# Future of Army Terramechanics

### **Capabilities and Needs**

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- Background on ERDC contribution to Army Terramechanics
- A little history
- Recent research efforts
- Thoughts on capabilities and limitations of computer simulation
- Concluding Remarks





- ERDC consists of seven laboratories located at four campuses
- Various field sites
- Two labs concentrating on mobility
  Mobility Systems (GSL-Vicksburg)
  CRREL (New Hampshire)





# **ERDC Mobility Research**

- Dedicated mobility group since the 1950s
- Vehicle testing
- Mobility models (NRMM)
- Historically, mobility research performed by the WES and CRREL.
- Computer simulation taking on greater role

#### **Historical Support to Apollo Program**



#### **VANE Computational Testbed**

Ground/Surface Mesh

#### Support UGV design trades and performance evaluations

- Autonomy systems and algorithms for mobility/ navigation
- Sensors for robotic perception and localization
- Vehicle platforms and components
- Tactical behaviors
- Tactics, techniques, and procedures (TTPs)
- Vegetation Insertion **Objects Insertion** Meteorological Data Observed Data Scene Initialization Manager Vehicle Simulation No New **Environment Simulation** Multi-body Vehicle Dynamics Ground Vegetation & Sensor Models Model Position Model Autonomous & Orien Yes Navigation Ray Casting Model Model Vehicle Terrain Post Processing (customer) Interface Model Analysis Archive Playback Scoring **Sensor Simulation** Ideal Images Sensor Images & Scene State Sensor Models & Scene State

Scene Generation

Material Attributions

- Integrates high-fidelity models for environment, terrain, vehicles, and sensors
- Core product simulates geoenvironmental influences on sensor responses and UGV platform mobility

#### **ANVEL - 'Face' of the VANE CTB**

#### **Features of ANVEL**

- 3-D vehicle dynamics simulator designed for the VANE CTB
  - Pre-simulation planning and postprocessing visualization
- Uses the Open Dynamics Engine (ODE) for multi-body physics
  - Simulates all vehicle components except for the wheels and tracks
- Uses the Ground Contact Element (GCE) with the Vehicle
   Terrain Interface (VTI) model to simulate the interaction forces on wheels/tracks
  - Longitudinal and lateral traction, motion resistance, and sinkage



#### **VANE CTB Terramechanics**

- Emerging implementation for vehiclesoil relationships in vehicle dynamics software
  - Vehicle Terrain Interface (VTI) model
    - Nodal-based terramechanics for wheels and tracks
  - Ground Contact Element (GCE)













#### **NASA Crawler Transporter Study**

- Study to investigate crawlerway compatibility for Ares V Crawler Transporter concepts
  - Analytical assessment of four wheeled crawler concepts to replace aging tracked platform
    - Concepts have 80, 192, 224, and 528 pneumatic tires
  - High resolution model of most complex concept
    - Early application of GCE with VTI in ANVEL Software









### **DEM at ERDC**

- (70s-80s)WES used Cundal's model for rock mechanics.
- (80s) Used home-grown codes (Palmerton)
- (90s-present) CRELL developed DEM for solving numerous application in Ice and Snow mechanics (Hopkins)
- (90s) Supported development of DDA (Shi)
- (90s-present) WES/ERDC developed granular mechanics research as extension to research on constitutive relationships on soils.

# ERDC Large-Scale Computing DEM Work



# The computational solution



• The discrete element method depends on high performance computing resources. • Discrete element models are fundamentally simple but display realistic *emergent* behavior.



• DEM is in its formative stages but with HPC support will become a powerful analysis tool

#### Simulation Details Non-Spherical Particles

 Rotation resistance derived from non-spherical particles fundamentally different from that derived from rotational resistance at contact.



#### Simulation Details Poly-Ellipsoid Particles

- Non-spherical particle readily implemented into any DEM code for ellipsoids.
- Peters, Hopkins, Kala and Wahl (2009), *Engineering Computations*



#### **Recent Work by Hopkins**



#### Ploy-ellipsoid particles

#### **Polyhedral particles**



# Limitations and Research Needs

- Application of DEM has an inherent limitation caused by the linkage between time and spatial scales – the smaller the length the shorter the time that can be modeled.
- Better understanding of the convergence of the method.
  - Theory not available for DEM systems
  - Softening of particles gives limited advantage, increasing mass not at all
  - Centrifuge-style scaling must account for size effects

#### **Principal Themes**

# 1. You cannot compute what you do not resolve. *The Numerical Sage*

2. Numerical error appears as real physics but at the wrong scale.

#### **The Particle Scale**



Cutaway View of Discrete Element Simulation of Plowing in Soil



# Calibration Issues and Convergence







# New Directions: Nano-Scale Granular Media



# Soil Mechanics in Space Science

- Must be careful applying soil mechanics derived from earth experience to other environments
  - Weathering (or lack thereof)
  - Lack of atmosphere
  - Surface charge
  - Initial condition
- DEM can make its greatest contribution in understanding space soil mechanics

# Grain-scale Studies and Media Simulation (CRREL)





# **Concluding Remarks**

- Suite of models needed
  - Small scales (DEM) to understand granular mechanics
  - Large scale (Anvil) for mission evaluation
- DEM can contribute to understanding engineering properties of materials we can't test

