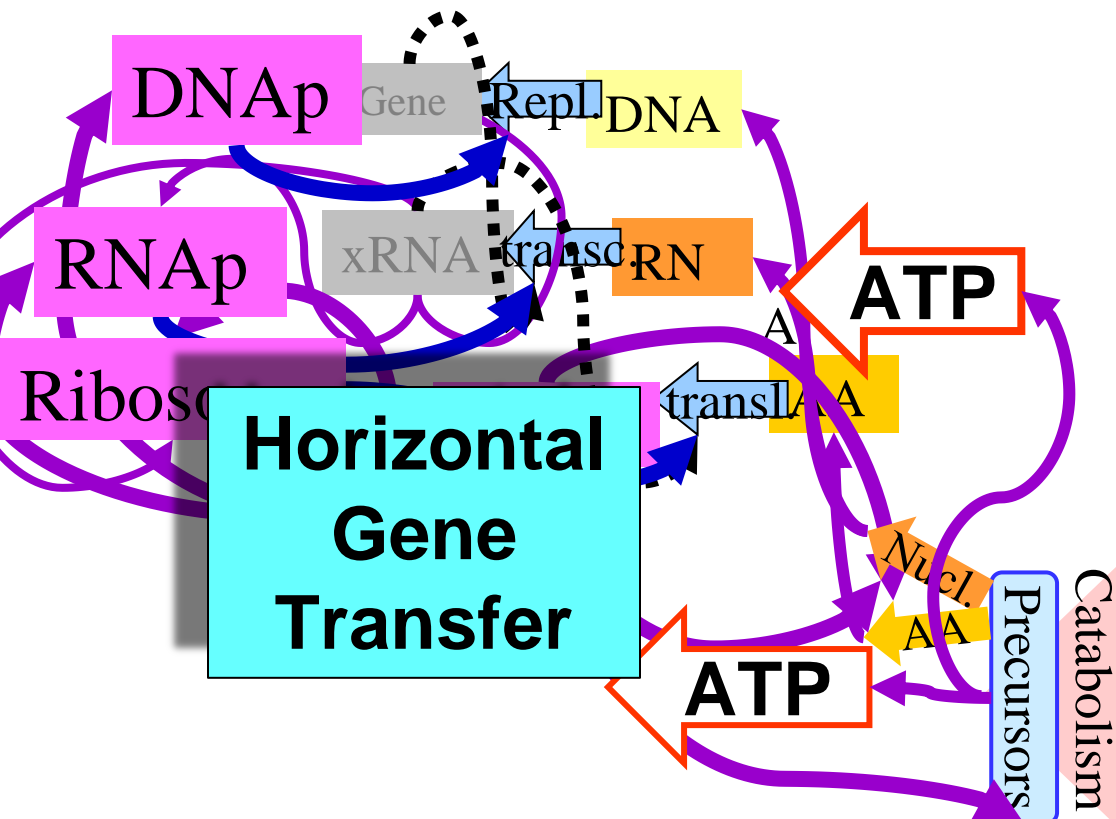


**Horizontal
Gene
Transfer**

**Depends
crucially on
layered
architecture**

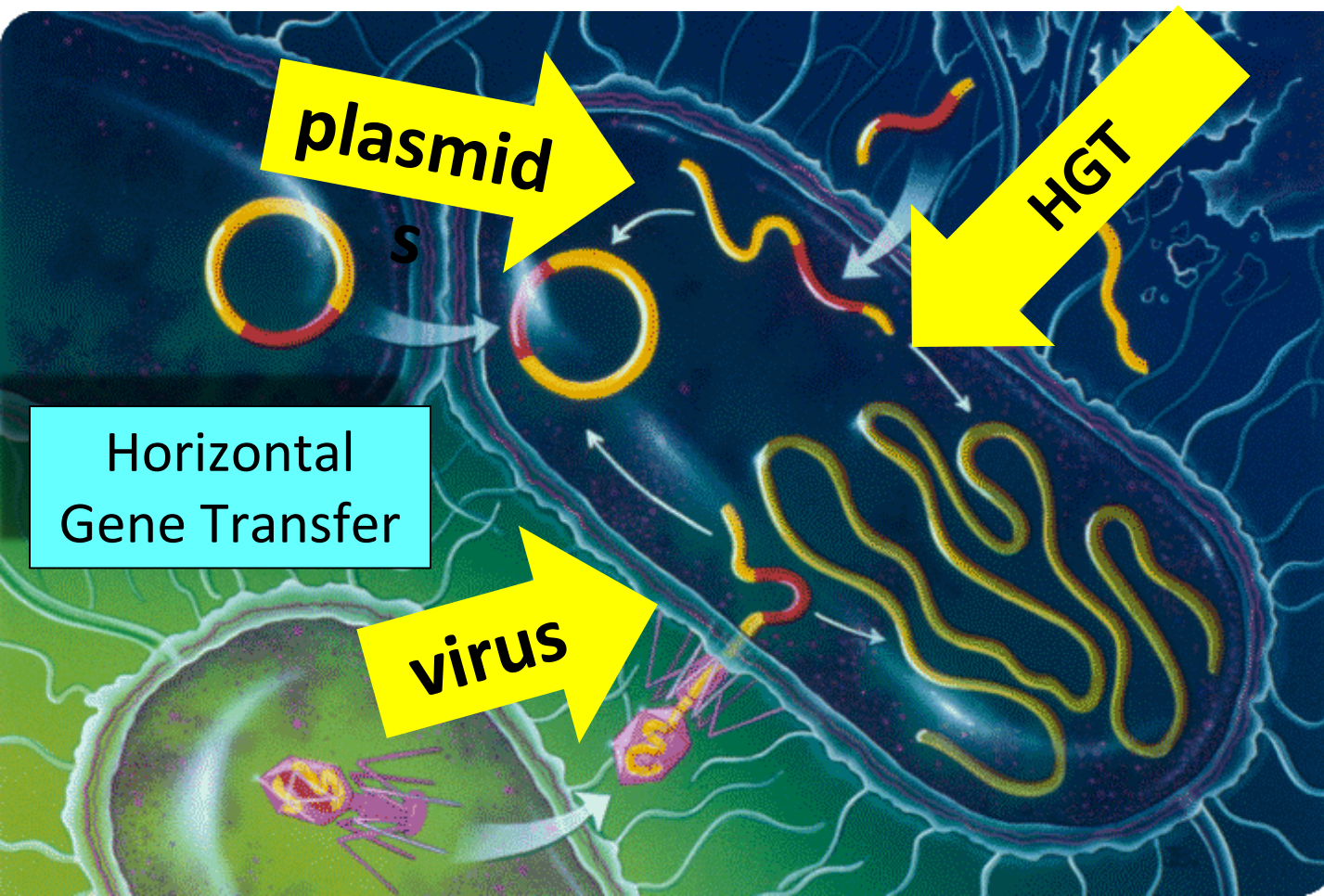
Sequence ~100 E Coli (*not* chosen randomly)

- ~ 4K genes per cell
- ~20K *different* genes in total
- ~ 1K universally shared genes



See slides on microbial biosphere laws and architectures.

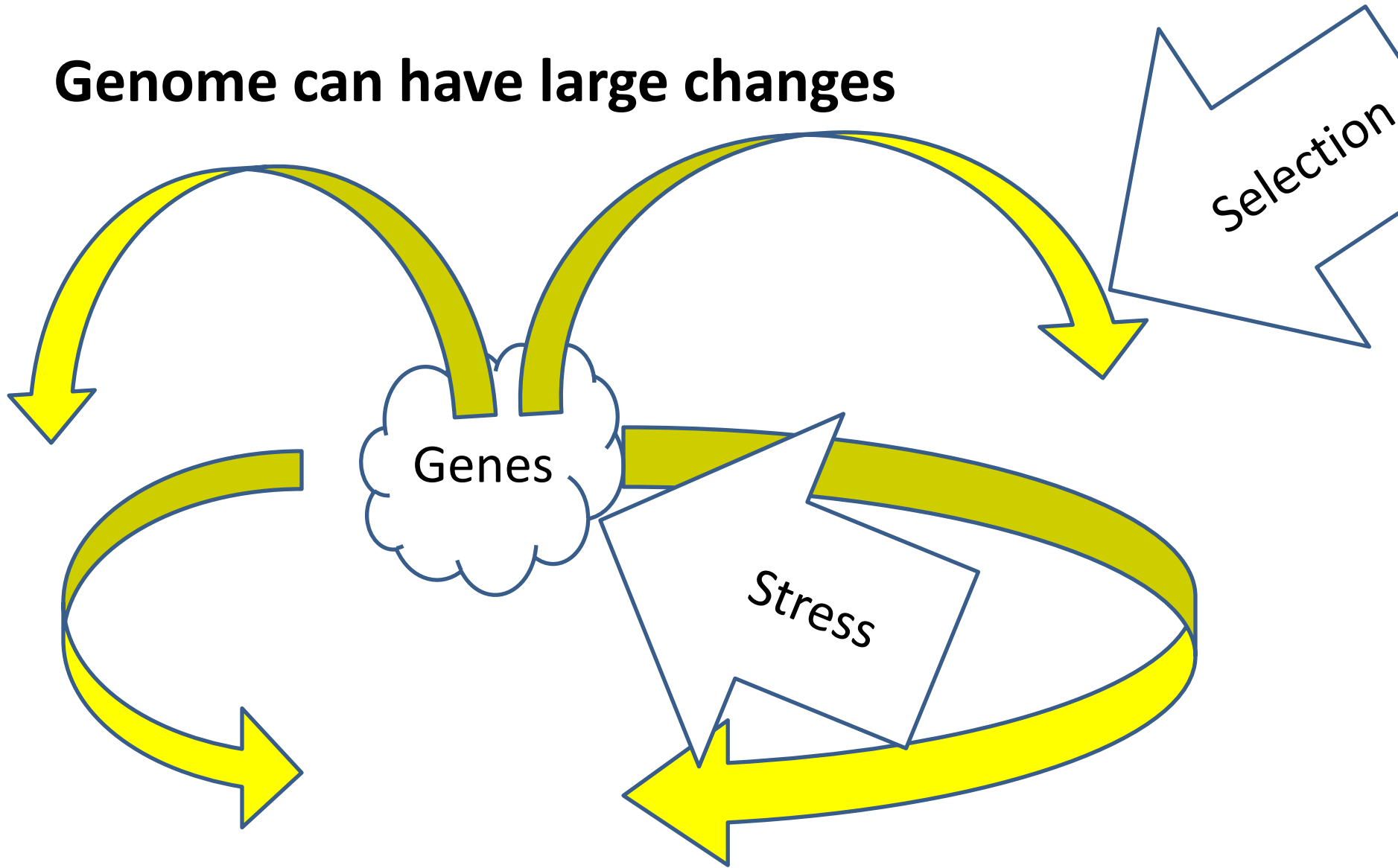
selection + drift + mutation + gene flow
+ facilitated *variation*



large
functional
changes in
genomes

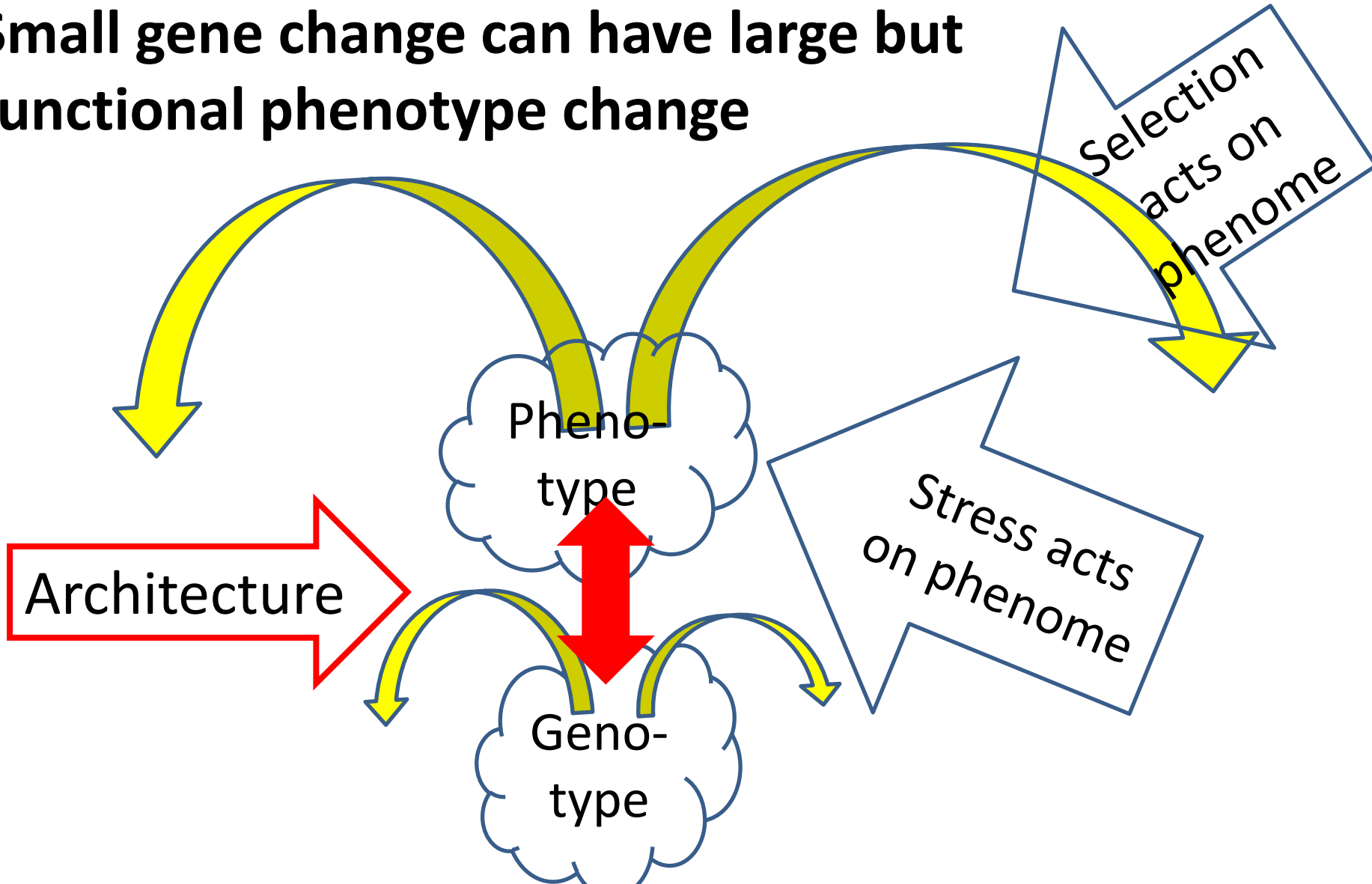
natural selection + genetic drift + mutation + gene flow
+ facilitated *variation*

Genome can have large changes



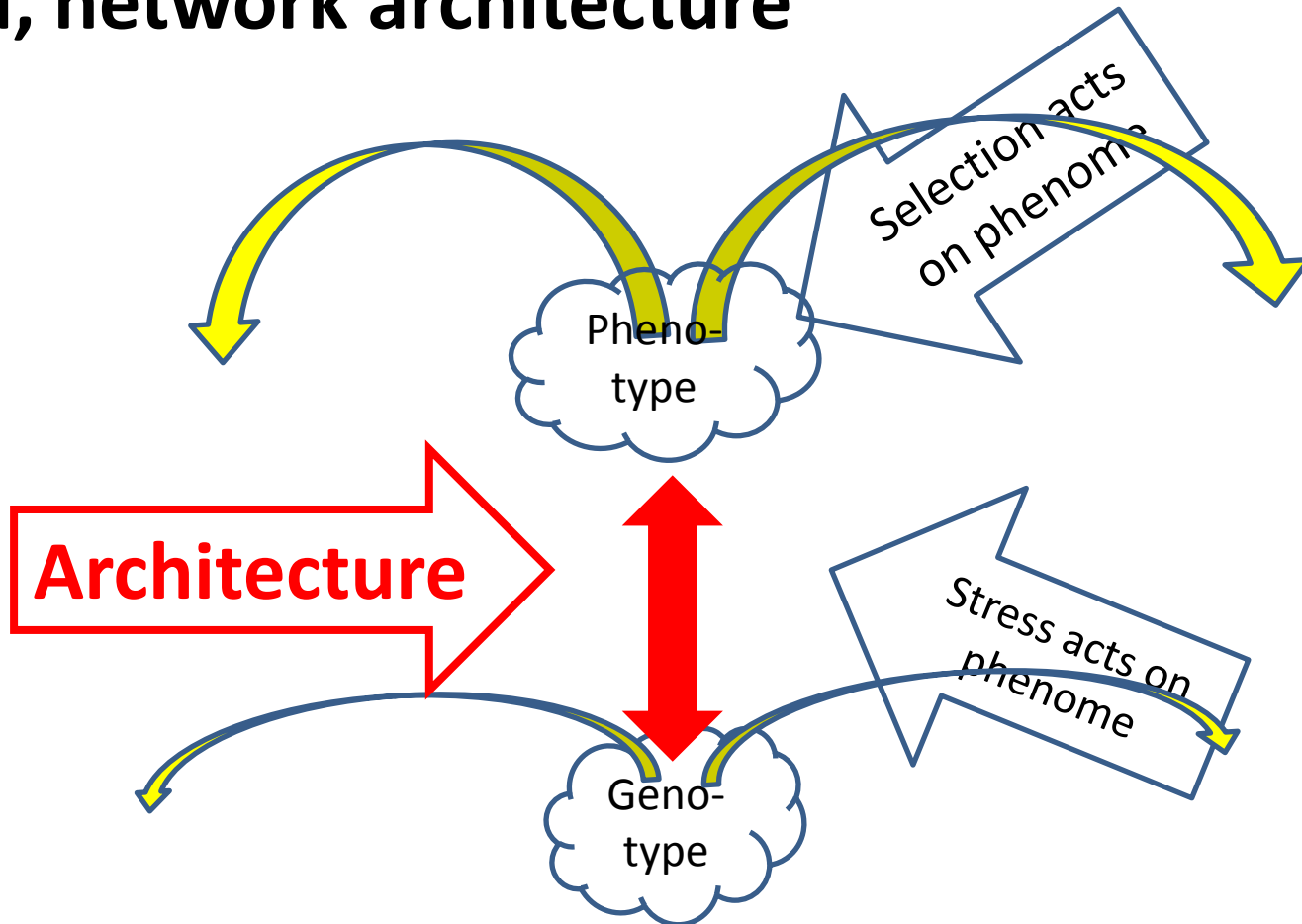
natural selection + genetic drift + mutation + gene flow
+ facilitated *variation*

**Small gene change can have large but
functional phenotype change**



natural selection + genetic drift + mutation + gene flow
+ facilitated *variation*

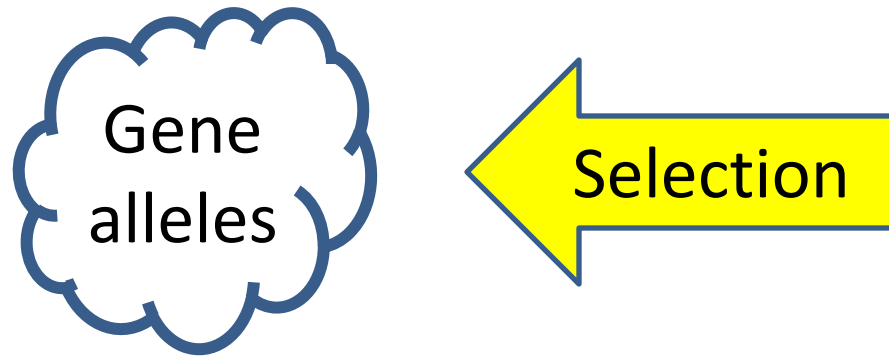
**Only possible because of shared,
layered, network architecture**



Standard theory:

natural selection + genetic drift
+ mutation + gene flow

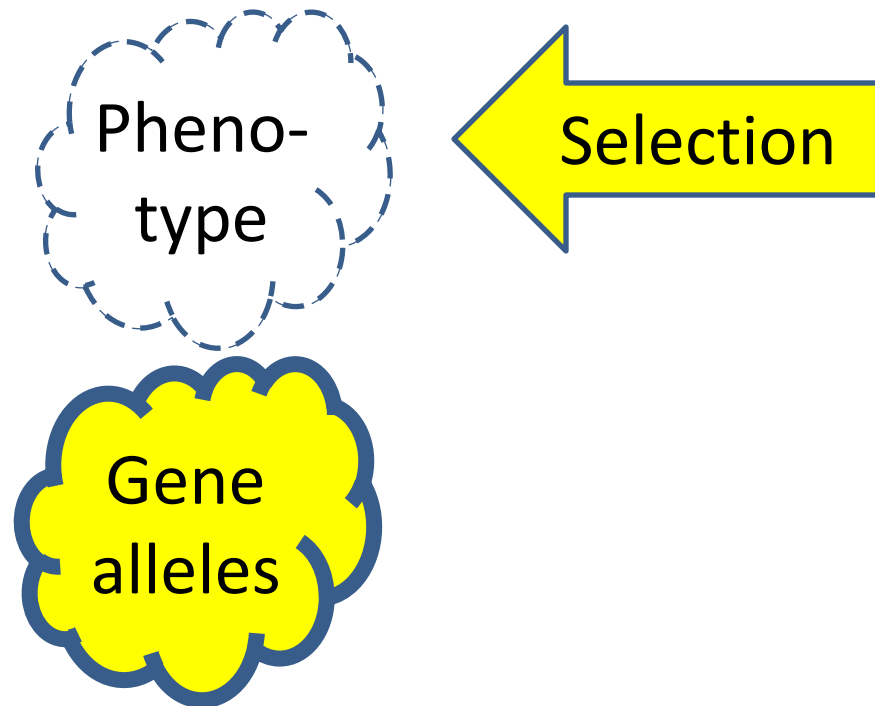
Greatly abridged cartoon here



Shapiro explains well what this is and why it's incomplete (but Koonin is more mainstream)

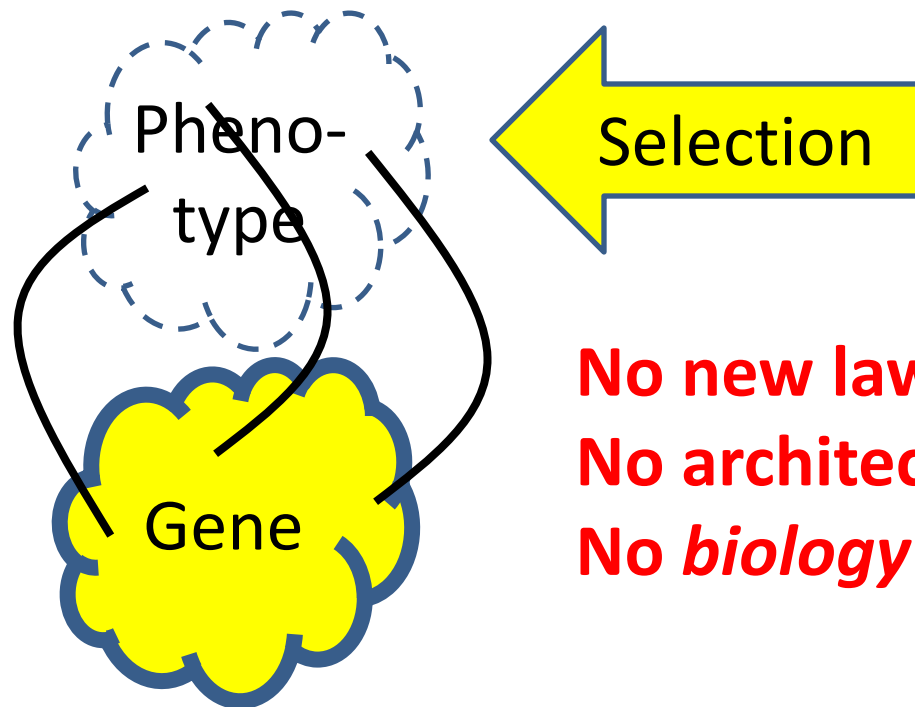
Standard theory:

selection + drift + mutation + gene flow



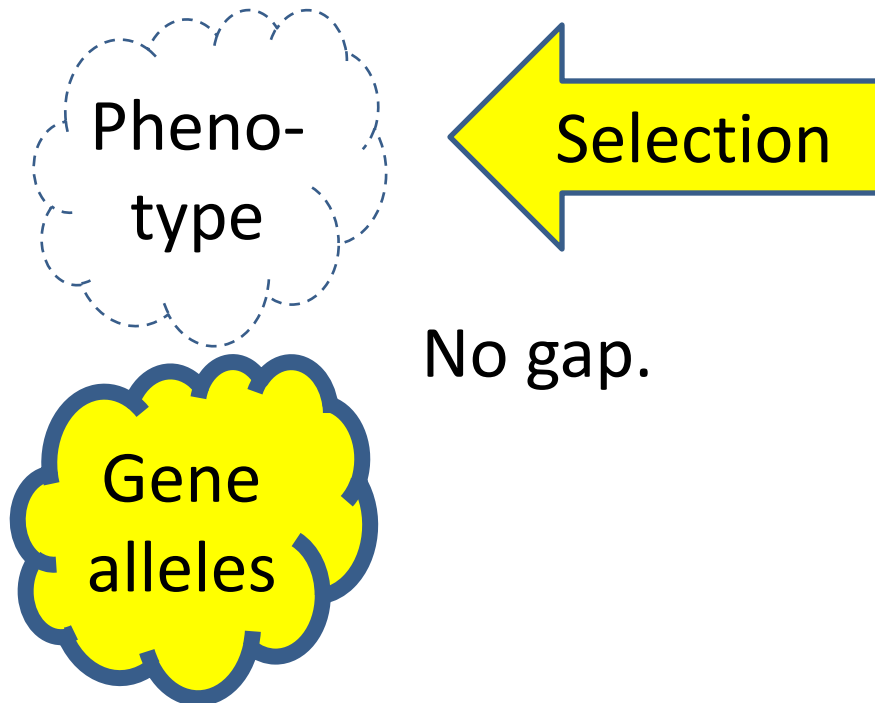
Standard theory:

selection + drift + mutation + gene flow



No new laws.
No architecture.
No *biology*.

selection +
drift +
mutation +
gene flow



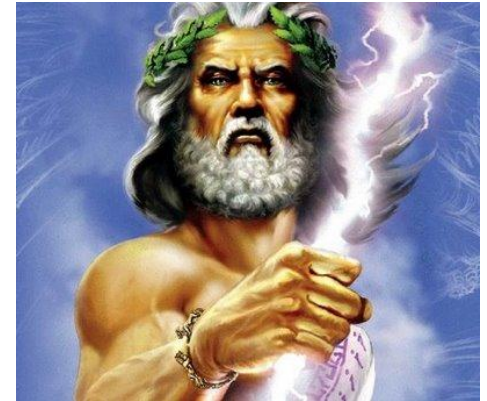
All complexity is emergent from random ensembles with minimal tuning .

No new laws.

No architecture.

The battleground

Pheno-
type



Huge gap.
Need
supernatural

Genes?

Pheno-
type

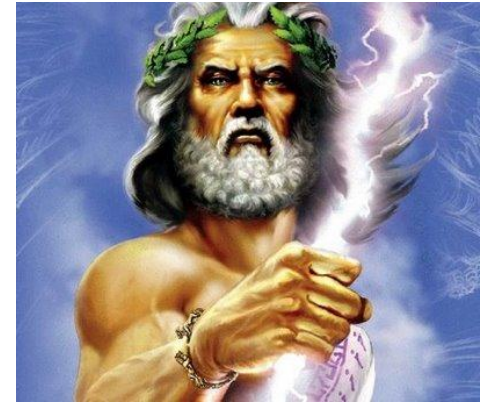
No gap.
Just physics.

Gene
alleles

What they agree on

No new laws.
No architecture.
No biology.

Pheno-
type



Huge
gap.

Pheno-
type

No gap.

Gene
alleles

Genes

Depends crucially on layered architecture

Analog

Digital



Motor

Sensory

Striatum

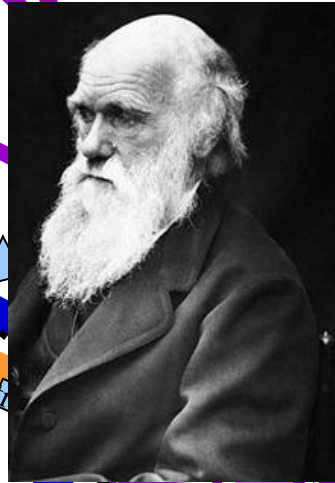
Ref

Horizontal Meme Transfer

Hardware

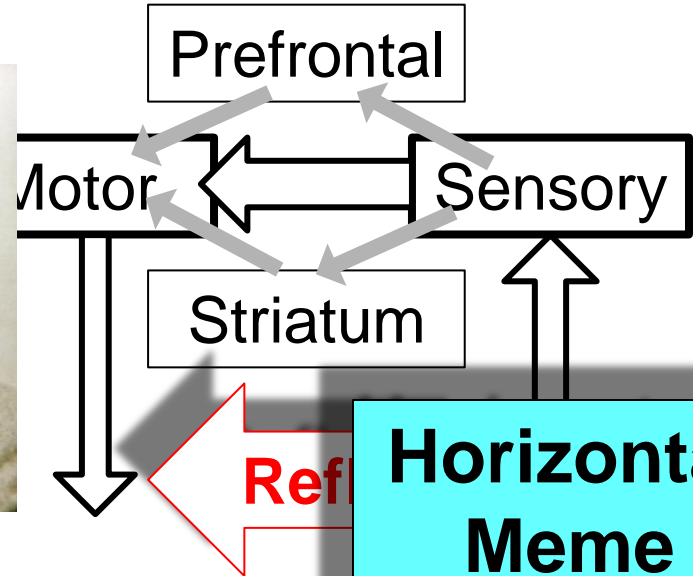
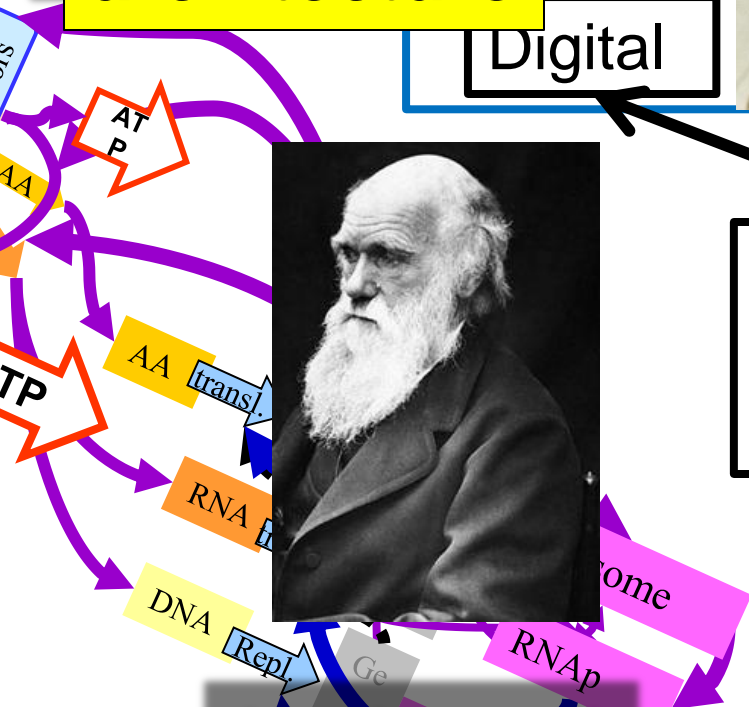
Soft

Horizontal App Transfer

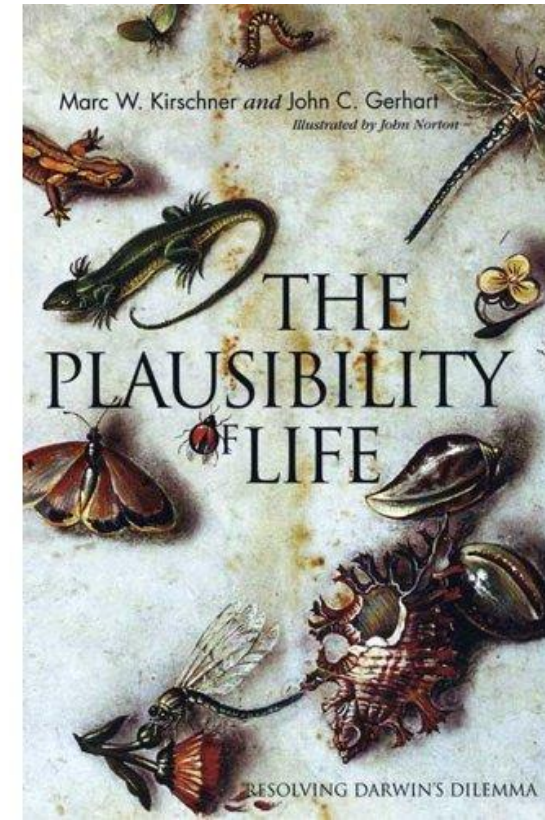
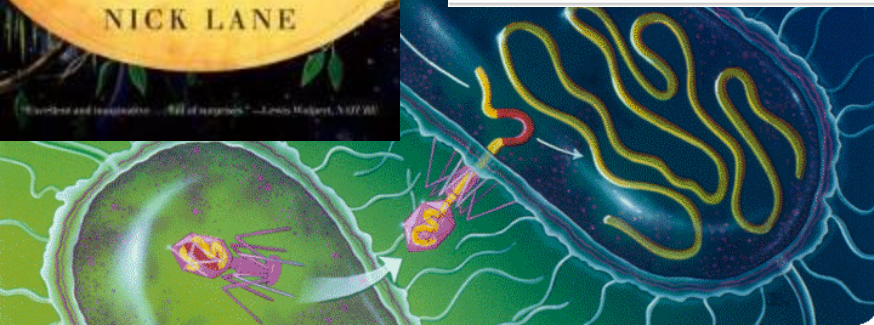
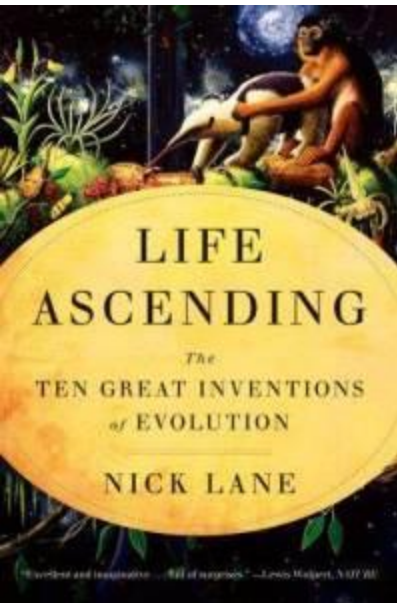
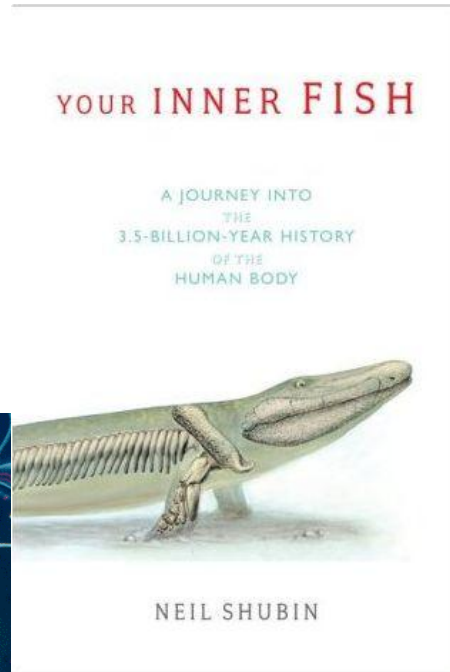


Horizontal Gene Transfer

Amazingly Flexible/Adaptable



Putting biology back into evolution



Universal architectures

What can go wrong?

Unfortunately, not
intelligent design

YOUR INNER FISH

A JOURNEY INTO
THE
3.5-BILLION-YEAR HISTORY
OF THE
HUMAN BODY

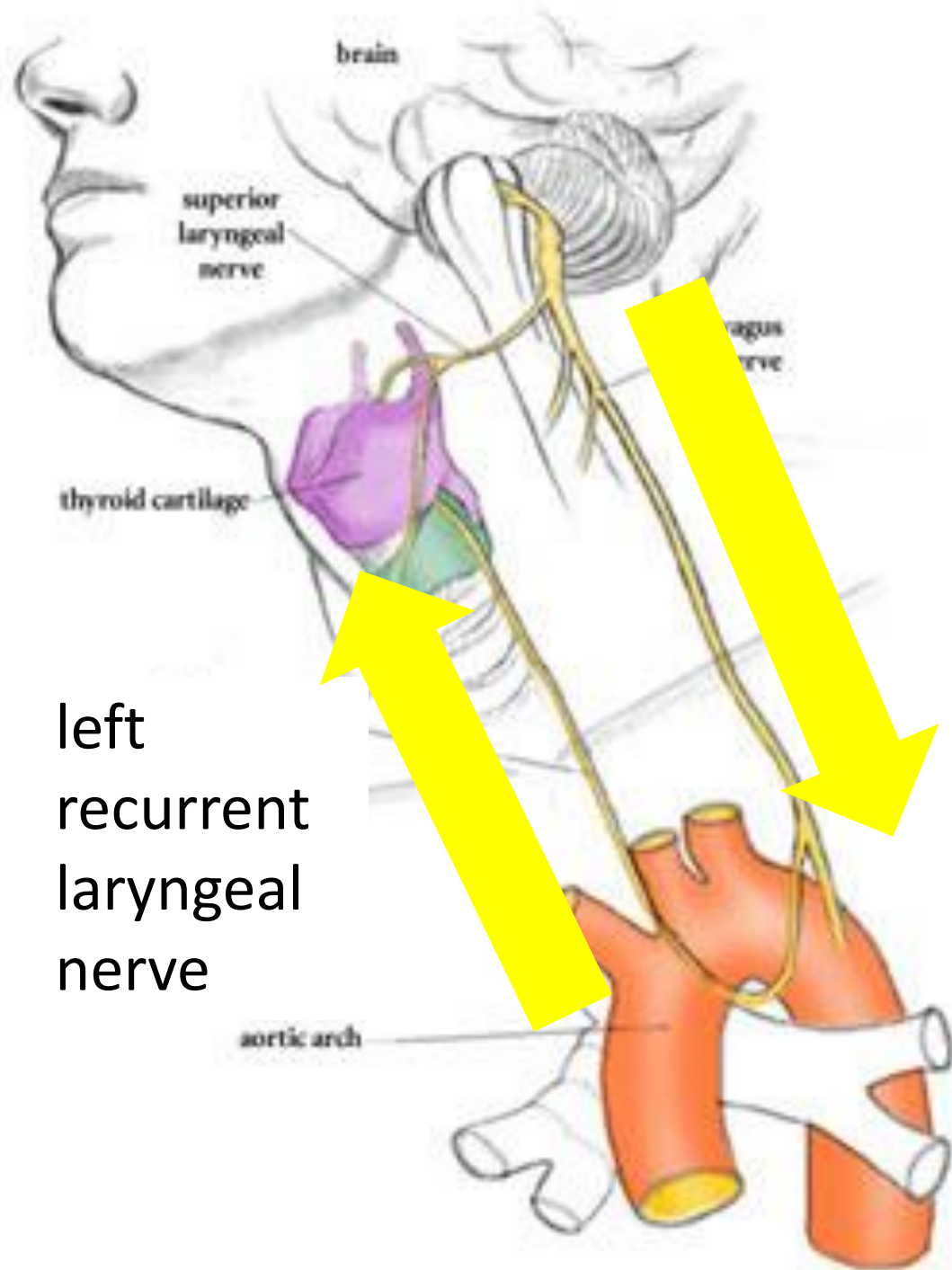
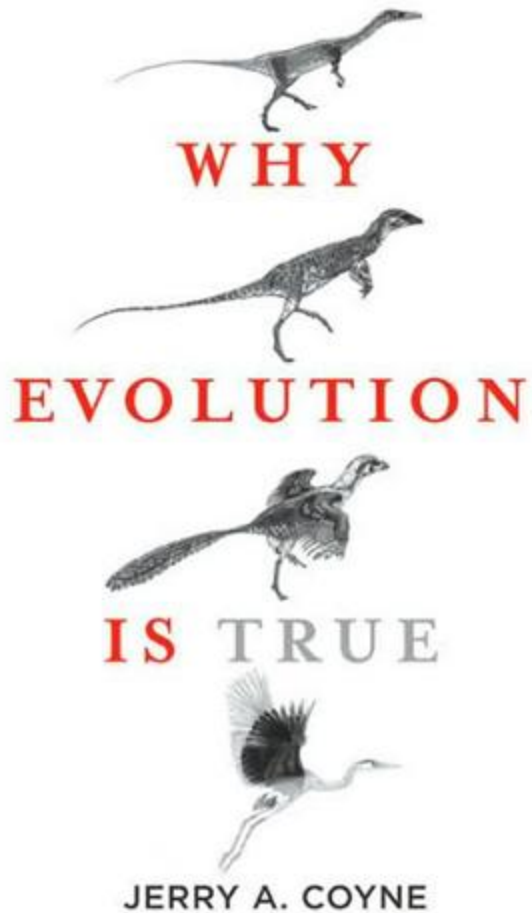


NEIL SHUBIN

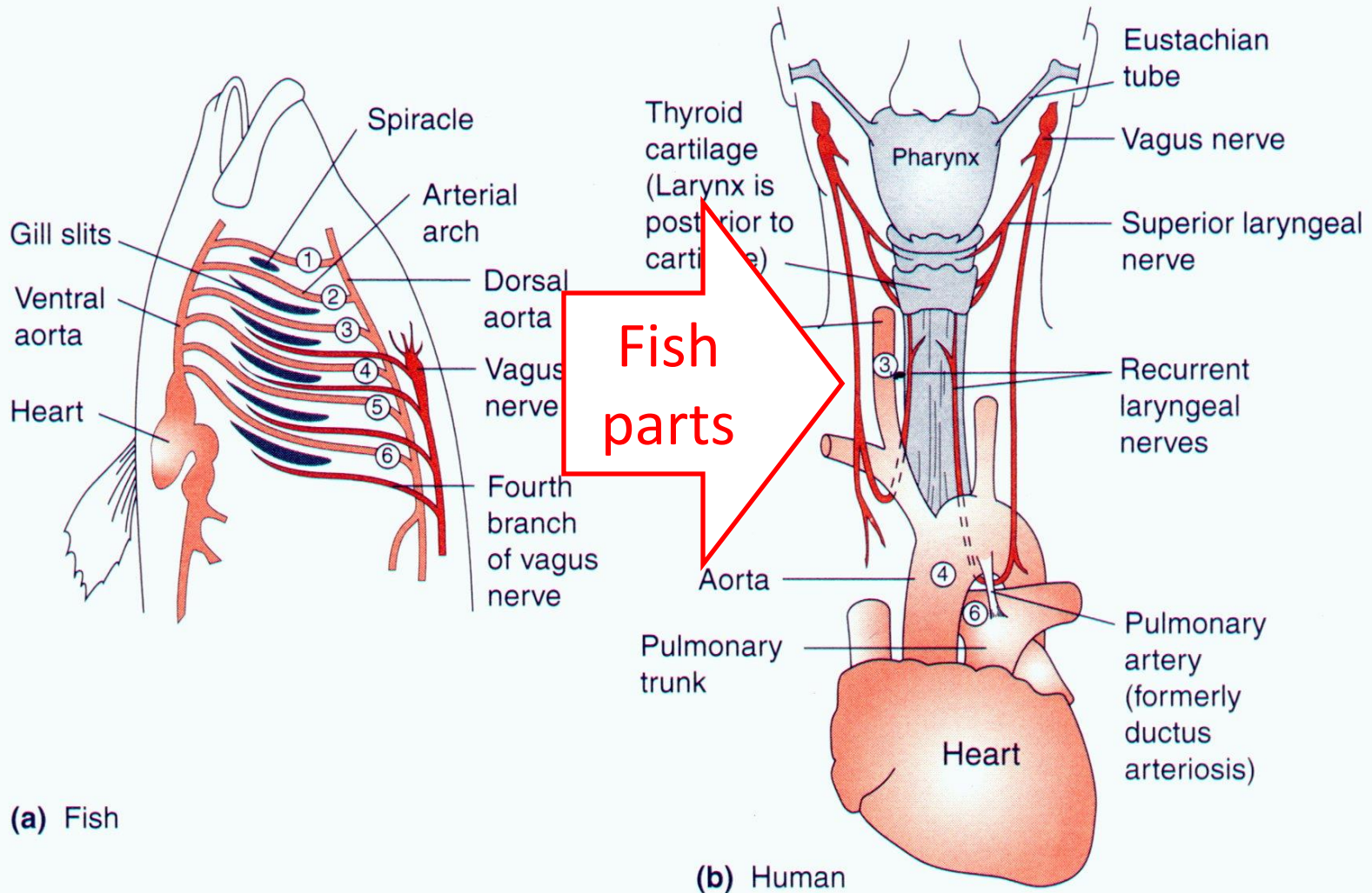


Ouch.

Why?



Why? Building humans from fish parts.

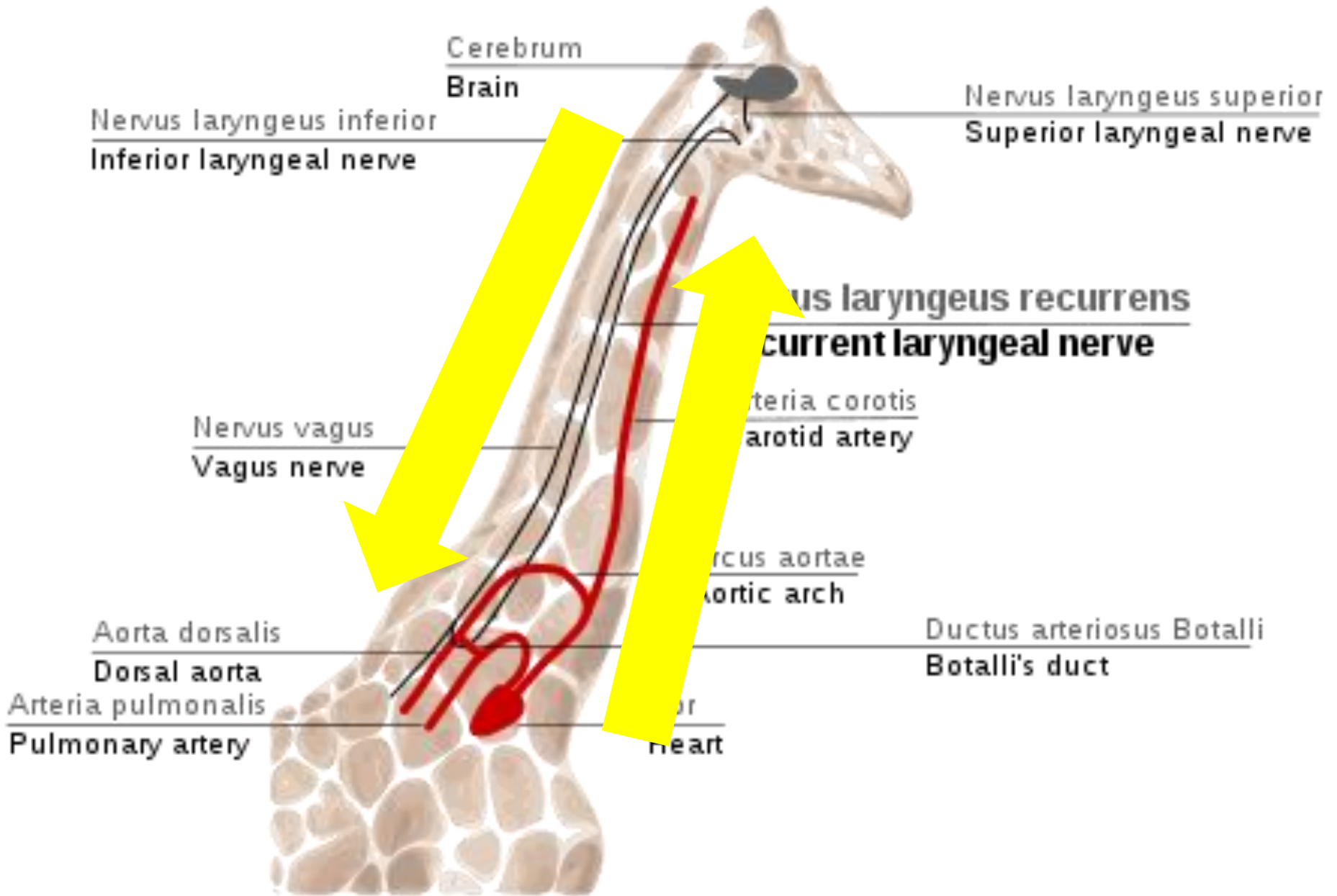


(a) Fish

(b) Human

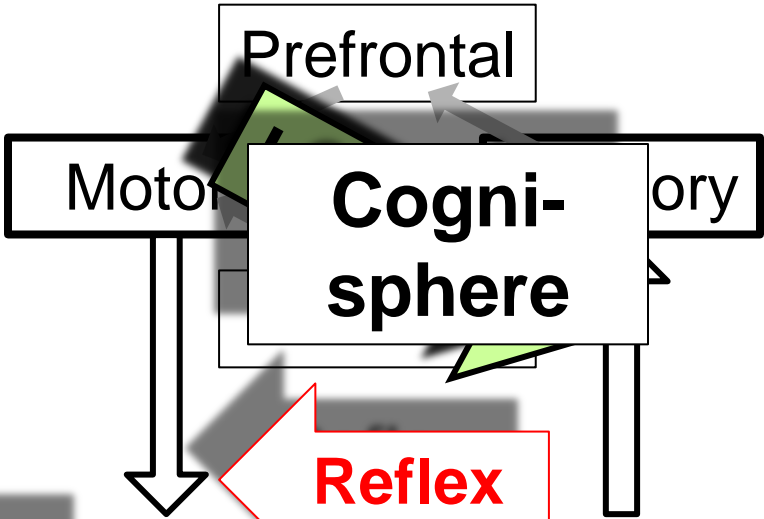
FIGURE 3-11 Schematic diagram showing the relationship between the vagus cranial nerve and the arterial arches in fish (a) and human (b). Only the third, fourth, and part of the sixth arterial arches remain in placental mammals, the sixth acting only during fetal development to carry blood to the placenta. The fourth vagal nerve in mammals (the recurrent laryngeal nerve) loops around the sixth arterial arch just as it did in the original fishlike ancestor, but must now travel a greater distance since the remnant of the sixth arch is in the thorax.

It could be worse.



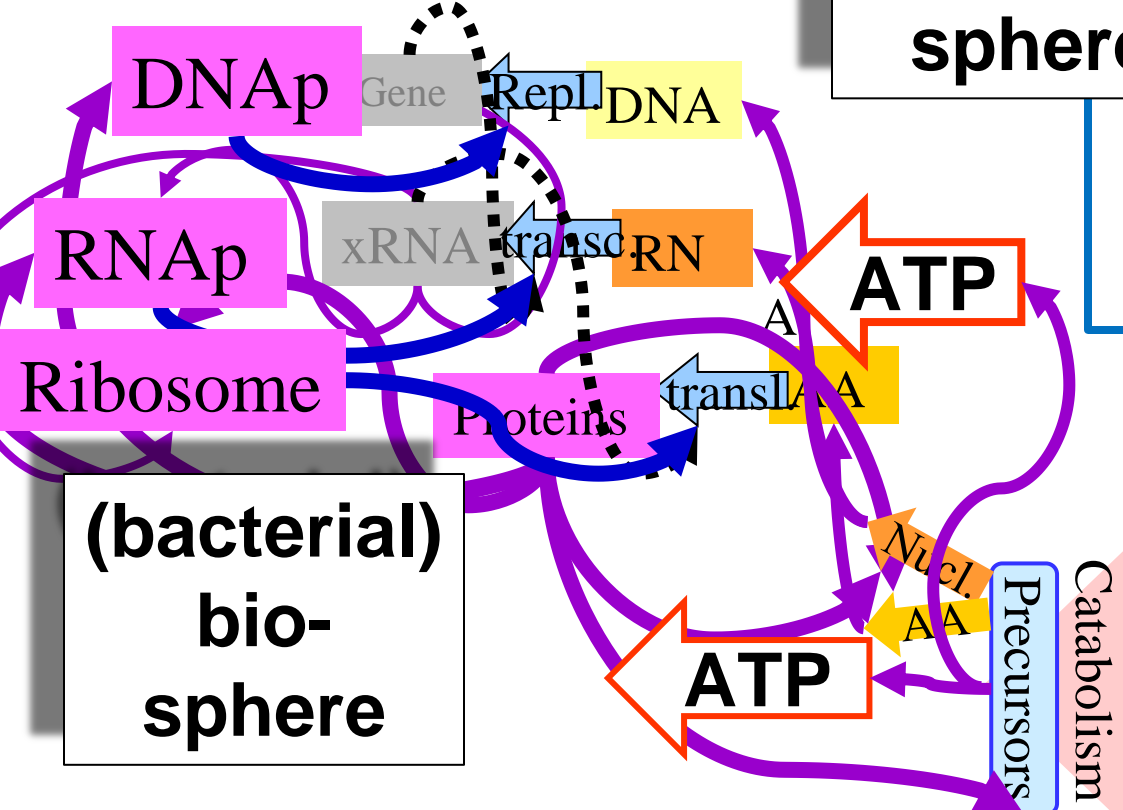
**Slow
Flexible**

Software
Hardware



**Techno-
sphere**

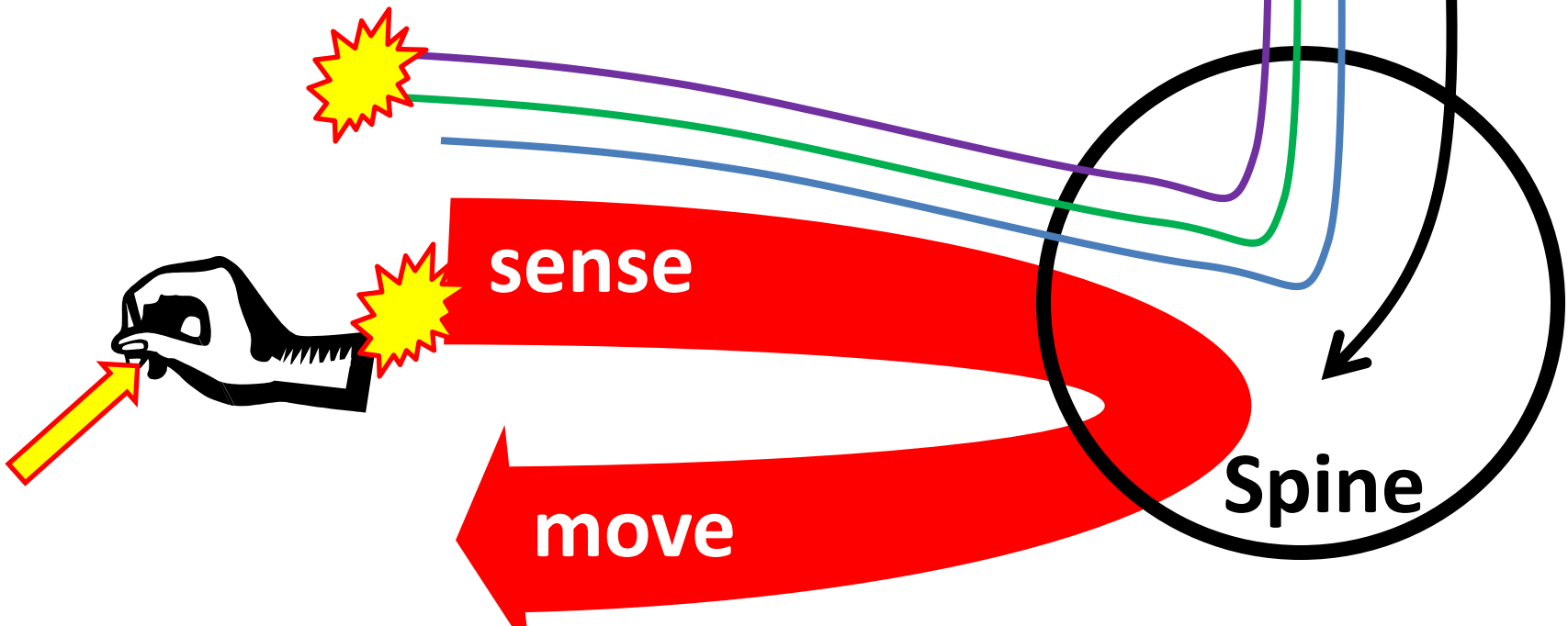
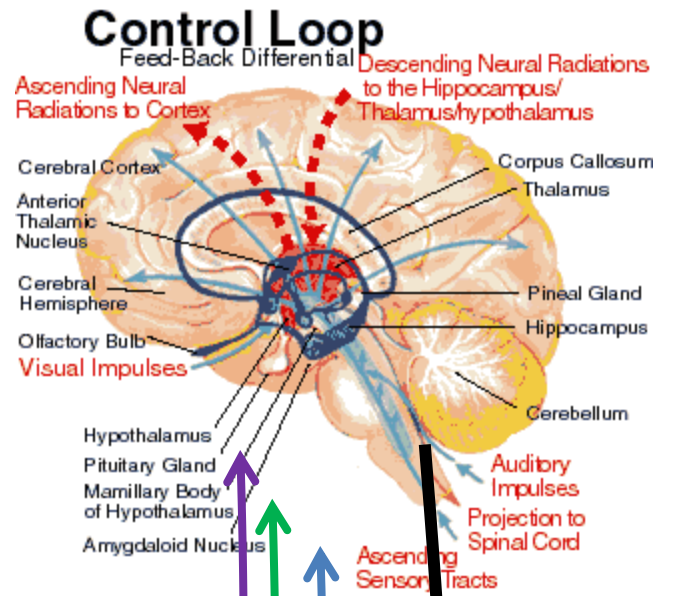
Digital
Analog



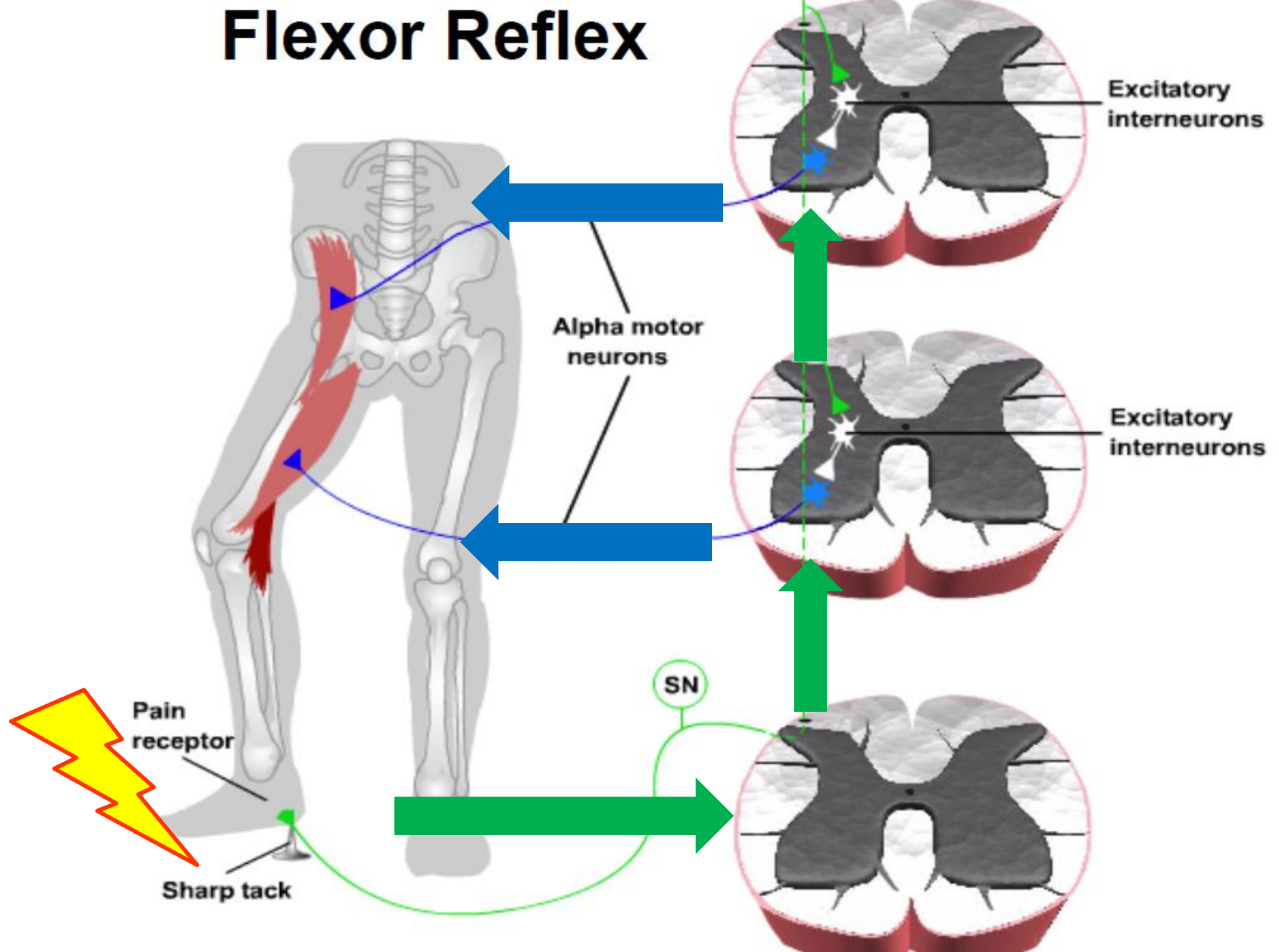
**(bacterial)
bio-
sphere**

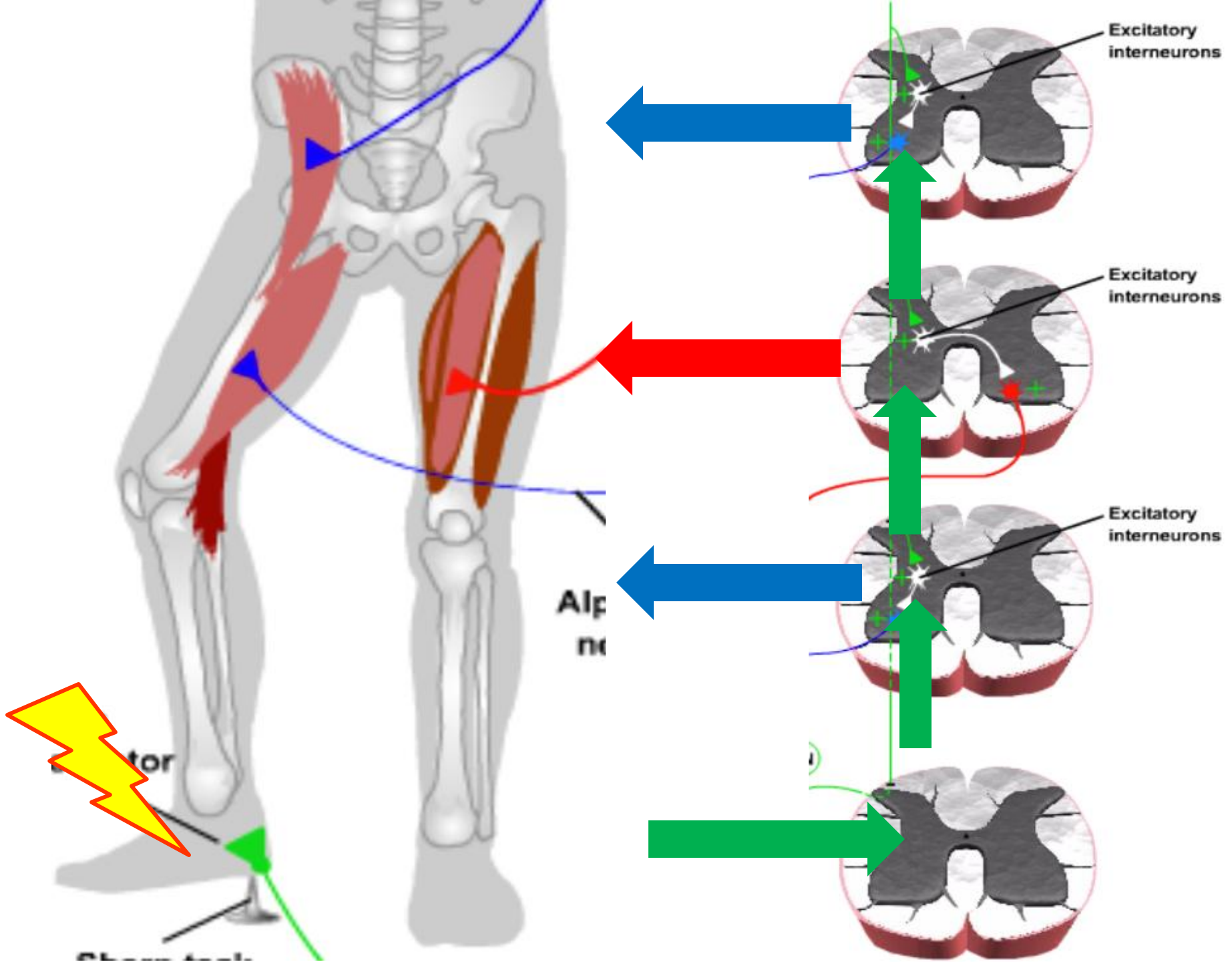
**Fast
Inflexible**

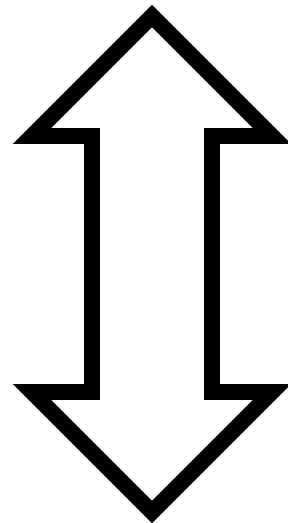
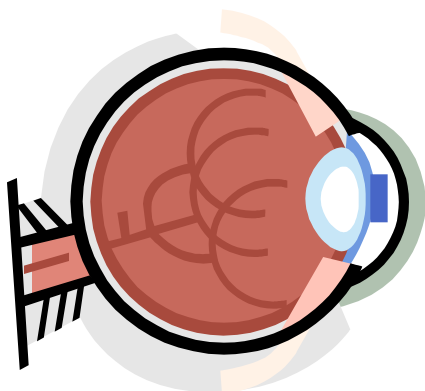
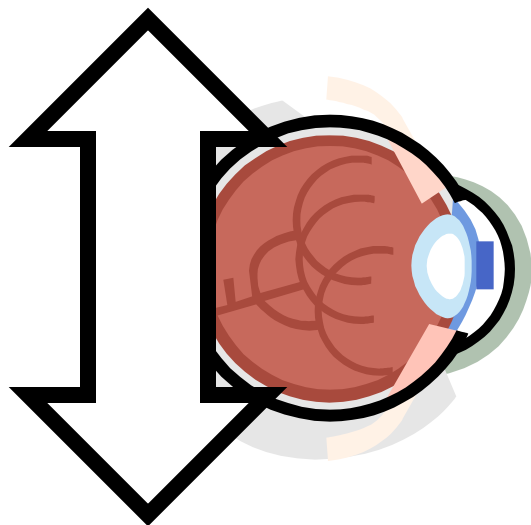
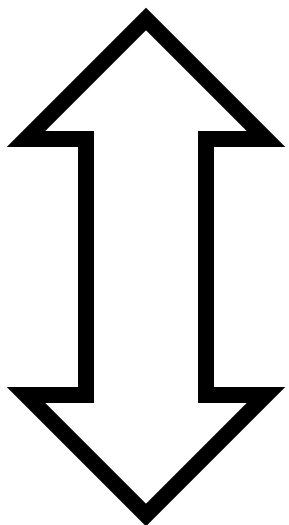
delay=death



Flexor Reflex







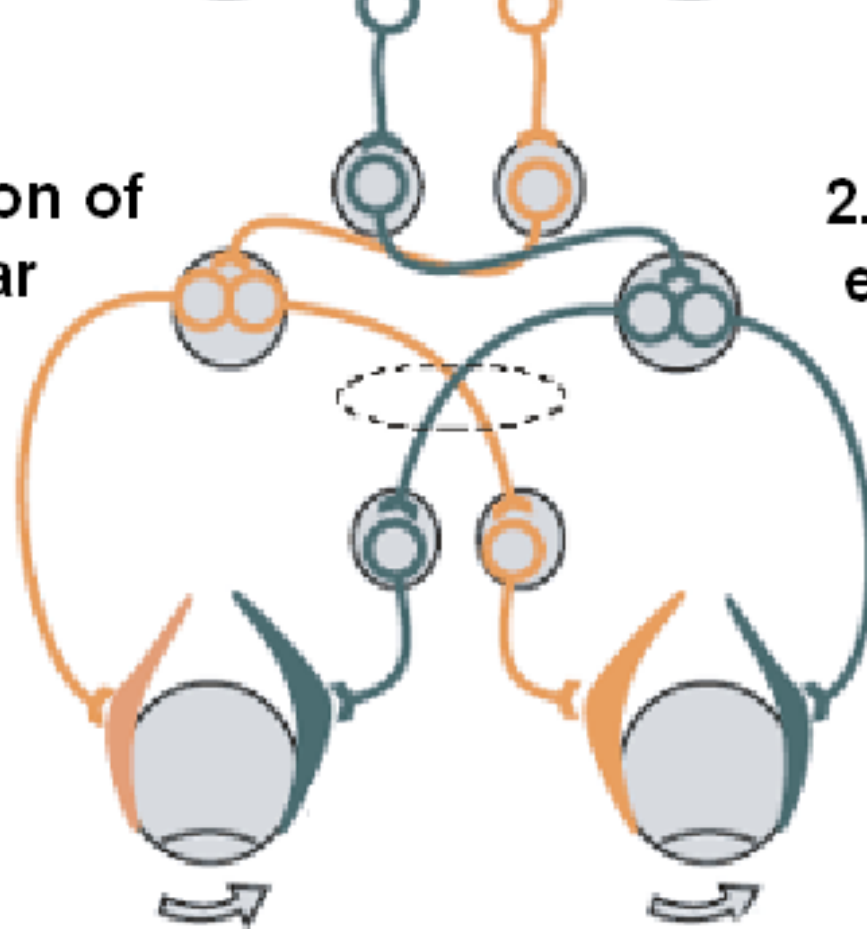
Vestibulo-ocular reflex

1. Detection of rotation

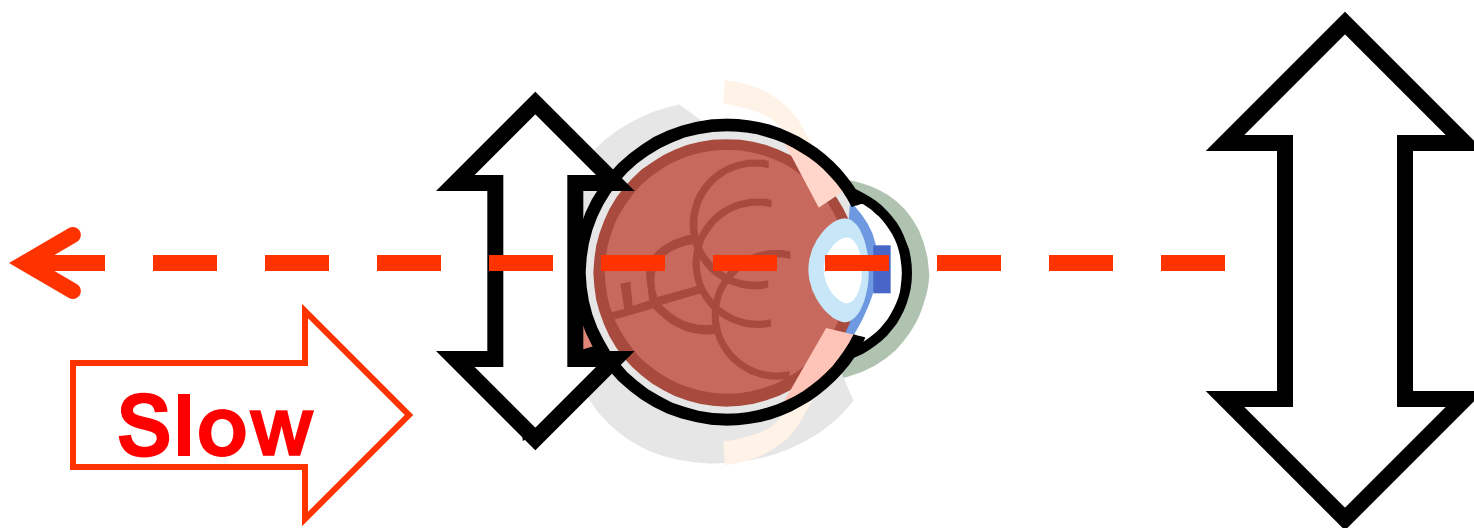
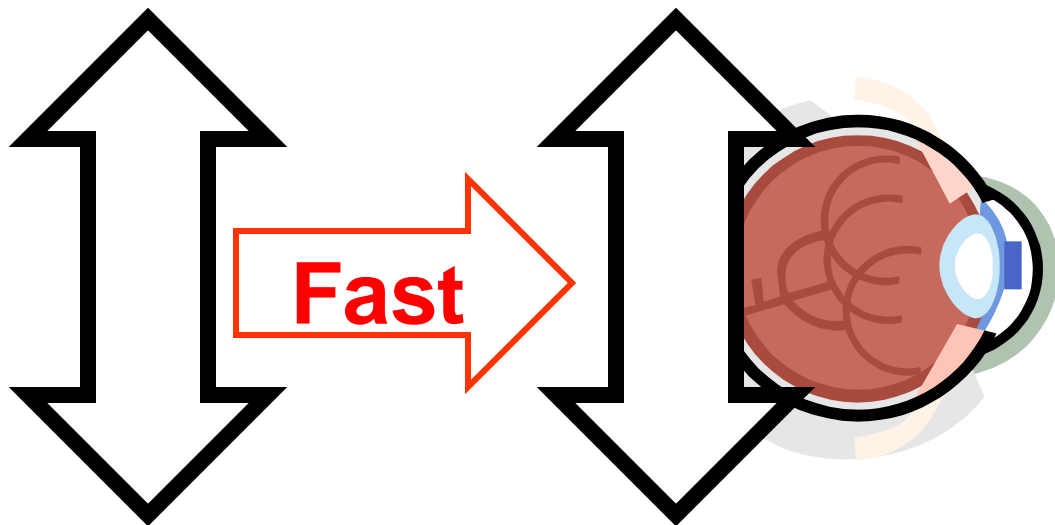


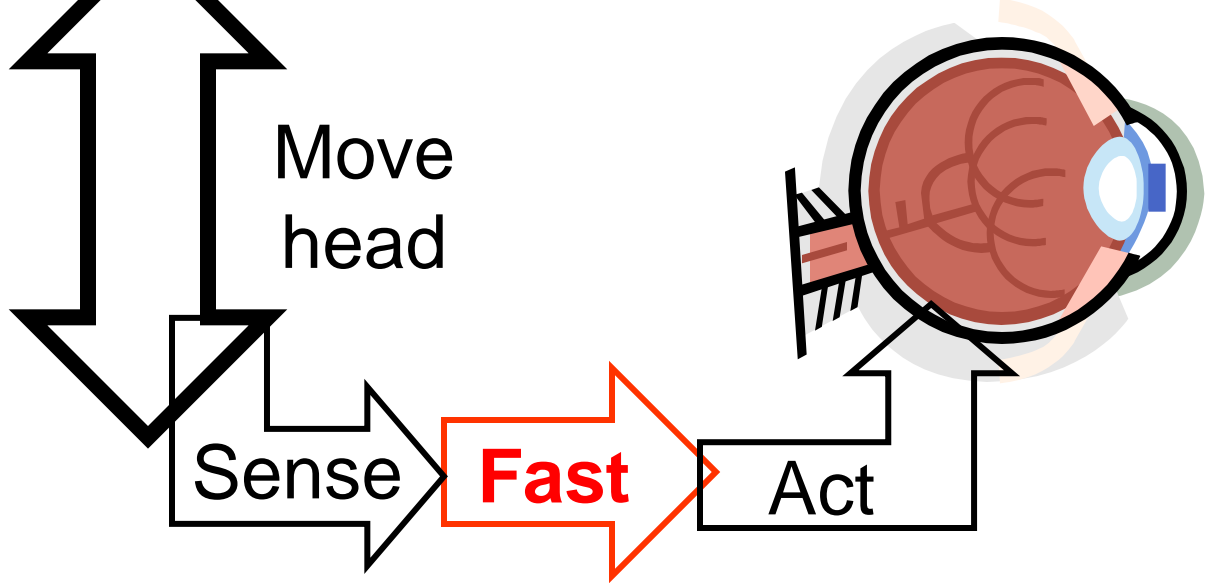
2. Inhibition of extraocular muscles on one side.

2. Excitation of extraocular muscles on the other side

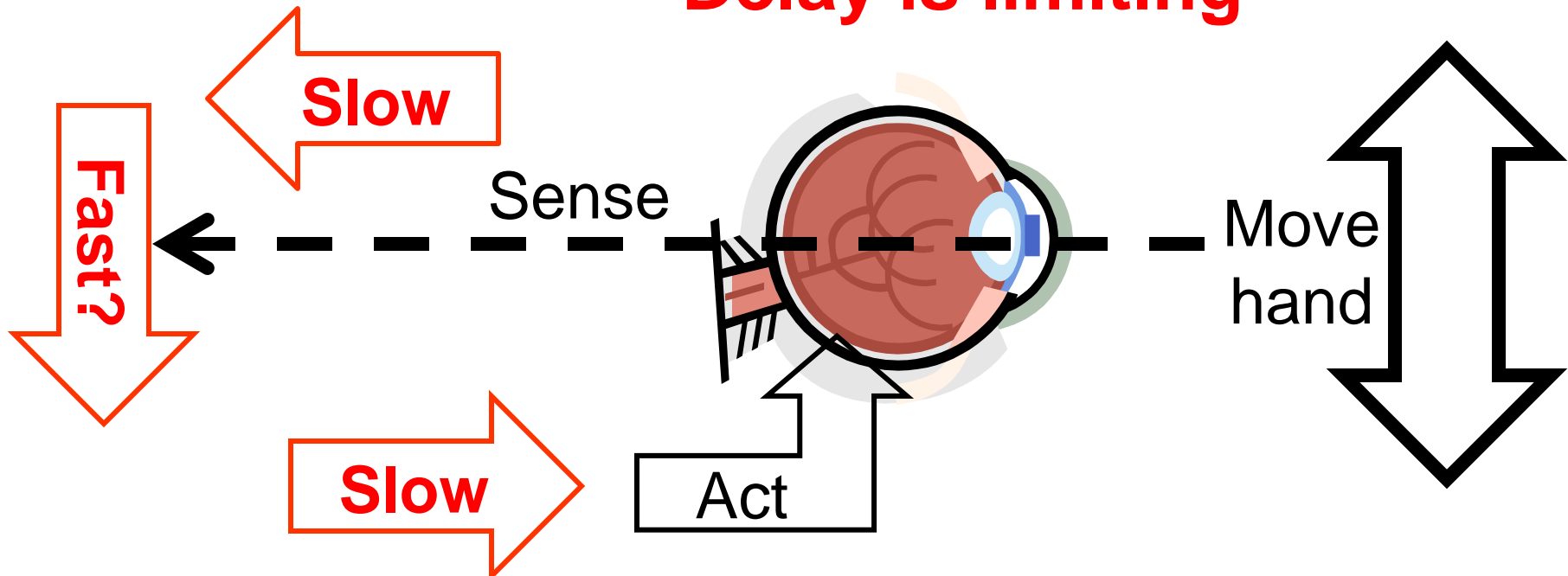


3. Compensating eye movement



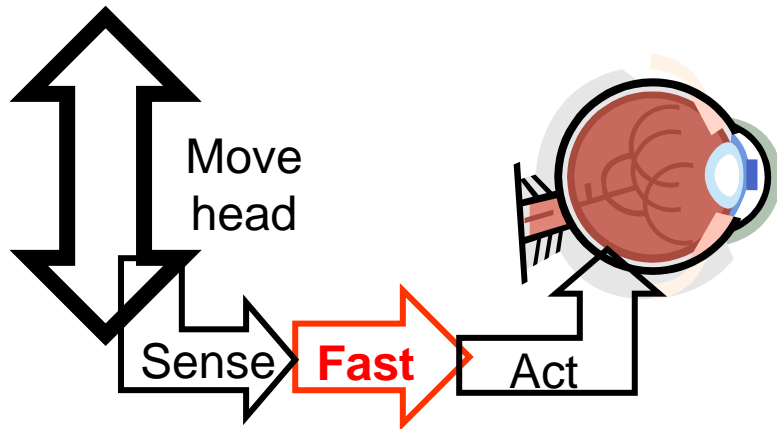


Same actuators
Delay is limiting

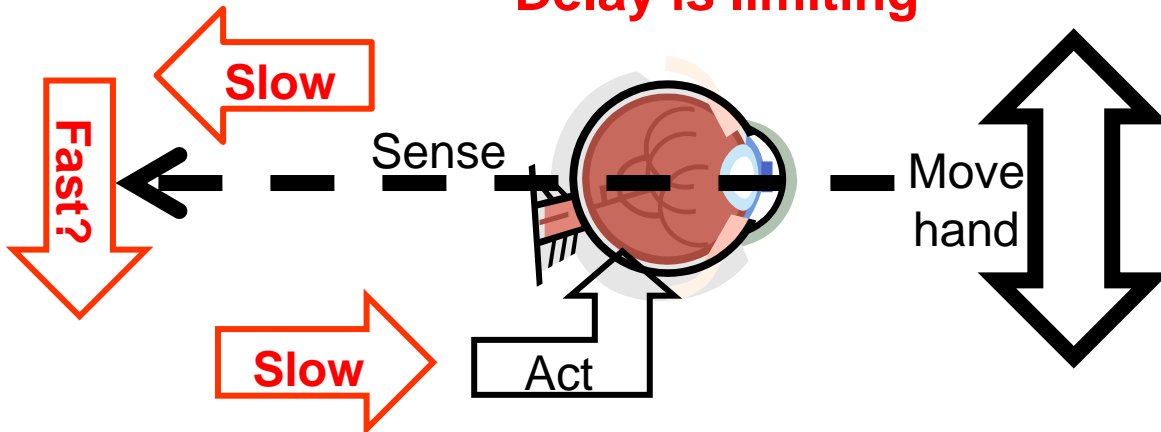


Versus standing on one leg

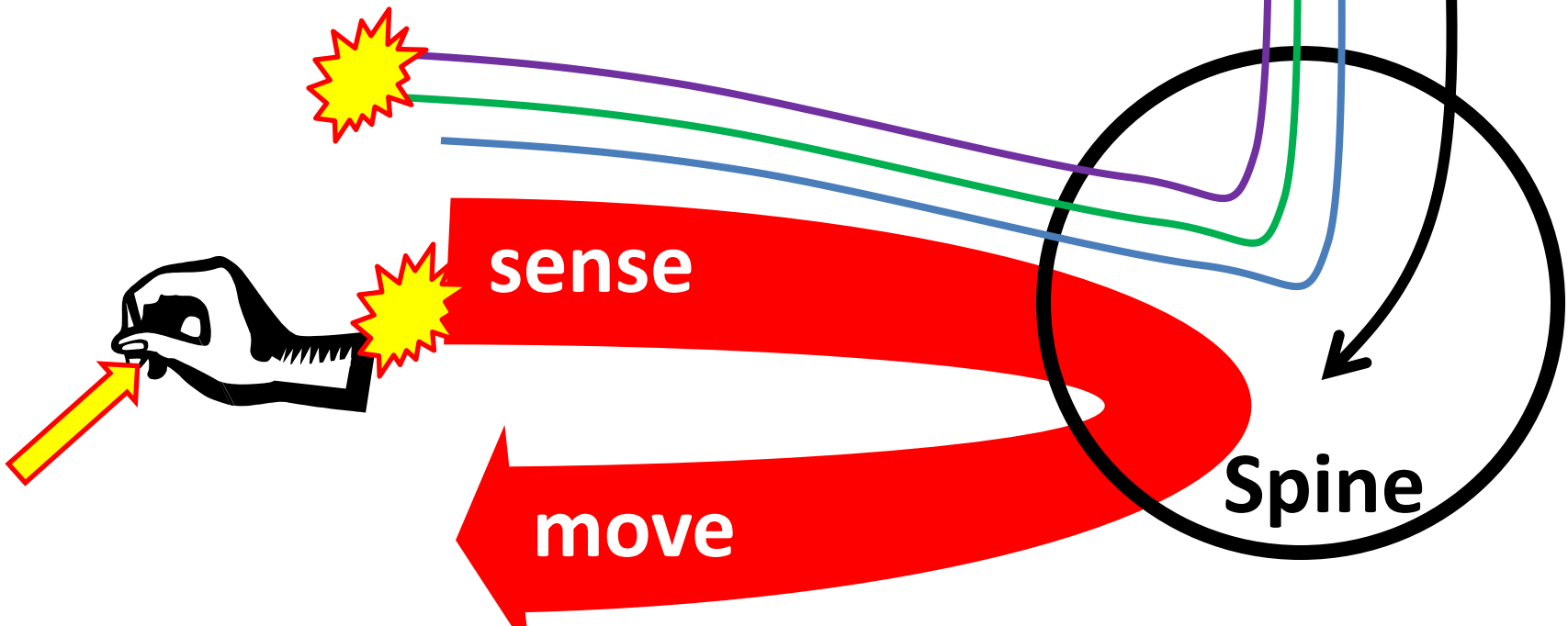
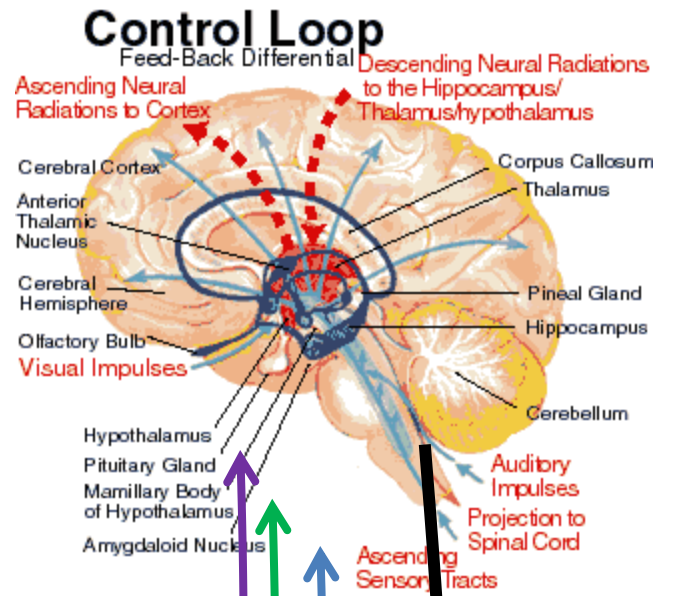
- Eyes open vs closed
- Contrast
 - young surfers
 - old football players



Same actuators
Delay is limiting



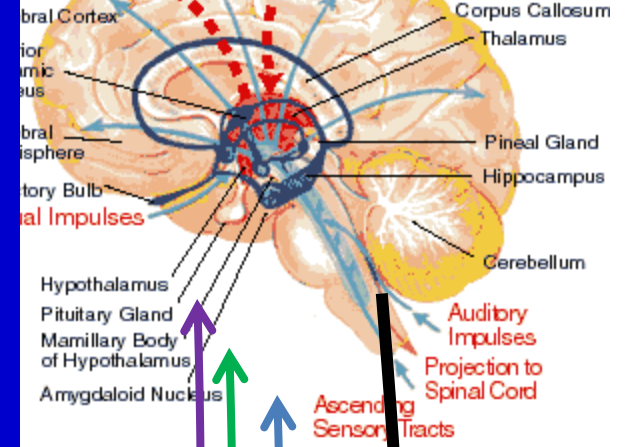
delay=death



Control Loop

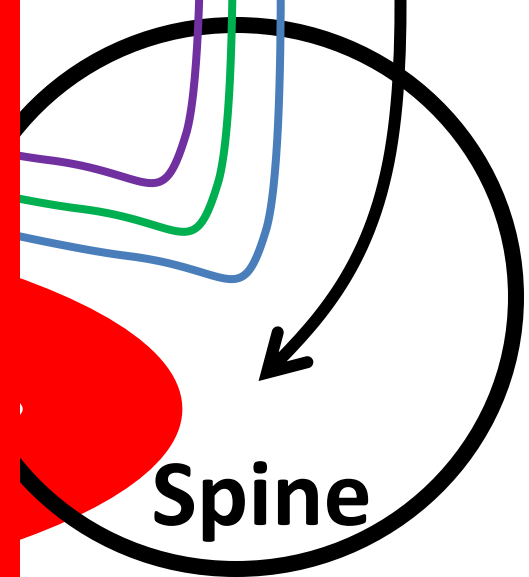
Feed-Back Differential

Descending Neural Radiations to the Hippocampus/Thalamus/hypothalamus



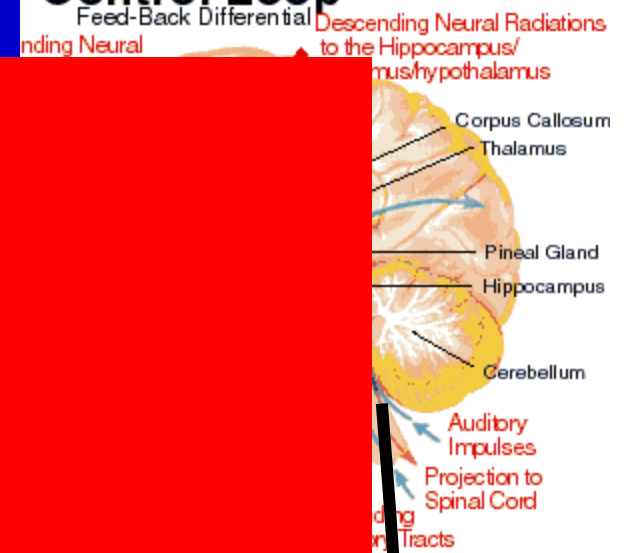
Reflect

Reflex



Reflect

Control Loop

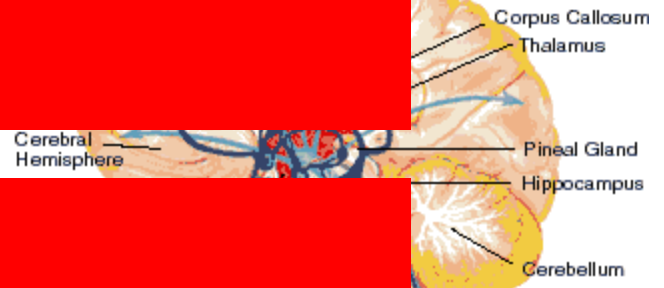


Reflex

Reflect

Control Loop

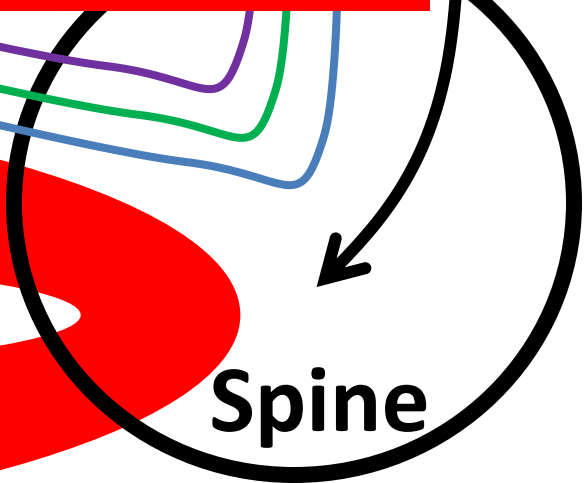
Feed-Back Differential
Descending Neural Radiations to the Hippocampus/
mus/hypothalamus



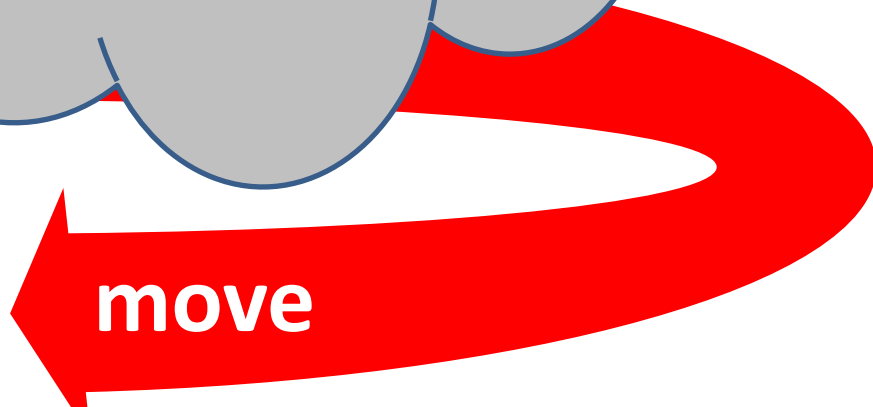
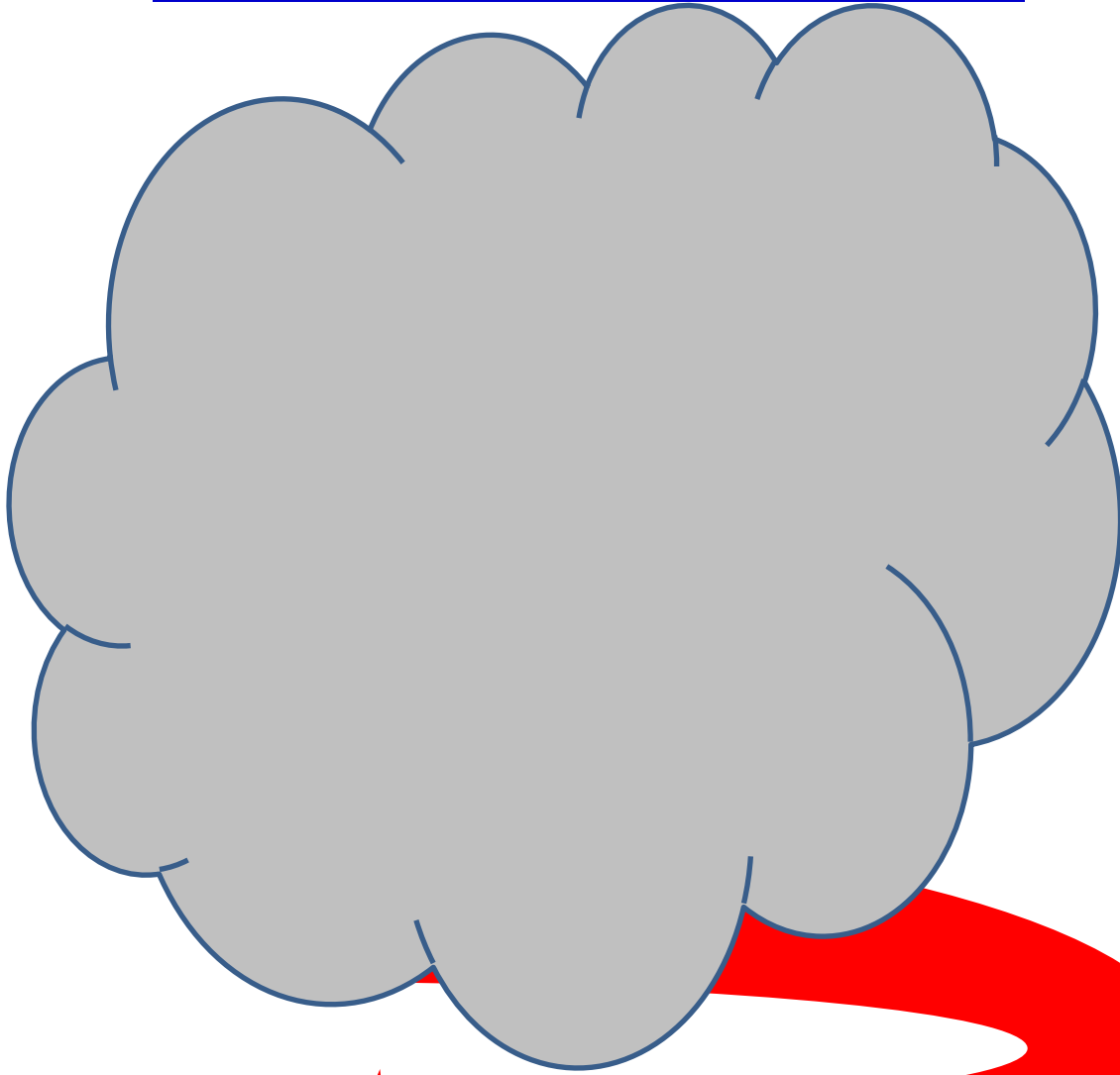
of Hypothalamus
Amygdaloid Nucleus
Auditory Impulses
Projection to Spinal Cord
Ascending Tracts

Layered

Reflex



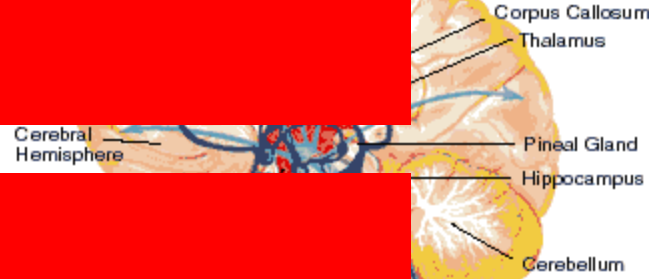
Reflect



Reflect

Control Loop

Feed-Back Differential
Descending Neural Radiations to the Hippocampus/
Auditory Impulses to Hypothalamus



of Hypothalamus
Amygdaloid Nucleus
Ascending Tracts
Projection to Spinal Cord

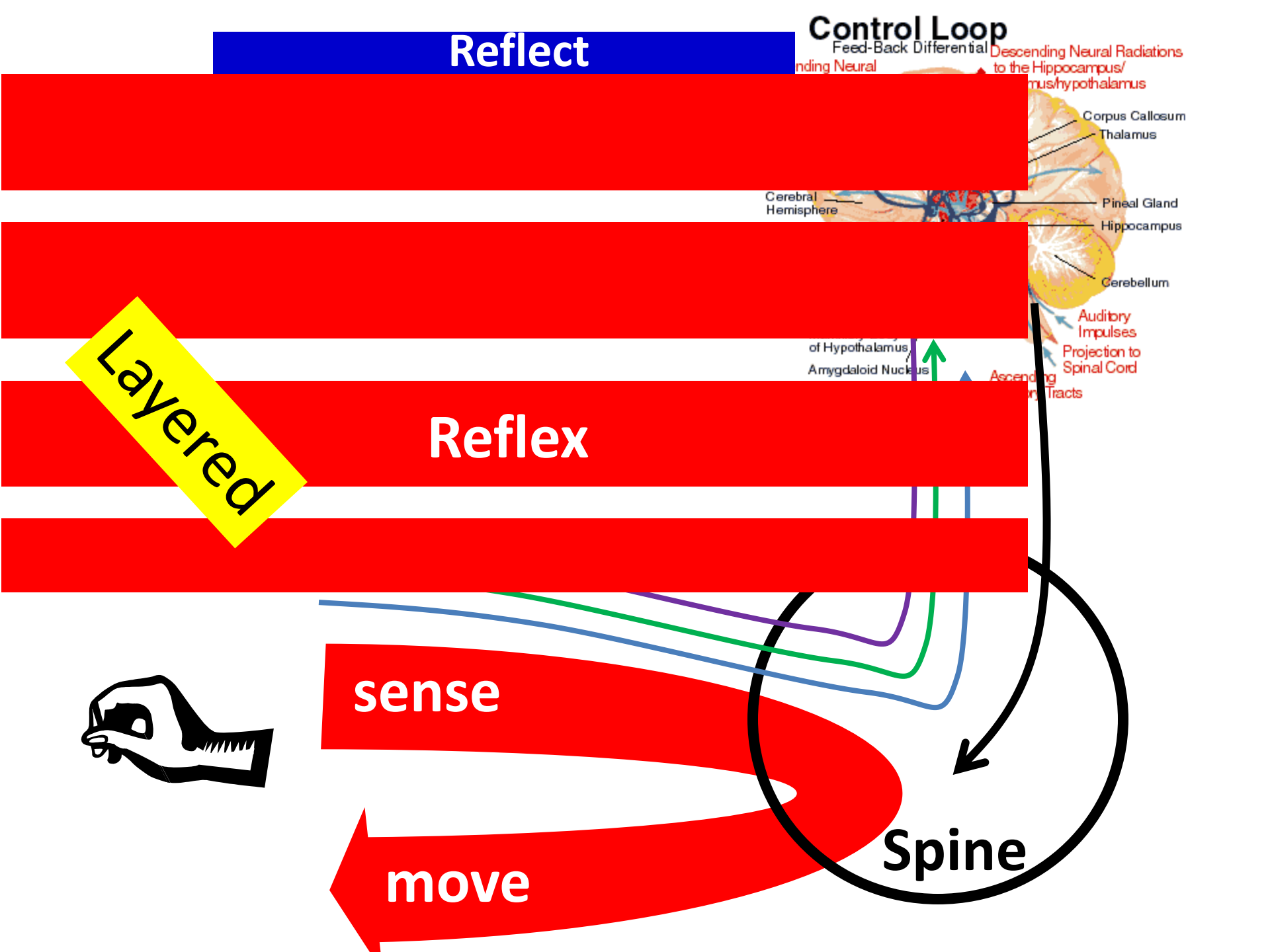
Layered

Reflex

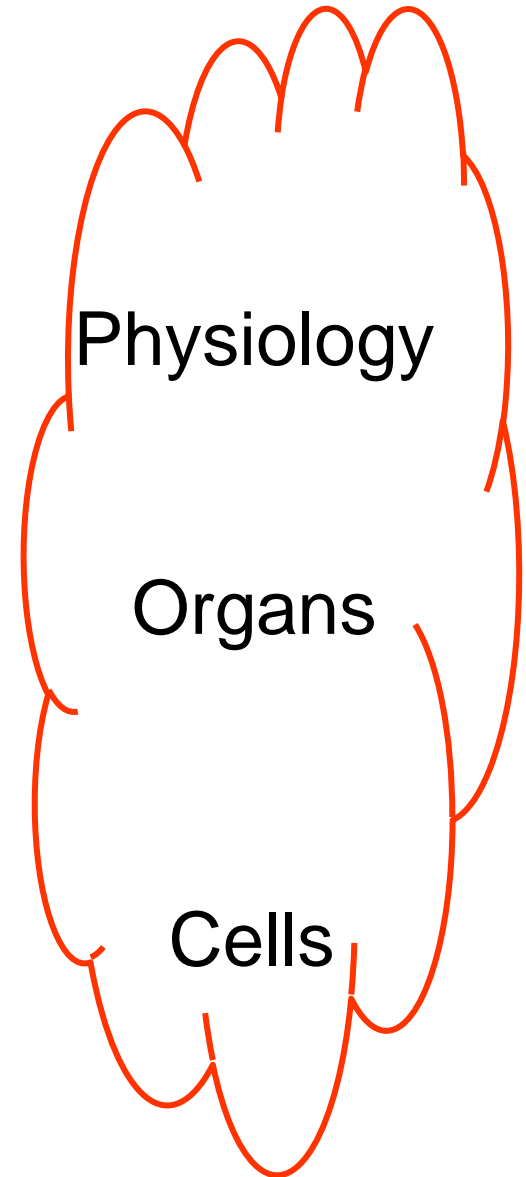
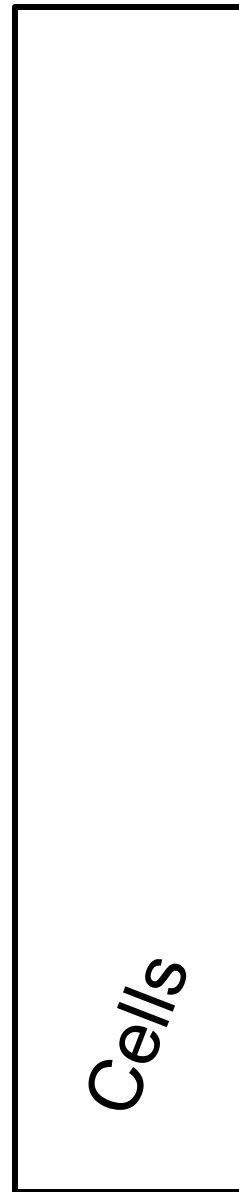
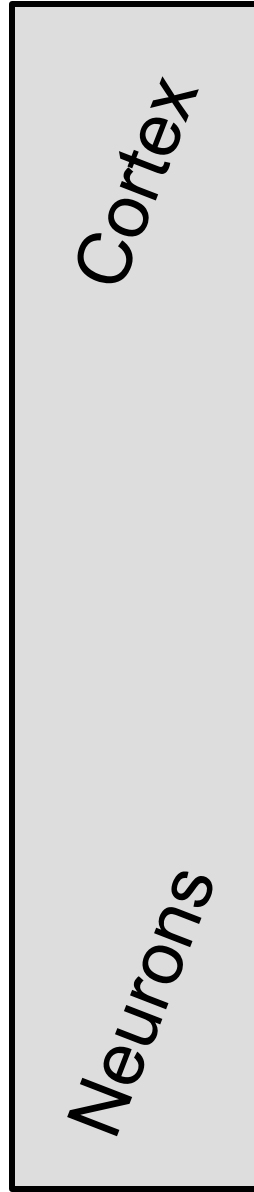
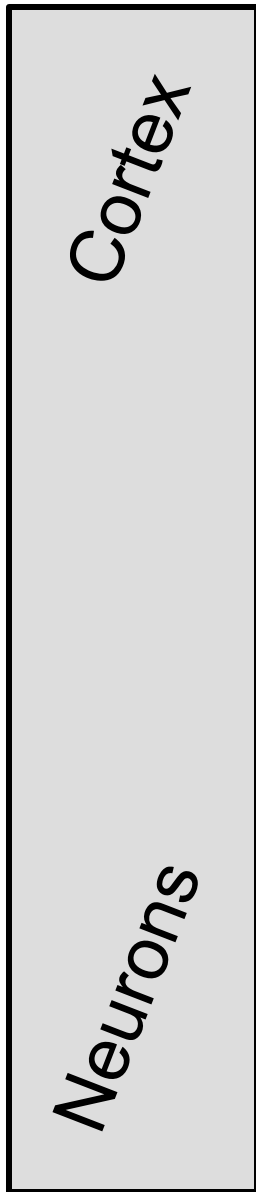
sense

move

Spine



Layered architectures (cartoon)



Control Loop

Feed-Back Differential
Ascending Neural
to the Hypothalamus'

Reflect

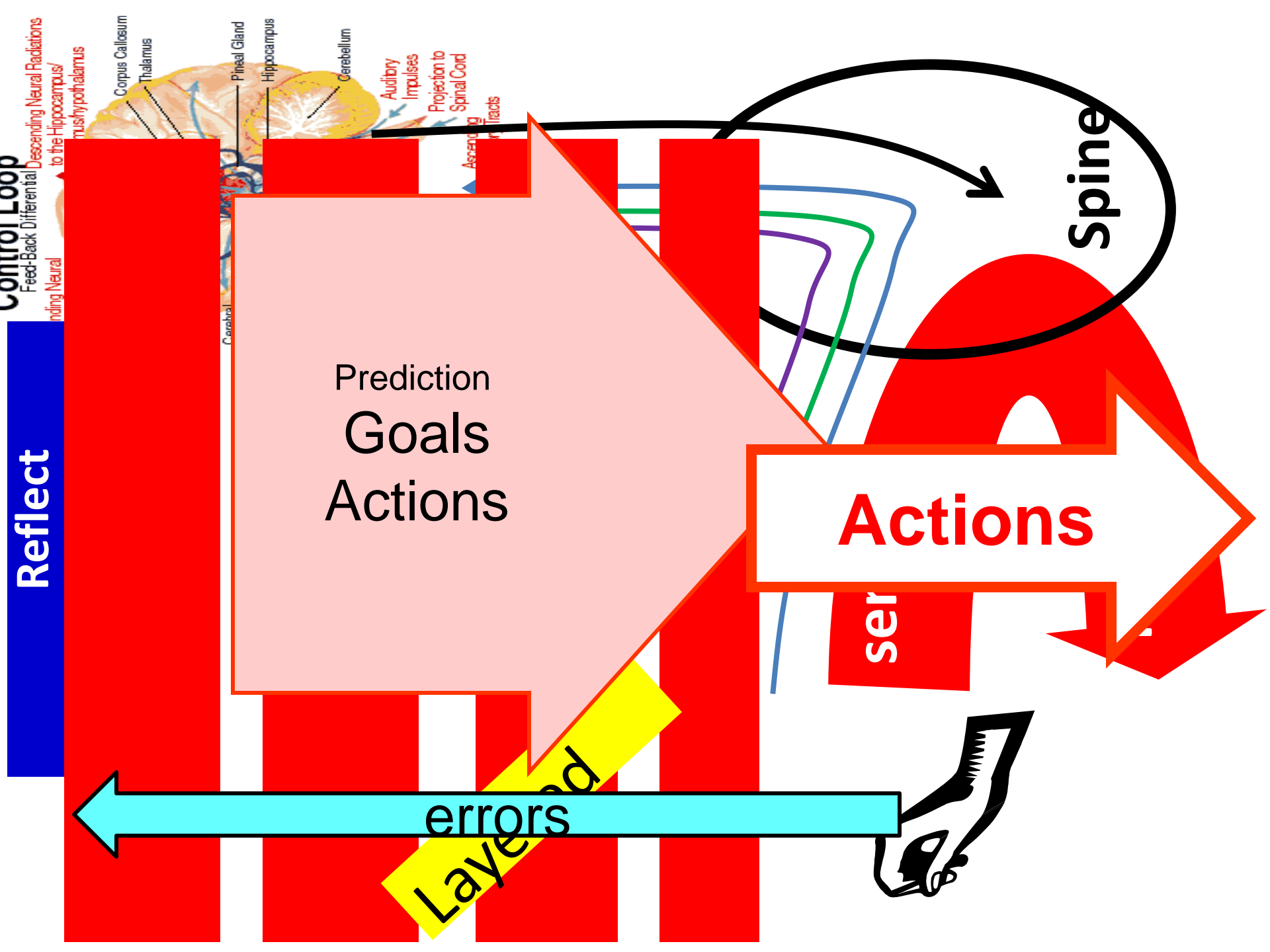
Prediction
Goals
Actions

Actions

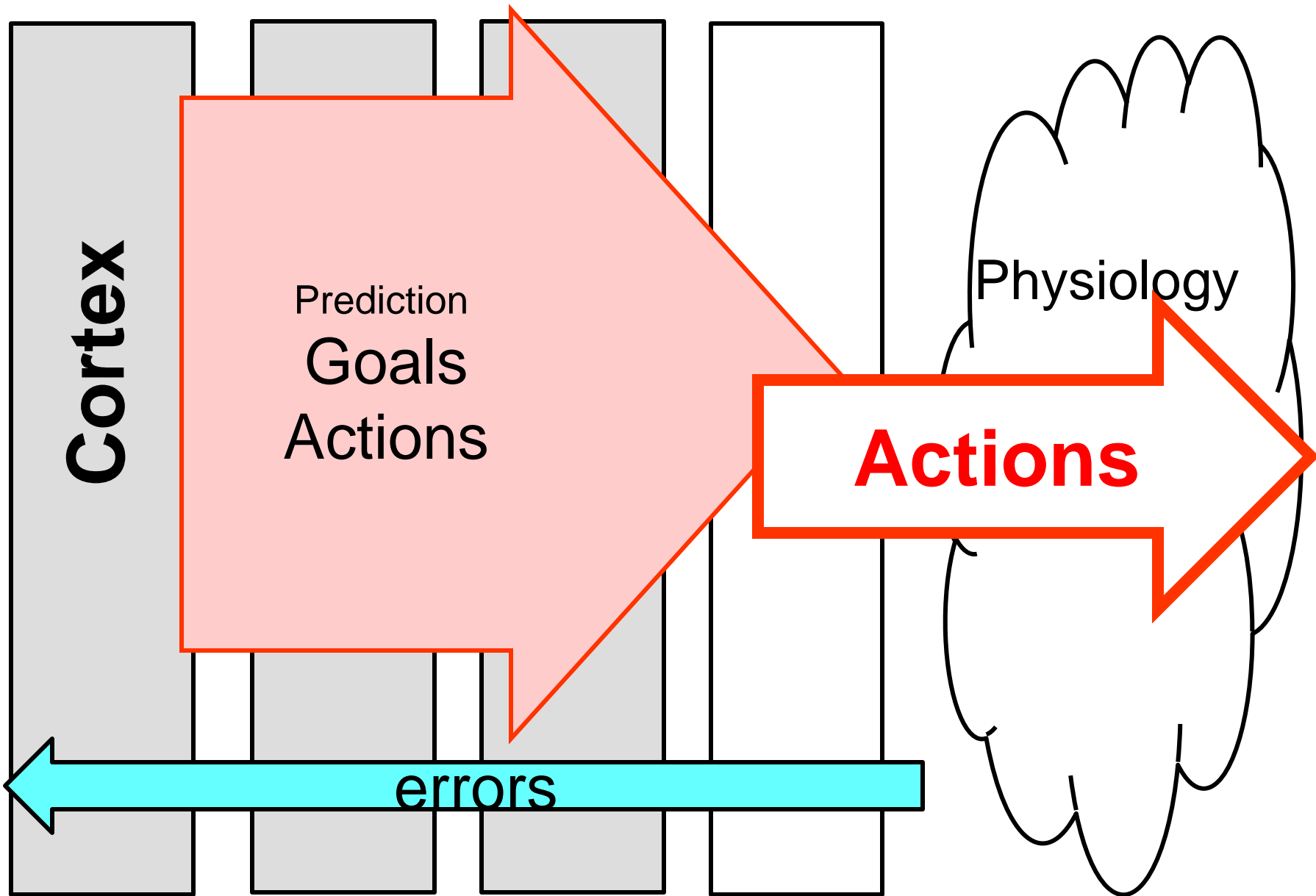
errors

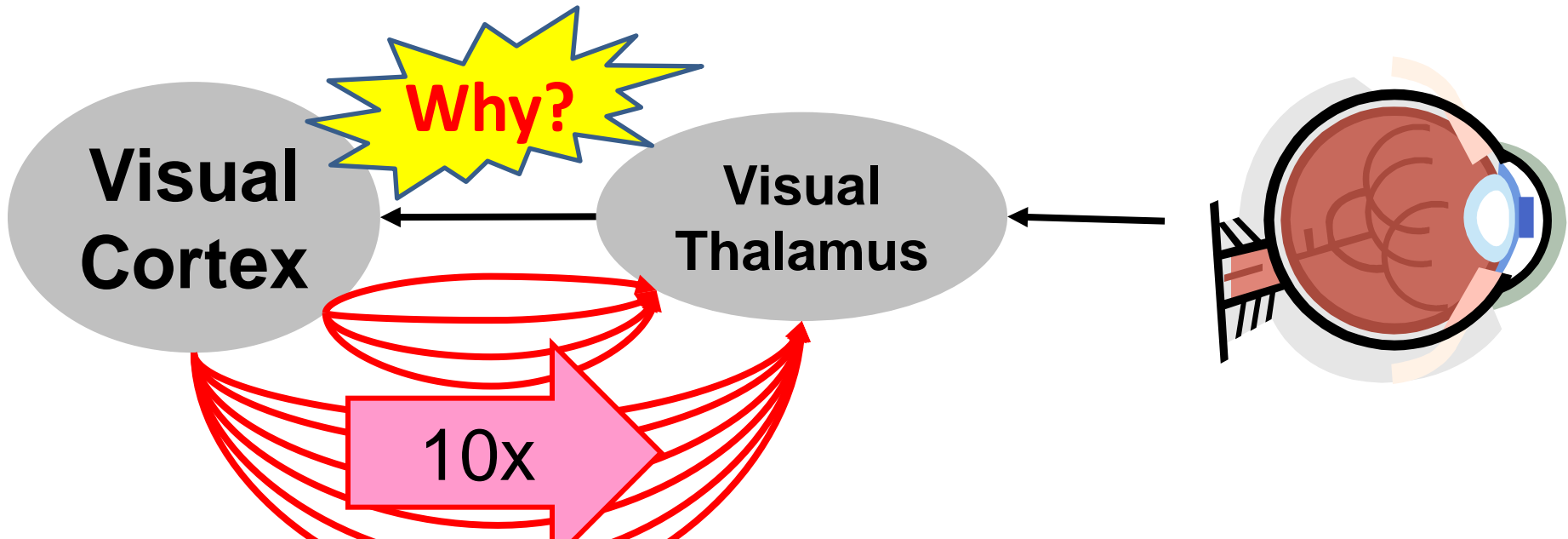
Layered

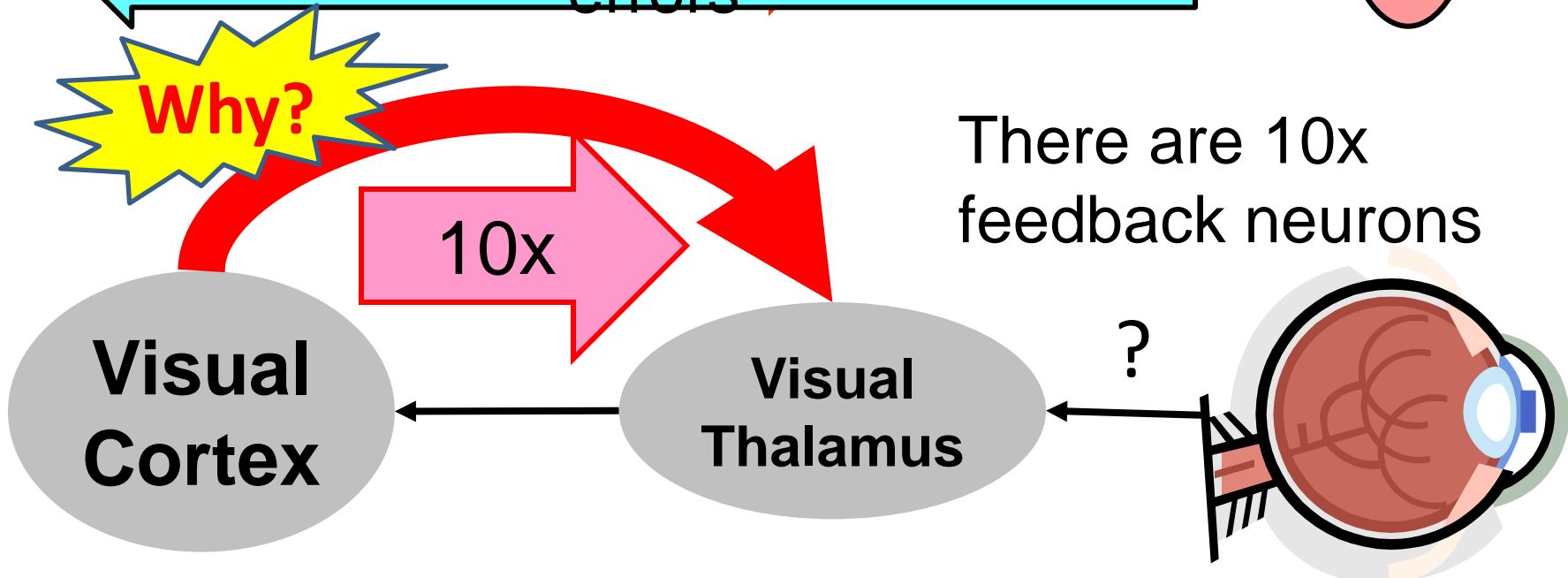
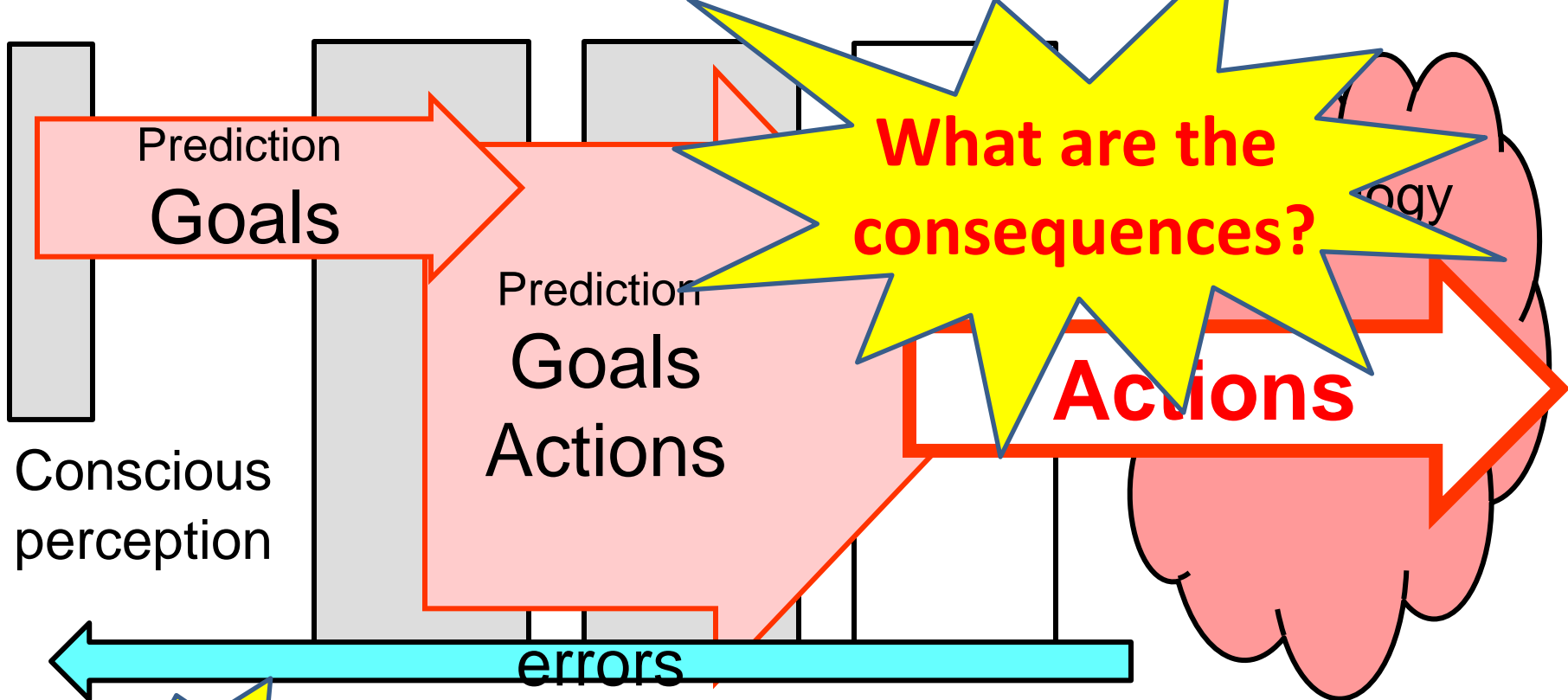
Spine



Meta-layers cartoon







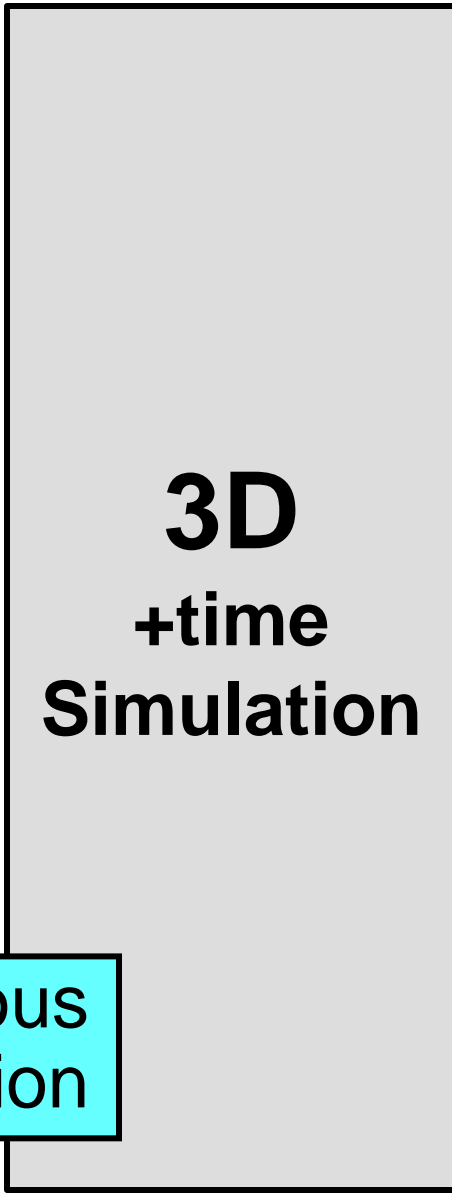
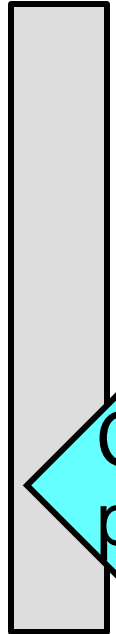
Seeing is *dreaming*

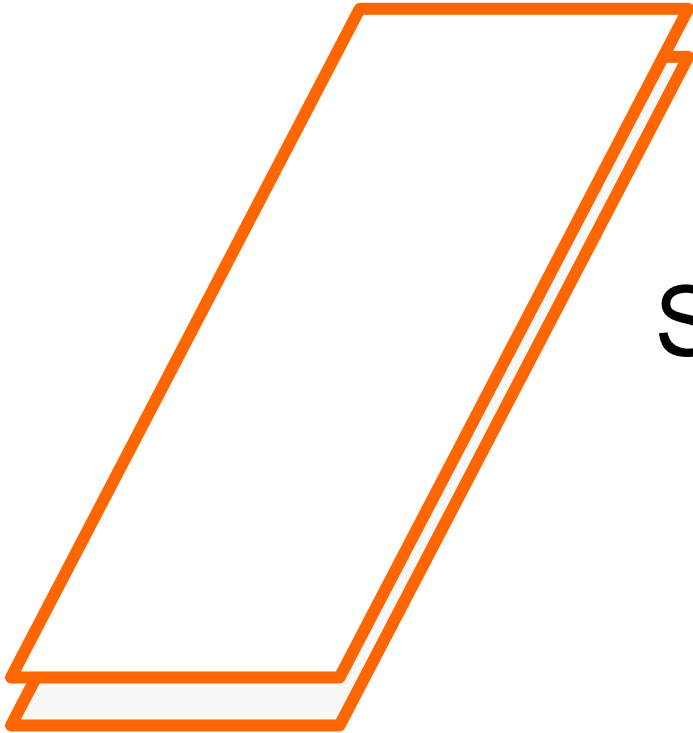
Conscious perception

3D
+time
Simulation



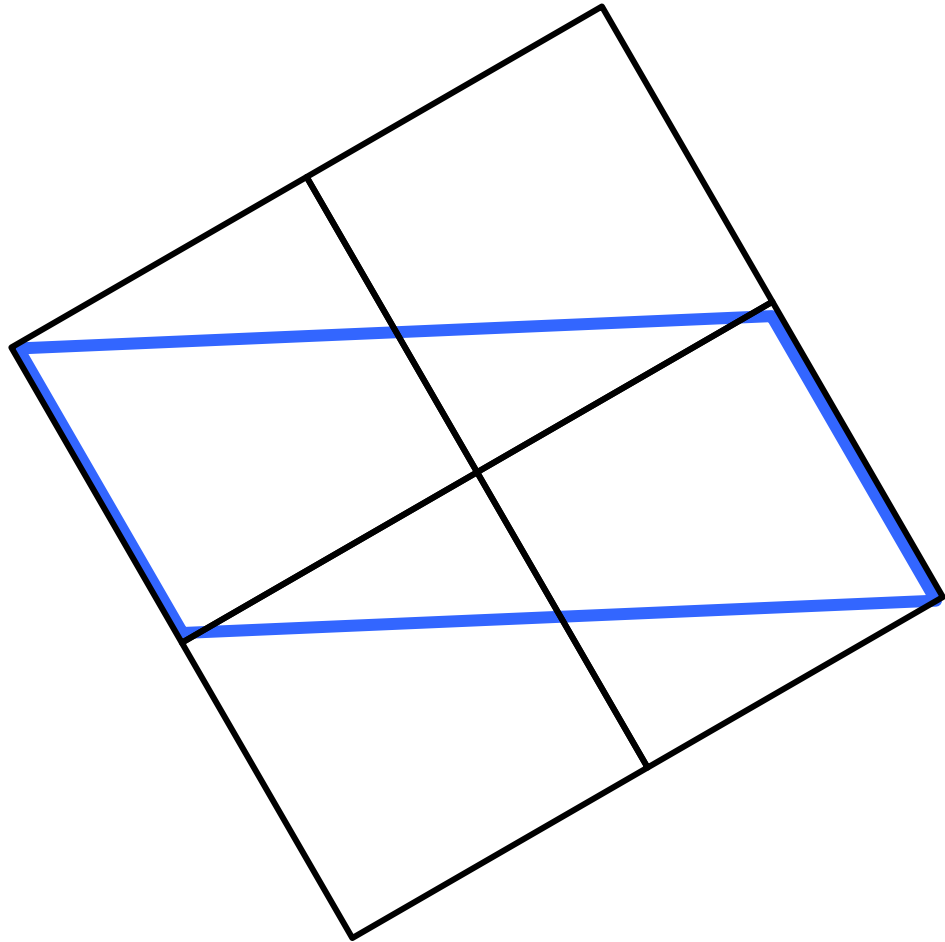
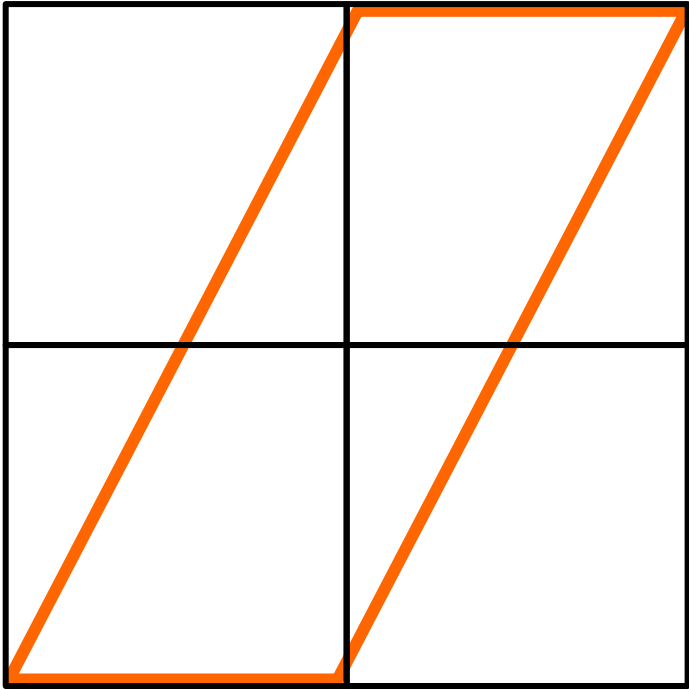
Conscious perception

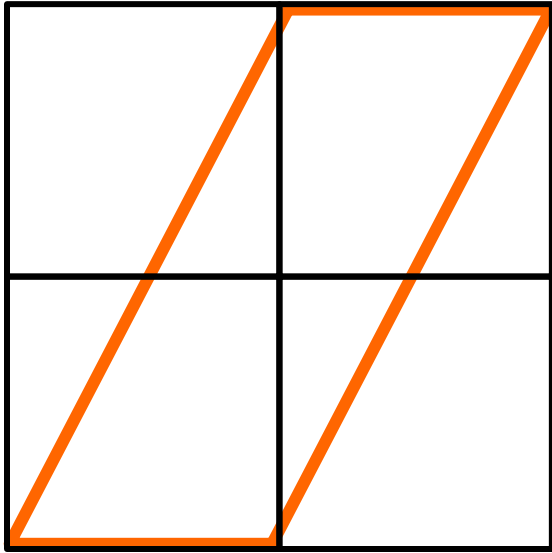




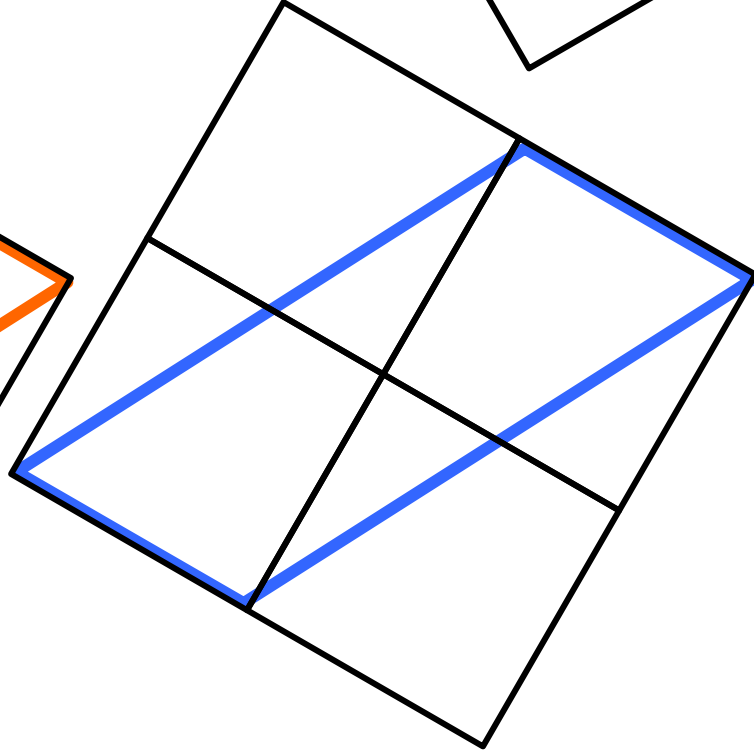
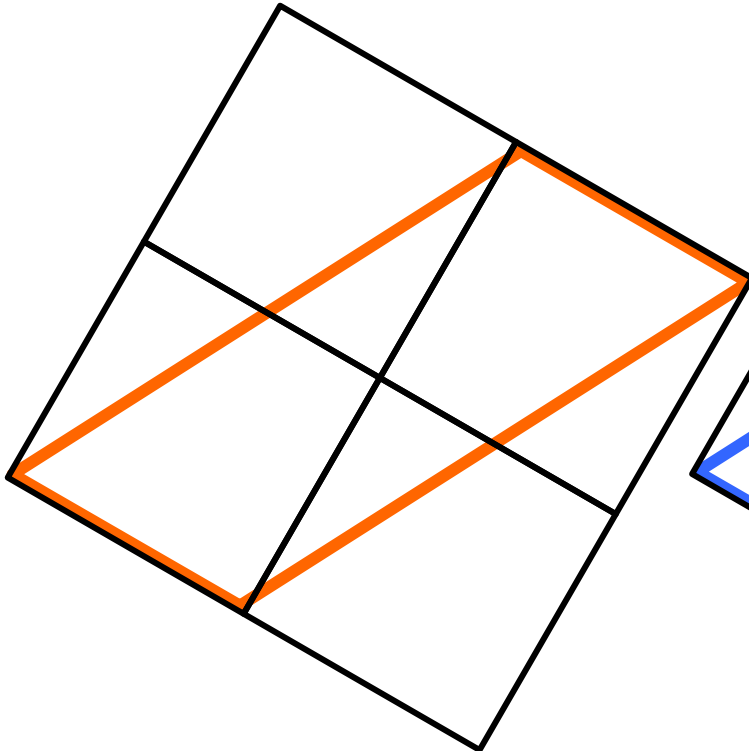
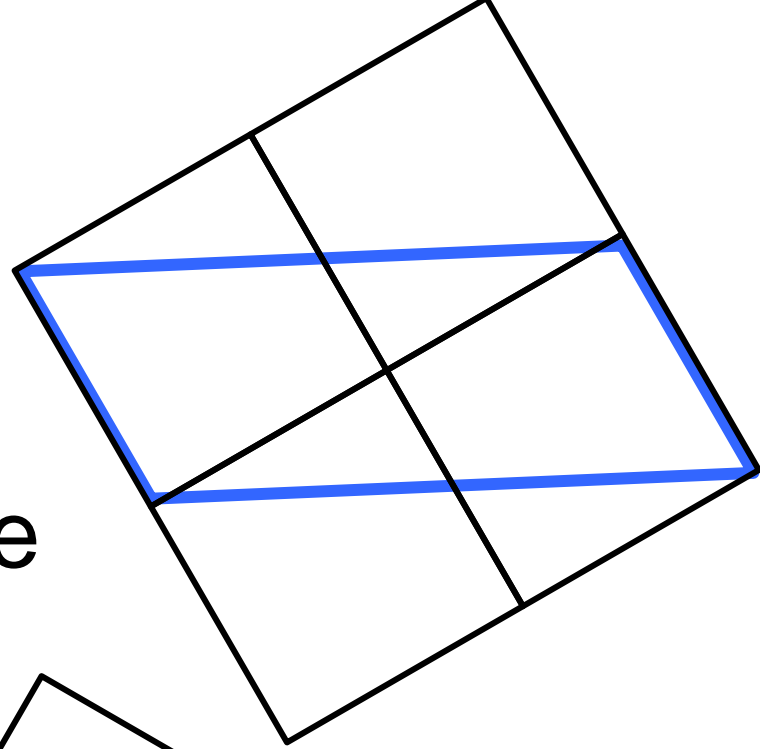
Same size?

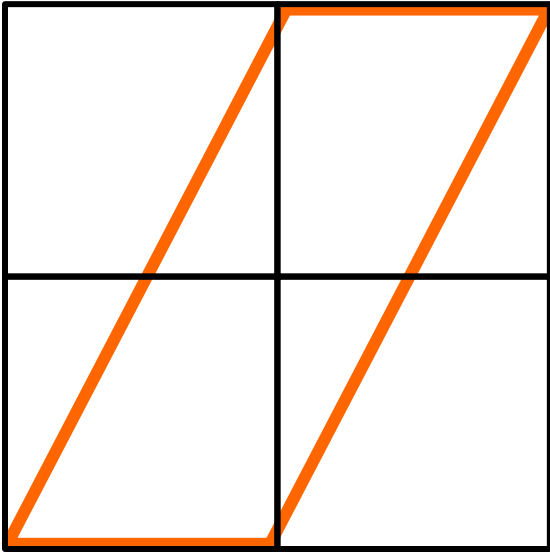




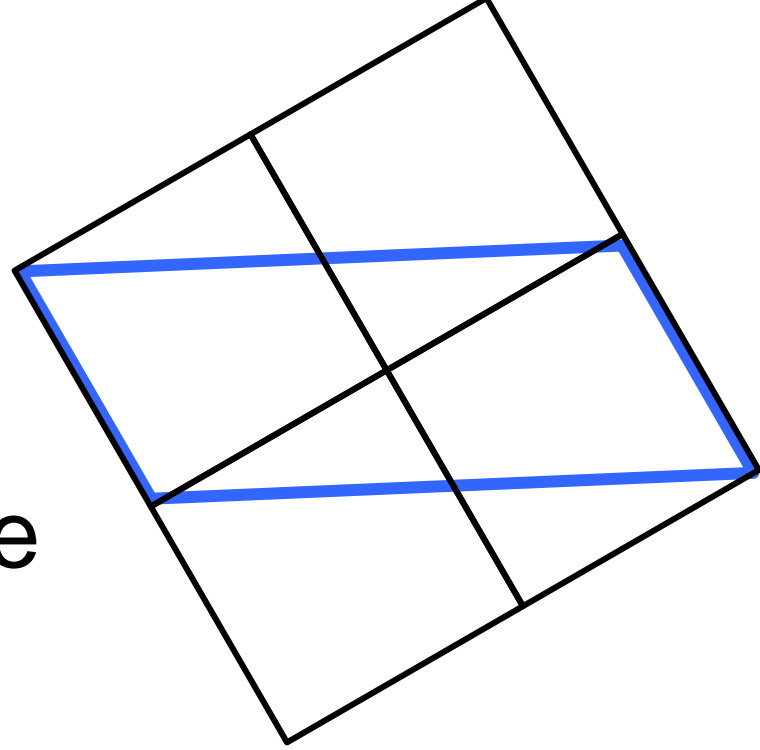


Same size





Same size





Same size



Toggle between this slide and
the ones before and after

Even when you “know” they are
the same, they appear different



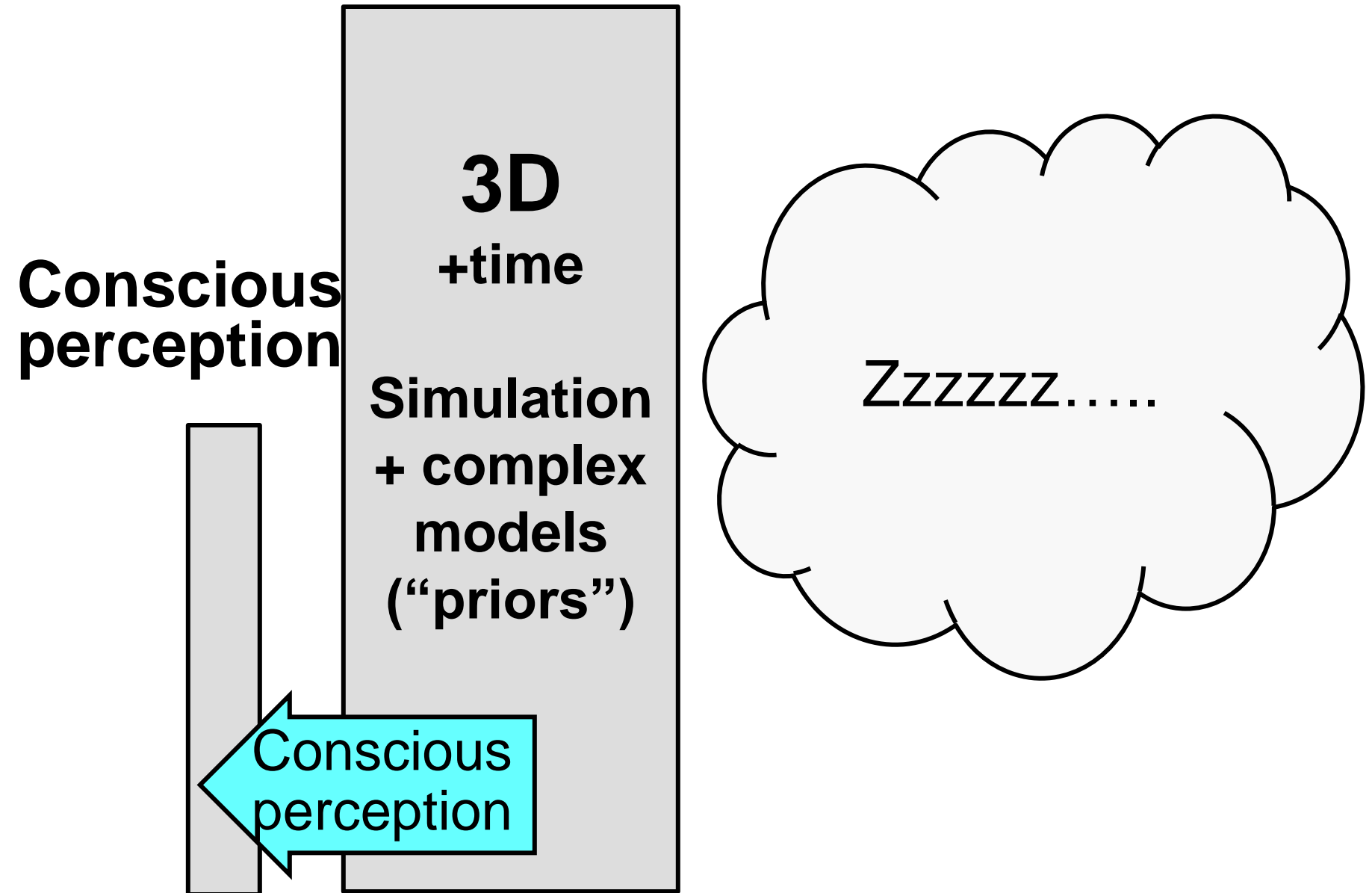
Same size?



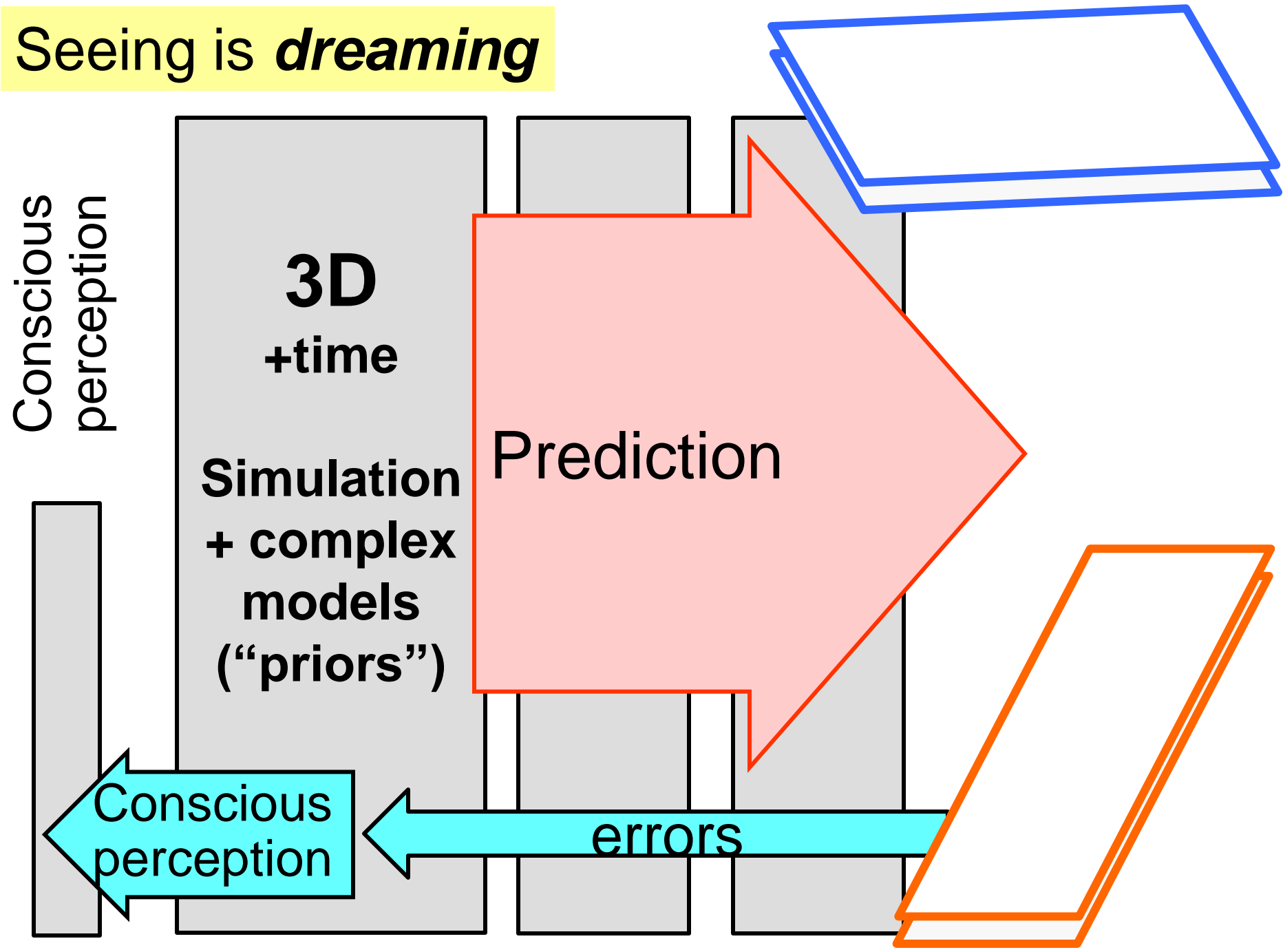
Vision: evolved for complex
simulation and control, not
2d static pictures

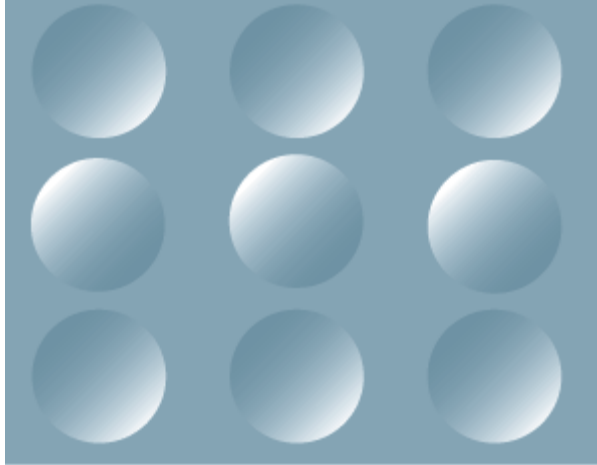
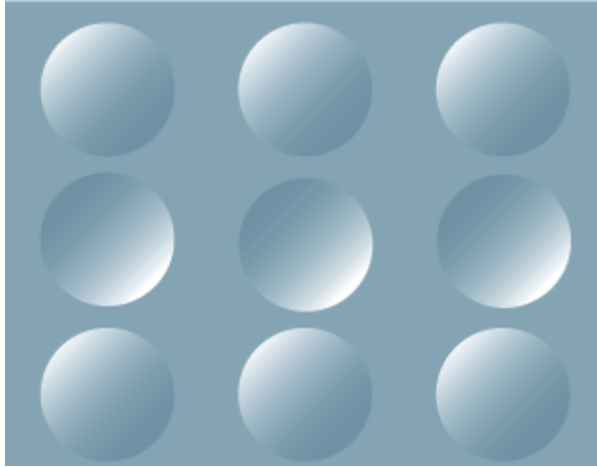
Even when you “know” they are
the same, they appear different

Seeing is *dreaming*

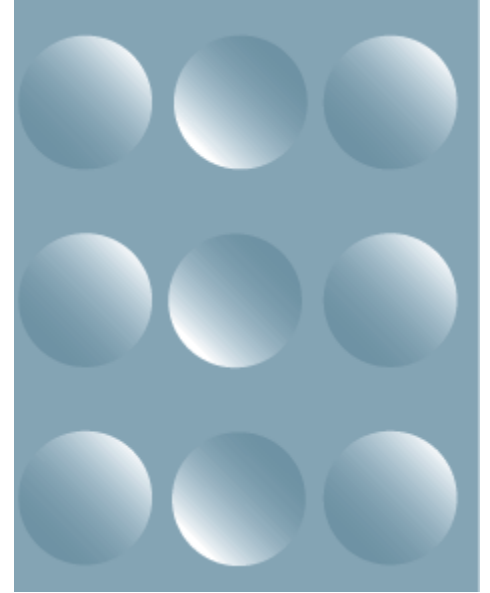


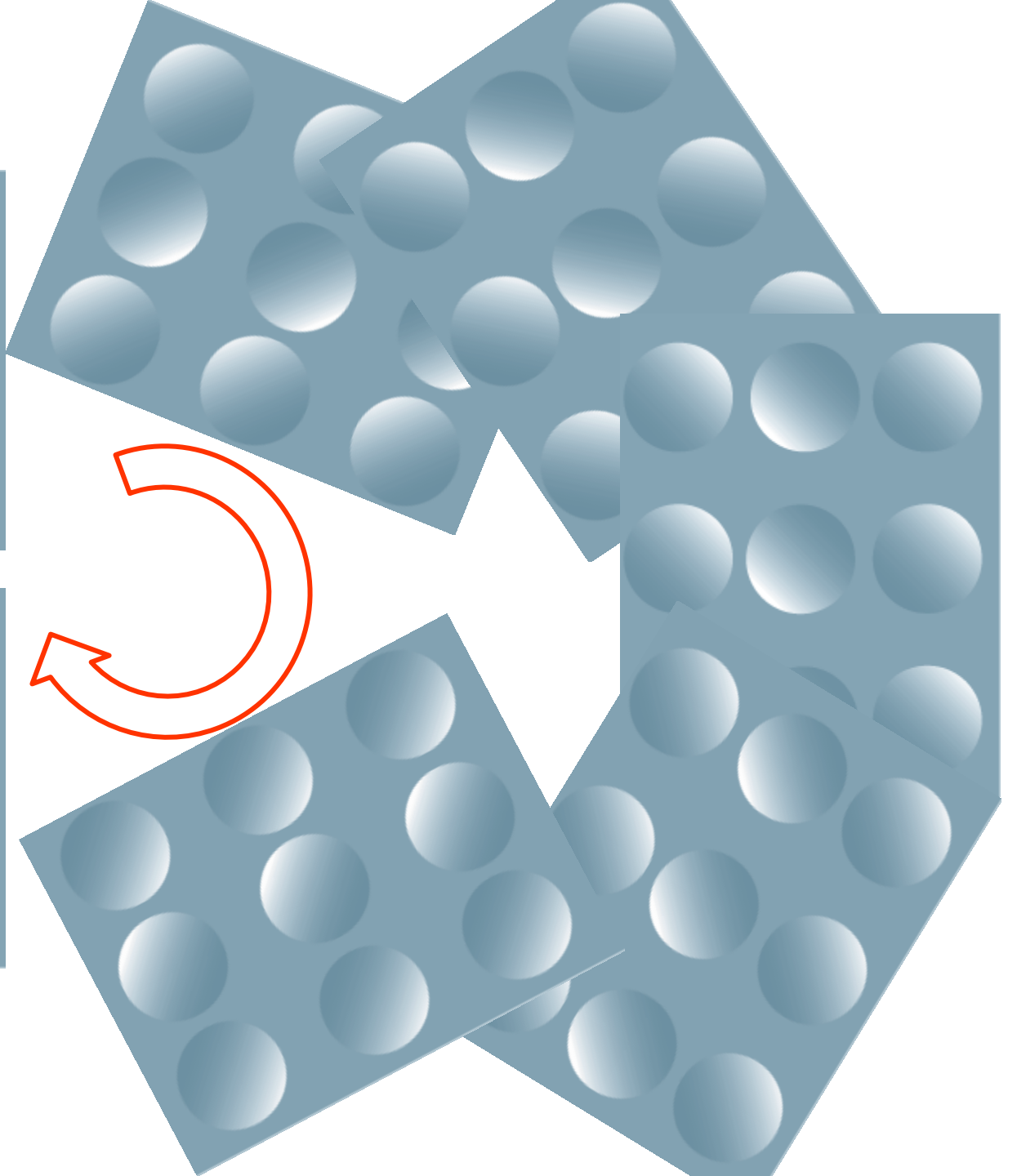
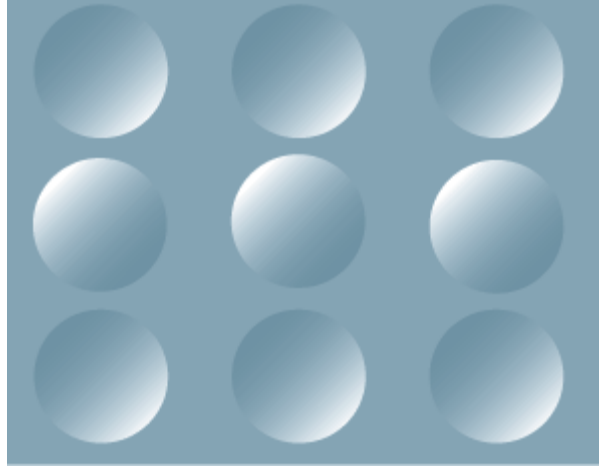
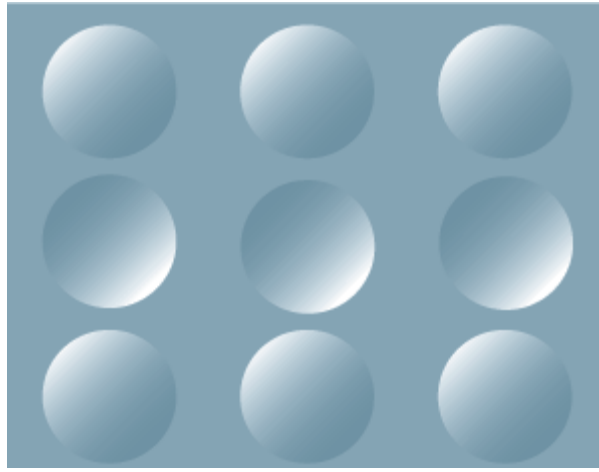
Seeing is *dreaming*



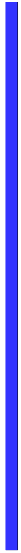


Inferring shape
from shading

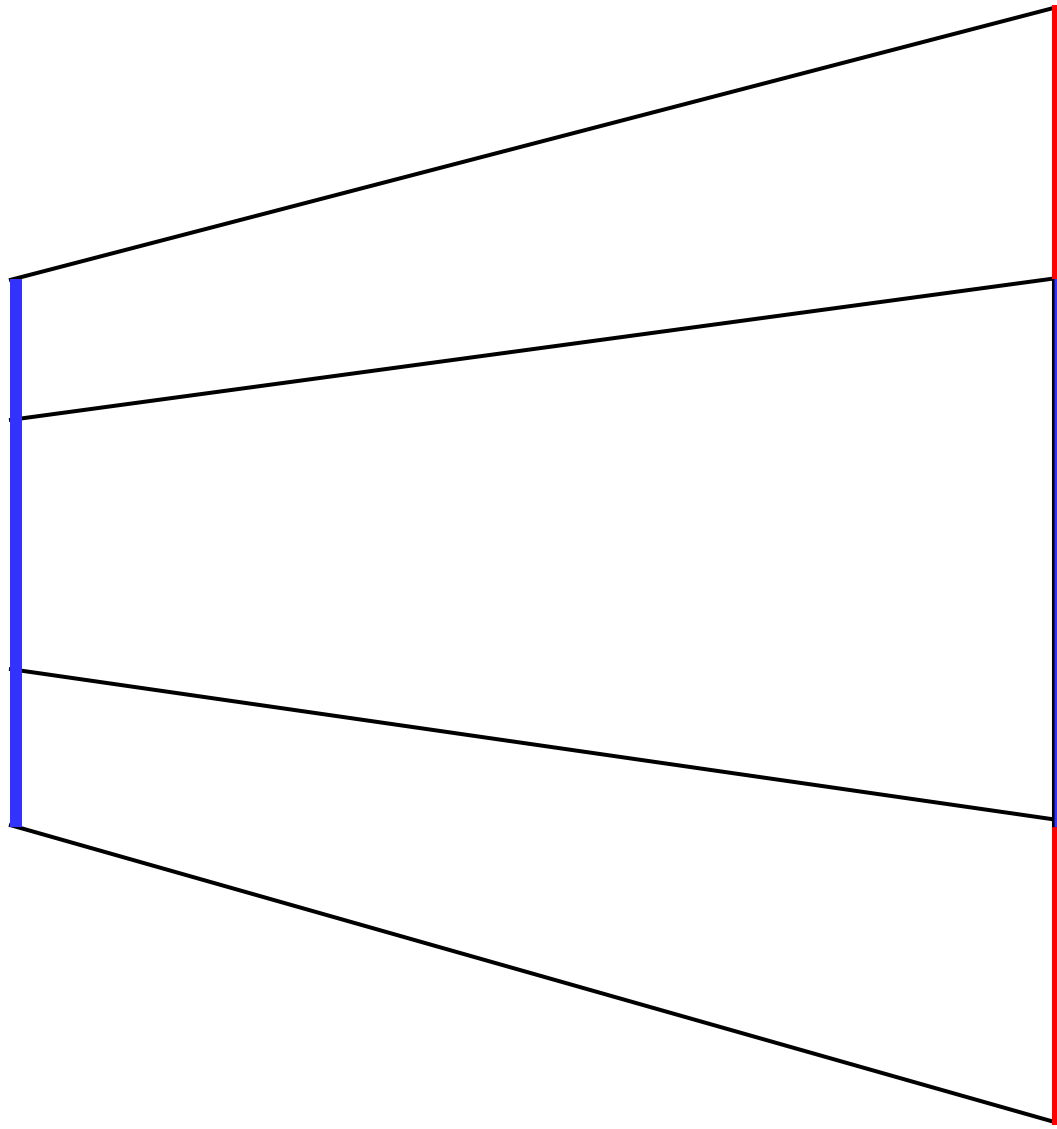




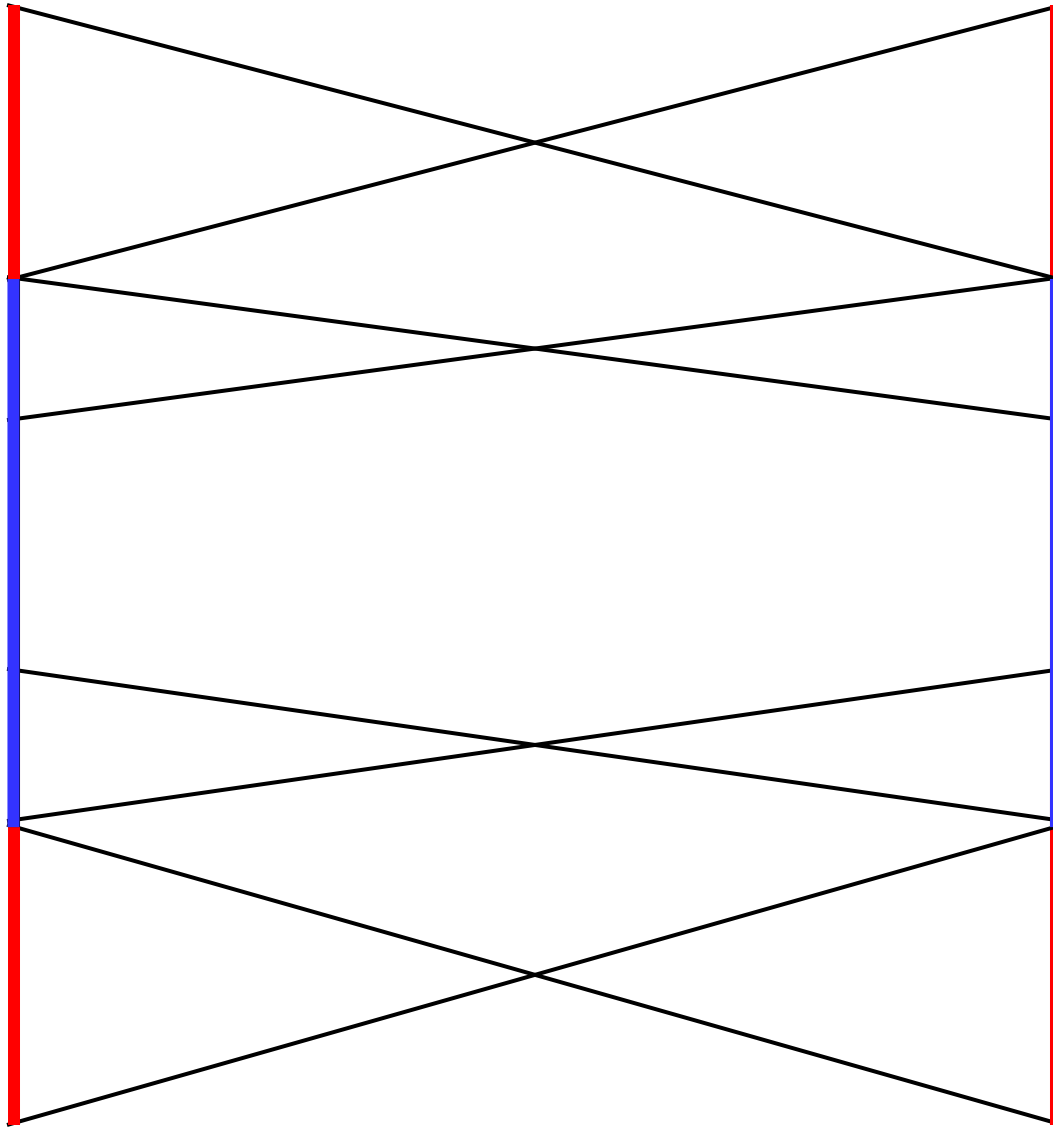
Which blue line is longer?



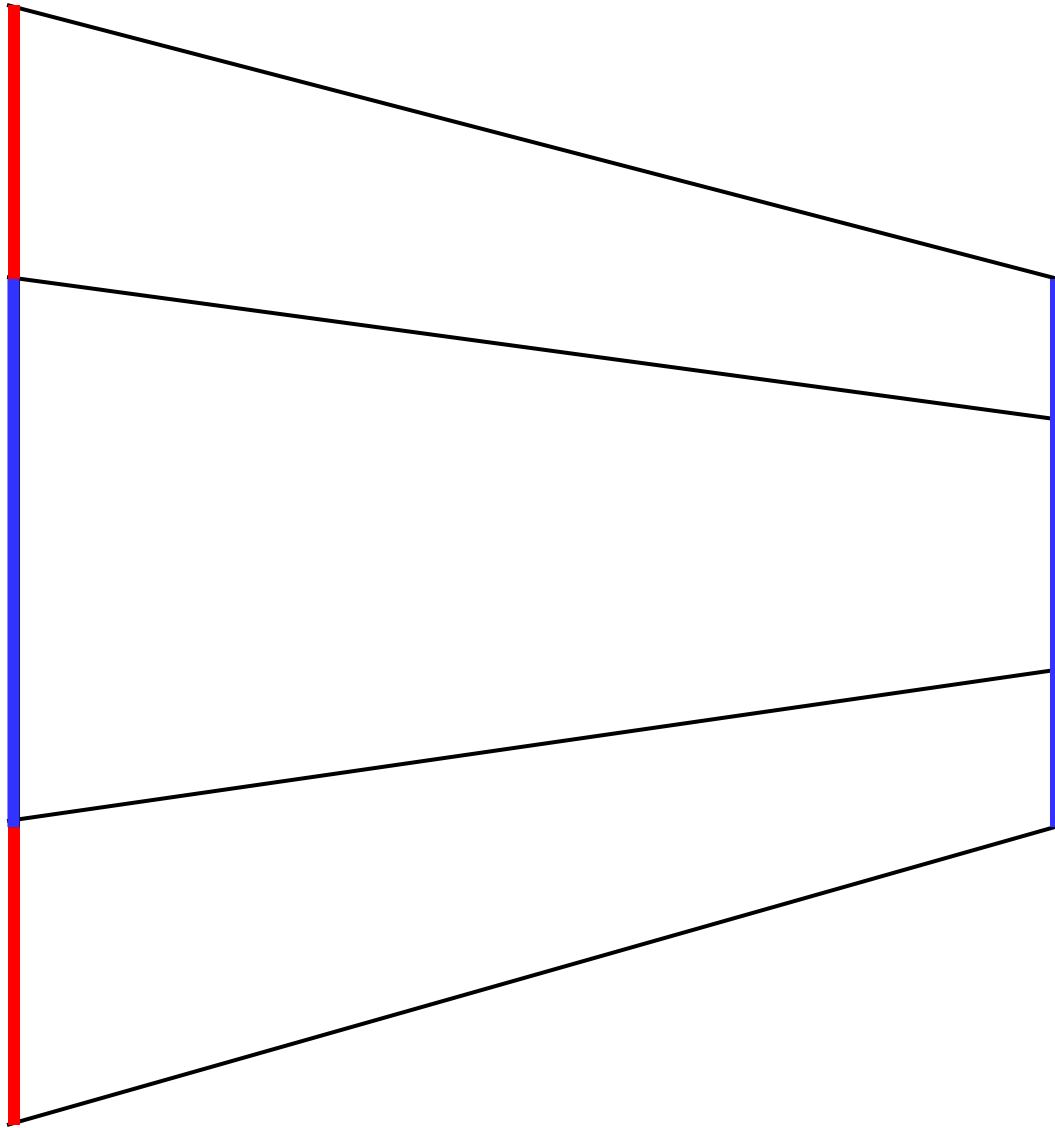
Which blue line is longer?



Which blue line is longer?



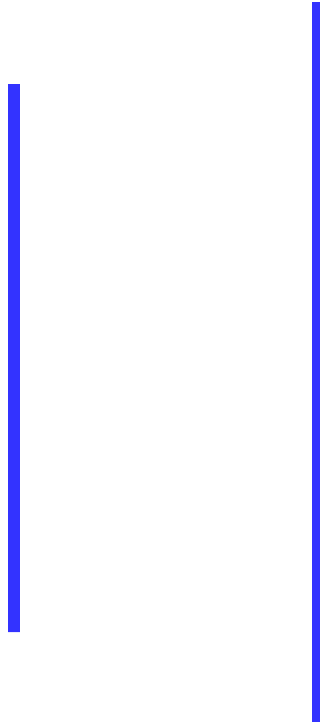
Which blue line is longer?



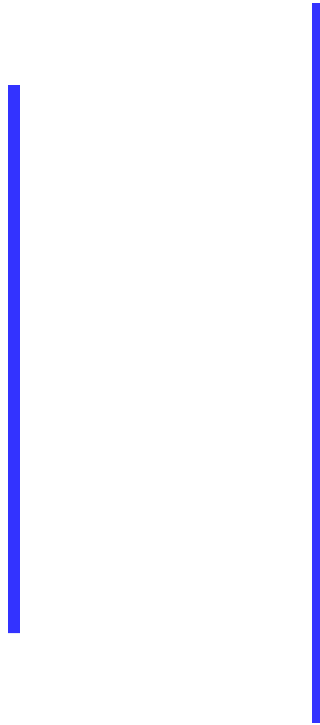
Which blue line is longer?



Which blue line is longer?



Which blue line is longer?



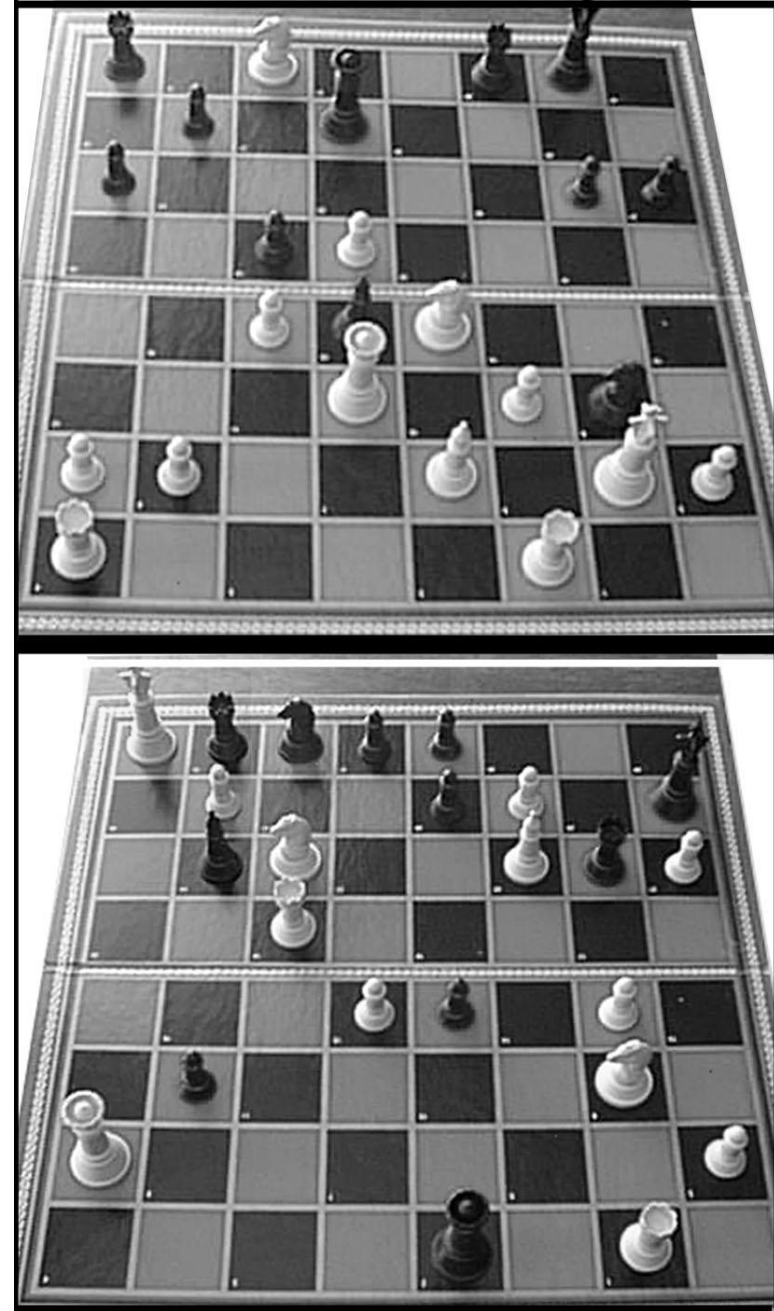
Standard social psychology experiment.



Chess experts

- can reconstruct entire chessboard with $< \sim 5s$ inspection
- can recognize $1e5$ distinct patterns
- can play multiple games blindfolded and simultaneous
- are no better on random boards

(Simon and Gilmartin, de Groot)



Specialized Face Learning Is Associated with Individual Recognition in Paper Wasps

Science

AAAS

Michael J. Sheehan* and Elizabeth A. Tibbetts

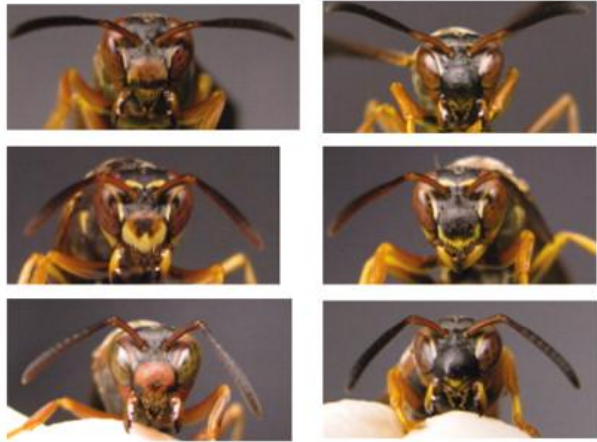
We demonstrate that the evolution of facial recognition in wasps is associated with specialized face-learning abilities. *Polistes fuscatus* can differentiate among normal wasp face images more rapidly and accurately than nonface images or manipulated faces. A close relative lacking facial recognition, *Polistes metricus*, however, lacks specialized face learning. Similar specializations for face learning are found in primates and other mammals, although *P. fuscatus* represents an independent evolution of specialization. Convergence toward face specialization in distant taxa as well as divergence among closely related taxa with different recognition behavior suggests that specialized cognition is surprisingly labile and may be adaptively shaped by species-specific selective pressures such as face recognition.

When needed, even wasps can do it.

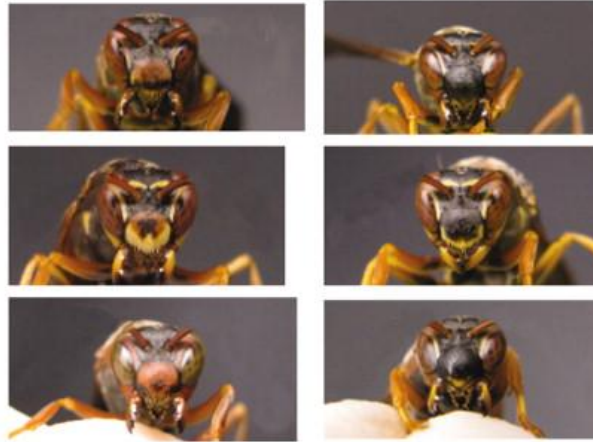
- *Polistes fuscatus* can differentiate among normal wasp face images more rapidly and accurately than nonface images or manipulated faces.
- *Polistes metricus* is a close relative lacking facial recognition and specialized face learning.
- Similar specializations for face learning are found in primates and other mammals, although *P. fuscatus* represents an independent evolution of specialization.
- Convergence toward face specialization in distant taxa as well as divergence among closely related taxa with different recognition behavior suggests that specialized cognition is surprisingly labile and may be adaptively shaped by species-specific selective pressures such as face recognition.

Fig. 1 Images used for training wasps.

***P. fuscatus* faces**



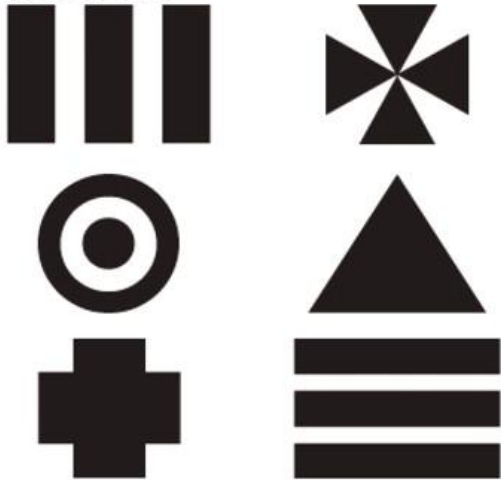
Antenna-less faces



Rearranged faces



Patterns



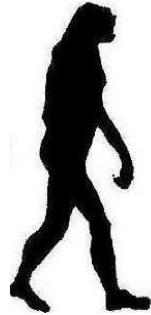
Caterpillars



***P. metricus* faces**



weak
fragile
slow



Human evolution

hands
feet
skeleton
muscle
skin
gut
long helpless childhood

All very
different.

strong
robust
fast



Apes

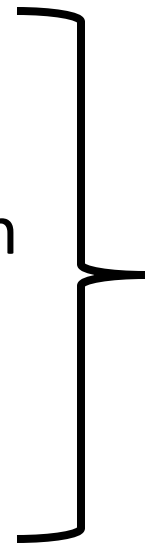
How is this
progress?

Homo Erectus?

weak
fragile



hands
feet
skeleton
muscle
skin
gut



Roughly
modern

Very
fragile

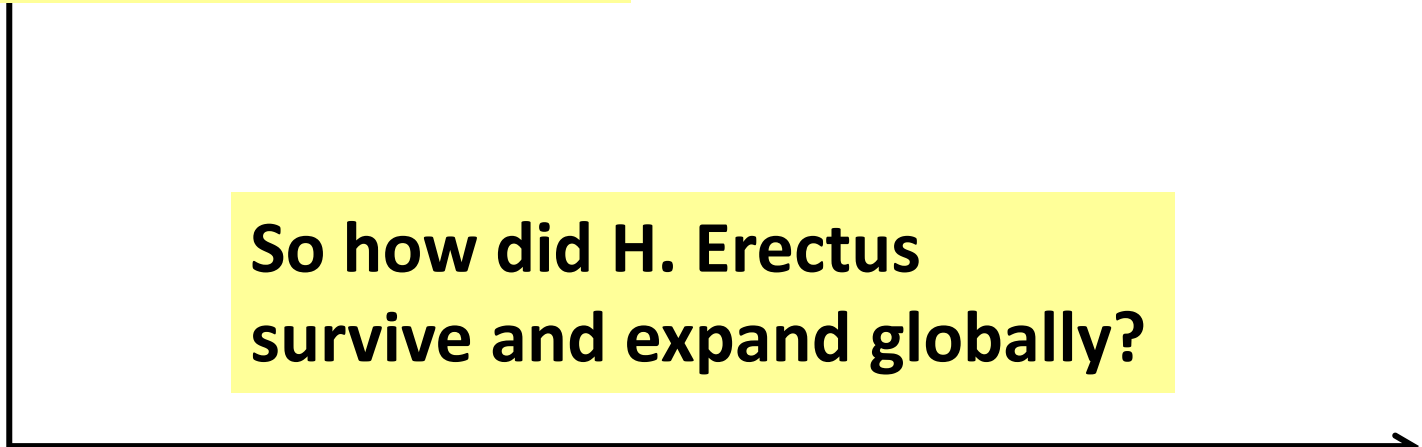
This much seems pretty
consistent among experts
regarding circa 1.5-2Mya

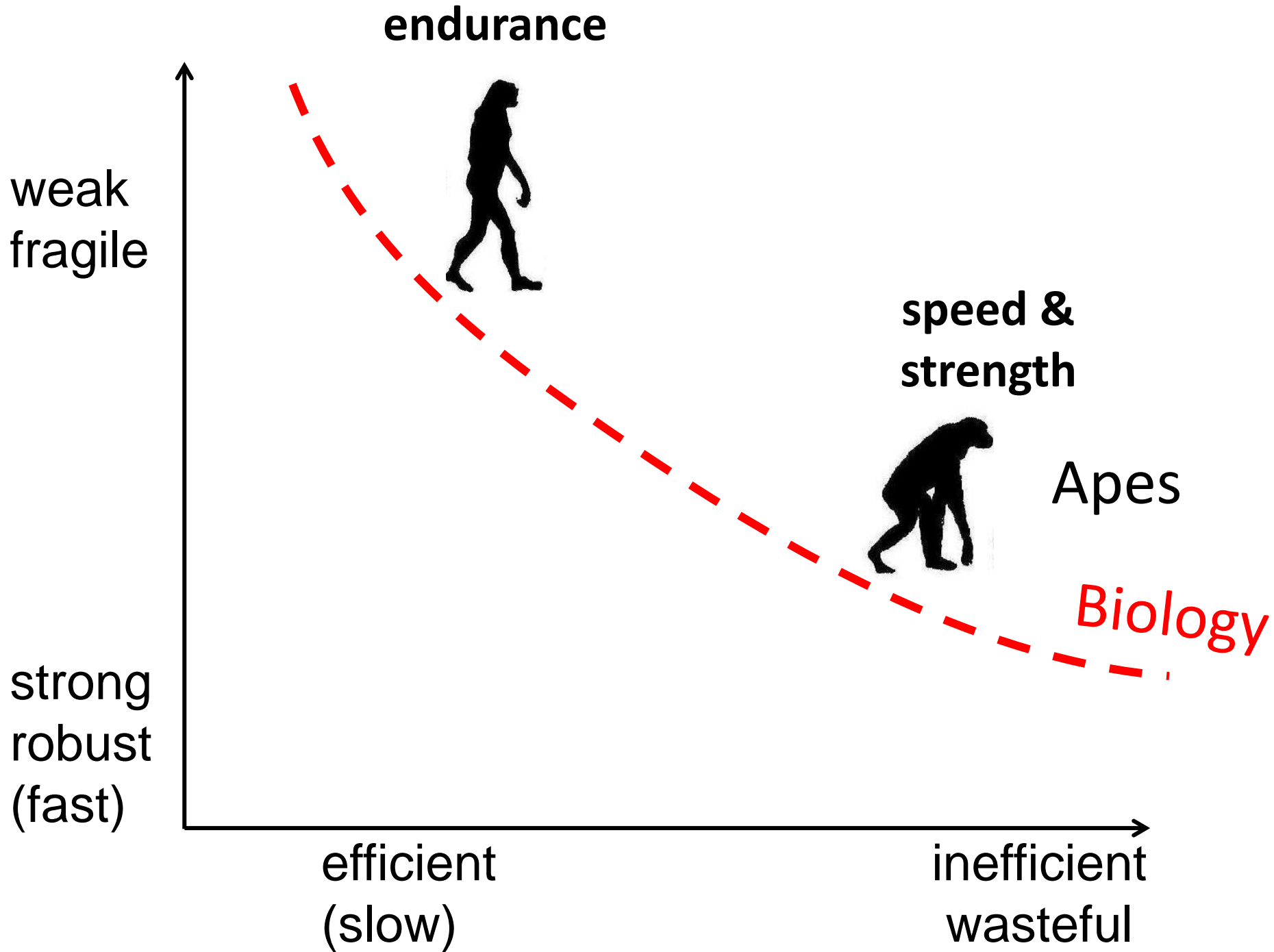
strong
robust

So how did H. Erectus
survive and expand globally?

efficient
(slow)

inefficient
wasteful





weak
fragile
(slow)

**Human
evolution**

hands
feet
skeleton
muscle
skin
gut

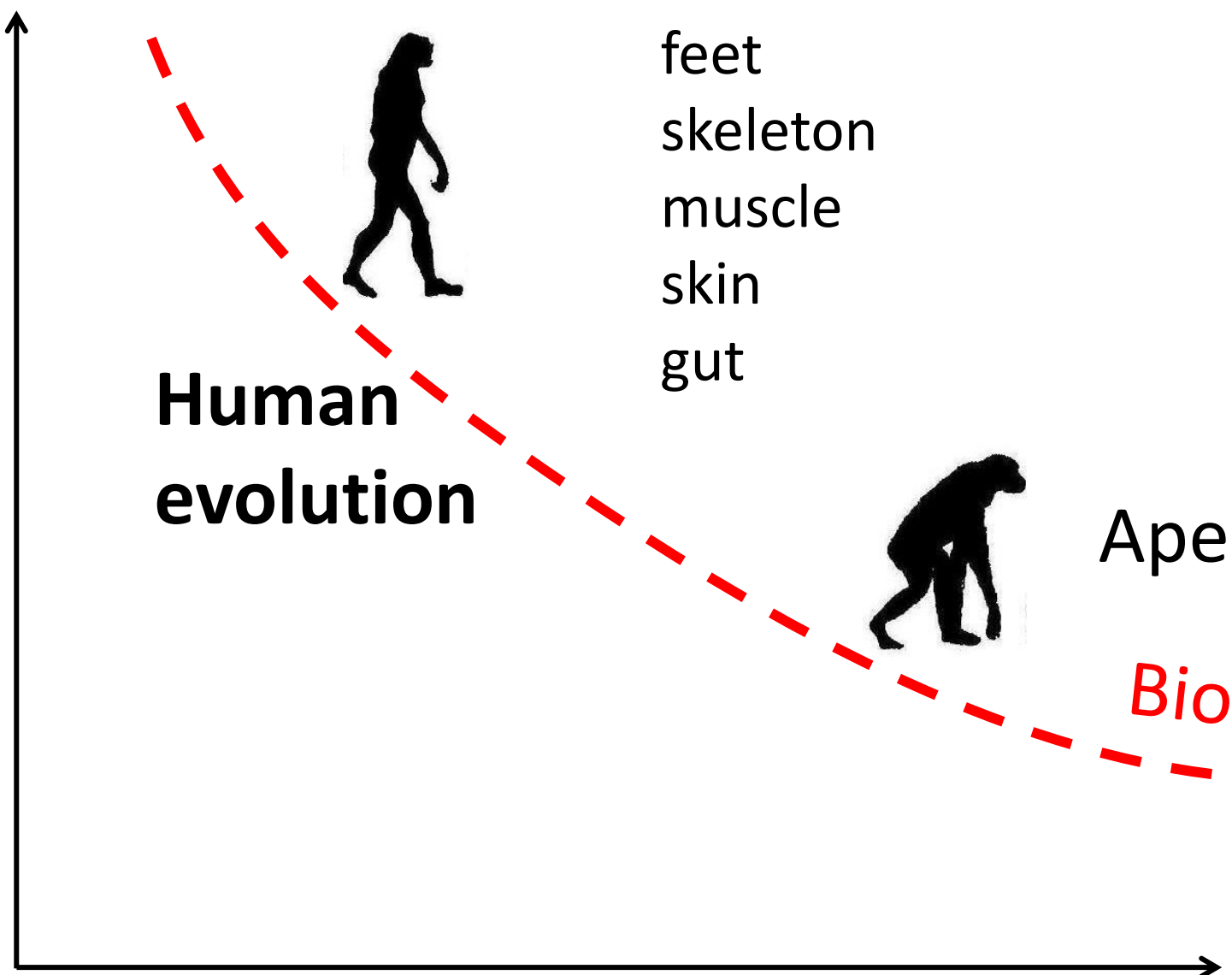
Apes

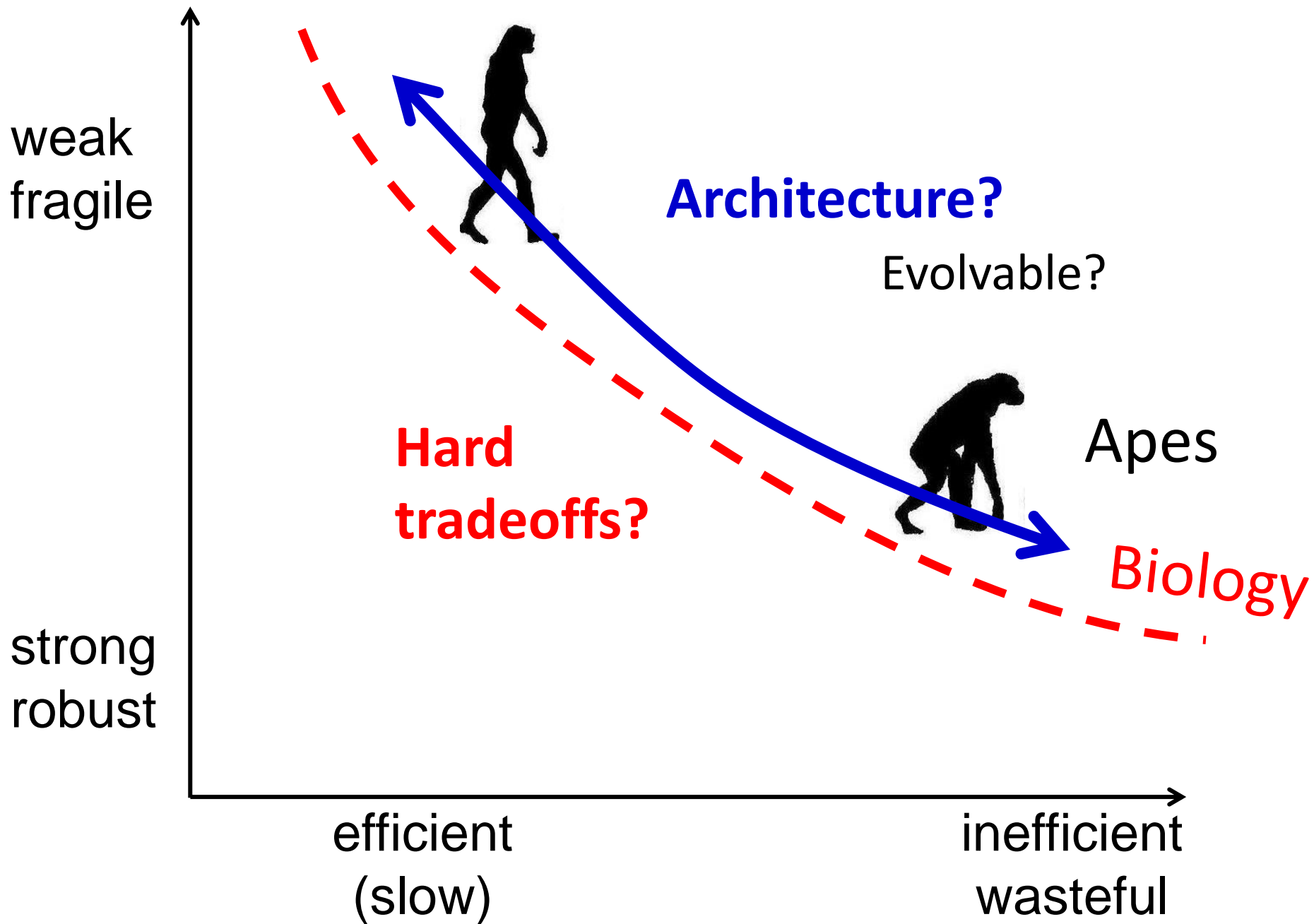
Biology

strong
robust
(fast)

efficient
(slow)

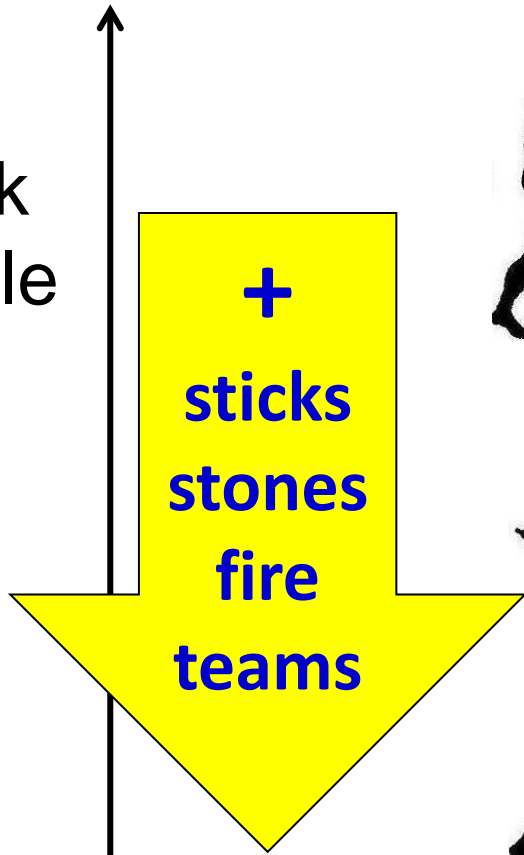
inefficient
wasteful





endurance

weak
fragile



From weak prey
to invincible
predator?

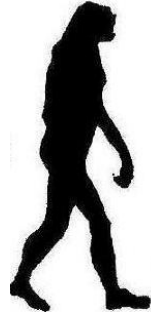
strong
robust



efficient
(slow)

Speculation? There is only evidence for crude stone tools. But sticks, fire, teams might not leave a record?

weak
fragile



Speculation? With only evidence for crude stone tools. But sticks and fire might not leave a record?

+
sticks
stones
fire
teams



From weak prey to invincible predator



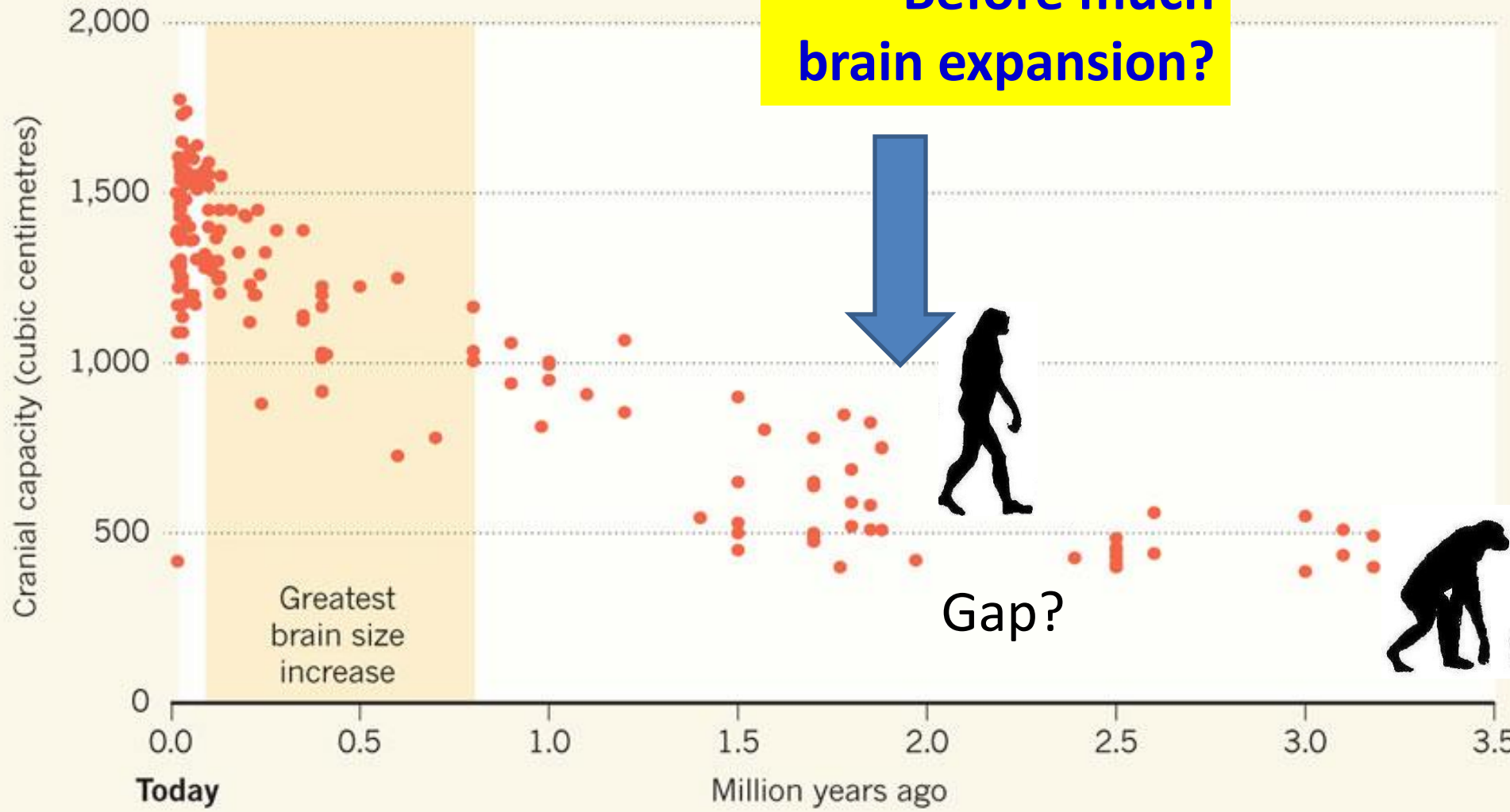
**Before much
brain expansion?**

strong
robust

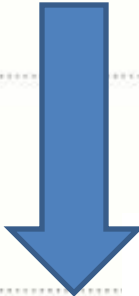
efficient
(slow)

Plausible but speculation?

Cranial capacity



Before much
brain expansion?



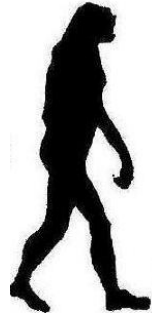
Gap?



Today

2Mya

weak
fragile



hands
feet
skeleton
muscle
skin
gut

+



sticks
stones
fire



From weak prey
to invincible
predator

strong
robust

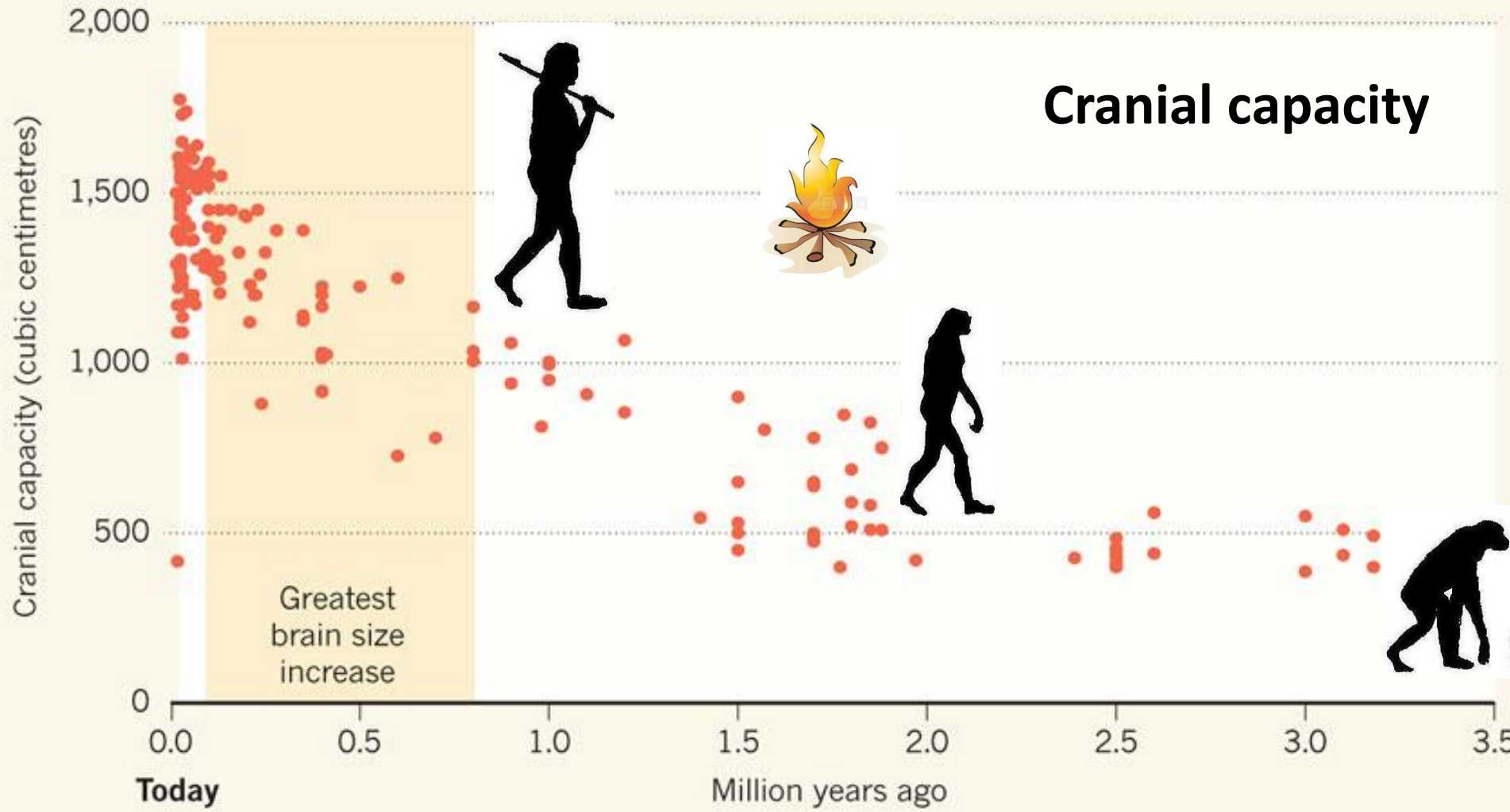
Before much
brain expansion?

efficient
(slow)

Key point:
Our physiology,
technology,
and brains
have co-
evolved

Probably true
no matter what

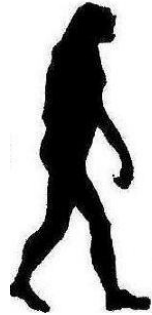
Huge
implications.



Today

2Mya

weak
fragile



hands
feet
skeleton
muscle
skin
gut

**Key point needing
more discussion:**
The evolutionary
challenge of big brains
is *homeostasis*, not
basal metabolic load.

strong
robust

+

sticks
stones
fire



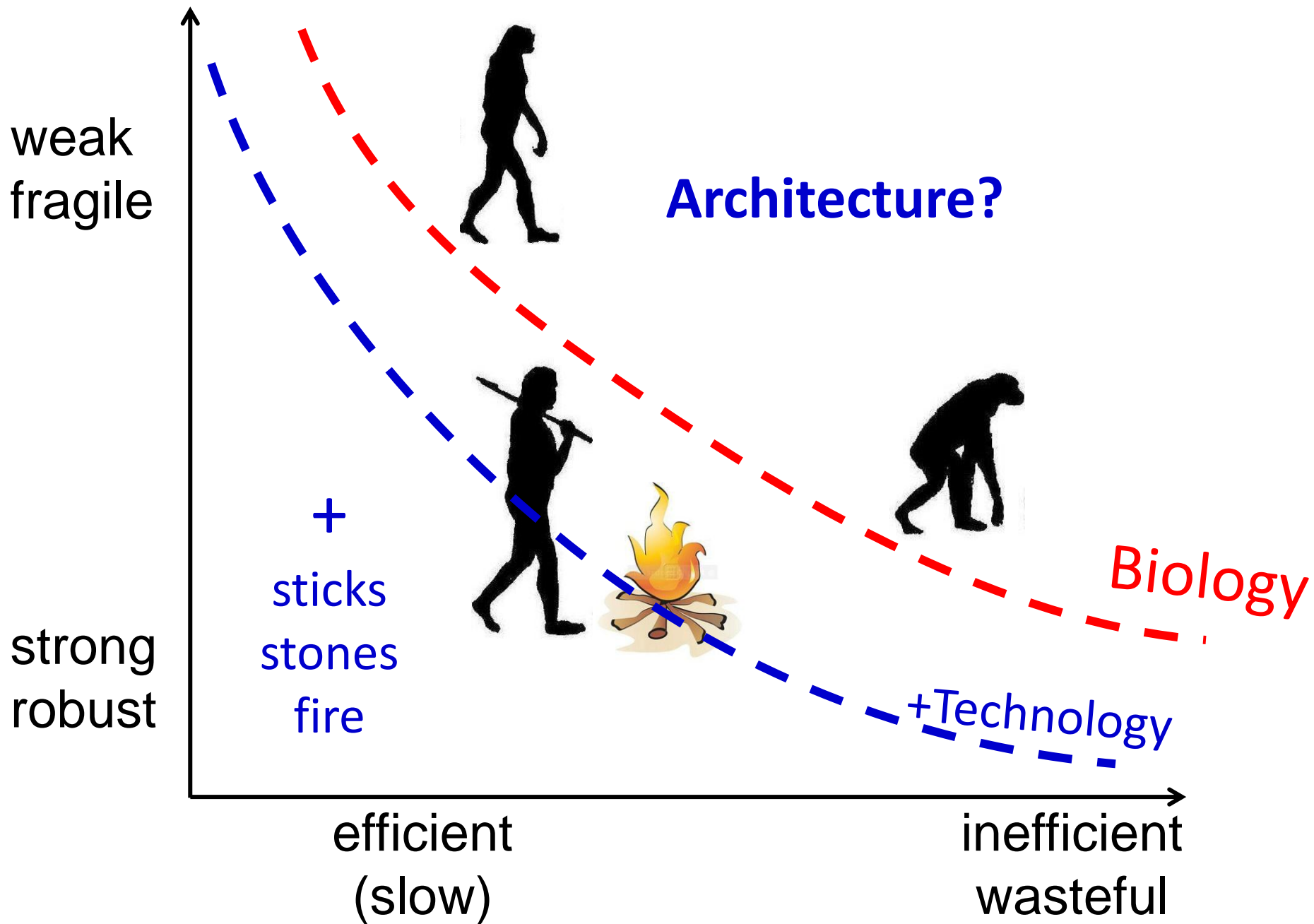
From weak prey
to invincible
predator

Before much
brain expansion?

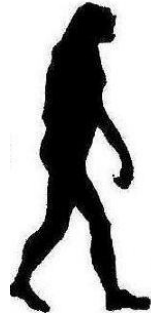
efficient
(slow)



Huge
implications.



weak
fragile



hands
feet
skeleton
muscle
skin
gut

+
sticks
stones
fire

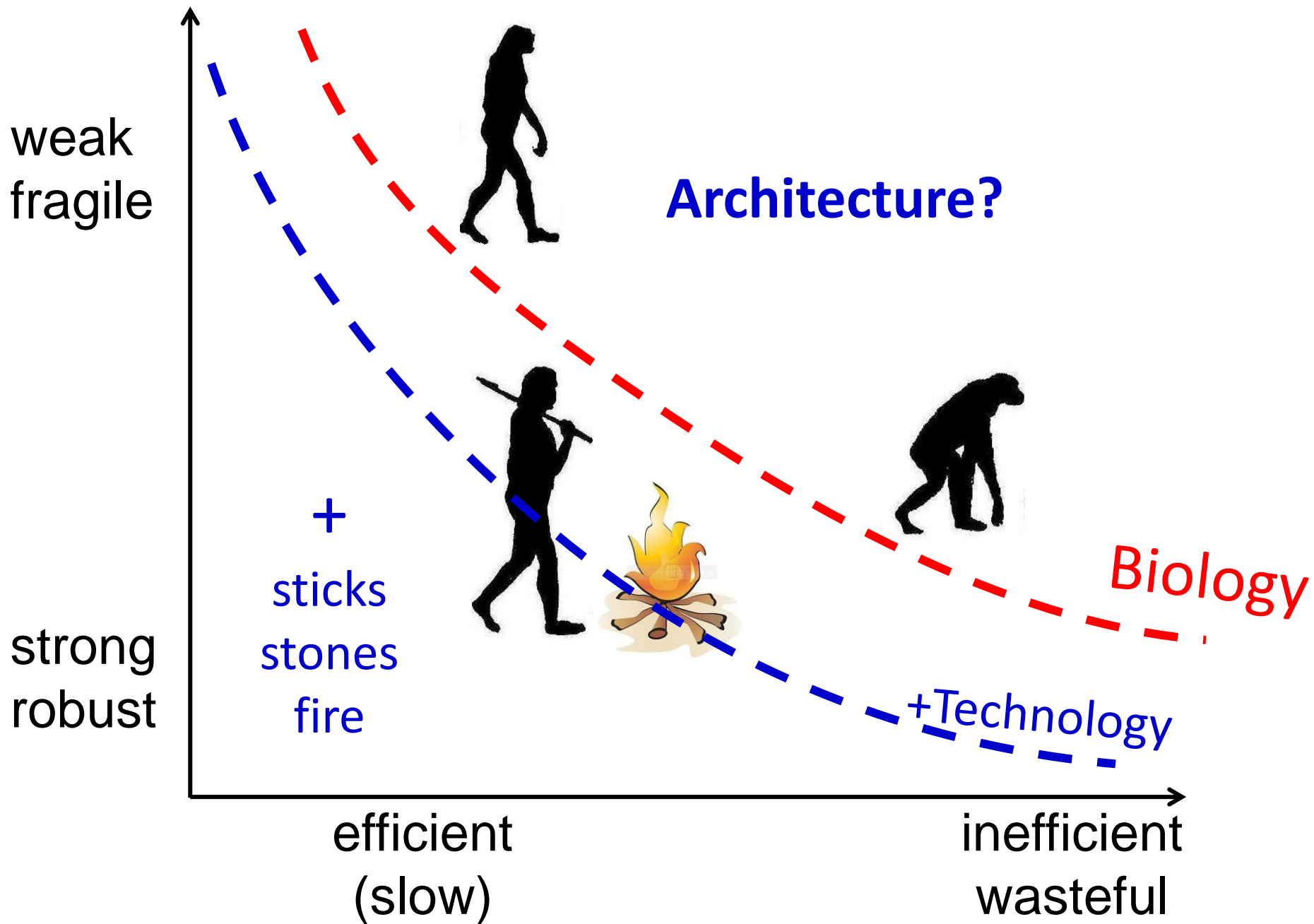


From weak prey
to invincible
predator

strong
robust

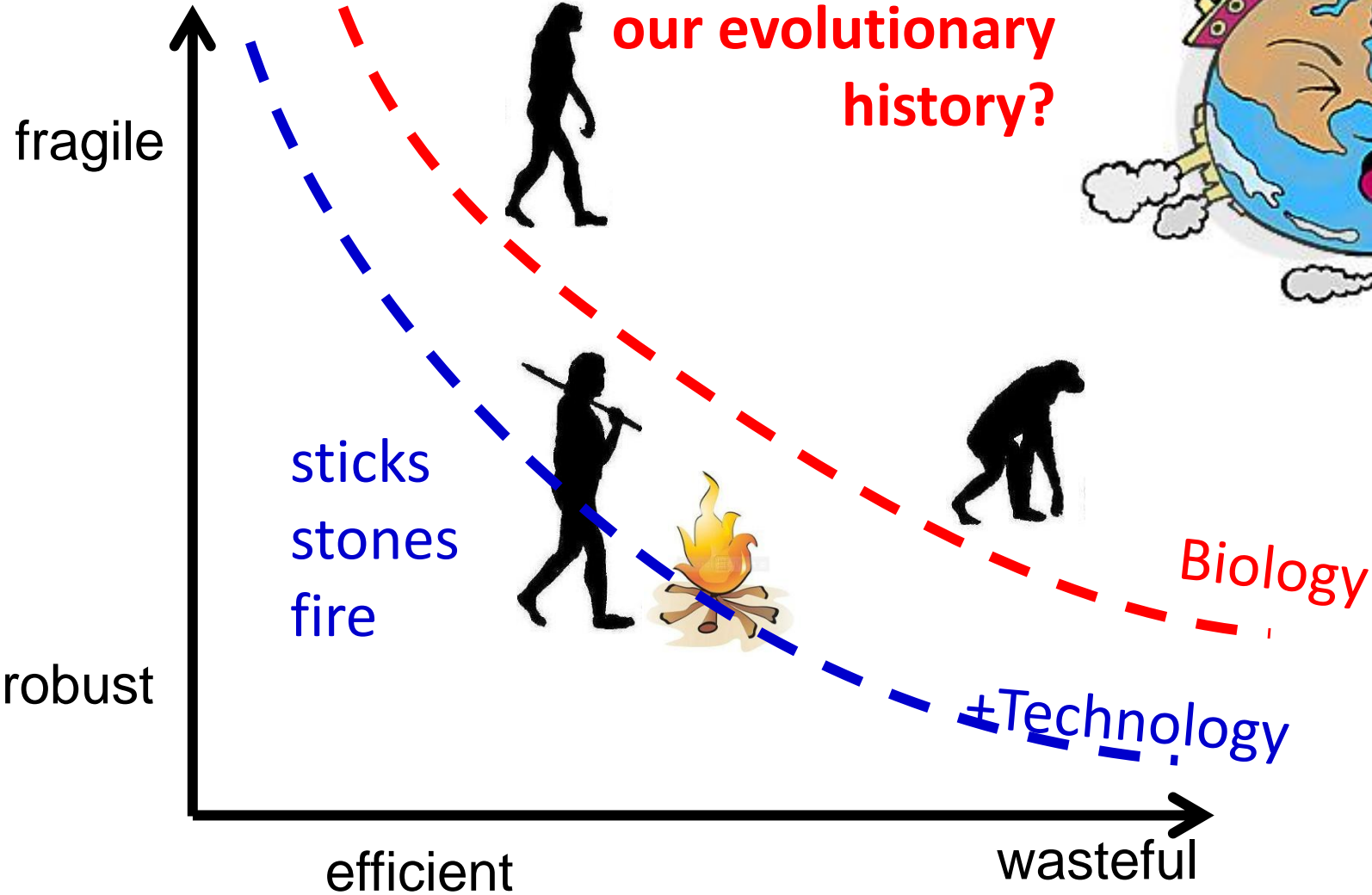
efficient
(slow)

Before much
brain expansion?



Human complexity?

Consequences of our evolutionary history?



sticks
stones
fire

Biology

Technology

fragile

robust

efficient

wasteful

Constraints (that deconstrain)

fragile



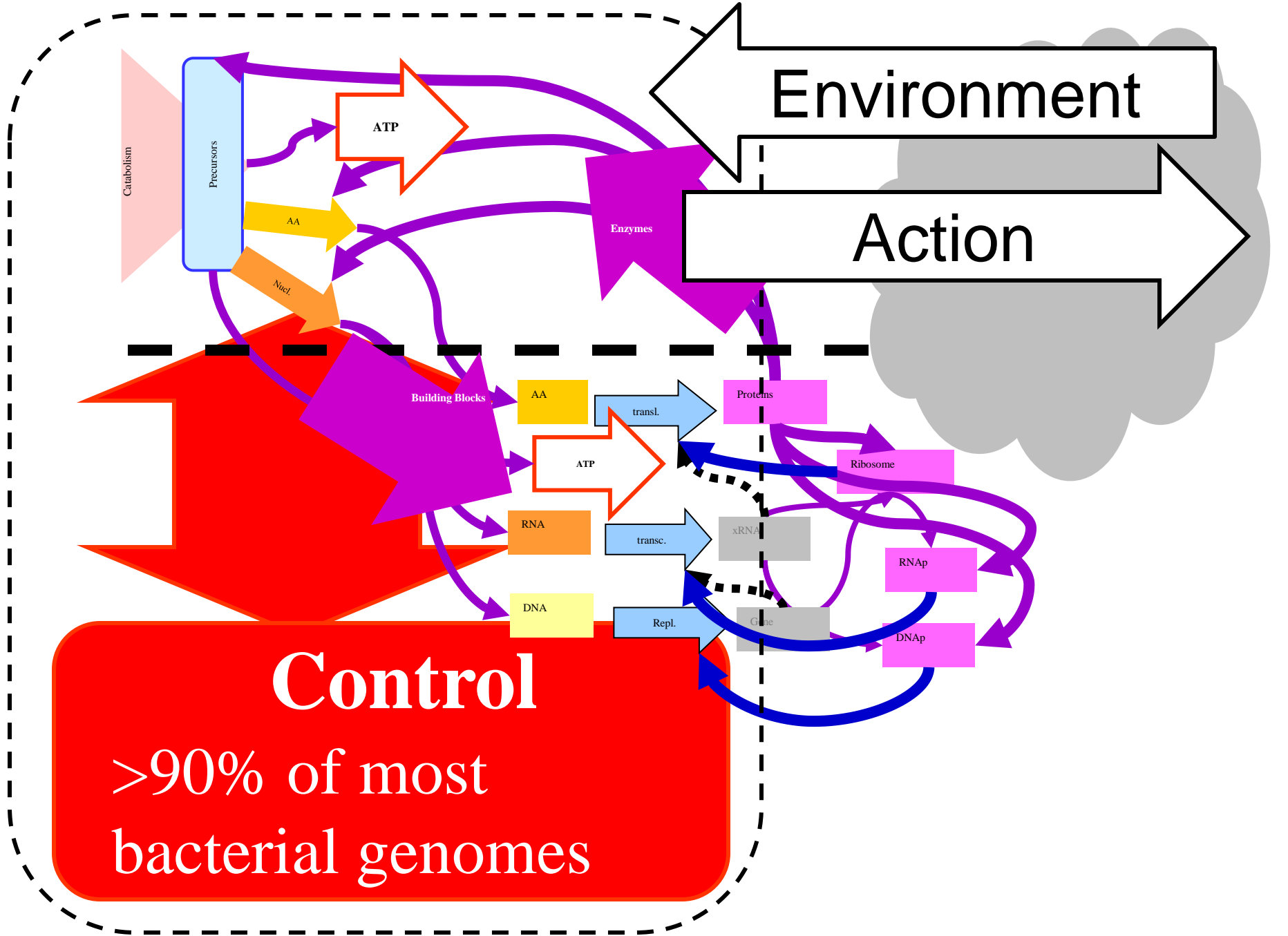
Architecture?

robust

**Hard
tradeoffs?**

efficient

wasteful



Environment

Action

Enzymes

Catabolism

Precursors

ATP

AA

Nuc.

Building Blocks

AA

ATP

RNA

DNA

transL.

transc.

Repl.

Proteins

Ribosome

xRNA

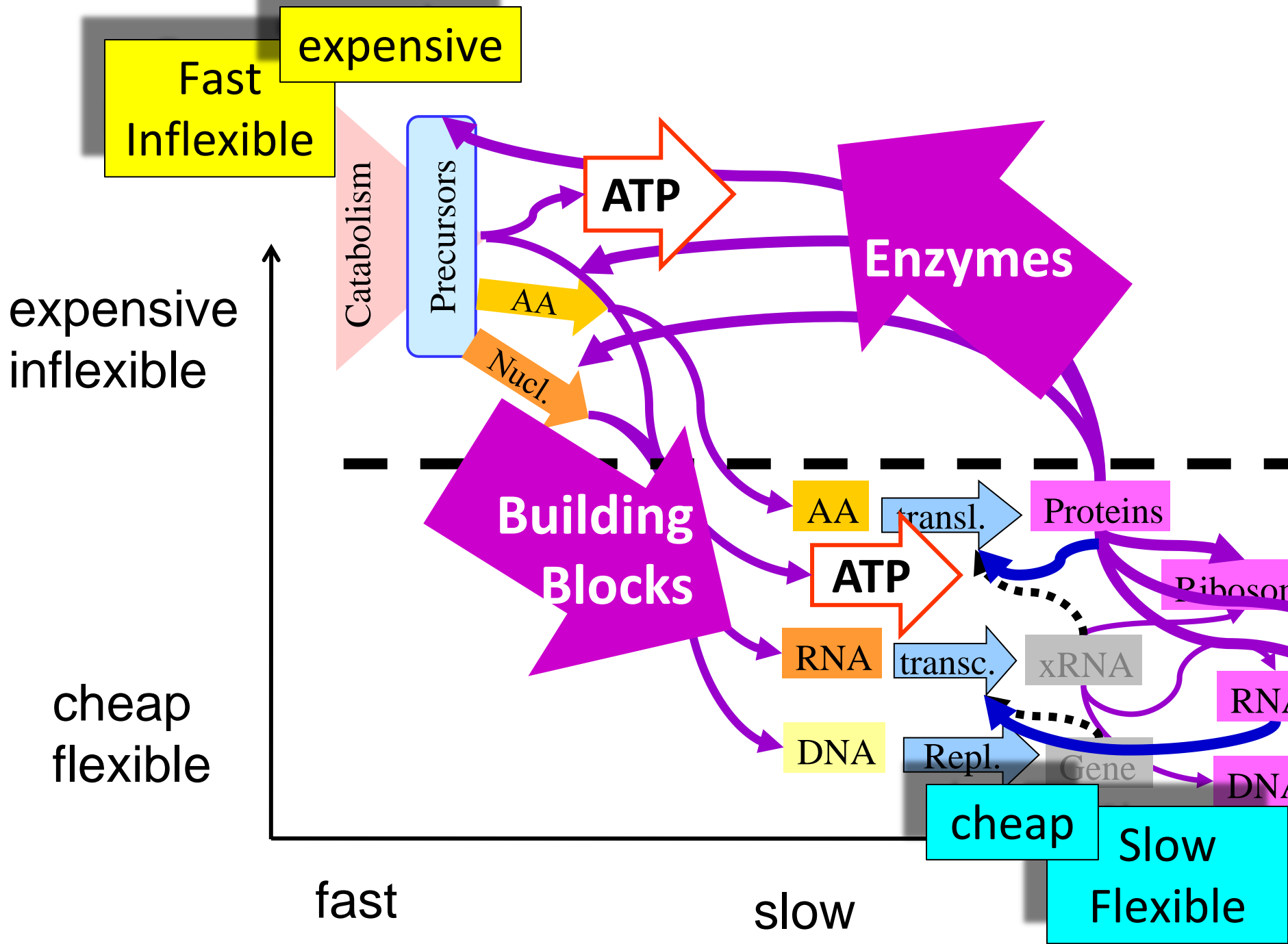
RNAP

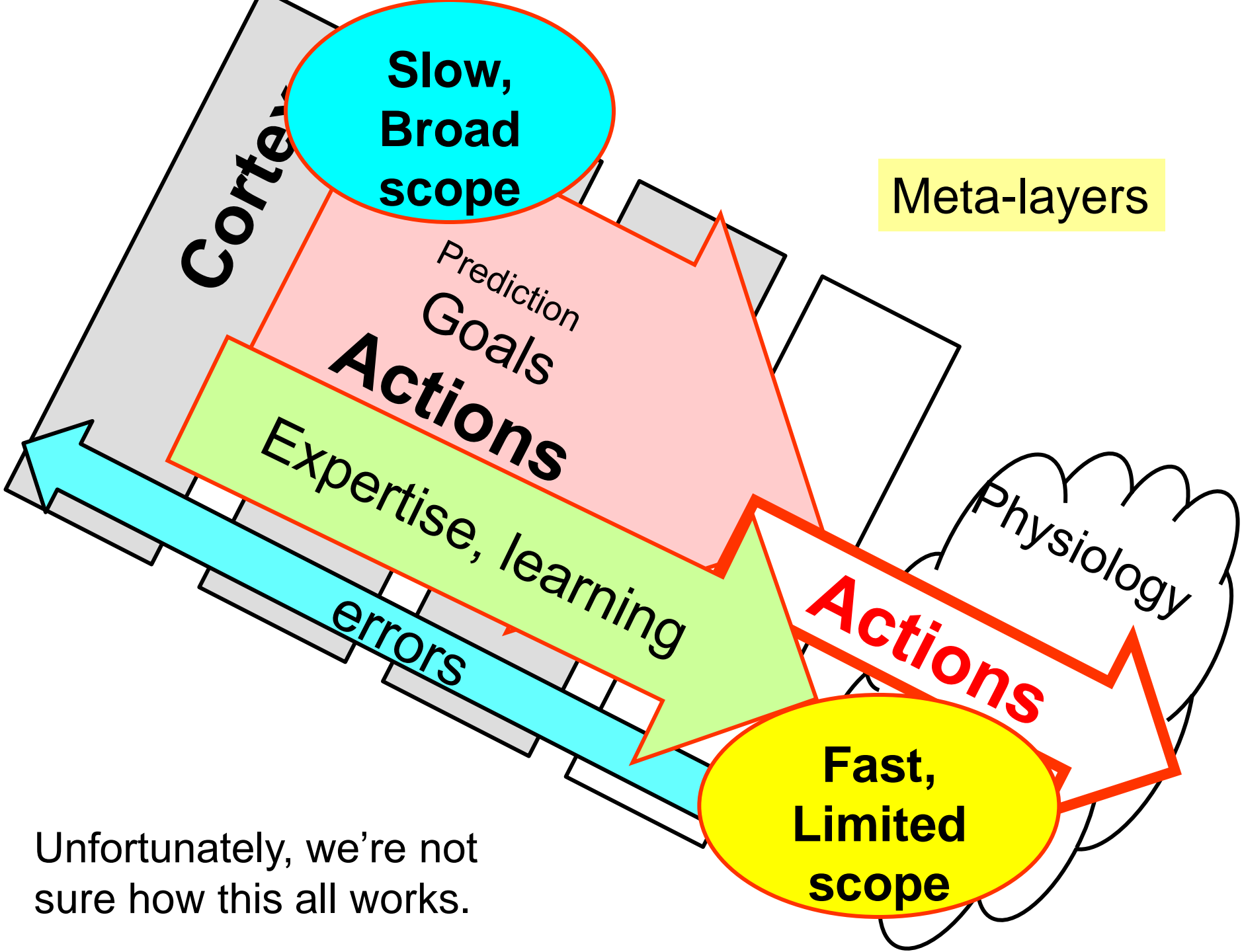
DNAP

Gene

Control

>90% of most bacterial genomes





**Flexible/
Adaptable/
Evolvable**

**Horizontal
Meme
Transfer**

frontal

Sensory

Learning

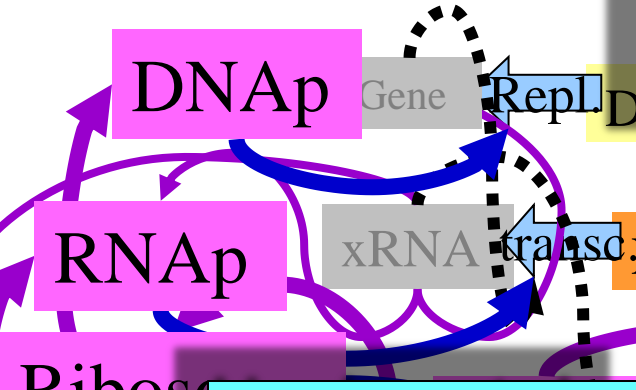
Striatu

Reflex

Software
Hardware

**Horizontal
App
Transfer**

Digital
Analog



**Horizontal
Gene
Transfer**

**Depends
crucially on
layered
architecture**

“New sciences” of
“complexity” and
“networks”?



Science as

- Pure fashion
- Ideology
- Political
- Evangelical
- Nontech trumps tech

- Edge of chaos
- Self-organized criticality
- Scale-free “networks”
- Creation “science”
- Intelligent design
- Financial engineering
- Risk management
- “Merchants of doubt”
- ...

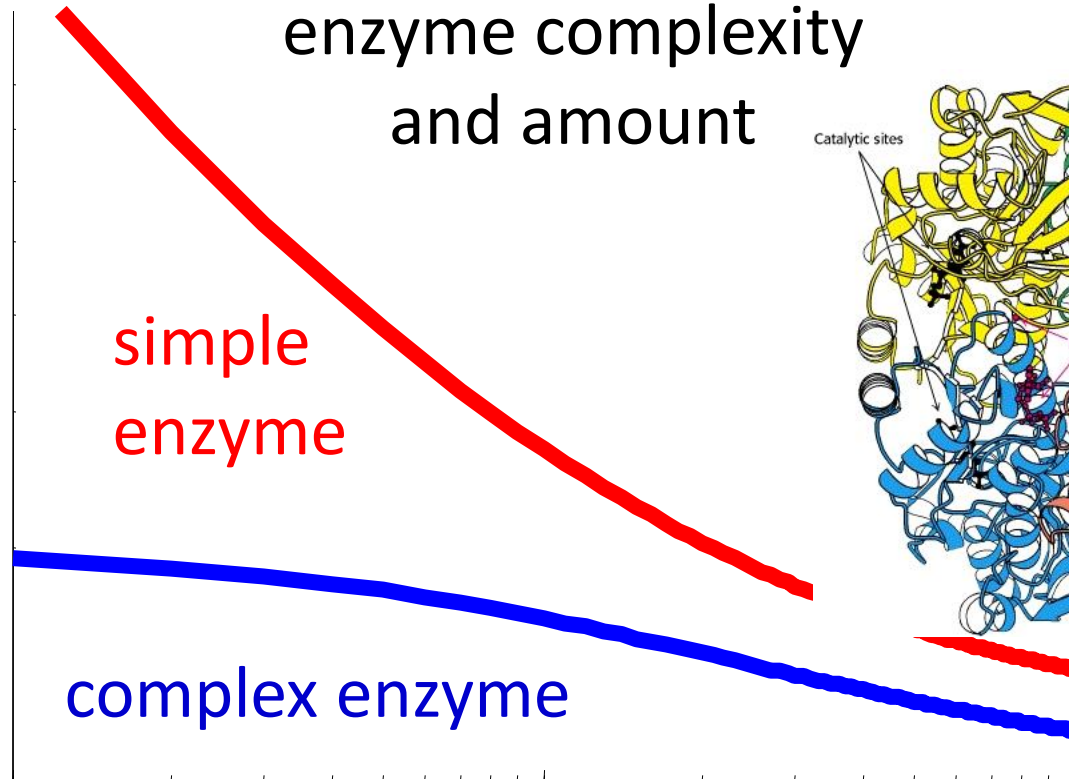
Theorem!

$$\frac{1}{\pi} \int_0^{\infty} \ln |S(j\omega)| \left(\frac{z}{z^2 + \omega^2} \right) d\omega \geq \ln \left| \frac{z+p}{z-p} \right|$$

z and p functions of enzyme complexity and amount

Fragility

$$\ln \left| \frac{z+p}{z-p} \right|$$



Enzyme amount

Fragility

hard limits

- General
- Rigorous
- First principle

simple

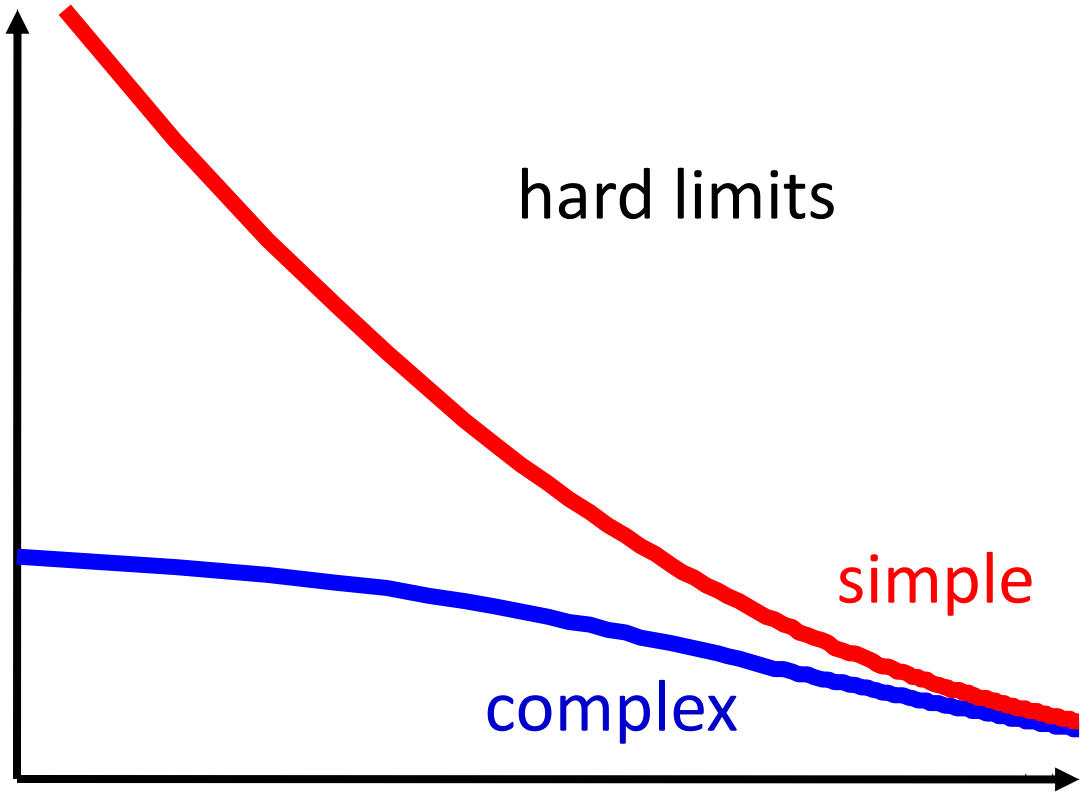
complex

Overhead, waste

**Plugging in
domain details**

?

- Domain specific
- Ad hoc
- Phenomenological



Control

Wiener

Comms

Bode

robust control

Shannon

Kalman

- General
- Rigorous
- First principle

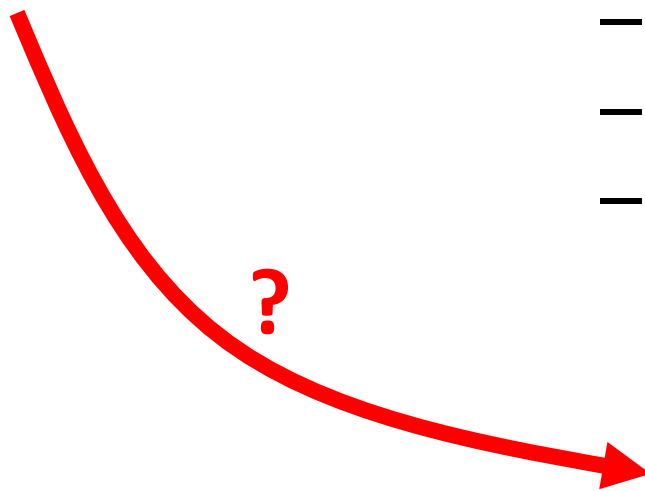
- **Fundamental multiscale physics**
- Foundations, origins of
 - noise
 - dissipation
 - amplification
 - catalysis

Carnot

Boltzmann

Heisenberg

Physics



What I'm not going to talk much about

- It's true that most "really smart scientists" think almost everything in these talks is nonsense
- Why they think this
- Why they are wrong

- Time (not space) is our problem, as usual
- Don't have enough time for what is true, so have to limit discussion of what isn't
- No one ever changes a made up mind (almost)
- But here's the overall landscape

Control

Comms

Complex
networks

Wildly “successful”



Compute

“New sciences” of
complexity and networks
edge of chaos, self-organized
criticality, scale-free,...

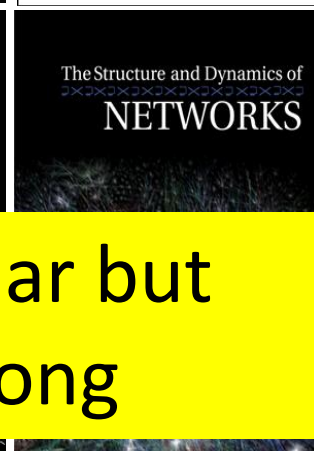
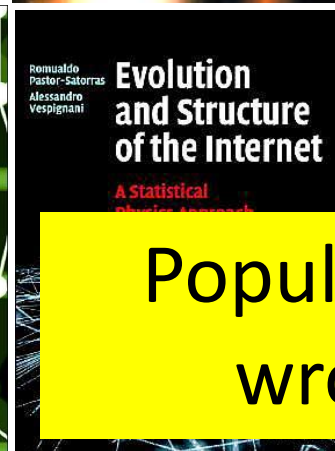
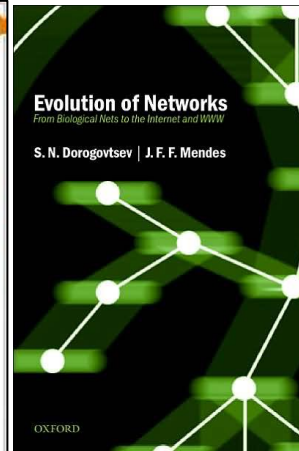
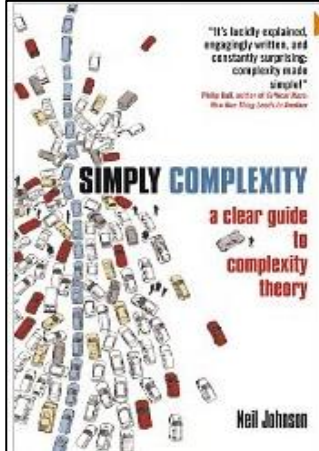
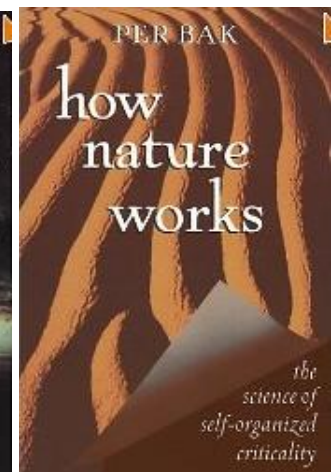
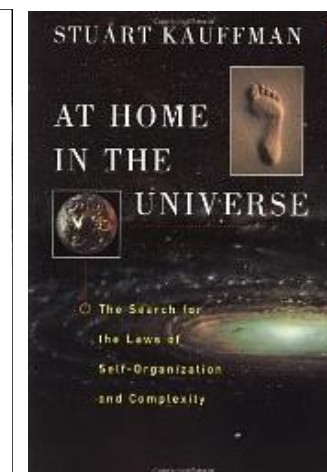
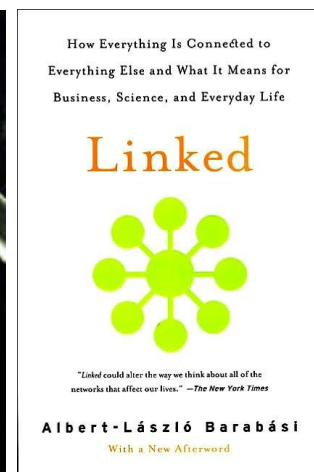
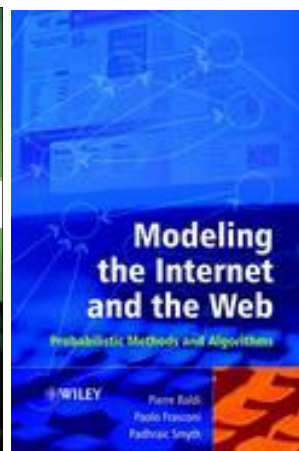
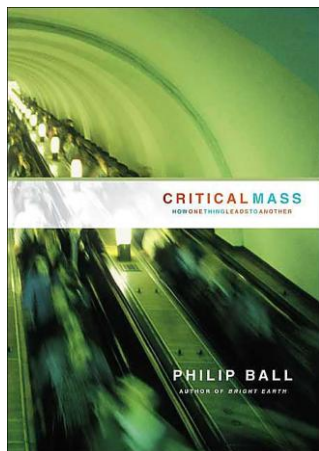
Stat physics

Carnot

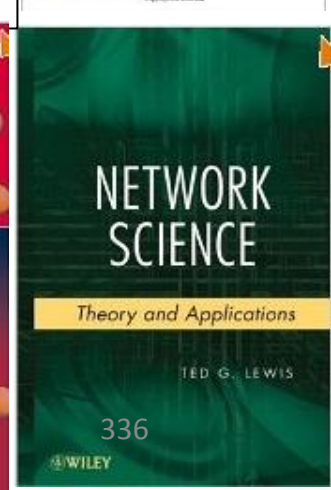
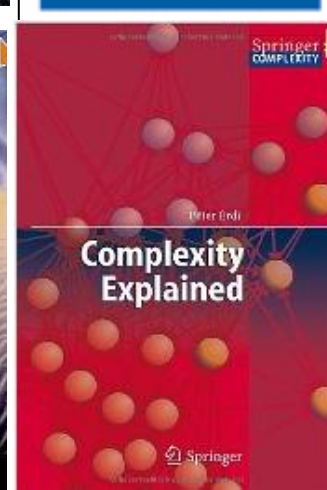
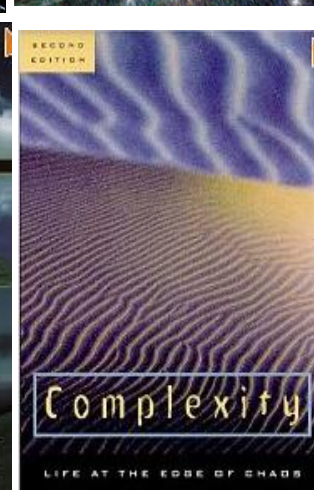
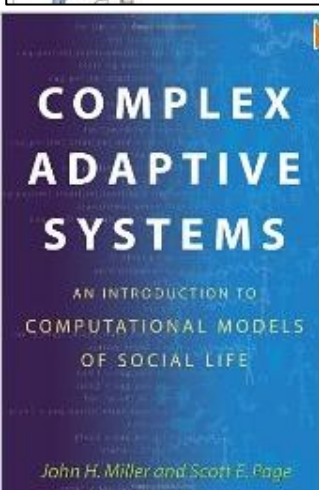
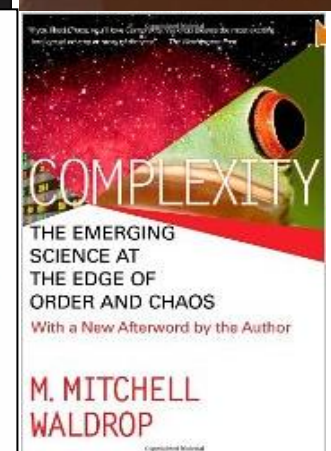
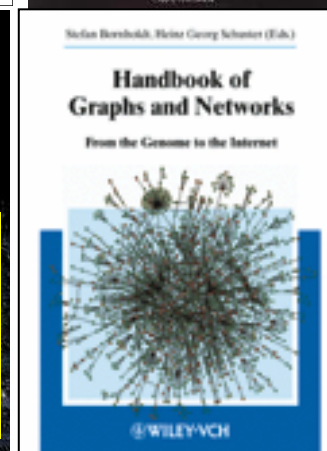
Boltzmann

Heisenberg

Physics



Popular but wrong



Complex systems?

Even small
amounts can
create
bewildering
complexity

Fragile

- Scale
- Dynamics
- Nonlinearity
- Nonequilibrium
- Open
- Feedback
- Adaptation
- Intractability
- Emergence
- ...

Complex systems?

Robust

- Scale
- Dynamics
- Nonlinearity
- Nonequilibrium
- Open
- Feedback
- Adaptation
- Intractability
- Emergence
- ...

Fragile

- Scale
- Dynamics
- Nonlinearity
- Nonequilibrium
- Open
- Feedback
- Adaptation
- Intractability
- Emergence
- ...

Complex systems?

Robust complexity

- Scale
 - Dynamics
 - Nonlinearity
 - Nonequilibrium
 - Open
 - Feedback
 - Adaptation
 - Intractability
 - Emergence
 - ...
- Resources
 - Controlled
 - Organized
 - Structured
 - Extreme
 - ***Architected***
 - ...

- These words have lost much of their original meaning, and have become essentially meaningless synonyms
- e.g. nonlinear \neq not linear
- Can we recover these words?
- Idea: make up a new word to mean “I’m confused but don’t want to say that”
- Then hopefully we can take these words back (e.g. nonlinear = not linear)

Fragile complexity

- Scale
- Dynamics
- Nonlinearity
- Nonequilibrium
- Open
- Feedback
- Adaptation
- Intractability
- Emergence
- ...

New words

Emergent

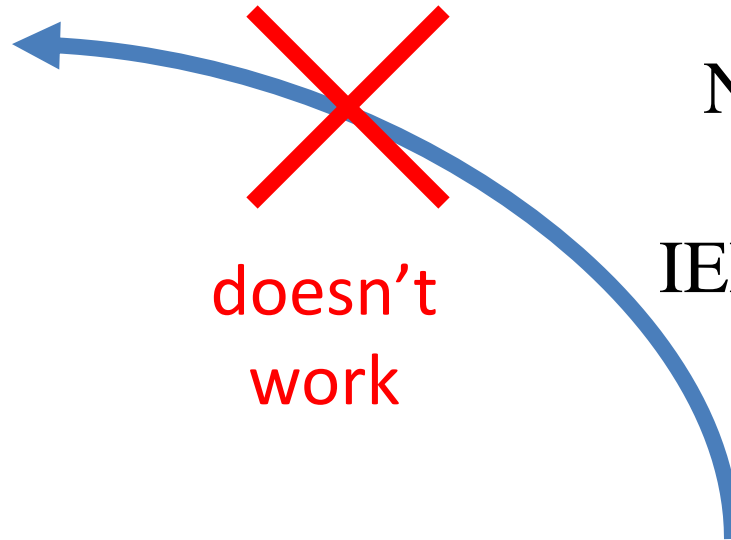
**Emergence
at the edge of
chaocritiplexity**

**Fragile
complexity**

- Scale
- Dynamics
- Nonlinearity
- Nonequilibrium
- Open
- Feedback
- Adaptation
- Intractability
- Emergence
- ...

Alderson & Doyle,
Contrasting Views of
Complexity and Their
Implications for
Network-Centric
Infrastructure,
IEEE TRANS ON
SMC,
JULY 2010

Complex
networks



doesn't
work

Stat physics

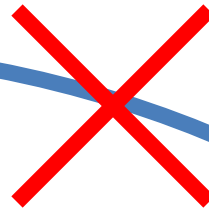
“New sciences” of
complexity and networks
edge of chaos, self-organized
criticality, scale-free,...

Complex systems?

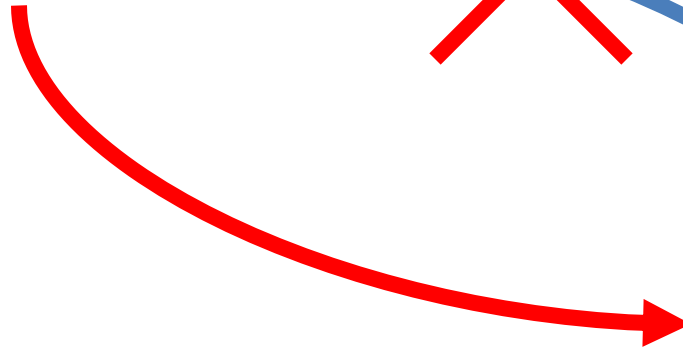
Control

Comms

Complex
networks



Compute



Stat physics

Carnot

Boltzmann

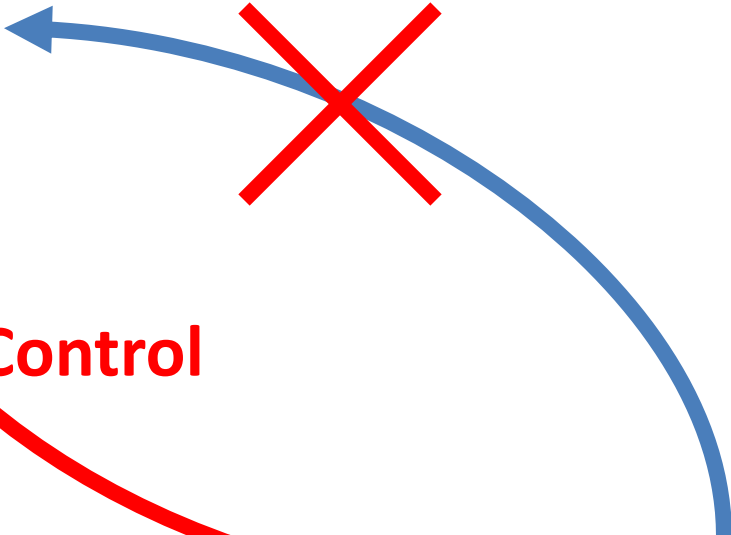
Heisenberg

Jean Carlson, UCSB Physics

Physics

Alderson & Doyle, Contrasting Views of Complexity and Their Implications for Network-Centric Infrastructure, IEEE TRANS ON SMC, JULY 2010

Complex networks



Control

Stat physics

Sandberg, Delvenne, & Doyle, On Lossless Approximations, the Fluctuation-Dissipation Theorem, and Limitations of Measurement, IEEE TRANS ON AC, FEBRUARY, 2011

Carnot
Boltzmann
Heisenberg
Physics

“The last 70 years of the 20th century will be viewed as the dark ages of theoretical physics.” (Carver Mead)

Complex networks

“orthophysics”

From prediction
to mechanism
to control

Fundamentals



Sandberg, Delvenne,
& Doyle, On Lossless
Approximations, the Fluctuation-
Dissipation Theorem, and
Limitations of Measurement,
IEEE TRANS ON AC,
FEBRUARY, 2011

Stat physics,
fluids, QM

Carnot

Boltzmann

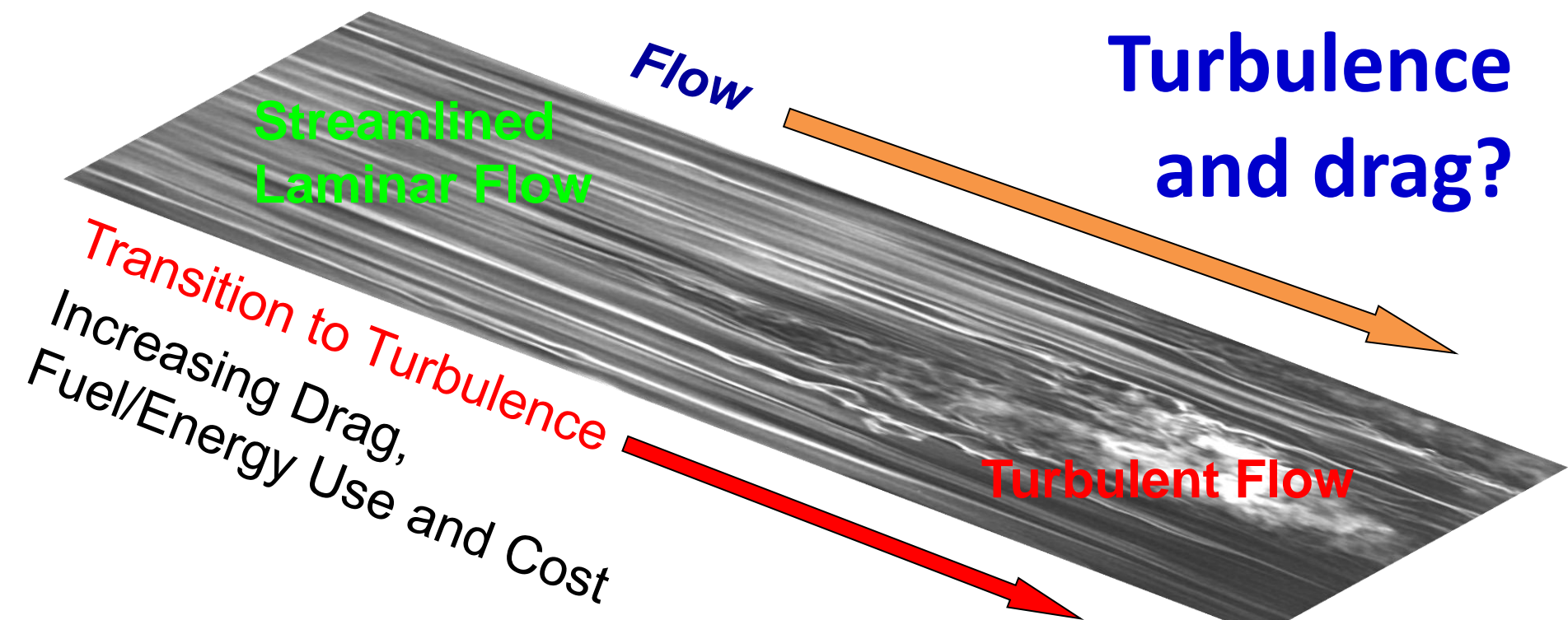
Heisenberg

Physics

J. Fluid Mech (2010)

A streamwise constant model of turbulence in plane Couette flow

D. F. GAYME¹†, B. J. McKEON¹,
A. PAPACHRISTODOULOU², B. BAMIEH³
AND J. C. DOYLE¹



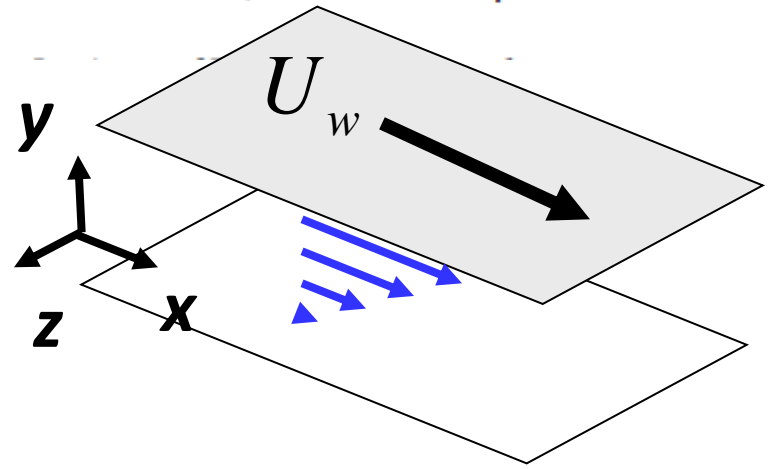
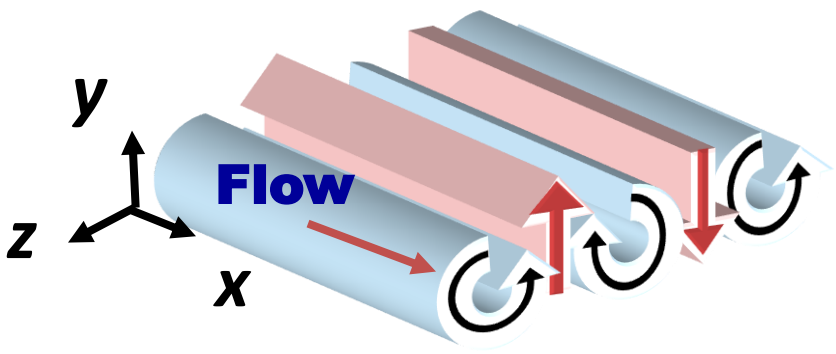
Amplification and nonlinear mechanisms in plane Couette flow

Dennice F. Gayme,¹ Beverley J. McKeon,¹ Bassam Bamieh,² Antonis Papachristodoulou,
and John C. Doyle³

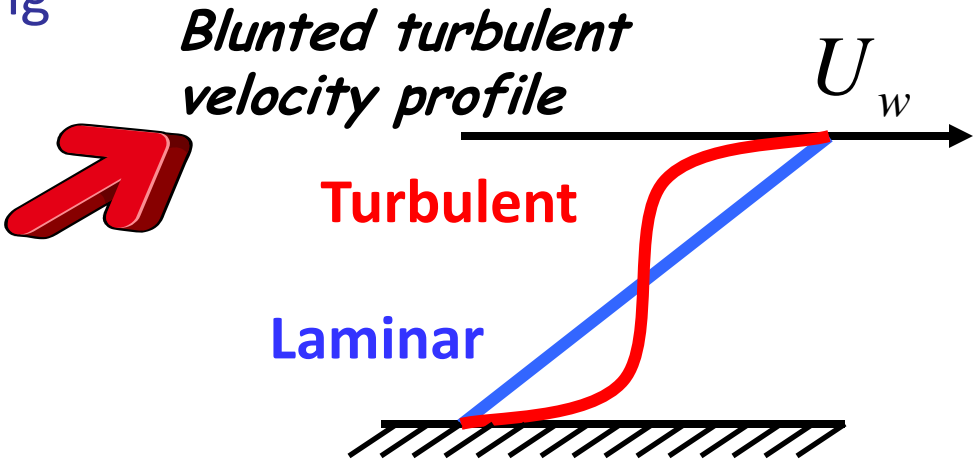
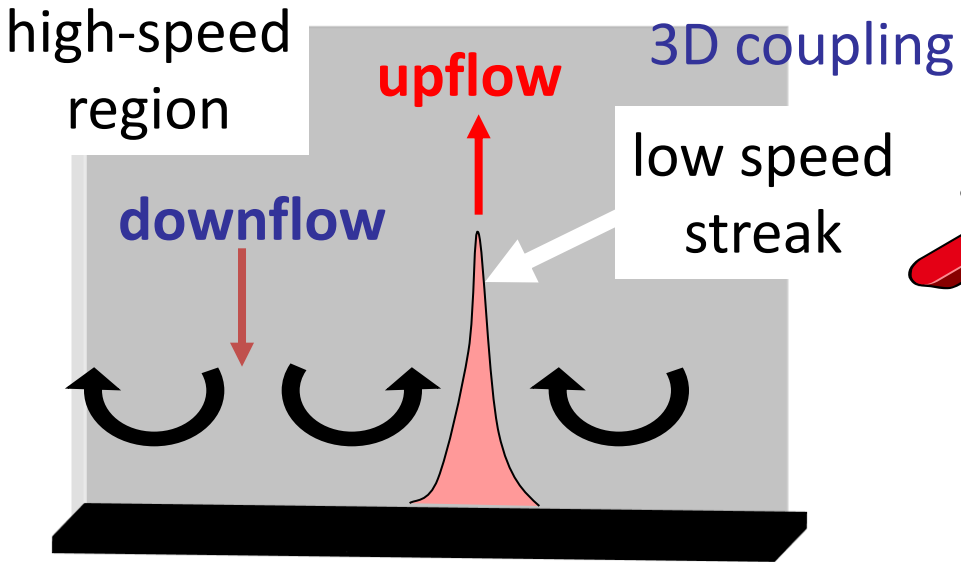
Dennice Gayme,
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John Doyle

Amplification and nonlinear mechanisms in plane Couette flow

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Coherent structures and turbulent drag





fragile

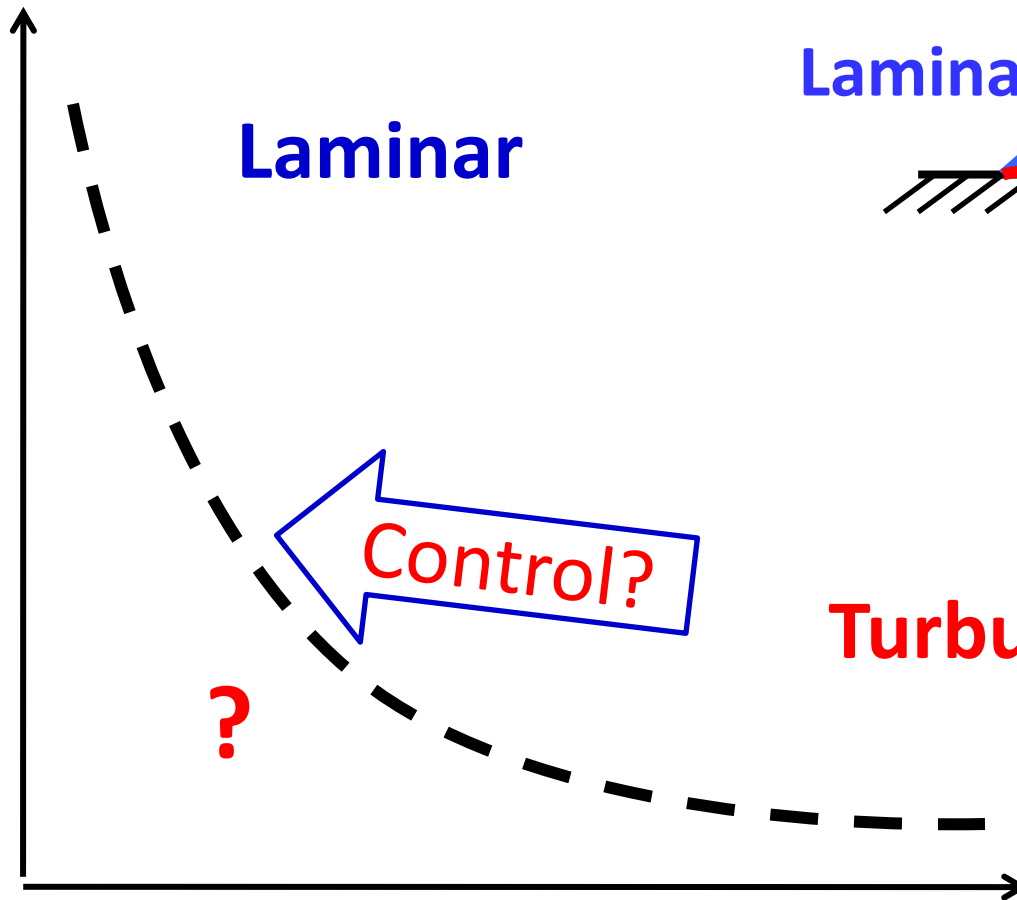
Laminar

robust

efficient

Turbulent

wasteful



Laminar

Turbulent

U_w



Existing design frameworks

- Sophisticated components
- Poor integration
- Limited theoretical framework

Fix?

